

## SYSTEM AND IMAGE FORMING

### INTRODUCTION

The generally optimistic technical attitudes expressed in the literature regarding multiple targets are felt to be without sufficient substantiation. The excess sensitivity of the electronic system, in addition to the overall system complexity, poses the question as to whether there is a real basis for such optimism. This portion of the discussion will be limited to those requirements involved in the image forming to image scanning processes, but will not concern itself with the telemetry link which is covered separately herein.

### SYSTEM REQUIREMENTS

The I-2 system's performance is quoted consistently at 200 lines per TVI high contrast of 10<sup>3</sup> lines per MIL. A direct conversion to measurement in object space immediately reveals discrepancies related to the anticipated 20-foot ground resolution. A high contrast target (100:1) at 200 lines per MIL yields a detectable dimension of approximately 9 feet on the ground at a scale of 500,000:1 (300 statute miles). It is generally accepted that to recognize an object, it must have from 3-5 times the detectable dimension. Therefore, this 9-foot dimension (detection) will be approximately 30-50 feet in size before recognition level is attained. In view of the fact that operationally we are dealing with low contrast targets (and assuming the same figure of 100 lines per MIL), the expected ground object size will be approximately 30-50 feet in size. At this point, it should be noted that the I-2 system is not designed to recognize objects smaller than 30-50 feet in size.

assumption that the above conditions are based upon a static relationship of camera to ground. The effects of system dynamics during the time of exposure are discussed in the further body of this report, in addition to the effect of weather upon system output.

Further, the above discussion is related to nadir position only, and obviously implies that conditions become worse for increased obliquity.

#### CAMERA ORIENTATION PROBLEM

The E-2 camera is basically a strip camera. The slit is, of necessity, oriented such that it is perpendicular to the flight path. The 70 MM film is then fed in a path parallel to the flight path, and at a velocity equivalent to the relative ground velocity. Object and image planes are thereby synchronized, and exposed by means of a slit in the focal plane. The slit width and film velocity establishes the exposure time, with the forward motion of the vehicle providing the "scan" motion. The camera is supported in a 3-axis gimbal system so that the optical axis may be directed to / 150 miles of the vehicle nadir for preselected target areas.

The preselection function is seriously questioned by virtue of the implicit aiming problem. The transverse dimension of the film represents for this focal length a total angular field of 3.2 degrees. Assuming a safety factor of 50%, a target must, therefore, be angularly determined within a strip of 1.6 degrees from a vertical height of 300 miles! This represents an accuracy of

approximately one part in 50 as related to the accuracy settings of three camera gimbals, comparable vehicle stabilization control, and accuracy of vehicle location in orbit. As may be seen in Table D-2, page D-6, the maximum tolerances for roll is inconsistent with the desired accuracy, and the suggested tolerance just adequate rather than a safe value. There is obviously a very low probability that the preselected 17x17 mile target area can be photographed.

In effect what has occurred in this design, is that the image motion compensation problem has been simplified and the aiming problem made substantially more difficult. For comparison, the "C" program equipment is more suited for the problem. The "C" camera is properly oriented such that a panoramic sweep occurs across the flight line. The long dimension of the "C" film (wide angle) is then suited to easily satisfy the E-2 aiming problem. With "C" cameras, non-overlap and overlapping photographs would then virtually insure target area coverage. The "C" configuration is decidedly an improvement over that of the E-2 configuration.

#### STABILIZATION PROBLEMS

As a further result of the tight control required, the vehicle stabilization demands motion control consistent with the anticipated performance. As may be seen in Table D-2, page D-6 (appendix), the tolerances for roll, pitch, and yaw rates are stated as maximums of  $\pm 2.1^\circ/\text{min}$ ,  $\pm 2.4^\circ/\text{min}$  and  $\pm 4.4^\circ/\text{min}$  respectively.

inherent in the system, coincides with the fact that from orbit attitude (roll rate) a roll rate of  $1^{\circ}/\text{minute}$  corresponds to a motion of 126 arc seconds/second, or 1.26 arc seconds in an exposure of 0.01 second. The 1.26 arc seconds represents a ground motion of approximately 9.6 feet which at nominal value already borders on deterioration of resolution. For this represents the blur component along the photographic slit axis. By the same token, the roll axis component contributes to a lack of DMC, which in turn contributes image flur in the film feed direction.

A twenty-(20) foot object on the nadir at an altitude of 300 miles represents an image on the film of 0.0004 inches, or 10 microns. Accepting for the moment the criterion of 60% image motion compensation the residual acceptable blur is but  $1^{\circ}/\text{min}$ . Small motion indeed for exposures of 0.01 seconds time. This means that in 0.01 seconds the stabilization equipment must be capable of maintaining this degree of control. If stabilization control is not closely affected, or, if exposure time increases (longer), resolution of the systems is adversely affected.

It is doubtful that this degree of accuracy is presently inherent in the E-2 system, or that this is even presently possible within the current state of the art of photographic equipment and satellite vehicles of these generic types. Vehicular stabilization to the degree required ( $0.5^{\circ}/\text{min.}$ ) is believed to be most optimistic and inaccurate.

#### WEATHER PROBLEMS

Despite the fact that much data exists regarding cloud cover, no true operational level of performance is stated for the E-2.

Optimal photographic performance does not mention the effect of haze (industrial or natural) which would most certainly effect end performance. The latter is of less significance as compared to the cloud cover problem.

From available weather data, it has been determined that approximately 50% of the area of the USSR is cloud covered most of the time. At least 40% of the remaining areas are determined to be partially cloud covered. Only 20% of the entire area is considered open and clear, and this on a rather sporadic basis as related to moving cloud pattern.

The E-2 system operates on a basis of preselected target areas. There are no sensors aboard which provide remote ground indication for the presence of cloud cover. This is a problem of significance as related to the E-2 photographic system, for the angular field of its film record is but 3.2 degrees square! It is therefore, not at all inconceivable that cloud cover can completely obscure the full field angle of 3.2 degrees. Moreover, this may occur even when a normally usable condition of 0.2 to 0.3 cloud cover exists. Here again the problem of narrow angle lenses obliquely related to cloud cover is evident. Solar position is important too for the sun at the incorrect angle to the cloud openings will provide undesirable shadow on the ground scene below the opening. Such a situation is at best most difficult, and reduces to approximately zero the probability of overlapping exposures. The low probability of accurately locating a single exposure through the cloud openings is most evident.

The effect of clouds on exposure, compatible with a high density system, is also discussed in the report.

CRITERIA

Photographic cameras of high resolution are particularly subject to deteriorating performance at high resolution. The greater the resolution, the more sensitive the camera becomes to the environment of motion. An increase in resolution (smaller image size) the reduced contrast options inherent in motion lead to a lowered performance. The atmosphere plays its usual role and this "usual" represents yet another large undesirable contribution among many others. The slit camera does have one unique characteristic which sets it apart from all other cameras - a dynamic shutter capable of very short exposures. There is no cheaper or more reliable means for minimizing the effects of motion than shutter speed. It is obvious that this markedly useful characteristic of the slit shutter has been forsaken under the attraction of "high resolution", overlooking the complexity of the exacting compensations necessary to make a strip camera useful at exposures of 0.01 second. This represents the penalty purchase of high resolution at the cost of very slow emulsion speed.

This leads next to the problem of camera exposure control. The camera is provided with a glass plate in the focal plane upon which metalized slits are plated. This metalized plate is employed as an expedient to the problem of slit width, which is difficult to maintain in parallelism at narrow separation. The slit plate is capable of indexing a variety of slit widths to a single exposure.

the ground coverage required by course and ground control systems. The present system cannot, however, provide the necessary control in presence of cloud cover. Here it is necessary to determine the cloud cover in order to reduce the ground coverage to a minimum. The present system does not accommodate this situation, nor does it supply the necessary sensory data to make such a reduction possible. It is even questionable as to whether the ground control system is capable of providing advance data for optimum exposure which accommodates the normal change of ground reflectivity encountered on each orbit.

Additionally, the base slit plate assembly also introduces the undesirable light loss by insertion into the optical path. While the thickness of the plate is not indicated, some light energy is lost due to surface reflection, and absorption over the thickness. While the narrow angular field is helpful in this circumstance, it is still not preferable where nominal exposures are already stipulated at 0.01 seconds.

#### FILM

The film, SO 24-3, is but another modified version of a very popular and long standing favorite, microfilm, an emulsion long known for its inherently high resolution and low speed. It is indeed surprising that the E-2 system, which represents a decided sophistication in the state of the art, has been tailored to this emulsion. There is

to provide the E-2 with a more effective stabilization system. The high resolution coupled with high sensitivity would have substantially lessened the design and control burdens until such time as the state of the art in resolution and sensitivity is adequate to the task of supporting the E-2 mission.

What this means at present, is that the 243 (600 lines/mm) resolution suffers markedly in the degradation of image quality. This image degradation is not linear in function, and therefore, with the added complexity and weight of the stabilization system, the control, the stabilization requirements increase exponentially with the resolution requirement.

Lower resolution film (e.g., 30 lines/mm) could provide an associated high resolution sensitivity (as much as 5-10 times higher than 243) resulting in a desirably short exposure time and attendant image freezing ability. This degree of relief would also remove the present E-2 burden of exacting control of its stabilization system ensuring its compatibility with the state of the art.

There is no question but that the emission problem is one which should receive pertinent attention and inclusion in present technical development planning. It is recommended that

OPTICAL SYSTEM WINDOW

No sufficiently detailed optical description is available so that one may determine if the lens system window has been designed as a part of the basic optics. The writers of this memorandum note the fact that in operation the optical system must be held so rigidly and hermetically that it cannot be expected to

effect of window qualification load and pressure loading.

The pressurization level is stated at one atmosphere of nitrogen. Assuming a 10-inch diameter window, the total load upon the window is 1100 pounds approximately. Unless the window thickness is sufficiently thick to withstand this load, the window will become bowed and its zero lens power characteristic changed. If lens power is so introduced, it may be of such magnitude as to shift the focal plane position. This is critical in view of the extremely narrow range of critical focus.

The lens system window is critical, under load, for internal stresses (from temperature gradients and/or pressure) can approach such magnitudes where its resultant quality sets the resolution limit of the entire optical system. It is essential that the window be kept in a stable condition, for the existence of thermal gradients will vary the quality until such time as the window resumes thermal stability.

The present LMD procedure for ground collimator test of the E-2 camera does not provide that the camera be pressurized to match the expected airborne situation. This should be remedied such that the ground and air conditions be as identical as possible. Data derived from adjacent program areas have also indicated that one atmosphere of pressurization is not required. Thus, 100, should be reviewed.

#### GROUND CONTROL OF PHOTOGRAPHIC

The E-2 photographic system provides for command control or resolution. This is accomplished through two servo-motors which are

on the ground is used to determine which of several targets is best.  
How is the operator to know if the target is normal mobility  
window effects, misalignment due to launch forces? In the absence  
of resolution targets somewhere on the ground, it is generally  
impossible to make an adjustment in resolution control. This  
operational mode absolutely requires redefinition and evaluation.

#### STEREO PHOTOGRAPHY

Brief comments are also included in the E-2 report regarding the availability of stereo photographic coverage at angles up to  $\pm 17$  degrees. It is not at all clear just how camera orientation is programmed for this purpose. Intuitively, the value of such stereo is questionable in view of the involved geometry. It is considered doubtful that such height data could be of value unless points of known elevation are located in the overlap area. On this basis relative measurements might be of some value, but at best, questionable. A convergence angle of 34 degrees at a scale of 528,000:1 (nadir only) cannot begin to provide elevation details much less than 500 feet. This is not considered worthwhile in the light of the equipment complexity required to provide this motion, nor in the light of the complex mission requirements previously discussed above.

### PROCESSING LIMITATIONS

The chemical processing in flight involves the use of monobath solutions. There is no doubt that if a data link is to be used that this be the process used. The monobath process does effect the latent image resolution, for unlike conventional processing it cannot provide the compensation for continuous gamma and density control. On a film recovery basis there is no doubt but that conventional processing with the close control available will yield desirably high results than a monobath process. The ground process would even compensate for the unexpected variations of airborne exposure.

### FILM SCAN METHOD

Subsequent to monobath processing and drying the film is then presented in a gate to be scanned by a flying spot scanner and related optics. Here image resection occurs. The 2x2-inch frame is then scanned in 0.1-inch x 2-inch strips for the data link transmission. This means that in a 2-inch frame length, the system deliberately introduces 19 breaks in image continuity. Assuming a 1% linearity (sweep) the abridged areas can vary by  $\pm .001$  inch, or  $\pm .44$  feet at each scan section interface. This appears most undesirable.

### SUMMARY

As a result of the above considerations, the following summary is offered in the hope of more properly reorienting the program direction. It is recommended that we proceed to:

1. Reevaluate for the X-2 system the "C" program equipment in view of the above data and the anticipated problems.

1. **What is the name of your company?**  
2. **What is the address of your company?**  
**3. What is the telephone number of your company?**  
**4. What is the name of your company's president?**  
**5. What is the name of your company's vice-president?**  
**6. What is the name of your company's treasurer?**  
**7. What is the name of your company's secretary?**  
**8. What is the name of your company's general manager?**  
**9. What is the name of your company's sales manager?**  
**10. What is the name of your company's advertising manager?**