### NRO APPROVED FOR RELEASE 1 AUGUST 2015

FINAL REPORT

TOP SEGREF ZARF

## BIT II MISSION 7065

17 June 1966

Cy of 7 Cys BYE-40028-66 Handle Via BYEMAN-TALENT-KEYHOLE Controls Jointly NRO APPROVED FOR RELEASE 1 AUGUST 2015

### FINAL REPORT

BIT II MISSION 7065

### PROGRAM OBJECTIVES.

The objective of this program is to determine if and when the Agena vehicle is tracked by a radar operating in the 150 to 300 MHz frequency range. The BIT II system, designed to fulfill this objective, covers the VHF band with a hunt-lock-on receiver which searches for strong signals having wide pulse widths characteristic of long range surveillance and tracking radars. On those signals which qualify, the system locks on to determine if the emitter is continuously tracking the vehicle. Gross parameter measurements are made during this period which enable an analyst to determine the signal characteristics for possible emitter

identification.

#### MISSION SUMMARY.

2.1

2.

Mission Highlights.

The BIT II system intercepted the signal on 11 March 1966 from 0847:31Z to 0849:14Z during orbit 23. Although the Agena vehicle was passing through the sector of coverage at a range of approxi-

mately 285 nm during the intercept, the emitter did not lock on and

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-- Continued. 2.1

continuously track as evidenced by the continuous frequency scan noted during the entire intercept.

The system made several intercepts of allied search radars located around the perifery of the Soviet Union. These included the

	Flight Summary.	•
	Vehicle number	1622
•	Launch date	9 March 1966
	Launch time	2202Z
•	Inclination	75 degrees
	Apogee	236.3 nm
	Perigee	97.8 nm
	Period	90.6 minutes
	BIT II system	Serial No. 8

2.3 Mission Coverage.

This mission, which was launched on 9 March, was prematurely terminated after orbit 173 on 20 March due to the depletion of the primary battery power. The mission was scheduled for a 200 orbit life. Of 74 programmed tape recorder readouts during the 173 orbits, one was

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3.

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cancelled, one was short, two were lost because of low battery voltage, and thirteen were lost because of tape recorder malfunction. Part of the data recorded prior to tape recorder readout failures were recovered on subsequent readouts. Data from approximately 20 orbits were lost completely due to the readout problems.

The system was typically operated whenever the vehicle was above 10 degrees north latitude. Once during each 24-hour period, it was operated during an entire orbit.

## OPERATIONAL RESULTS.



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Pulse interval

Pulse width

Pulse count

Discriminator range

(g)

Duration of sweep lock

l to 100 msec Low Channel 1 to 50 msec High Channel 20 to 200 μsec

20 to 1500 pps non-qualified

10 to 500 pps qualified

-3.5 to +4.0 MHz centered at 70 MHz

4 sec

# 4.2 System Operation.

A general description of the BIT II system is given in the Appendix of the Final Report for Mission 7063. The system block diagram is also shown in previous Mission Reports.

The BIT II unit used on this mission functioned properly throughout the mission. The unit did not generate false pulse qualifications when subjected to dense signal environments as did the units used on the first two missions. This was the first unit flown with the modified Pulse Width Qualifier integrator circuit which has a fast (less than 0.5  $\mu$ sec) decay time to prevent false stops from groups of narrow pulses. Although this modified circuit apparently corrected the problem of false stops, the uitlimate effectiveness of this circuit modification will not be determined until a unit is flown using the maximum detection sensitivity of -60 to -65 dbm. This

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## 4.2 -- Continued.

mission was flown with the sensitivity preset to -50 dbm which considerably

reduced the pulse density of the signal environment as seen by the BIT II

system.

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