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27 September 1962

(TE) SUMMARY OF SATELLITE RECONNAISSANCE PROGRAM

1. CORONA-M - 162

The CORONA-M project is an extended version of the CORONA effort, consisting of two CORONA 34" focal length f3. 5 panaramic cameras mounted at a 30° convergent angle for storeo. Capacity of each camera is 7800 feet of 70 mm thin-base film, covering 4.5 million square miles per flight. In addition, a 1.8" focal length framing camera and 85 mm Stellar camera is included, to enhance the use of the panoramic photography. The system utilises the THOR/Agena vehicle and the recovery method is the same as previously used in the singlecamera CORONA flights.

The first CORONA-M flight launched in February 1963 resulted in a satisfactory mission and subsequent operation has confirmed the high qualities and dependability of this configuration. To date, there have been 12 launches - ten of which have resulted in the successful recovery of the payload.

Since 15 June 1982, seven launches have been accomplished and all have been successful.

Mission 9037 was launched on 22 June and was recovered after 50 orbits with no malfunction. 9038, the first using an Agena D.

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was launched on 28 June and recovered after 63 orbits, but the framing camera did not operate. 8039, launched on 20 July, was recovered after 2 days because of a programmer failure. The frame camera again failed and there was fogged film. 8040, launched on 37 July was recovered after 4 days. The frame camera failed. 9041 launched on 1 August, and recovered on schedule, showed fogging of the frame camera film. 9042 was launched on 39 August and again the frame camera failed. The frame camera failures have resulted from shutter malfunctions due primarily to the shutter design. The new Frame/Stellar camera has been redesigned and will be in all future missions. 9043 was launched on 18 fleptember and due to velocity meter malfunction

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had an orbit that was higher than normal (363 nm). Apogee was in the

In addition to the 7 CORONA-M vehicles presently scheduled for flight (see schedule on last page) 8 CORONA-J vehicles are scheduled for next year. The CORONA-J is a CORONA system modified to have two complete recovery systems. These will provide double the present

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capacity and will result in a 7-day active life. A total of 30 days can elapse (130 nm perigee decaying to a minimum of 80 nm) between launch and recovery of the second capsule. The first operation will be for 4 days. Subsequent to the first recovery the arbiting vehicle will be spun up and infrequent TLM readings will be taken to determine status. Ephemoris will be maintained by SPADATS. The second operation will be for 3 days with the same recovery procedures for recovery of the second operation. The problems are to provide heat to the IRP and restabilization. The first COROMA-J/TAT system is planned May 1963, with a total of 8 scheduled for CT 63. COROMA-M will be interchangeable with COROMA-J.

2. LANYARD

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This project was initiated in May 1963, in order to obtain photography at an early date with resolution between and CORONA-M. The system consists of a greatly simplified version of the discontinued 101B (E-5) project, using the same 66" focal length optical system and some of the camera hardware already produced. The recovery system is the same as that used for CORONA-M. The launch vehicle is a THOR/Agena, with the THOR augmented by three XM-33 solid rochet

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boosters which will be dropped at about 60 seconds after launch. The vehicle will have a 4-day life and should produce photography with a ground resolution of from 4.5 to 5.5 feet at altitudes of 110-130 nm.

The 5 LANYARD payloads will be interchangeable with the additional CORONA-M and ARGON payloads which are available, affording considerable flexibility.

3. ARGON

ARGON is a photographic project for geodetic and mapping purposes. It consists of a 3" focal length frame-type terrain camera of high geometric fidelity, supplemented by a 3" focal length stellar camera, both recording images on a single roll of 5" film. The terrain camera capacity is 6000 photographs (235 x 235 nm format) covering 186 million square miles in a 4-day mission. Storeo is provided by overlap in the photographs. Expected positional accuracy obtainable from this photography (alone) is 750 feet, and expected contour accuracy is 1500 feet. The same basic THOR/Agena vehicle and recovery system is used for ARGON as for CORONA.

After 4 previous unsuccessful attempts, the May 1962 ARGON flight was successful. Results were useful but not as good as expected

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due to incorrect stellar exposure, and due to a terrain camera shutter malfunction during the latter part of the flight.

Mission 9042 was launched on 1 August 1962, and performed successfully. However the capsule was lost when the parachute separated from the capsule during the aircraft anatch operation.

Two ARGON missions are scheduled for October, but some doubt exists as to whether the second one, presently scheduled for 28 October, will be launched before spring as sun angle and snow coverage in the target areas reduce the value of such film taken that late in the year.

4. 722 (698BJ-201/E-6)

Project 722 is a photographic area coverage system designed for 8-10 feet resolution. The sensor consists of two 36" focal length 1/4 panoramic cameras with a 23.4 degree stores angle. Development was initiated in October 1960. The system will obtain 14,000,000 square nautical miles of coverage during a 5-day mission of which 9,000,000 square nautical miles will be non-redundant.

Four flights have been made with this system. While these flights did not result in obtaining record, they were extremely valuable in obtaining data relating to the design, development and operation of

the system. PAKOLF VIA TALENT. VEYHOLE CURNHELS BANDLE VIA TALENT STEEL ONLY

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The first flight, on 26 April 1962, was described in the June report, but is included in the attached summary chart.

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The second test validle was launched on 17 June 1962. The vehicle experienced a high centrol gas consumption rate caused by a constant pitching and yawing force apparently resulting from a lask in the Agens fuel system. As a result of the high gas rate, a decision to attempt to recover the vehicle on the 10th orbit (a night, south-tonorth pass near Hawaii). The de-boost velocity was low due to Agena fuel depletion caused by the leak and the vehicle impacted 600 miles long. The re-entry vehicle did not separate from the mid-section because of a short in the separation equils circuit. Both cameras apparently operated property, although there was an indication that B camera failed after transporting 3600 feet of film. Analysis indicates that this was probably a telemetry mentior point failure rather than a camera failure.

The third flight test vehicle was launched on 18 July. The secondary propulsion system did not fire prior to Agena burn during injection. Orbital operations were nominal except that A camera failed after transporting 3600 feet of film. When de-boost was attempted, the Agena ullage rocket again failed to fire and since the remaining Agena

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fuel was not properly positioned in the tanks after having been in a zero-G suvironment, the Agena engine did not fire.

The fourth flight test vehicle was launched on 5 August. The vehicle operated properly throughout the launch, injection and orbital phases of the mission. The A camera film transport was inoperative during the entire mission. This was most probably due to a spurious command during pre-launch activities. B camera failed after transporting 1620 fast of film. The de-boost and separation sequences were performed as programmed. The parachute did not open, and the recovery vehicle was destroyed on impact. This failure was most probably caused by wake heating entering the access holes in the aft end of the vehicle. The recovery vehicle is being subjected to considerable testing and modification to prevent a recurrence of this failure prior to the next flight. The access holes are being closed or buffled, wires are being re-routed and the thermal protection compound on the aft end has been changed.

As may be noted, from the above, each problem with the exception of film transport has been corrected and has not occurred a second time. Extensive minor redesign and modification of the film transport system and changes in the test procedures promise better performance in this area on subsequent flights.

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Significant changes since the June report are:

a. The program haunch rate has been decreased as shown on the schedule chart.

b. A decision has been reached with regard to recovery methods. Air snatch of the recovery vehicle has been determined to be feasible and will become the primary recovery mode at an early date.



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There have been three other attempts to launch POPPY devices, one in 1960 and two in 1962. All of these failed to orbit due to booster failure. Although original planning provided for two more launches using SCOUT vehicles during 1962, steps have been taken to provide a launch of OPPY payload in November, using a TEOR/Agens booster, in place of the two SCOUT launches.



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Project 417 was initiated in August 1961, with the objective of

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providing dely cloud cover information of the area of interest in direct support of the forecasting activities which support the satellite reconnaissance program. The 417 space vehicle weighs 100 pounds, and is spin stabilised in a 400-mile orbit. Expected useful life on orbit is 90 - 120 days. Through magnetic tape recording of a video image, vertical cloud cover pictures of about one-mile resolution will be provided to read-out stations at Vandanberg AFB and New Boston, N. H.

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The first launch was attempted on 23 May 1962. On that launch the second stage of the BLUE SCOUT vehicle exploded and orbit was not achieved.

The second launch was accomplished 23 August 1962. All booster systems operated normally, and the 417 payload achieved an excellent orbit with apogee of 463 nm and perigee of 340 nm. The progression rate is just over 1° per day. This is well within the nominal required for successful accomplishment of the mission. All satellite subsystems have been operating satisfactorily since the launch. Attitude re-orientation was completed by the 50th pass and full mission coverage began on pass 51. As of 23 September 1963 (one month after launch). 1411 pictures were received of a total of 1627 which could have been received. This represents a retrieval rate of approximately 90%.

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Of the pictures retrieved, fewer than 5% have been unuseable -- all others have been incorporated into daily operational forecasts propared by the Global Weather Central, in direct support of the satellite recommissance activities. Present indications are that the satellite can continue to provide useful information through about mid-January 1963. The Global Weather Central has evaluated the picture quality and usefulness of 417 material as being excellent to superior.

The third 417 vehicle will be ready for launch by late October, but it is not planned to make this launch until the psyload presently on orbit fails.

The program costs to date, which include buying the first four vehicles and payloads, have been just over

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PROGRAM SISSION PERFORMANCE

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Mission No.	Atles	Agene B	Paylood Vokisie	Transported-Astual Vi. Cammaaded	Receivery Vehicle	C and C	
t	OK	Plane of solid ullage restot im- NC pinged an main nezzie causing debaset fullure.	OK	70 %	NA	OK	
H .	OK	OK	Demoge to abouts at hatch out dis- NB abid separation programmer.	78 %	NA	OK	
18	OK	Electrical failure in SPS led to NG main angles no- fire an debeast (no ullage)	OK	78 %	NA	OK	
. IV	OK.	ex	64	23 %	Reservery failed to activate - probable MB cause improper air- cult protection against webs hasting.	OK	
NOTES: C.B.	C Covers (round station at wall a	eranand system op	erstien.	······································		· · · · ·

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LAUNCH SCHEDULE

as of 28 Sep 62

