



170 SERIES
PAYLOAD OPERATIONS MANUAL
POM 11-71

NAVAL RESEARCH LABORATORY

170 SERIES

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I.1. R. F. SYSTEM

R.F. SYSTEMI R.F. SYSTEM DESCRIPTION

The R.F. System employed in these payloads is designed to improve:

a. Transmitters -

- (1) Better frequency stability
- (2) Lower incidental A.M. and F.M.
- (3) Higher R.F. efficiency and output power level
- (4) Lower spurious responses and unwanted harmonics
- (5) More stable modulation
- (6) Short and open circuit protection
- (7) Better E.M.I. characteristics

b. A.M. Command Receivers

- (1) Preselector bandwidth
- (2) More linear A.G.C. characteristics
- (3) Better E.M.I. characteristics

(a) Housekeeping Telemetry Transmitter -

This unit is a Phase Modulated (P.M.) transmitter operating at a fundamental frequency in the band from 136 to 138 MHz. The transmitter modulator accepts digital or analog voltages and provides an output carrier of 0.25W at a modulation index from 0.5 to 1.5. The input + D.C. power lines are isolated from ground, and both supplies are internally regulated. The regulators provide a constant R.F. output with voltage inputs of +11

to ± 15 V.D.C. Any transmitter power variation will be due to temperature change (-10 to $+ 60^{\circ}\text{C}$) and will be less than 1 dB. The transmitter output is protected against short and open circuit conditions by a ferrite isolator (block diagram Figure 1).

(b) Command Receiver (A.M.) -

The command receiver is a fixed tuned 142.XXX, single conversion, superheterodyne receiver designed for use on a rocket launched, earth orbital satellite with a minimum mission life of two years. The command receiver will demodulate an amplitude modulated carrier at this frequency and provide an audio output that is representative of the original amplitude modulation. Considerable effort has been made to make this unit immune to E.M.I. and R.F.I. Exceptionally sharp R.F. selectivity is accomplished by using an input crystal filter. The crystal filter is a 6-pole design with an input and output impedance of 50 ohms. It has a -3 dB bandwidth of 35 KHz, -60 dB bandwidth of 0.5 MHz, and -80 dB bandwidth of 1MHz. The crystal filter exhibits greater than -100 dB rejection of all other out-of-band signals. The in-band-loss is approximately

5 dB. The receiver has a sensitivity of -105 dBm for 10 dB $\frac{S + N}{N}$ (signal-plus-noise to noise ratio) with a dynamic range of -105 dBm to -50 dBm. The output voltage into 100 ohms is 6.0 \pm 1.5V p-p, can operate on a positive or negative D.C. supply, and draws 18 mA stand-by current (Block Diagram Figures 2 and 3).

(c) Antenna Design Description -

The telemetry and command systems employ a common antenna system consisting of four $\lambda/4$ elements mounted on the northern hemisphere of the spacecraft. These elements are fed in a turnstile arrangement to produce essentially omni directional radiation characteristics. The radiation from the south pole of the spacecraft towards earth is essentially right-hand circularly polarized for telemetry and left-hand circular for command.

II R. F. SYSTEM SUMMARY

The TM and Command Receiver Block Diagrams can be seen in Figures 5 and 6. From the Effective Radiated Power (ERP) measurements tabulated below, coupled with the antenna patterns in Figures 7, 8, 9, various R. F. Link calculations can be made with respect to look angle. In the following, only zenith and horizon will be considered since these are the worst and best cases for signal strength.

TYPICAL E.R.P.

<u>System</u>	<u>Measured R.F. Output in dBm</u>	<u>Measured ERP</u> <u>Ref. to Eθ (dBm)</u>	
		<u>θ = 120°</u>	<u>θ = 180°</u>
TM	23.7	23.7	22
Command Receiver	-102 (Input)		

170 SERIES LINK CALCULATION (UP-LINK) TM

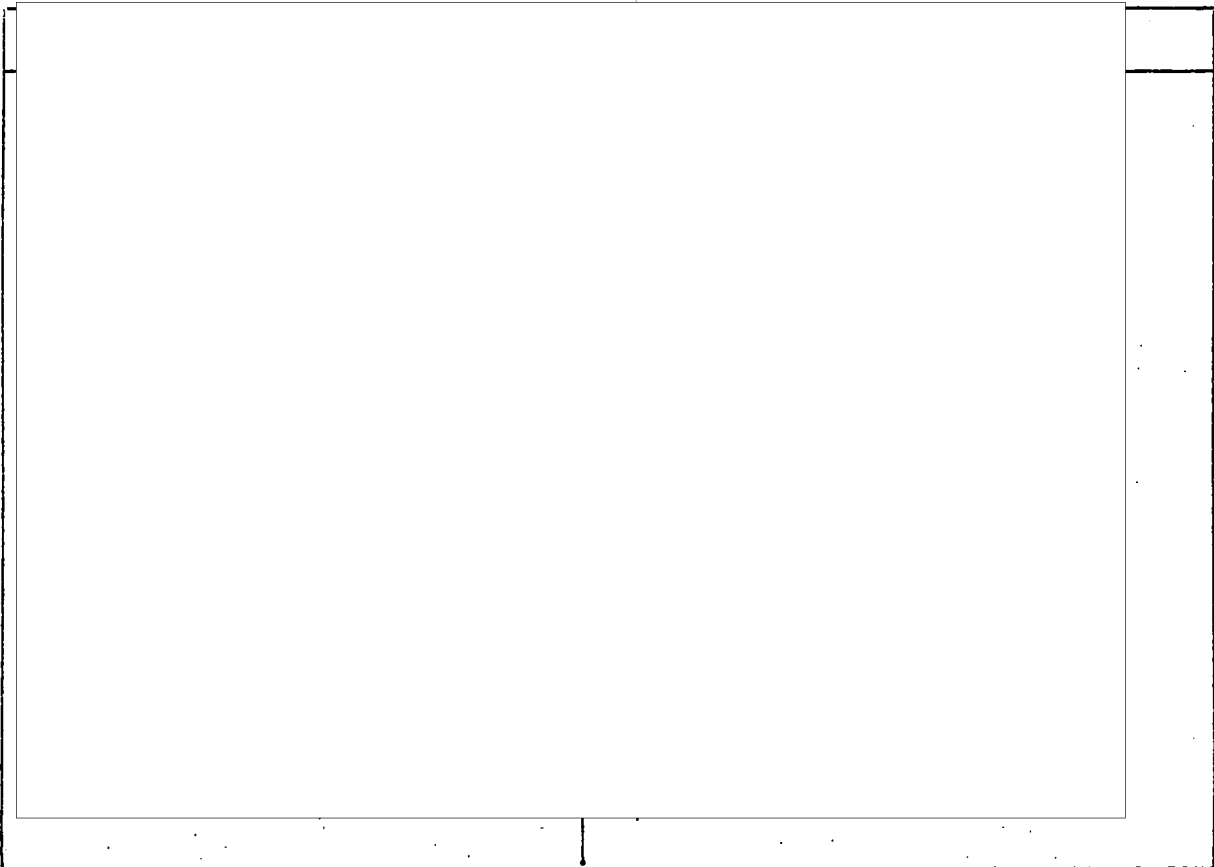
Cir. Orbit 4/3 earth R

527 N.Mi. - To Zenith $P_L = 135.2$ dB

2210 N.Mi. - To Horizon $P_L = 147.8$ dB

Rec. Sen. @ Peak - $R_S = -102$ dBm

Radiated Power - $K = +57.5$ dBm



170 SERIES LINK CALCULATION (DOWN-LINK) TM

E.R.P. = Horizon +23.5 dBm

Zenith +22 dBm

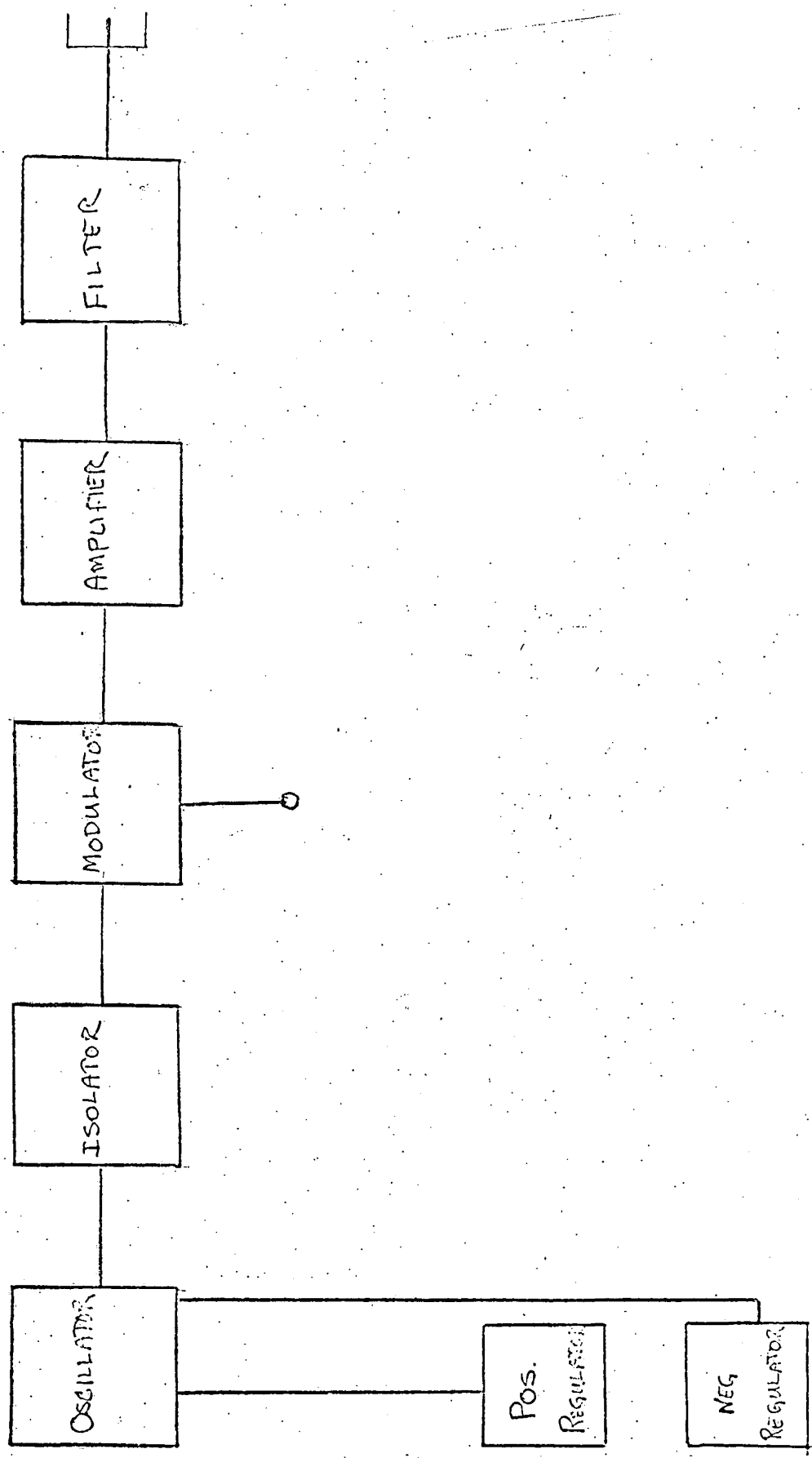
Note: Linear Polarization E_θ (Horizontal)

Orbit - 527 N.Mi. Circular d₁ = 527 N.Mi. P_L = -134.8 dB

d₂ = 2210 N.Mi. P_L = -147.6 dB

Note

FIG 1 T M TRANSMITTER



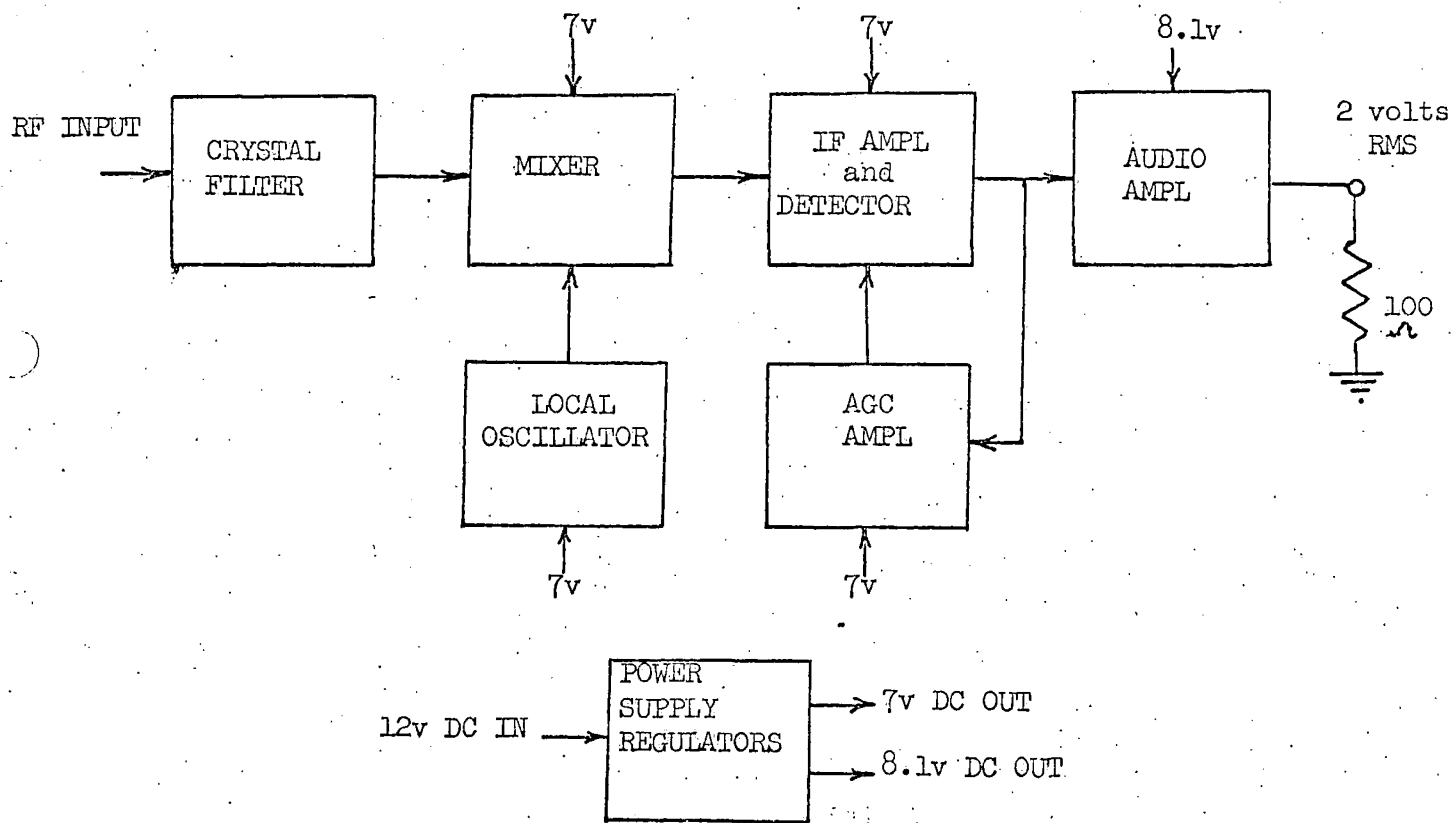


FIGURE 2 - VHF AM COMMAND RECEIVER, BLOCK DIAGRAM

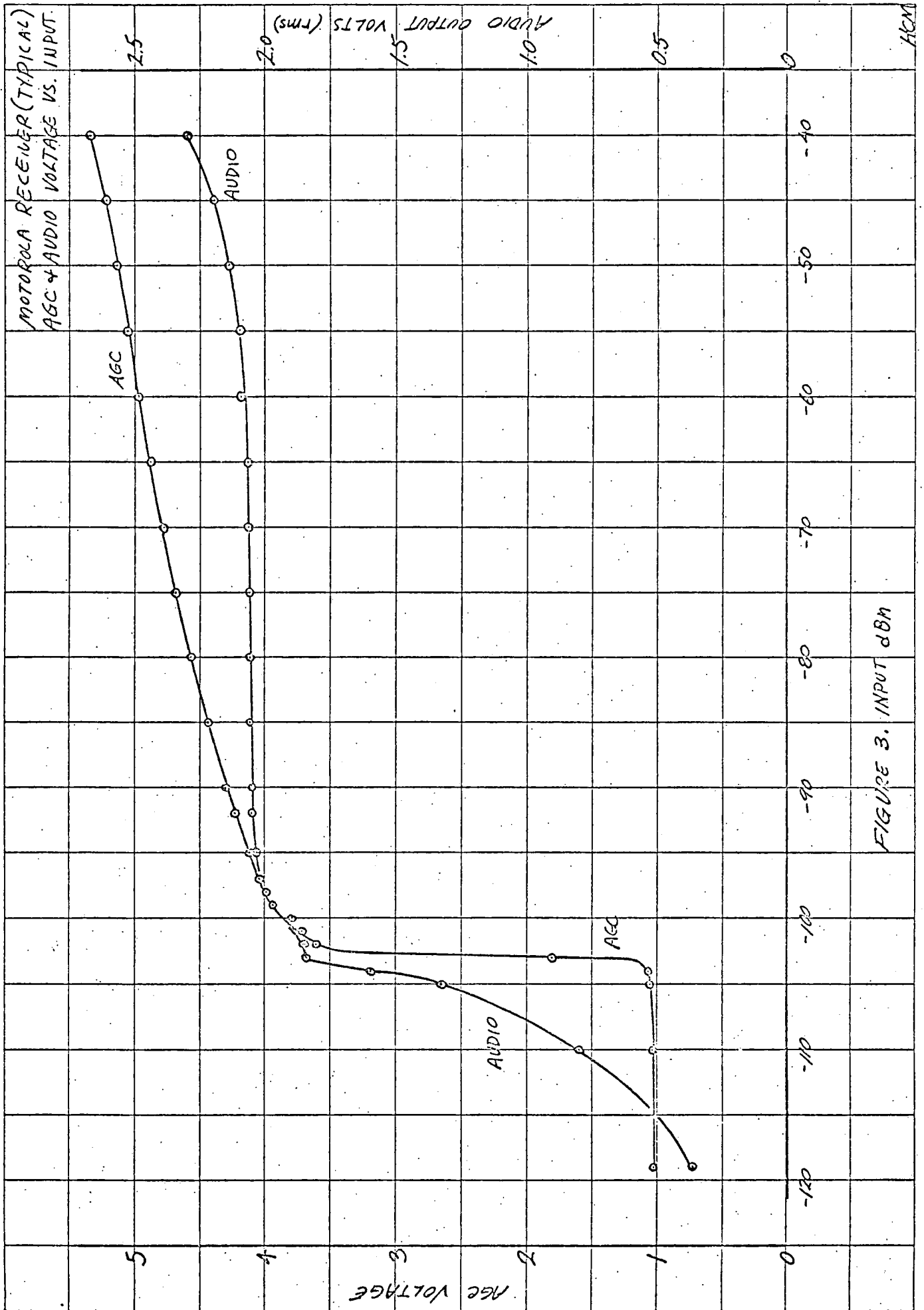


FIGURE 3. INPUT dBm

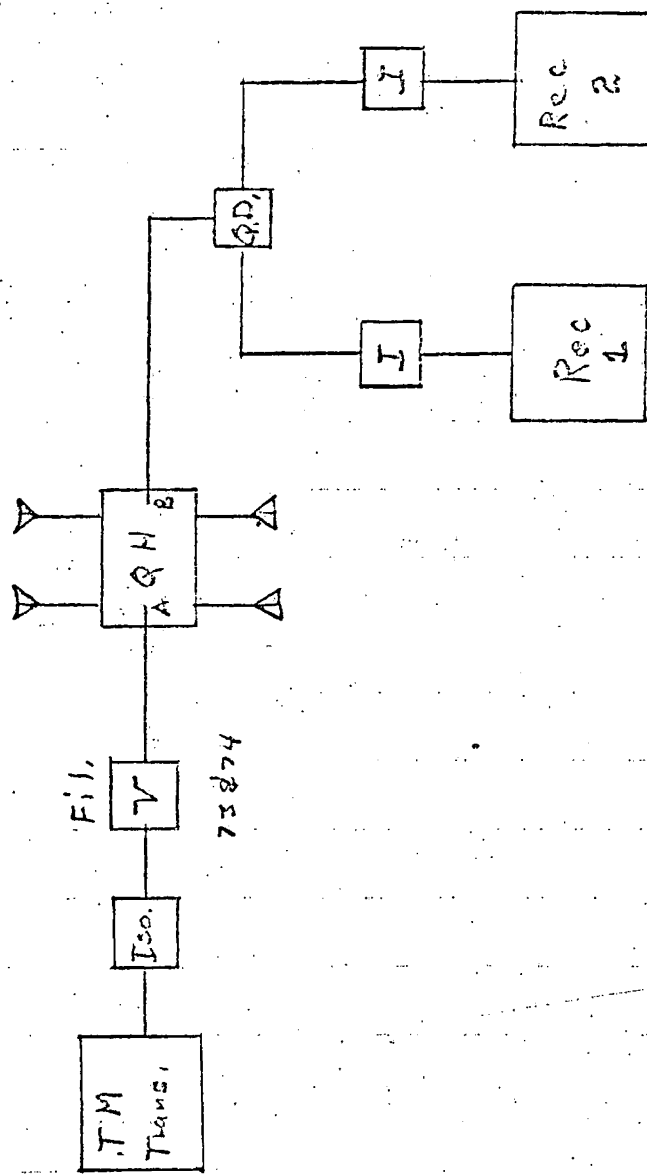


Fig. 5 TM & Command Rec. Block Diagram

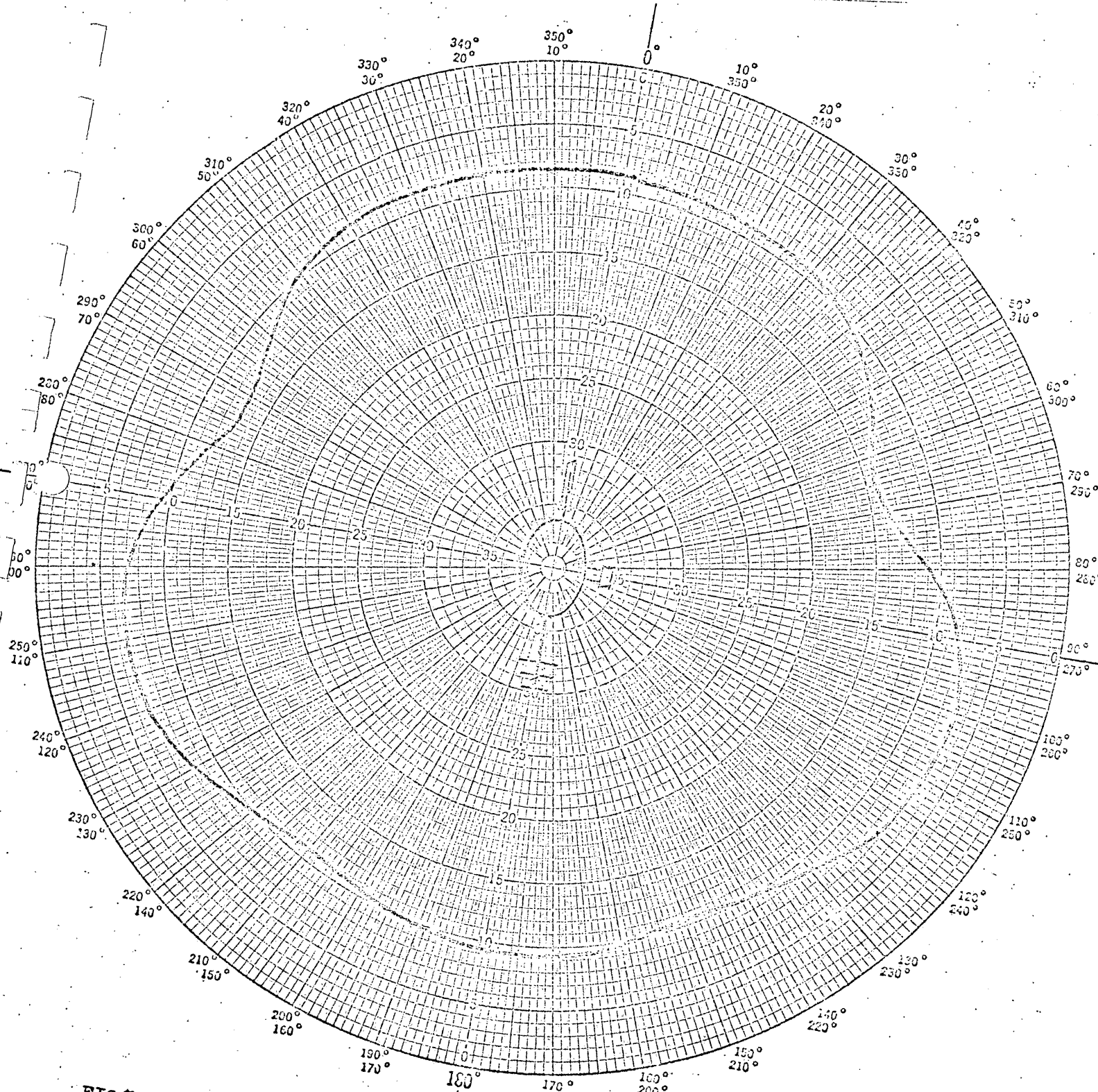


FIG 7. TYPICAL COMMAND RECEIVER ANTENNA PATTERN
Chart No. 1270 $\theta = 30^\circ$, E POLARIZATION
ATLANTA, GEORGIA

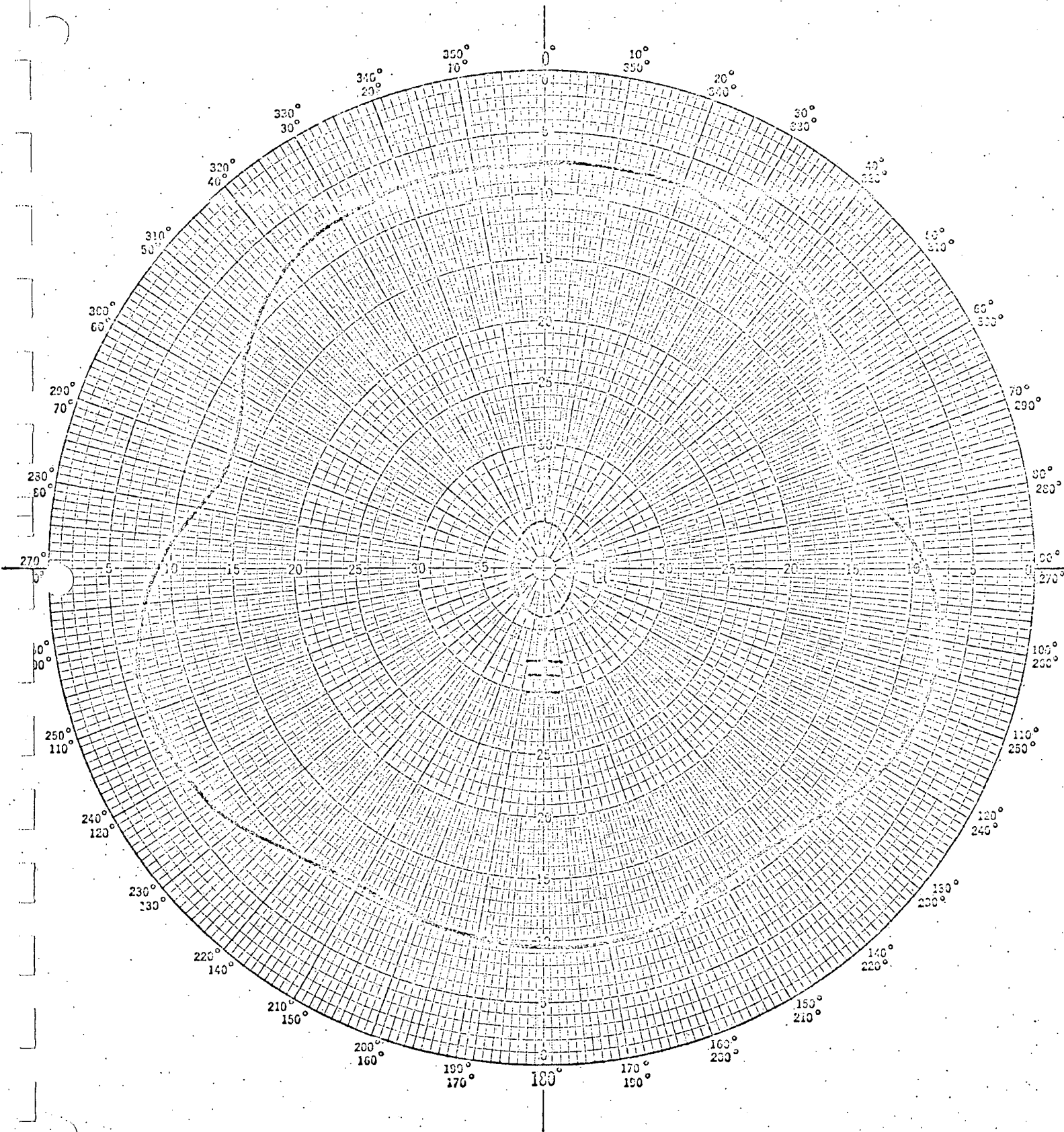


FIG. 8. TYPICAL TELEMETRY TRANSMITTER ANTENNA PATTERN

Polar Chart No. 127D $\theta = 30^\circ$, $E\theta$ POLARIZATION, ALL NUMBERS BELOW 30 DBI ERP
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ATLANTA, GEORGIA

I.2. COMMAND SYSTEM

I.3. MEMORY SYSTEM.

170 SERIES DIGITAL TELEMETRY AND MEMORY SYSTEM OPERATION

The 170 Series PCM Telemetry System performs very similar to the 160 Series System. The major changes to the system are in the areas of increased redundancy. The system performs three main functions: samples and encodes realtime telemetry data, samples and formats telemetry data for storage in the satellite memory, and provides the necessary control for reading this data out of the memory and formatting it for transmission over one of the payload R.F. down-links (Figure 1).

The PCM Encoder is formatted into a main frame of 128 words consisting of 8 subframes of 16 words each. The encoder samples 56 single-ended, high level (0 to 5.00^V) analog channels and 16 differential high level analog channels, converting each sample to an eight-bit binary coded word. The system also samples 308 discrete inputs as 38 eight-bit words. The 110 samples along with sync words constitute a major frame. The real-time major frame format is detailed in Figure 3 .

The encoder provides all the necessary timing and control signals to sequentially store the last 8 eight-bit words of any preselected minor frame or subframe in the accompanying satellite memory. The subframe to be stored is selected by forming a binary coded word with the subframe select 1, 2, and 3 commands and the subframe reset command. The system has four sampling rates once every frame, 4 frames, 32 frames or 64 frames where a frame is 2.56 seconds. The encoder functional time periods are given in Figure 2 . The Mem A1 Sample, Mem A0 Sample, Mem B1 Sample, and

Mem B0. Sample commands are used to control the states of the command code flip-flops that are used to control the sample rate according to the following table:

<u>F_B</u>	<u>F_A</u>	<u>Sample Rate/Frame</u>
0	0	1
0	1	4
1	0	32
1	1	64

The encoder will continue to sample at this rate and store data in the memory until 512 samples (the memory capacity) have been stored. The encoder senses the last address output from the memory and inhibits further storage until the memory has been read out.

The encoder maintains the memory in a standby condition until it receives an external read-command. The encoder will start the readout of the memory at the beginning of the next major frame after receipt of this command. Encoder outputs labeled PCM realtime and memory will contain memory data during memory readout. The transition from realtime data to memory data is coherent when the memory is read out. The clock, clock phase, frame sync and subframe sync remain the same during a memory readout. The exact format is shown in Figure 4. During readout, words 6 thru 15 are replaced with a 4-bit flag word, a 12-bit word containing the contents of the memory address register for the block of each eight eight-bit words that were stored. The remaining eight 8-bit words will be the stored sample. The entire 512 samples will be read out four (4) times. At the

completion of the fourth readout, the encoder will return to its realtime mode of operation. At this time, the encoder will initiate a fifth memory readout with the purpose of restoring a test pattern of alternate 1's and 0's. This fifth readout will not be inserted into the output data channels. Its purpose is to place a test pattern into memory which will be read out of all locations that have not had data stored into them. This will be the case when a read command is received prior to the encoder's storing the complete 512 samples into memory. The test pattern serves as a diagnostic aid in the event of system malfunction.

The entire system can be operated at two commandable bit rates, 400 bps or 1600 bps. All memory data sampling is referenced to the 400 bps rate, e.e., the 2.56 sec frame rate, and will not change at the higher bit rate (Figure 2). Example, at a sample rate of 32 frames, it will take 11.65 hours to fill the memory at either a 400 bps or 1600 bps realtime data rate.

All memory samples can be related to an exact Greenwich mean time by use of the PCM system absolute timer. The timer consists of an eight-bit vernier timer and a 16-bit absolute timer forming a 24-bit time word. The vernier timer is driven at the main frame rate of 2.56 sec. and is displayed in every main frame in word 1-3. When the vernier time reaches a count of 255, the contents of the 16-bit absolute timer will be displayed in words 1-4 and 1-5. The normal data in words 1-4 and 1-5, the cell monitors will not be displayed at this time. The PCM timer system is easily synchronized to GMT since the entire system is synchronous. The timer can

be reset to zero by using the PCM timer reset command at a precise GMT setting or the system can be synchronized by recording GMT at precisely the moment the vernier timer increments. Once a time reference between GMT and the vernier timer is established, all memory samples can be tied to an exact time in the orbit, as the absolute time and vernier time are stored in the very first sample stored into memory, and all succeeding samples are spaced at exact time intervals from the absolute time and vernier time increments. On the first sample of eight eight-bit words stored in the memory, the first three words are replaced with a 24-bit time word (8-bit vernier time and 16-bit absolute time). This is true regardless of the subframe being stored.

At the completion of the four memory readouts and the load test pattern, the first memory sample is taken and the 24 bits of time are stored. At the instant the data is shifted into memory, words 8, 9, and 10 of the particular subframe being stored will display the contents of the 24 bit time that is loaded into memory. The previous system in the 160 Series had to wait to acquire sync with the incrementing 16-bit absolute timer before storing its first sample. This was necessary as we were storing only 16 bits of time. On this system, since we store the contents of the vernier timer, it is not necessary to wait for the 16-bit absolute timer to increment. Once the system has loaded the test pattern, the system goes directly into the sampling mode.

The main encoder of this system was designed such that any random failure it might suffer would be a soft failure and would not be catastrophic.

The system has redundant commandable oscillators, A/D converters, power regulators, master timer and multiplexers, and output serializers and code converters. The distributed data buss is designed such that the digital multiplexer gates are isolated from each other so that a single bit failure in any one word will not affect any other word. The strobe signals and timing to the gate is such that no more than four words analog or digital would be lost by a single component failure in the worst case. In addition to the PCM encoder being redundant, much of the telemetry data is also available on a back-up analog system.

The PCM system's 32K memory system is not a redundant system. A single component failure in a critical circuit would be catastrophic, but would not jeopardize the mission or make its operational use difficult as would the main encoder.

The encoder system has four data outputs, two realtime all the time and two that have realtime data interleaved with stored data. Two are NRZ-L and two are bi phase-L coded. Figure 1 shows the various combinations of possible downlink routing. The only data routed to Irig CH 12 is NRZ-L and can only be 400 bps due to the frequency response of CH 12. If the higher bit rate of 1.6 Kbps is selected, a different downlink other than subcarrier CH 12 must be selected. When the system is commanded into the Mod. digital mode, there will be no analog data present. The modulation will be bi phase-L PCM data as it will on any alternate downlink. The selectable modulation and downlinks allows the system to remain operational in the event of a modulator failure by selecting an alternate link.

All data is binary coded with a scale factor of 255 equal to an input voltage of 5.080 volts. The data is aligned LSB first. The subframe sync is the complement of the main frame sync and uses the unique recycling code as the method of subframe sync.

The ground station equipment used for "quick look" of the PCM telemetry data consists of either Data Control Systems model 4002 or 4004 decoms. The major difference between the 4002 and the 4004 is that an external Bit sync is necessary with the 4004. Word selectors for stripping out both analog and digital words have been designed by NRL and tailored to meet all NRL spacecraft requirements. The words to be displayed are thumbwheel selectable by word and frame. Figures 3 show the entire PCM telemetry format. Each word is labeled by the frame and word position in the frame, i.e., 7-14, frame 7 and word 14. The entire format is programmed on a plastic card that controls the 4002 and the 4004. The programming of the 4002 and the 4004 is different; therefore, a red card is used to identify the 4004 and a white card for the 4002. Both units can be programmed to accept data either MSB aligned or LSB aligned. All units will be supplied programmed for LSB operation. When programmed for LSB operation, the thumbwheel settings must be advanced by one for each word for words 0-14 and for words 15 both the frame and the word must be advanced by 1. Figure 3 denotes this with an asterisk. The difference in the thumbwheel settings for LSB or MSB programming for the 4002 or 4004 represents an operational nuisance. Once the decom is programmed and the

proper thumbwheel settings are known for each word in the format, they will not change; but it is important to remember this if the card programming is changed or decoms changed for any reason.

IRL PCM ENCODER

Functional Time Periods

	<u>DATA RATE</u> <u>400 bps</u>	<u>DATA RATE</u> <u>1600 bps</u>
Clock Frequency	819.20 khz	819.20 khz
Clock	204.80 khz	204.80 khz
Bit Time	2.5 ms	625.0 ms
Word Time	20.0 ms	5.0 ms
Subframe Time	320.0 ms	80.0 ms
Frame Time	2.56 sec	640.0 ms

MEMORY STORAGE TIMES (Memory Storage is referenced to the 400 bps DATA RATE at all times)

ONE SAMPLE = Eight - 8 bit words

MEMORY CAPACITY = 512 Samples

SAMPLE RATE: EVERY FRAME	1,310.72 sec	(21.8453 m ; 0.364 hr)
EVERY 4 FRAMES	5,242.88 sec	(87.3813 m ; 1.4563 hr)
EVERY 32 FRAMES	41,943.04 sec	(699.0506 m ; 11.6508 hr)
EVERY 64 FRAMES	83,886.08 sec	(1398.1013 m ; 23.3016 hr)

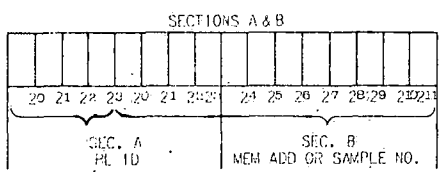
TEST PATTERN LOAD TIME 163.84 sec (2.7306m) 40.96 sec (0.6826m)

MEMORY READOUT TIME

ONE READOUT	163.84 sec (2.7306m)	40.96 sec (0.6826m)
FOUR READOUTS	655.36 sec (10.9224m)	163.84 sec (2.7306m)

Figure 2

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
0	SYNC L8B	SYNC U8B	SF SYNC L8B	SF SYNC U8B	+ CELL MON 2	- CELL MON 10	PLID	MEM. ADD (SAMPLE NUM)									
1			DIG WD ACD	VERNIER TIME	3	11		TO 512									
2			DIG WD CMD	DIG WD MEN	4	12											
3			DIG WD PCM	DIG WD CMD	5	13	SEC. A	SEC. B	THIS 8 BIT COUNTER IS THE SAME AS THE VERNIER TIME-WORD 1-4								
4			DIG WD WAT	SPARE	6	14			LOWER 8 BITS ABSOLUTE TIME	MIDDLE 8 BITS ABSOLUTE TIME	UPPER 8 BITS ABSOLUTE TIME						
5			DIG WD RED. 1-2	DIG WD RED. 2-2	7	15	THESE 3-8 BIT WORDS REPLACE THE NORMAL 3-8 BIT WORDS OF PART OF ANY SUBFRAME THAT IS STORED AS THE FIRST MEMORY SAMPLE AFTER A MEMORY READ OUT.										
6			DIG WD EXP 17	DIG WD EXP 17	8	16											
7			DIG WD EXP 17	DIG WD PAR	9	17											

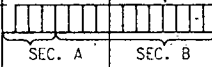


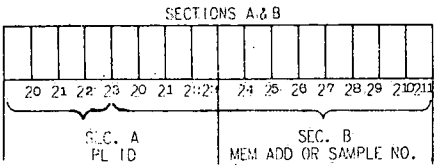
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ID PART

DATA PART OF SUBFRAME 0-7 STORED IN MEM. SAME AS PART OF PCM SUBFRAME 0-7 WORD FOR WORD EXCEPT FOR THE FIRST MEM. SAMPLE AND WHERE A DIFFERENT SUBFRAME IS COMMANDED TO BE STORED

MEMORY READ OUT DATA

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	SYNC LBB	SYNC URB	SF SYNC LBB	SF SYNC UBB	+ CELL MON 2	- CELL MON 10	PLID	MEM. ADD (SAMPLE NUM)								
1			DIG WD ADD	VERNIER TIME	3	11	↓	TO 512								
2			DIG WD CMD	DIG WD MEM	4	12										
3			DIG WD PCM	DIG WD CMD	5	13		<p>THIS 8 BIT COUNTER IS THE SAME AS THE VERNIER TIME-WORD 1-4</p>								
4			DIG WD BAT	EXP. 17 A, B	6	14			<p>LOWER 8 BITS ABSOLUTE TIME</p>	<p>MIDDLE 8 BITS ABSOLUTE TIME</p>	<p>UPPER 8 BITS ABSOLUTE TIME</p>					
5			EXP. 18	EXP. 19	7	15			<p>THESE 3-8 BIT WORDS REPLACE THE NORMAL 3-8 BIT WORDS OF PART OF ANY SUBFRAME THAT IS STORED AS THE FIRST MEMORY SAMPLE AFTER A MEMORY READ OUT.</p>							
6			EXP. 20	EXP. 21	8	16										
7			RETEP	PAR	9	17										



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ID PART

DATA PART OF SUBFRAME 0-7 STORED IN MEM. SAME AS PART OF PCM SUBFRAME 0-7 WORD FOR WORD EXCEPT FOR THE FIRST MEM. SAMPLE AND WHERE A DIFFERENT SUBFRAME IS COMMANDED TO BE STORED

MEMORY READ OUT DATA

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	SYNC L8B 1110 1011	SYNC U8B 1001 0000	SF SYNG L8B 0001 0100	SF SYNG U8B 0110 1111	+ CELL MON. 2	- CELL MON. 10	DIG WD EXP 1	DIG WD EXP 2	+ BATT V ABSTIM	- BATT V ABSTIM	RW TACH ABSTIM	MAG X	MAG Y	MAG Z	DIG WD ADCOLE A	DIG WD ADCOLE B
1			DIGITAL WORD ADD	VERNIER TIME	+ CELL 3	11	DIG WD EXP 3	DIG WD EXP 4	SV CAL.	REC 1- AGC	REC 2- AGC	BOOM LENGTH	+ CELL MON 1	- CELL MON 18	DIG WD SPRO	DIG WD SPRO
2			DIG WD CMD	DIG WD MEM	4	12	5 A, B	6 A, B	TEMP 19 SCP	TEMP 24 BAT BYP	PRESS TH 1 CONTROL	PRESS TH 2 CONTROL	DL TIMER CMD 1	DL TIMER CMD 2	DIG WD BOOM CTL	DIG WD RW CTL
3			DIG WD PCM	DIG WD CMD	5	13	7 A, B	8 A, B	+ SEC V MON	- SEC V MON	TEMP 2 PKG.	TEMP 15 SCP 1	TEMP 3 + SEC BATT	TEMP 4 - SEC BATT	DIG WD THRUSTER CTL	SPARE
4			DIG WD BAT	SPARE	6	14	9 A, B	10 A, B	+ BAT V	- BAT V	TEMP + BAT T 25	TEMP - BAT T 26	+ CHG 1	+ DISC 1	- CHG 1	- DISC 1
5			RED DIG WD SAME AS 1-2	RED DIG WD SAME AS 2-2	7	15	11 A, B	12	TEMP + BAT T 25	TEMP - BAT T 26	TEMP 10 HC 1	TEMP 16 SCP 2	TEMP 20 S TUBE	TEMP 21 BAT 3	TEMP 22 CHG CTL	TEMP 23 V CTL
6			DIG WD EXP 17	DIG WD EXP 17	8	16	13 A, B	14 A, B	TEMP 8 SKIN 1	TEMP 9 SKIN 2	TEMP 17 INNER SC 2	TEMP 12 B BAND	TEMP 13 INR. SC 1 NON STD	TEMP 14 OUTR. SC NON STD	+ SC CHG 1 MON	- SC CHG 1 MON
7			DIG WD EXP 17	DIG WD PAR	9	17	15 A, B	16	TEMP 5 TANK	TEMP 6 NOZ 1	TEMP 7 RW 2	TEMP 18 BB SC 2	TEMP 11 DL BOOM	TEMP 1 POM PK	PRESS TH 2 PLENUM	PRESS TH 1 PLENUM

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	SYNC LBB 1110 1011	SYNC UBB 1001 0900	SF SYNC LBB 0901 9100	SF SYNC UBB 0110 1111	+ CELL MON. 2	- CELL MON. 10	DIG WD EXP 1	DIG WD EXP 2	+ BATT V ABSTIM	- BATT V ABSTIM	RW TACH ABSTIM	MAG X	MAG Y	MAG Z	DIG WD AUXCOL A	DIG WD AUXCOL B
1			DIGITAL WORD ADD	VERTICAL TIME	+ CELL 3	11	DIG WD EXP 3	DIG WD EXP 4	5V CAL	REC 1- AGC	REC 2- AGC	BOOM LENGTH	+ CELL MON 1	- CELL MON 18	DIG WD SPRO	DIG WD SPRO
2			DIG WD CMD	DIG WD MEM	4	12	5 A, B	6 A, B	TEMP 19 SCP	TEMP 24 BAT BYP	PRESS TH 1 CONTROL	PRESS TH 2 CONTROL	DL TIMER CMD 1	DL TIMER CMD 2	DIG WD BOOM CTL	DIG WD RW CTL
3			DIG WD PCM	DIG WD CMD	5	13	7 A, B	8 A, B	+ SEC V MON	- SEC V MON	TEMP 2 PKG.	TEMP 15 SCP 1	TEMP 3 + SEC BATT	TEMP 4 - SEC BATT	DIG WD THRUSTER CTL	SPARE
4			DIG WD BAT	EXP 17 A, B	6	14	9 A, B	10	+ BAT V	- BAT V	TEMP + BAT T 25	TEMP - BAT T 26	+ CHG 1	+ DISC 1	- CHG 1	- DISC 1
5			EXP 18	EXP 19	7	15	11 A, B	12	TEMP + BAT T 25	TEMP - BAT T 26	TEMP 10 HC 1	TEMP 16 SCP 2	TEMP 20 S TUBE	TEMP 21 BAT 3	TEMP 22 CHG CTL	TEMP 23 V CTL
6			EXP 20	EXP 21	8	16	13 A, B	14 A, B	TEMP 8 SKIN 1	TEMP 9 SKIN 2	TEMP 17 INNER SC 2	TEMP 12 B BAND	TEMP 13 INR. SC 1 NON STD	TEMP 14 OUTR. SC NON STD	+ SC CHG 1 MON	- SC CHG 1 MON
7			RETEP	PAR	9	17	15 A, B	16	TEMP 5 TANK	TEMP 6 NOZ 1	TEMP 7 RW 2	TEMP 18 BB SC 2	TEMP 11 DL BOOM	TEMP 1 PCM PK	PRESS- TH 2 PLENUM	PRESS- TH 1 PLENUM

I.4. POWER SUPPLY SYSTEM

170 SERIES POM
POWER SUPPLY SYSTEM

1. The power supply system consists of power source and power conditioning. The power source is composed of rechargeable batteries and solar cell array. The power conditioning consists of charge control, voltage control, battery select, trickle charger, battery bypass, battery bypass voltage control, battery bypass inhibit logic and undervoltage system.

2. Power Source -

a. Battery - There are two battery packs; primary and secondary.

Number of cells - 18

Cell capacity - 5 ampere hours (F-size)

Cell type - Cylindrical - nickel - cadmium employing polypropylene separators

Cell resistance - .01 ohms

Maximum charging rate - .85 amps

Maximum permissible cell voltage - 1.55 volts

Nominal pack voltage - +12v

Maximum voltage excursion - +10v to +14v

Typical voltage excursion - +11v to +13v

Maximum depth of discharge (PLUS) - 9.5%

The primary battery pack has a cylindrical form factor (7" DIAM x 6" HIGH), weighs 12.5 lbs. and is located in the lower support tube. The secondary pack has a rectangular form factor (6.5" x 4.5" x 8" HIGH), weighs 14.3 lbs. and is located on the top honeycomb. Each pack is instrumented with two to three temp. sensors.

b. Solar cell array - The solar cell array consists of 40 body mounted panels and one paddle.

Type	No. of Panels	Strings per Panel	Cells per String	Cell Size (CM)
Small Trapezoid	16	2	32	1 x 2
Large Trapezoid	20	3	32	1 x 2
Rectangular Belly Band	4	2	32	2 x 2
Rectangular Paddle	1	12	32	2 x 2
Total Strings	1 x 2 2 x 2	92 20		

Each string of 2 x 2 cm cells develops 110 ma; each string of 1 x 2 cm cells develops 50 ma. The strings are assigned to the plus or minus side of the line to produce the following:

CONDITION	ma per String	+12 v		-12 v		TOTAL	
		MA	WATTS	MA	WATTS	MA	WATTS
Available power, min. sun	50 & 110	710	8.52	530	6.36	1240	14.88
Available power, max. sun	50 & 110	800	9.6	620	7.44	1420	17.04
Peak power (min sun)	50 & 110	1230	14.76	980	11.76	2210	26.52
Max Peak power (min sun)*	60 & 120	1476	17.71	1176	14.11	2652	31.82
Typical load (TM & RW)		383	4.6	238	2.86	621	7.45
Typical load (TM & RW & EXP.)		724	8.69	509	6.1	1234	14.8

* If solar cells run cool, their output could increase from 50 to 60 ma and 110 to 120 ma.

3. Power conditioning system -

This system controls the maximum charge rate of the battery, the maximum line voltage, provides a solar cell only mode of operation (battery bypass) and unloads the line and selects the secondary battery in the event of low voltage. Monitors are provided for Solar cell current, primary battery charge and discharge current, primary battery individual cell voltage, secondary battery voltage, line voltage, battery temp, solar cell temp, charge control and voltage control heat sink temp.

a. Parameters -

Max charge rate (LO charge) - 200 ma

Max charge rate (HI charge) - 850 ma

Max voltage (Batt Byp Off) - \pm 13.8 volts

Max voltage (Batt byp On) - \pm 13.0 volts

Undervoltage activation - \pm 9 volts

b. Charge Control - This system is designed to limit the maximum charge rate to the primary battery. Two command selectable charge rates limit the current to 200 ma (Lo Charge) or 850 ma (Hi Charge). See curves Nos. 7 and 8. The low charge rate is recommended for the max sun orbit. The operation is as follows: Consider max sun, low charge. The solar cells will supply the current to the load and charge the battery. When the charge rate equals 150 ma, the charge control will start shunting current into the charge control heat sink. This is a proportional control - the higher the charge rate the higher the shunt current. When the charge rate equals 200 ma, the shunt current will be saturated at 900 ma. In

minimum sun, the high charge rate is used. When the charge rate equals 800 ma, the charge control starts shunting current into the charge control heat sink. Since the maximum possible solar cell current is 1.47 amps (+ side), it is not possible to saturate the charge control in the high charge mode. Note the following about the charge control system:

- (1) The charge current monitor provides the control signal to the charge control.
- (2) The charge current monitor receives its power from the HK sensors ON-OFF relay and therefore, the HK sensors must be on for charge control to operate.
- (3) The charge current monitor is provided on the primary battery only; therefore, when secondary battery is selected, there will be no automatic charge control. The charge current into the secondary battery will have to be controlled by adjusting the load.
- (4) The charge control on the plus and minus side of the line operate independently.

c. Voltage Control - This system is designed to limit the line voltage to + 13.8 volts. It is turned on at the same time as the charge control. When the line voltage reaches 13 volts, the voltage control starts shunting current into the voltage control heat sink. At 13.8 volts, the voltage control is saturated and approximately 1 amp is flowing in the shunt. Note the following about the voltage control:

- (1) The voltage sensor provides the control signal to the voltage control.

- (2) The voltage sensor receives its power from the HK sensors ON-OFF relay and therefore, the HK sensors must be on for the voltage control to operate.
- (3) The voltage control will operate on the primary or secondary battery.
- (4) The voltage control is on the line during Battery Bypass operation but will not conduct since the Battery Bypass voltage control is set for a lower voltage.

d. Battery Bypass - This system provides a solar cell only mode of operation, where the battery is taken off the line. A bank of capacitors provides a low impedance source and a shunt regulator (Battery Bypass voltage control) controls the voltage between 12.5 and 13 volts. The Battery Bypass enable provides an alternate method of putting the battery back on the line. Both of these ON commands require ordnance enable. Since a high current load could cause the line voltage to drop, a circuit is provided to inhibit the thruster heaters on command, if either the Battery Bypass or the Battery Bypass Enable relays are on. Also, if the Battery Bypass or the Battery Bypass Enable on commands are sent while the heaters are on, the heaters will be automatically turned off. The following table summarizes the Battery Bypass operation.

Please note as per Jim Winkler that Batt Bypass and Batt Bypass enable are in series. The battery is not truly bypassed unless you have both. This would then explain the underlined sentence in the above para.

Condition -	Battery Bypass	Battery Bypass Enable	Thruster Heaters
Normal-Battery on line	OFF	OFF	ON or OFF as desired
Normal-battery on line	OFF	ON	Cannot be turned on
Battery on line; capacitor bank on line; Battery Bypass voltage control limits line voltage to 13 volts	ON	OFF	Cannot be turned on
Battery off line (on trickle charge); capacitor bank on line; voltage control limits voltage to 13 volts *	ON	ON	Cannot be turned on

* Obviously, if the spacecraft moves into eclipse, all power will be removed from the line.

e. Battery Select - A relay is provided for each side of the line and can be commanded individually to select Primary Plus Battery or Primary Minus Battery and Secondary Plus Battery or Secondary Minus Battery. Four trickle charge circuits are provided to charge each stack when it is off line. The trickle charge rate is 30 ma. The battery, which is on line, is charged directly from the line. Note that in the dark, the battery with the highest potential will charge the other side.

f. Undervoltage System - If either the plus or minus line voltage drops to 9 volts or below, this system will generate a signal which turns off the Reaction Wheel, and the thruster heaters selects both secondary batteries, and resets the experiment. The primary batteries can then be monitored using the cell monitor system on PCM TM. If the plus or the minus batteries are OK, they can be commanded back on the line individually. If not OK, they can be allowed to trickle charge at the 30 ma rate. If the undervoltage circuit is malfunctioning, it can be commanded off.

g. Cell Monitor - In addition to telemetering the total voltage of the primary battery, each individual cell is monitored in both the primary positive and negative package. A 16 Channel differential input commutator that is controlled by the PCM telemetry system monitors the cells of the primary pack placing the data in Words 4 and 5 of each PCM frame. The differential amplifiers for the plus pack and the minus pack both have a gain of 3; thus, the maximum cell voltage when monitored will be 3×1.55^V . The cell monitor commutator and it's associated electronics have been designed such that no single component failure can cause it to load or short out a cell in the pack. The remaining two cells in the pack are monitored directly and appear on Words 1-12 and 1-13 of the PCM system. The individual cells are monitored so that it can be determined, whether or not an individual cell might be losing capacity or the entire pack might be down.

I.5. REACTION WHEEL SYSTEM

REACTION WHEEL SUBSYSTEM

1. The "Reaction Wheel" is a motor driven flywheel that provides the third axis of stability to the payload. While the gravity gradient boom provides roll and pitch stability, the Reaction Wheel provides yaw stability required for thrusting and satellite pointing.
2. The Reaction Wheel Subsystem consists of the "Reaction Wheel", a "Power Amplifier" and a 'Control' unit. The Reaction Wheel is a 400 Hz motor driven flywheel with a tachometer attached to the rotor shaft. The "Power Amplifier" provides the 400 Hz AC power to the "Reaction Wheel" under the supervision of the "Control" unit. The 'Control' unit measures the angular speed of the Reaction Wheel motor from information derived from the Reaction Wheel tachometer, decides whether the speed is less than or greater than a preprogrammed value and then commands the 'Power Amplifier' to deliver power to the "Reaction Wheel" motor if the speed is too low or not to deliver power if the speed is too high.
3. The electronic units of the subsystem, i.e., the control unit and power amplifier are completely redundant. Furthermore, the Primary Control Unit can control the Secondary Power Amplifier and the Secondary Control Unit can control the Primary Power Amplifier. There is only one "Reaction Wheel."
4. The status of the Reaction Wheel Subsystem located on Channel 7, Segments 29, 30, 31, and 32, of the analog telemetry are as follows:

- a. Segment 29 indicates whether the subsystem is ON or OFF and in what direction the sheel will rotate if the system is turned on.
 - b. Segment 30 indicates which control unit and which power amplifier is in use.
 - c. Segment 31 indicates whether the Digital Speed Monitor (See PCM) is ON or OFF.
 - d. Segment 32 gives an analog value of the speed (See RW Tachgraph)
5. A more complete view of the status of the 'Reaction Wheel' Subsystem can be obtained from Words 0-10, 7-10, 2-15, 1-15, and 1-14, of the PCM format.
- a. Word 0-10 contains the same information that Channel 7, Segment 32 of the analog telemetry contains, i.e., Reaction Wheel Speed (See RW Tach Curve). Nominal speed is 800-1000 RPM, any other speed should sound an alarm.
 - b. Word 7-10 contains the temperature of the Reaction Wheel bearings (See RW Bearing Temperature Curve). If this information indicates that the bearings are 5^oC warmer than the immediate surroundings, action should be taken to determine if there is bearing wear and methods of preventing further wear.
 - c. Word 2-15 contains the commanded status of the subsystem.
 - (1) Bit 1 (LSB) indicates that the Digital Speed Monitor (Words 1-15 and 1-14 and Bit 6 of Word 2-15 are capable of giving true information) is ON or OFF.
 - (2) Bit 2 indicates if the Reaction Wheel Subsystem is ON or OFF.

- (3) Bit 3 indicates the direction that the wheel should rotate in, if the subsystem is ON.
- (4) Bit 4 is NOT used.
- (5) Bit 5 indicates which control unit is in use.
- (6) Bit 6 indicates the actual direction of rotation of the wheel (if the following conditions are met: 1. The Reaction Wheel Subsystem is ON and, 2. The Speed Monitor is ON). Bits 3 and 6 of Word 2-15 should be identical. The only normal case when they can differ (given that the subsystem and speed monitor are ON) is if the wheel were rotating in one direction and the command to change the direction of rotation was sent. Bit 3 would change upon receipt of the command and Bit 6 would only change when the wheel had stopped rotating in the original direction and started rotating in the new direction.
- (7) Bit 7 is NOT used.
- (8) Bit 8 indicates which power amp is in use. NB This information is only accurate when the Reaction Wheel Subsystem is ON.

Words 1-14 and 1-15 contain the deviation of the reaction wheel speed from the desired preprogrammed speed and a random reset pattern.

- a. Word 1-15, Bit 6 contains the sign of the deviation while Bits 5

- through Bit 1 contain the MSB of the deviation through the least significant bit of deviation available in this Word. That is, Bit 5 of Word 1-15 contains the MSB or Bit 14 of the deviation and Bit 1 of Word 1-15 contains Bit 10 of the deviation.
- b. Word 1-15 contains Bit 9 of the deviation through Bit 2 of the deviation in Bit 8, the MSB, of Word 1-14 through Bit 1 of Word 1-14. Bit 1 of the deviation or the least significant bit of the deviation is not sent back.
- c. Conditions a. and b. are only valid when a Reset Pattern is not present. A Reset Pattern appears below where a
- Light = 1 No light = 0

(Word 1-15 Bits 6 through 1) 100111

(Word 1-14 Bits 8 through 1) 00101011

When a Reset Pattern occurs, it may be ignored unless there is a gross change from the nominal speed. If a gross change in speed occurs and a continuous Reset Pattern or any other non-changing pattern occurs, a failure within the Reaction Wheel Subsystem has occurred.

I.G. GRAVITY GRADIENT SYSTEM

170 SERIES POM
GRAVITY GRADIENT SYSTEM

1. The Gravity Gradient system consists of two redundant micro-thrusters, a 60 foot extendable boom, and a magnetically anchored eddy-current damper.
 2. Thruster System - The Thruster System provides very low thrust for payload station keeping. There are two redundant systems: Thruster 1, and Thruster 2. These two systems share a common spherical tank five inches in diameter which contains one (1) lb of anhydrous ammonia. Each thruster system consists of a pulse valve, a plenum, a control pressure transducer, a potentiometric transducer, a controlled orifice, a latch valve, a porous plug and a nozzle. Temperature sensors are provided for the tank and the two nozzles. A high intensity heater is provided for each nozzle to improve the specific impulse of the fuel. A control circuit compares the output of the control x-ducer to one of two command selectable levels and controls the opening and closing of the pulse valve.
 - a. Parameters -
 - Thrust levels: LO Thrust - 10 micro-lbs
 - LO Thrust with heat - 10 micro-lbs
 - HI Thrust - 35 micro-lbs
 - HI Thrust with heat - 32 micro-lbs
- Pressure x-ducers (control & potentiometric) - 50 PSI full scale = 5 volts
- Control Pressure x-ducer power - .48 watts (20 ma @ 24 v)

the pulse valve. The output of the comparator is clamped for 30 milliseconds to allow the control x-ducer to stabilize and prevent the pulse valve from opening. The x-ducer output is less than the reference (no pressure in plenum) so the comparator turns on. After 30 ms., the clamp is released and the pulse valve opens. Liquid or gaseous ammonia flows into the plenum. This pressure is sensed by the control x-ducer and its output rises. When the output equals the reference voltage, the comparator turns off closing the pulse valve. This all occurs in approximately 20 ms for liquid service and as high as 150 ms for gas service. The pressure in the plenum is now allowed to bleed off through the porous plug and nozzle providing micro-pounds of thrust. After approximately 40 to 120 seconds, the pressure in the plenum has decreased to the lower trip point of the comparator (hysteresis equals approximately 0.3 volts or 3 PSI.) and the comparator turns on, opening the pulse valve and starting the cycle again. Note that the 30 ms clamp only occurs when power is first applied to the system. The Thruster ON command is also applied to the Thruster Heater Relay (as long as the Battery Bypass logic does not inhibit it) which turns on the heater. If it is not desired to have the heater on, the Thruster Heater OFF command must be sent. This turns off both heaters. Commanding High or Low thrust changes the reference of the comparator and allows the pressure to be high or low. (See Parameters, Section 2a.). The thrusters OFF Command turns off both thrusters and closes both latching valves.

3. Gravity Gradient Boom - A sixty foot extendable boom with a magnetically anchored eddy-current damper mounted at the end provides gravity gradient stability in two axis (pitch and roll). A reaction wheel (discussed in another Section) provides stability in the third axis (yaw). The boom can be retracted to a 20 foot length (defined as the "mid Position") which is optimum for a pitch axis change from "up" to "down". A boom control circuit applies power to the boom motor; senses when the boom reaches the "mid" position, and turns the boom motor off. Full retract and full extension switches are provided to interrupt boom power. The boom motor drives a potentiometer, the output of which is the analog of boom length.

a. Parameters -

Boom Mechanism Manufacturer - Spar Aerospace

Boom Length - 60'

Boom "mid" Length - 20'

Boom Motor - Manufacturer - Clifton

Type - 28v DC

Current - 150 to 250 ma @ 12v

Stall Current - 830 ma @ 12v

Extension Voltage - +12v

Retraction Voltage - -12v

Boom Motor Filter - 2 Section PI Filter

Boom Element - Silver coated, beryllium copper,
 $\frac{1}{2}$ " Diam, interlocked bi-stem

b. Commands -

Boom Motor ON; GG Boom Release	1100JK*
Boom Motor OFF	1101JK
Boom Motor IN	1110JK
Boom Motor OUT	1010JK

* Ordnance Enable required

c. Operation - Once the payload has separated from the vehicle, an ordnance arm switch actuates and enables the GG Boom release command to be sent. The boom motor "out" command is sent. The GG Boom Release command, when issued, actuates a relay which applies power to two double bridge wire bolt cutters. These cutters release the clamp holding the damper in place. The clamp, in turn, releases the GG Boom Release switches which apply power to the motor and begin to drive the boom out. The boom length indicator can be monitored during the extension. When the boom extends past the "mid" position, the boom control circuit, which employs a comparator, will reset and be ready to actuate when the boom is retracted. The boom will continue to extend and at 60 feet, the full extension switch will actuate and interrupt power to the motor. The boom motor "off" command can now be sent.

When it is desired to perform the pitch-flip maneuver, the boom "in" command is sent followed by the boom "on" command. The boom will retract to the "mid" position. At that time, the comparator, using the boom length indicator potentiometer and a fixed reference, will generate a boom "off" command. Since in a pitch-flip maneuver the next step is to re-extend

the boom, the boom "out" command is sent. After a given coast period, the boom "on" command is sent and the boom extends to 60 feet again. If, at the "mid" position, it is desired to fully retract the boom, the boom "on" command can be sent. When full retract position is reached, the full retract switch will interrupt the power to the motor.

I.7. ORDNANCE SYSTEM

170 SERIES ORDNANCE SYSTEM

1. There are eight double bridge wire cutters.

They are as follows:

1. TM ANT REL CUT 1
2. TM ANT REL CUT 2
3. DL BOOM REL CUT 1
4. DL BOOM REL CUT 2
5. GG BOOM REL CUT 1
6. GG BOOM REL CUT 2
7. DL BOOM ARRAY CUT 1
8. DL BOOM ARRAY CUT 2

2. Sequence of events - There are two banks of switches. Each one has an "ordnance arm" switch which puts +12v to the ordnance box after separation. A single "ant release sep switch" mechanically coupled with one of the ord arm switches dumps a charged capacitor into the driver of the ordnance separation timer start circuit. This timer has a duration of five minutes minimum. When it times out, it dumps the charge of a capacitor into the drivers of two relays. Each relay fires one bridge wire in the TM ANT REL CUT, DL BOOM REL CUT and the DL BOOM ARRAY CUT. This will release the TM antennas and the DL BOOM. The DL boom array uses 16 sec. delay cutters and will release after the DL boom is deployed

and locked in place. One other bridge wire in each cutter is fired by two relays which are actuated by command. If the timer circuit works, this command will not be necessary. A final relay operated by command fires the GG Boom release cutters. All commands require ordnance enable.

I.8. THERMAL SYSTEM

Satellite Thermal Design

A thermal study and design is made on NRL satellites to provide a suitable temperature environment for the electronic components and external surfaces of the satellite structure in orbit. Analytical methods have been devised and used in making this thermal study.

The thermal design of the satellite is performed "in house" with the use of six computer programs. Temperature predictions are based on a mathematical model which consists of a series of interconnected isothermal nodes. This model represents the geometry, heat transfer paths and thermal characteristics of the flight payload. The relationship between nodes regarding thermal conduction and radiative interchange is determined and an energy balance for each node of the thermal model is developed and solved by the main heat transfer program. Other programs which determine thermal input, shading, radiative interchange, etc. are used to support the main program.

The internal temperature of the satellite is generally restricted to 0° and 40° C. This can usually be achieved by passive temperature control whereby all thermal precautions are made during prelaunch. Using passive means for controlling the temperature of the satellite increases reliability since there is no dependence on mechanical components, thermal power, and thermo-electric devices.

The principal means of controlling the spacecraft temperatures are by the absorbed and emitted radiation energy and internal power. Most important consideration in establishing shell temperature is the solar absorptivity (α) and emissivity (ϵ) of the shell. As a result passive thermal control can be achieved by thermal coatings and finishes, and the selection and optimization of conduction paths.

Materials and methods commonly used for temperature control of NRL satellites are thermal control points, special finishes, aluminized and silverized teflon for low α/ϵ values, interference coatings (black mirror) for high α/ϵ values, silicon monoxide coatings, thermal tapes, thermal grease at mechanical interfaces, and super insulation.

In future applications active temperature control may be required for some components. As a result investigations are being conducted in the use and application of louvers, heat pipes, thermal electric devices, and phase change materials.

A thermal vacuum facility is available for thermally testing satellites in a space environment. By using a motion simulator and solar simulation tests can be programmed to simulate both the maximum and minimum sun orbital conditions. These tests can be used to check out satellite components under a thermal vacuum environment and to confirm or corroborate temperature predictions of the mathematical model. They are useful in determining thermal time constants in transient heating and temperature gradients in the satellite.

170 Series - Thermal Design

The 170 Series satellites, except as noted later, have the same basic configuration as Exp 162 launched in Sept. 1969. Except for several specific problem areas such as the battery pack and solar panels Exp 162 satellite temperatures were in the designed operating range. The main honeycomb mounting panel and associated electronic equipment temperatures varied between 13°C and 42°C during minimum and maximum sun orbits. As a result no major changes in multiface satellite thermal design were made in the 170 Series satellites.

Passive means have been used in controlling the temperature of the multiface satellite. This is achieved by proper selection of thermal coatings and finishes and optimizing conduction paths. In the 170 Series this has been accomplished by the proper area ratio of silicon monoxide coated and polished aluminum surfaces. Optimization of conduction paths was achieved by using thermal grease and Berlon at critical interfaces. Several exterior changes and additions have been made to the 170 Series satellites. The exterior configuration of the satellites is similar to Exp 162 except for the installation of a 7" x 25" solar paddle on the top shell and the addition of 4 solar panels on the equatorial band and 4 small trapezoid solar panels on the bottom shell. These additions to the external configuration will have some effect on the average maximum, minimum temperatures of the satellite; however, a complete thermal study using a mathematical model would be required to determine the actual effect. Preliminary basic calculations and thermal analysis were made and it was decided that this study would not be necessary.

The following special thermal control procedures were used on the 170 Series satellites.

1. Exp 171, 172, 173 Battery Packs - Ceramic discs were cemented to the bottom of each cell with Berlon to provide a high conductance path to the heat sink surface. Thermal grease was used at all joints.

Exp 174 Battery Pack - Cell mounting plate was anodized and ceramic disc omitted.

2. Solar Panels - The following steps were taken to lower operating temperature of solar cells.

a. External surface of substrate was coated with Dow Corning Thermal Control Coating to lower solar absorptance.

b. Inside surface of panel was painted with 3M Black Velvet Coating to increase internal radiation.

c. Thermal grease was used between mounting flange and satellite skin to increase thermal conductivity.

3. RF Boom - Antenna Assembly - Driven Element. This package will tend to run cold. To neutralize the effect of gold plating on exterior surfaces during the maximum sun orbit the nylon antenna spacer plate attached to the bottom surface of the package was painted with Dow Corning Thermal Control Coating.

4. RF Packages - Thermal grease applied to joint between package and honeycomb mounting panel.

BY _____ DATE _____ SUBJECT EXP 171 SHEET NO. 1 OF 6
 CHKD. BY _____ DATE _____ TEMPERATURE SENSORS JOB NO. _____

SUB COMM INPUT	GROUP	FUNCTION	COMMENT	FIGURE
1	7	PCM. PKG. TEMP.		
2	3	PKG. TEMP.		
3	3	+ SECONDARY BATTERY TEMP.		3
4	3	- SECONDARY BATTERY TEMP.		3
5	7	THRUSHTER TANK TEMP.		
6	7	" 1 NOZ. "		
7	-	" 2 NOZ. "		
8	6	UPPER FRAME TEMP 1		1,4
9	6	UPPER FRAME TEMP 2		1
10	5	HONEYCOMB TEMP.	ABOVE PRIMARY BATTERY PK.	3
11	7	DL BOOM TEMP.	LOCATED ON HYBRID ENCLOSURE	7
12	6	EQUATORIAL BAND TEMP		2
13	6	SOLAR PANEL TEMP 1	LOCATED ON SOLAR CELL	1,4
14	6	SOLAR PANEL TEMP 2		1,4
15	3	SOLAR PADDLE TEMP 1	LOCATED ON SIDE FACING MAG. BOOM	5,7
16	5	PLATE ON MTG FLANGE		1,2,3
17	6	SOLAR PANEL TEMP 3		1,4
18	7	SOLAR PANEL TEMP 1 EQ. BAND		1,2,6
19	2	SOLAR PADDLE TEMP 2		5,6
20	5	SUPPORT TUBE TEMP	ADJACENT TO BATTERY PK.	3
21	5	BATTERY TEMP 3	BOTTOM OF CELL	3
22	5	CH CON H.S. TEMP		
23	6	VOLT CON. H.S. TEMP		
24	2	BATT. BYP " "		

TEMP (MAIN FRAME)

A	(4)(5)	+BATTERY TEMP.		3
B	(4)(5)	- BATTERY TEMP.		3

BY _____ DATE _____
CHKD. BY _____ DATE _____

SUBJECT EXP. 171
TEMPERATURE SENSOR LOCATION

SHEET NO. 2 OF 6
JOB NO. _____

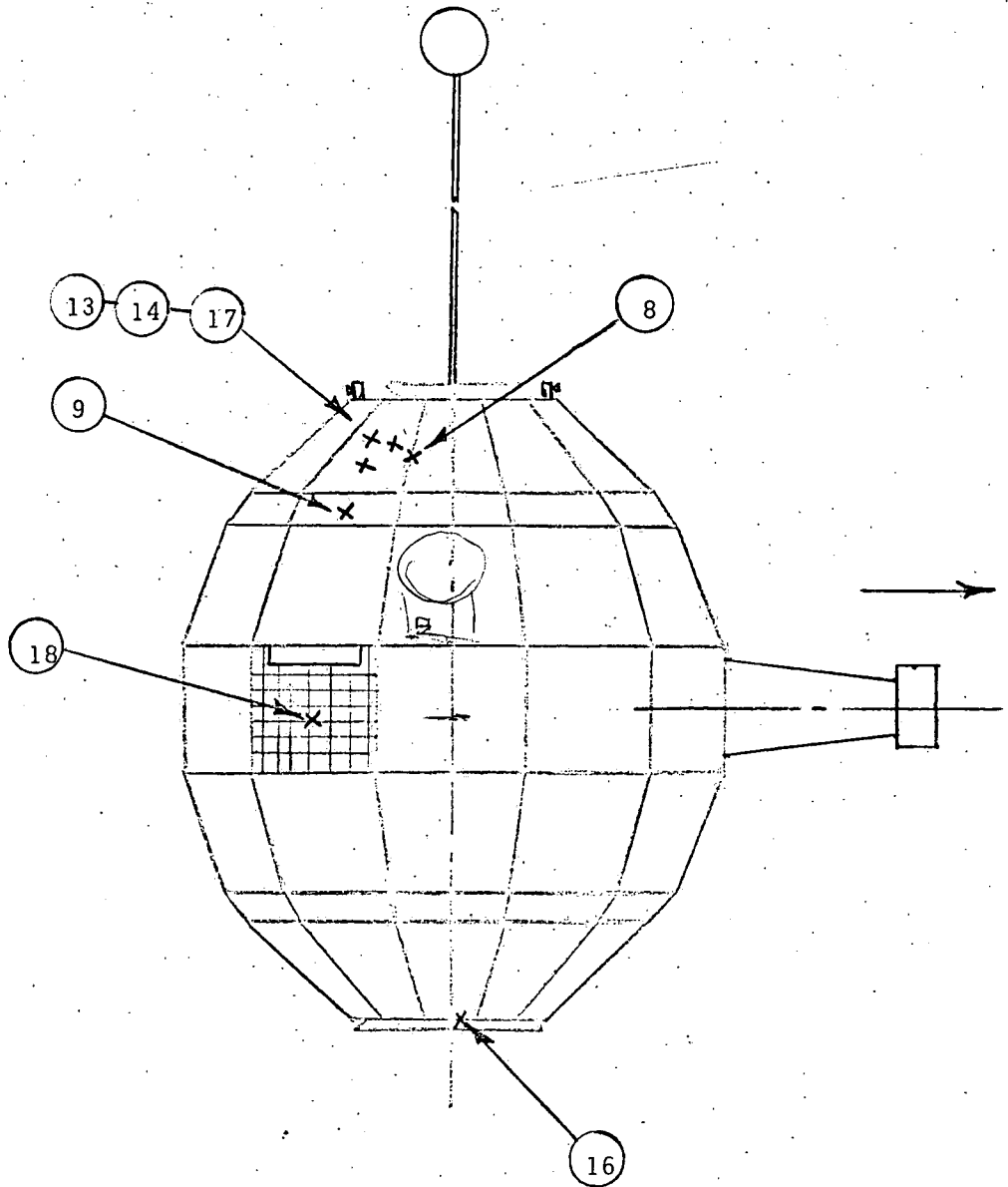


FIG 1

SOLAR PADDLE & RF BOOM
OMITTED FROM THIS VIEW

BY _____ DATE _____ SUBJECT EXP 171 SHEET NO. 3 OF 6
CHND. BY _____ DATE _____ TEMPERATURE SENSOR JCB NO. _____
_____ LOCATION _____

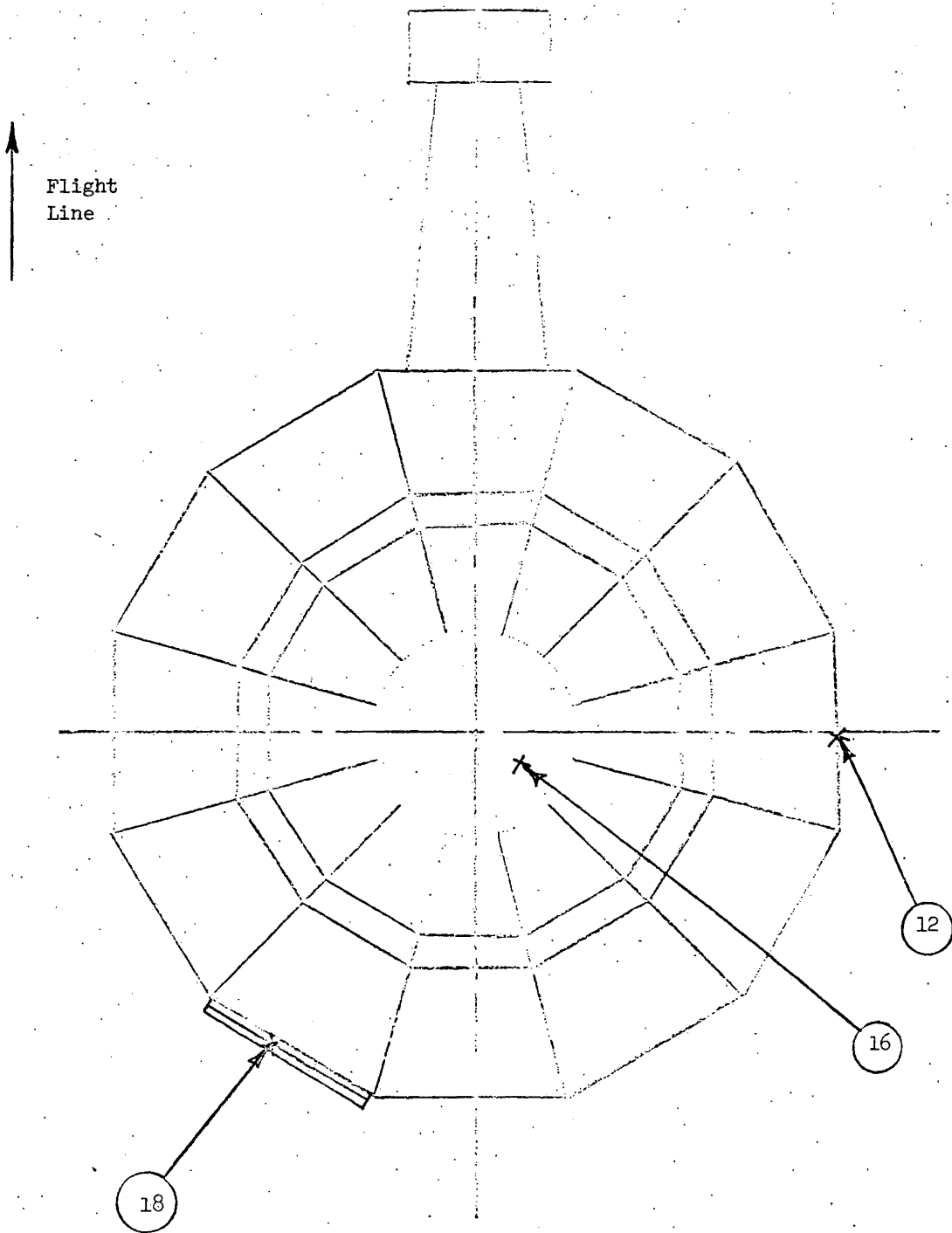


Fig. 2
Lower Skin

BY _____ DATE _____ SUBJECT EXP 171 BATTERY PACKS SHEET NO. 4 OF 6
 CHKD. BY _____ DATE _____ TEMPERATURE SENSOR
 LOCATION _____ JOB NO. _____

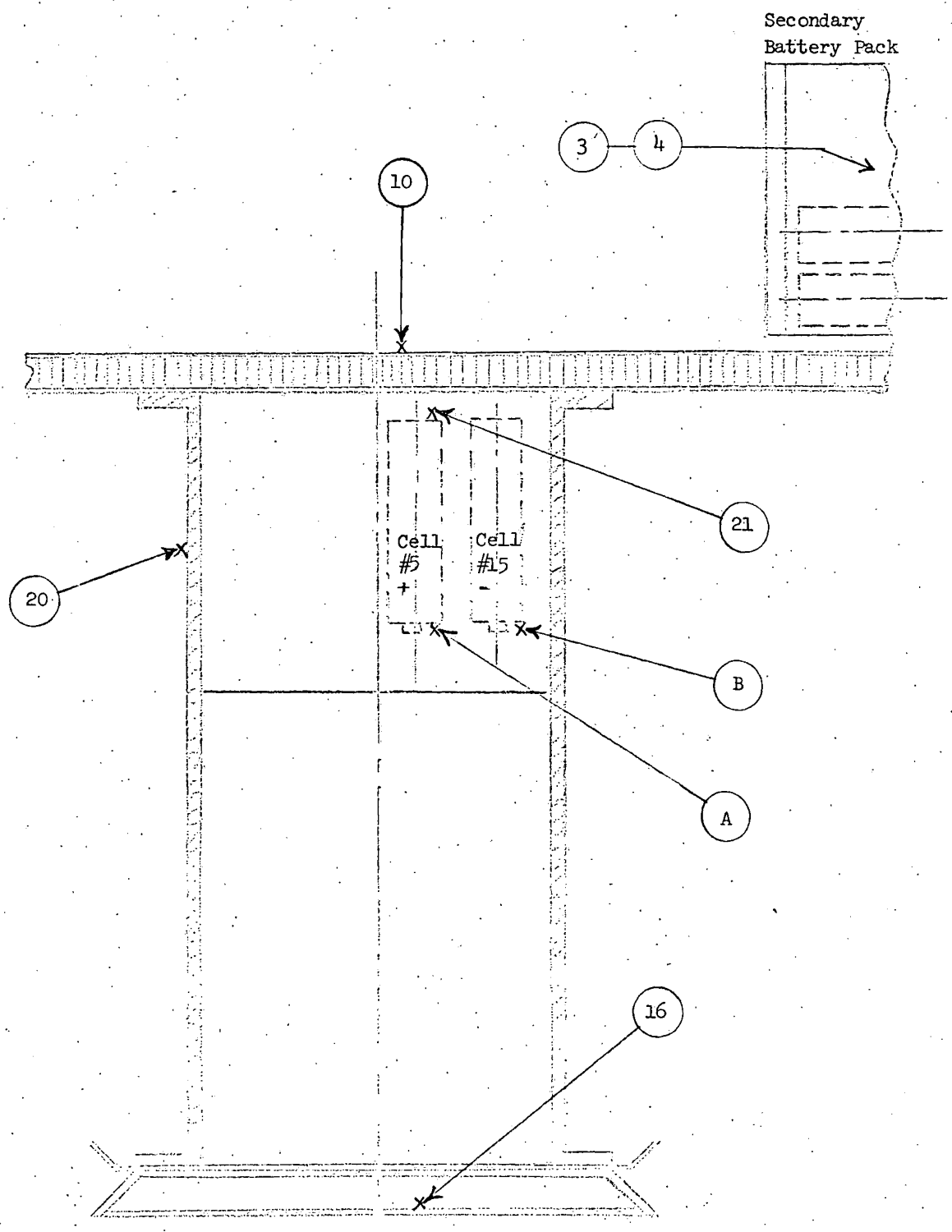


Fig. 3

BY _____ DATE _____
CHKD. BY _____ DATE _____

SUBJECT SOLAR PANELS
TEMPERATURE SENSOR LOCATIONS
EXP 171

SHEET NO. 5 OF 6
JOB NO. _____

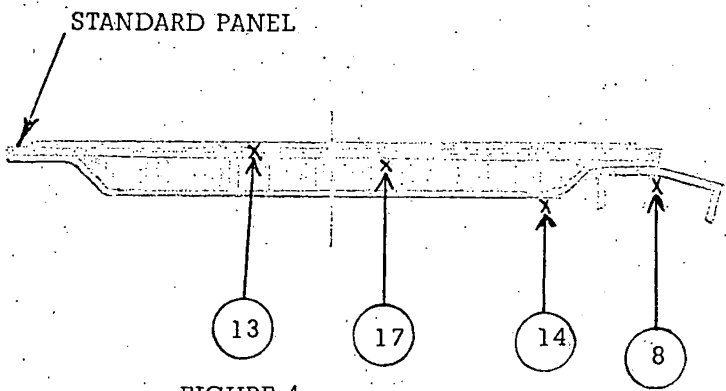
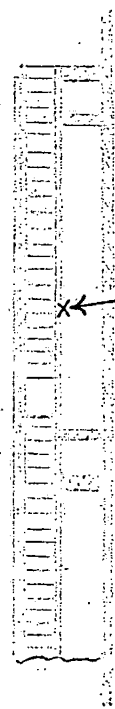


FIGURE 4



SOLAR PADDLE
FIG 5



EQUATORIAL BAND PANEL
FIG 6

BY _____ DATE _____ SUBJECT EXP 172 SHEET NO. 1 OF 6
 CHKD. BY _____ DATE _____ TEMPERATURE SENSORS JOB NO. _____

SUB COMM GROUP INPUT		FUNCTION	COMMENT	FIGURE
1	7	PCM. PKG. TEMP.		
2	3	PKG. TEMP.		
3	3	+ SECONDARY BATTERY TEMP.		3
4	3	- SECONDARY BATTERY TEMP.		3
5	7	THRUSTER TANK TEMP.		
6	7	" 1 NOZ. "		
7	-	" 2 NOZ. "		
8	6	UPPER FRAME TEMP 1		1, 4
9	6	UPPER FRAME TEMP 2		1
10	5	HONEYCOMB TEMP.	ABOVE PRIMARY BATTERY PK	3
11	7	DL BOOM TEMP.	LOCATED ON HYBRID ENCLOSURE	7
12	6	EQUATORIAL BAND TEMP		2
13	6	SOLAR PANEL TEMP 1	LOCATED ON SOLAR CELL	1, 4
14	6	SOLAR PANEL TEMP 2		1, 4
15	3	SOLAR PADDLE TEMP 1	LOCATED ON SIDE FACING MAG. BOOM	5, 7
16	5	PLATE ON MTG FLANGE		1, 2, 3
17	6	SOLAR PANEL TEMP 3		1, 4
18	7	SOLAR PANEL TEMP 1 EQ. BAND		1, 2, 6
19	2	SOLAR PADDLE TEMP 2		5, 6
20	5	SUPPORT TUBE TEMP	ADJACENT TO BATTERY PK.	3
21	5	BATTERY TEMP 3	BOTTOM OF CELL	3
22	5	CH CON H.S. TEMP.		
23	6	VOLT CON. H.S. TEMP.		
24	2	BATT. BYP. " "		

TEMP (MAIN FRAME)

A	(4) (5)	+ BATTERY TEMP.		3
B	(4) (5)	- BATTERY TEMP.		3

BY _____ DATE _____ SUBJECT EXP 172 SHEET NO. 2 OF 6
CHKD. BY _____ DATE _____ TEMPERATURE SENSOR LOCATION JOB NO. _____

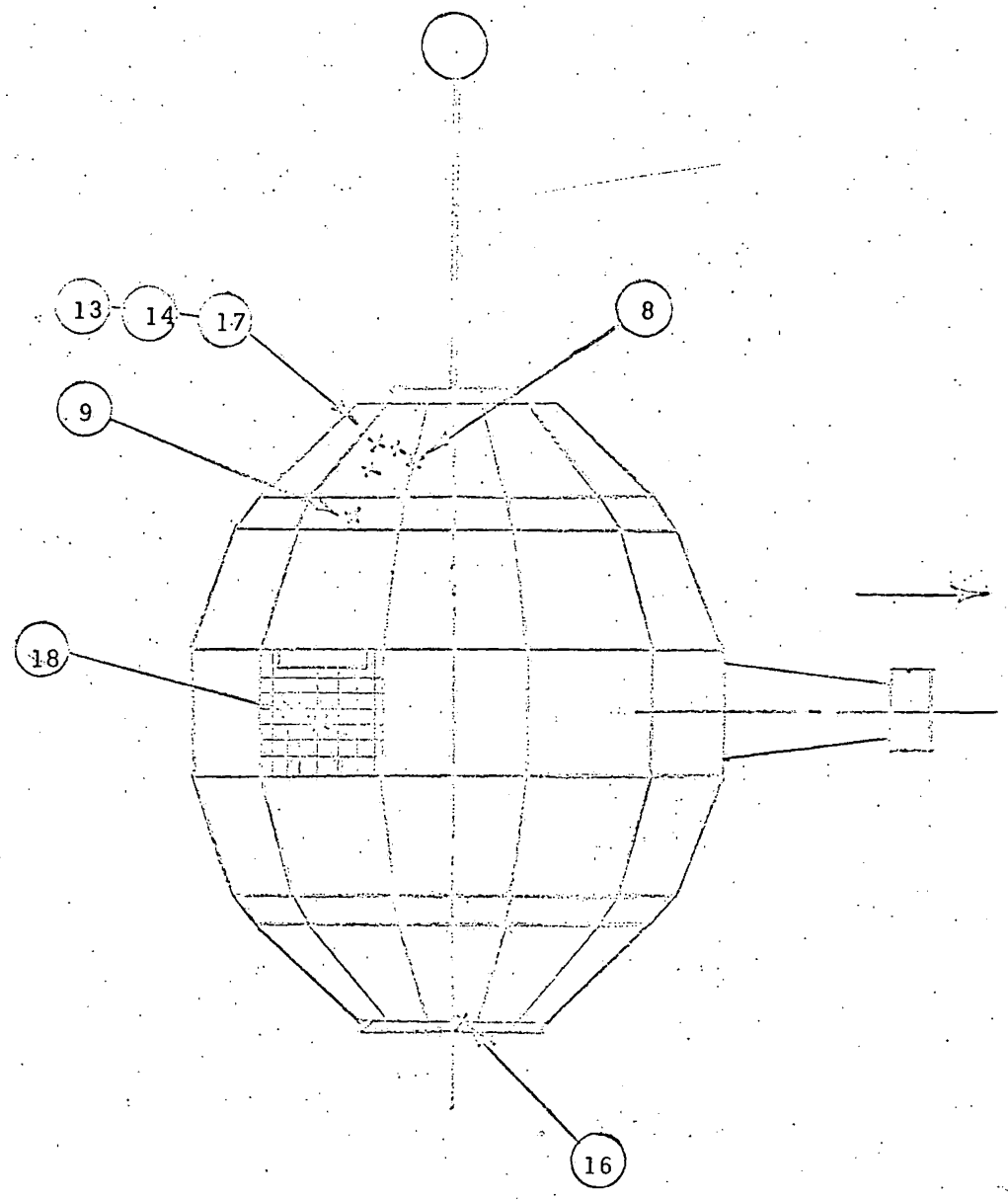


FIG 1

SOLAR PADDLE & RF BOOM
OMITTED FROM THIS VIEW

BY _____ DATE _____ SUBJECT EXP 172 SHEET NO. 3 OF 6
CHKD. BY _____ DATE _____ TEMPERATURE SENSOR JOB NO. _____
_____ LOCATION _____

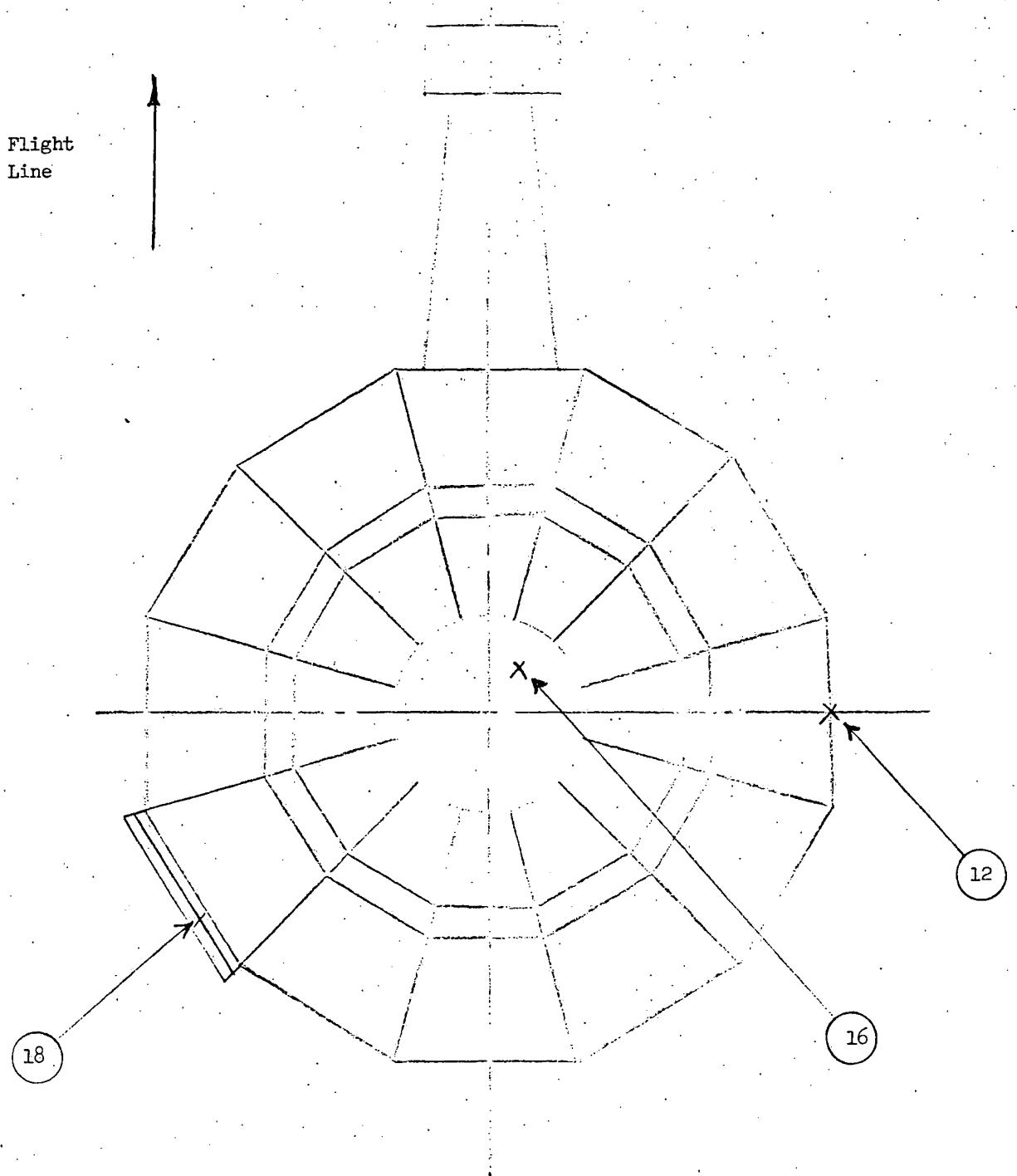


Fig. 2
Lower Skin

BY _____ DATE _____ SUBJECT **EXP 172 BATTERY PACKS** DRAWING NO. **4** OF **6**
CHKD. BY _____ DATE _____ TEMPERATURE SENSOR JOB NO. _____
LOCATION _____

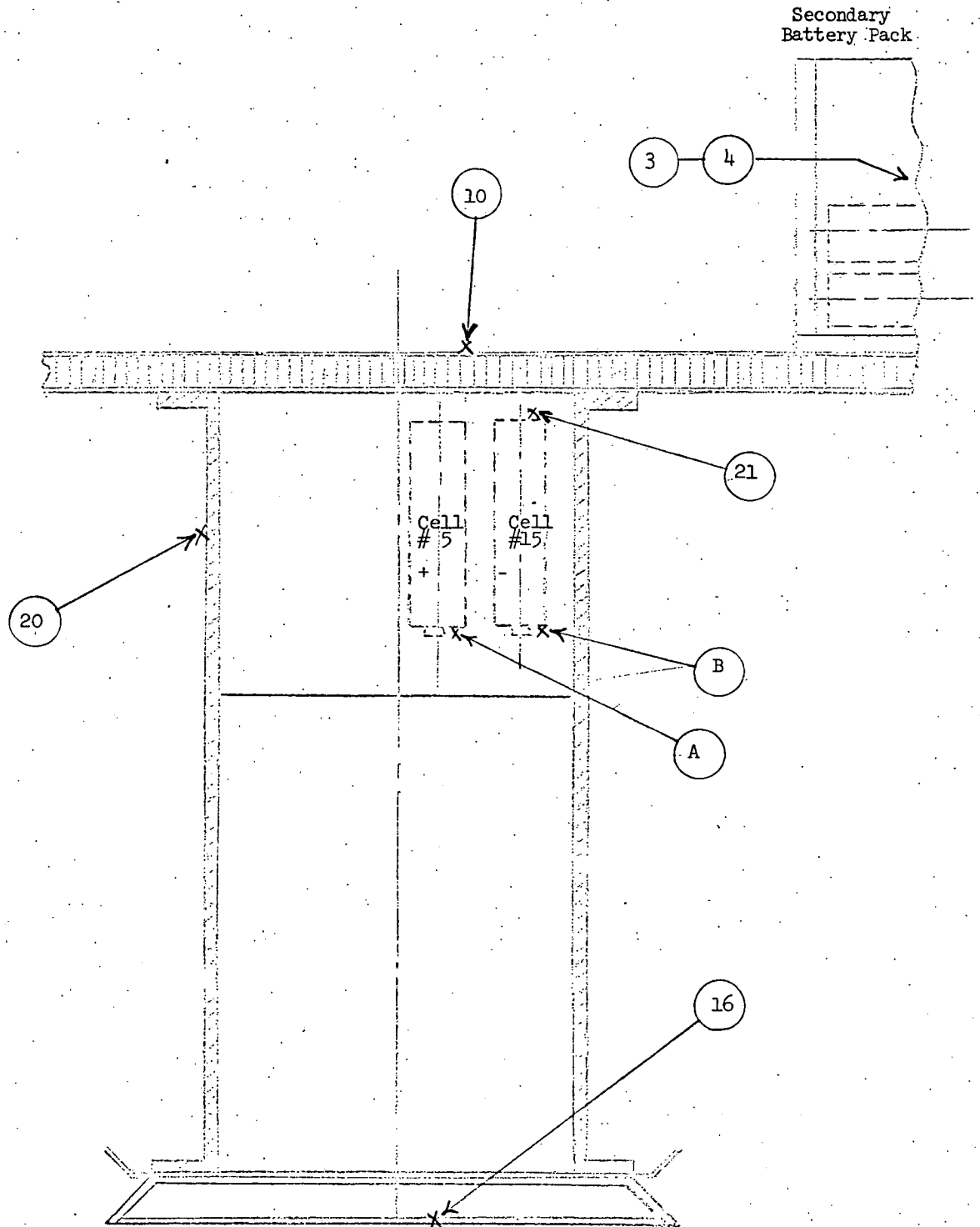


Fig. 3

BY _____ DATE _____ SUBJECT SOLAR PANELS SHEET NO. 5 OF 6
 CHKD. BY _____ DATE _____ TEMPERATURE SENSOR LOCATIONS JOB NO. _____
 EXP 172

ANODIZED SURFACE
 SOLAR CELLS MOUNTED WITH RTV
 TERMINALS COATED WITH THERMAL CONTROL COATING

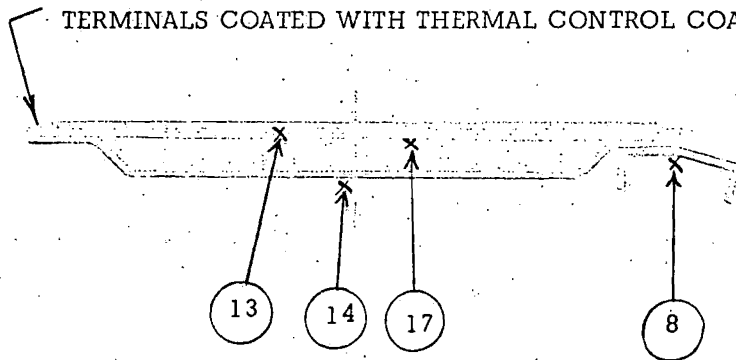
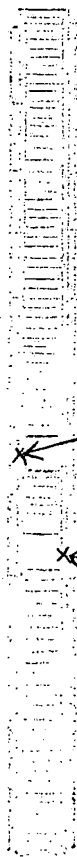


FIG 4



SOLAR PADDLE
FIG 5



EQUATORIAL BAND PANEL
FIG 6

BY _____ DATE _____ SUBJECT EXP 173 SHEET NO. 1 OF 6
 CHKD. BY _____ DATE _____ TEMPERATURE SENSORS JOB NO. _____

SUB COMM GROUP INPUT		FUNCTION	COMMENTS	FIGURE
1	7	PCM. PKG. TEMP		
2	3	PKG. TEMP.		
3	3	+ SECONDARY BATTERY TEMP.		3
4	3	- SECONDARY BATTERY TEMP.		3
5	7	THRUSTER TANK TEMP.		
6	7	" 1 NOZ. "		
7	-	" 2 NOZ. "		
8	6	UPPER FRAME TEMP 1		1, 4
9	6	UPPER FRAME TEMP 2		1
10	5	HONEYCOMB TEMP.	ABOVE PRIMARY BATTERY PK.	3
11	7	DL BOOM TEMP.	LOCATED ON HYBRID ENCLOSURE	7
12	6	EQUATORIAL BAND TEMP		2
13	6	SOLAR PANEL TEMP 1	LOCATED ON SOLAR CELL	1, 4
14	6	SOLAR PANEL TEMP 2		1, 4
15	3	SOLAR PADDLE TEMP 1	LOCATED ON SIDE FACING MAG. BOOM	5, 7
16	5	PLATE ON MTG FLANGE		1, 2, 3
17	6	SOLAR PANEL TEMP 3		1, 4
18	7	SOLAR PANEL TEMP 1 EQ. BAND		1, 2, 6
19	2	SOLAR PANEL TEMP 2 EQ. BAND	ON SOLAR CELL	1, 2, 6
20	5	SUPPORT TUBE TEMP	ADIACENT TO BATTERY PK.	3
21	5	BATTERY TEMP 3	BOTTOM OF CELL	3
22	5	CH CON H.S. TEMP		
23	6	VOLT CON. H.S. TEMP.		
24	2	BATT BYP. " "		

TEMP (MAIN FRAME)

A	(4)(5)	+ BATTERY TEMP.		3
B	(4)(5)	- BATTERY TEMP.		3

BY _____ DRAWN _____ SUBJECT: EXP 173 SHEET NO. 2 OF 6
CHKD. BY _____ DATE _____ TEMPERATURE SENSOR LOCATION _____ JOB NO. _____

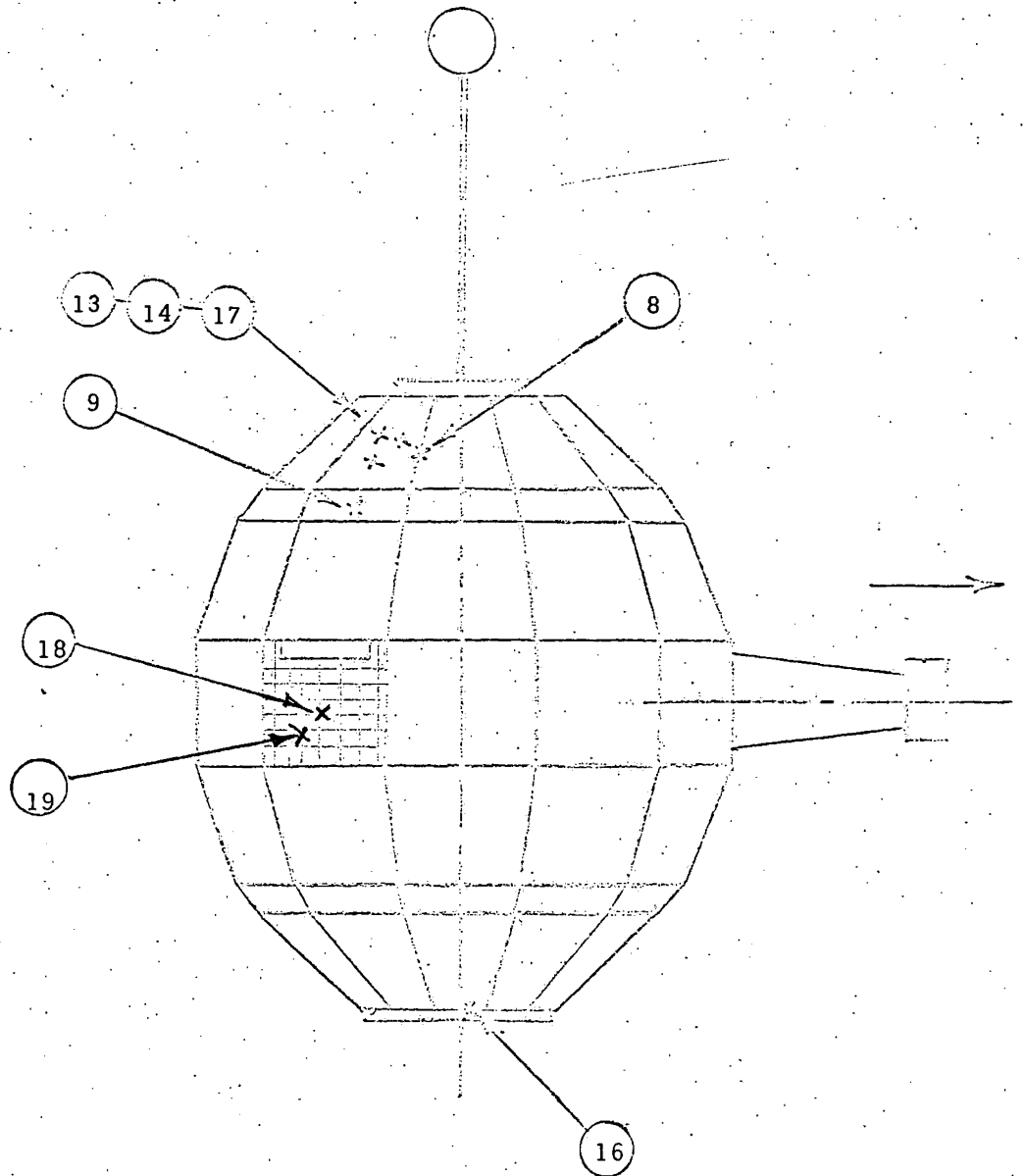


FIG 1
SOLAR PADDLE & RF BOOM
OMITTED FROM THIS VIEW

BY.....	DATE.....	SUBJECT.....	EXP 173	SHEET NO. 3	6
CHKD. BY.....	DATE.....	TEMPERATURE SENSOR LOCATION		JOB NO.....	

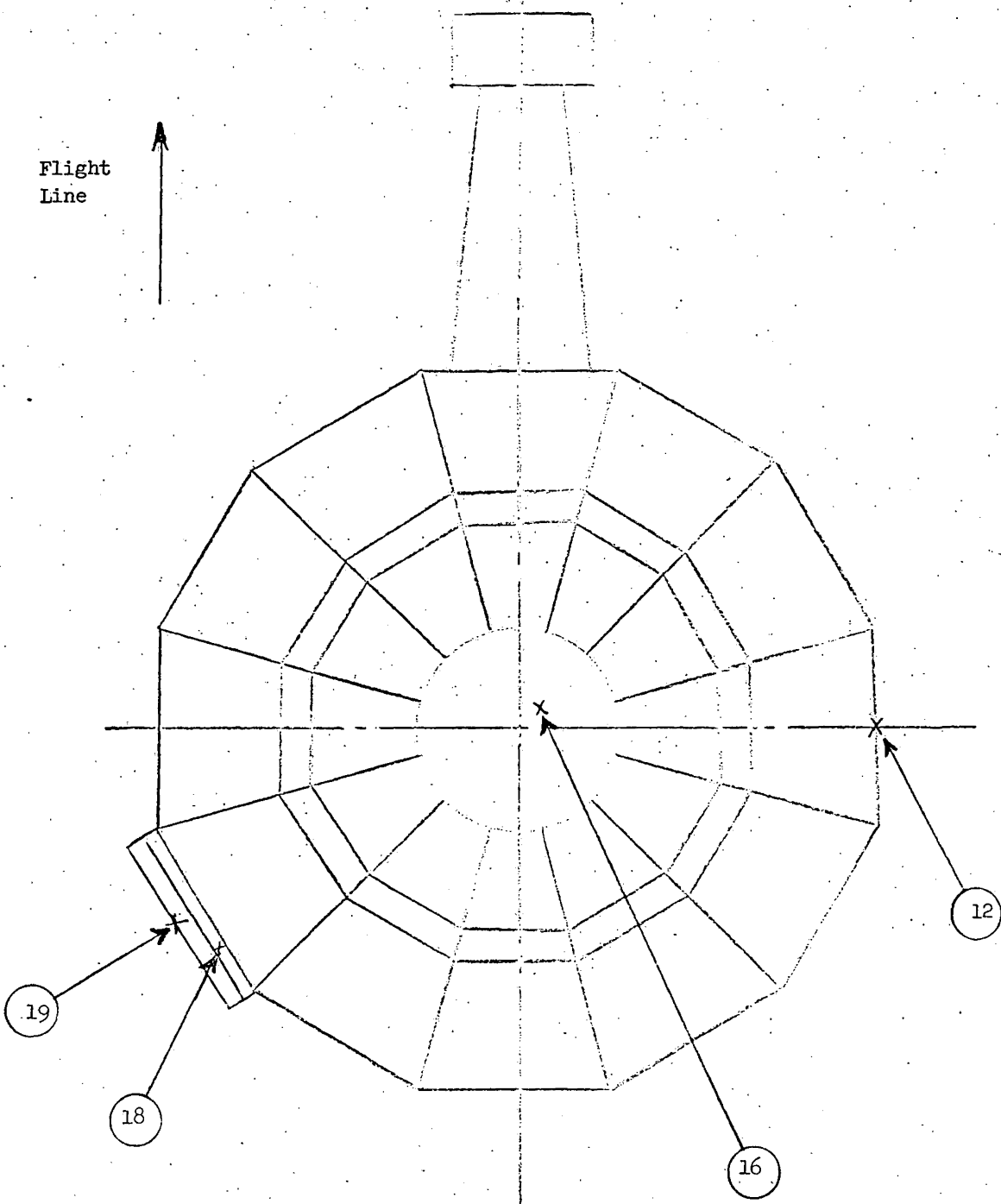


Fig. 2
Lower Skin

DATE	START	EXP 173 BATTERY PACKS	DATE NO.	4	6
CHKD. BY.	DATE	TEMPERATURE SENSOR	JOB NO.		
		LOCATION			

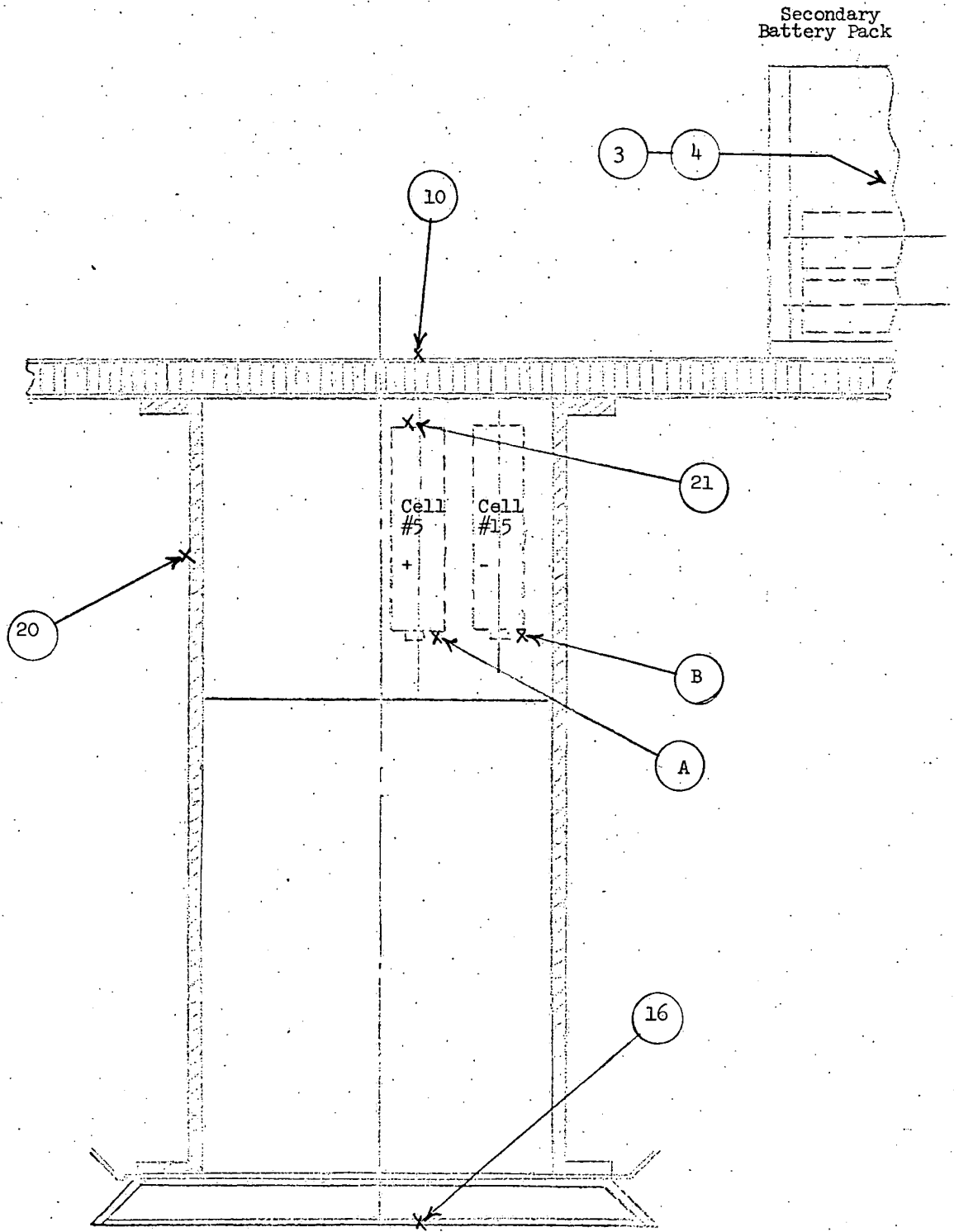


Fig. 3

ANODIZED SURFACE.
 SOLAR CELLS MOUNTED WITH BERLON
 TERMINALS COATED WITH THERMAL CONTROL COATING

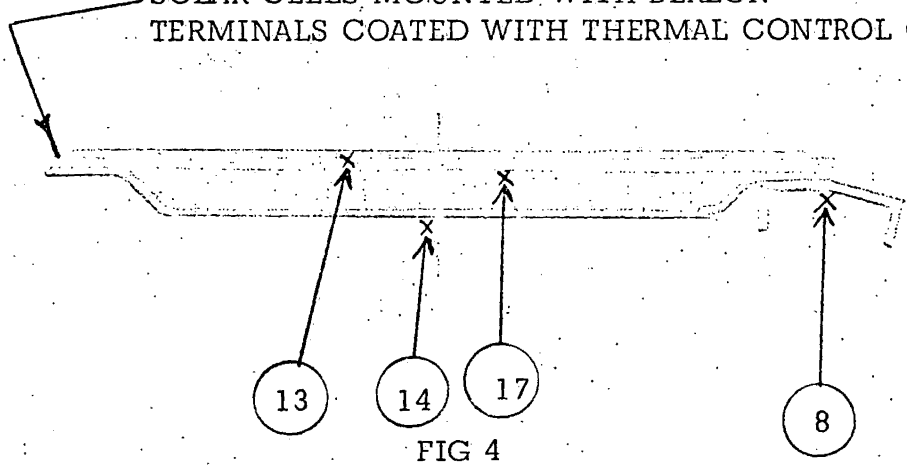
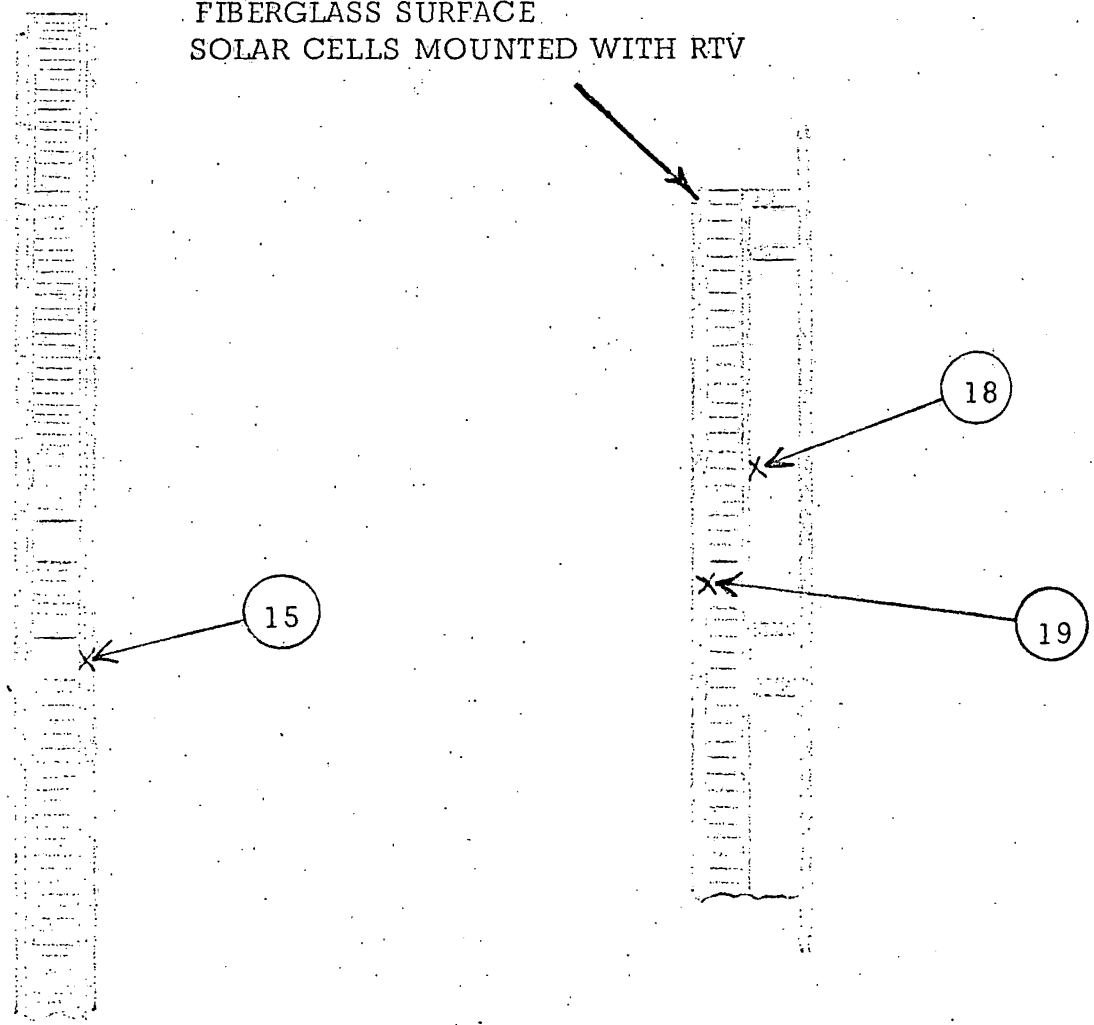


FIG 4

FIBERGLASS SURFACE
 SOLAR CELLS MOUNTED WITH RTV



SOLAR PADDLE
FIG 5

EQUATORIAL BAND PANEL
FIG 6

SUB COMM GROUP INPUT	FUNCTION	COMMENT	FIGURE
1	7	PCM. PKG. TEMP.	
2	3	PKG. TEMP.	
3	3	+ SECONDARY BATTERY TEMP	3
4	3	- SECONDARY BATTERY TEMP.	3
5	7	THRUSTER TANK TEMP.	
6	7	" 1 NOZ. "	
7	-	" 2 NOZ. "	
8	6	UPPER FRAME TEMP 1	1,4
9	6	UPPER FRAME TEMP 2	1
10	5	HONEYCOMB TEMP.	ABOVE PRIMARY BATTERY PK. 3
11	7	DL BOOM TEMP.	LOCATED ON HYBRID ENCLOSURE 7
12	6	EQUATORIAL BAND TEMP	2
13	6	SOLAR PANEL TEMP 1	LOCATED ON SOLAR CELL 1,4
14	6	SOLAR PANEL TEMP 2	1,4
15	3	SOLAR PADDLE TEMP 1	LOCATED ON SIDE FACING MAG. BOOM 5,7
16	5	PLATE ON MTG FLANGE	1,2,3
17	6	SOLAR PANEL TEMP 3	1,4
18	7	SOLAR PANEL TEMP 1 EQ. BAND	1,2,6
19	2	SOLAR PANEL TEMP 2 EQ. BAND	ON SOLAR CELL 1,2,6
20	5	SUPPORT TUBE TEMP	ADJACENT TO BATTERY PK. 3
21	5	BATTERY TEMP 3	BOTTOM OF CELL 3
22	5	CH CON H.S. TEMP	
23	6	VOLT CON " "	
24	2	BATT. BYP. " "	

TEMP (MAIN FRAME)

A	(4)(5)	+ BATTERY TEMP	3
B	(4)(5)	- BATTERY TEMP	3

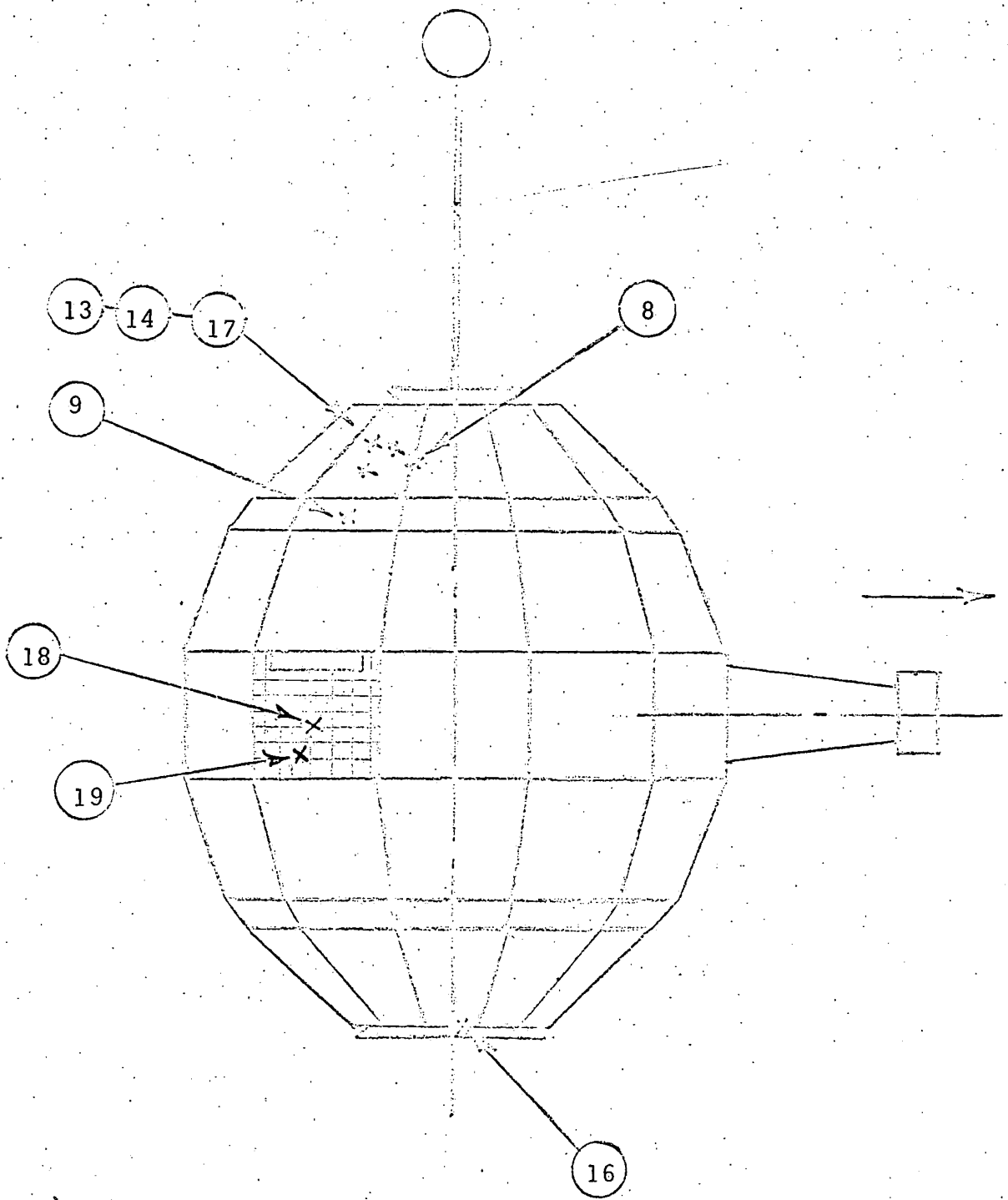


FIG 1

SOLAR PADDLE & RF BOOM
OMITTED FROM THIS VIEW

Flight
Line

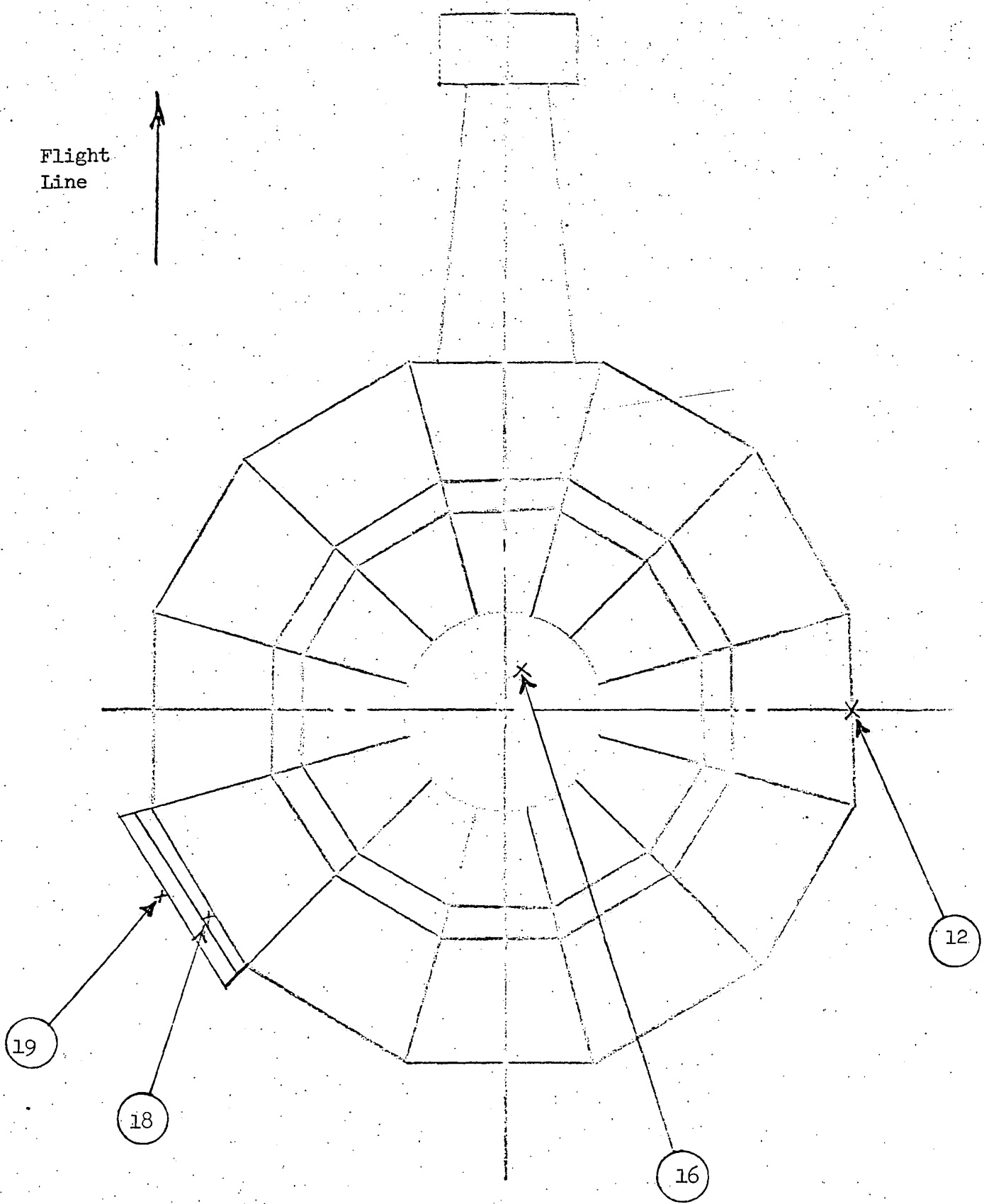


Fig. 2
Lower Skin

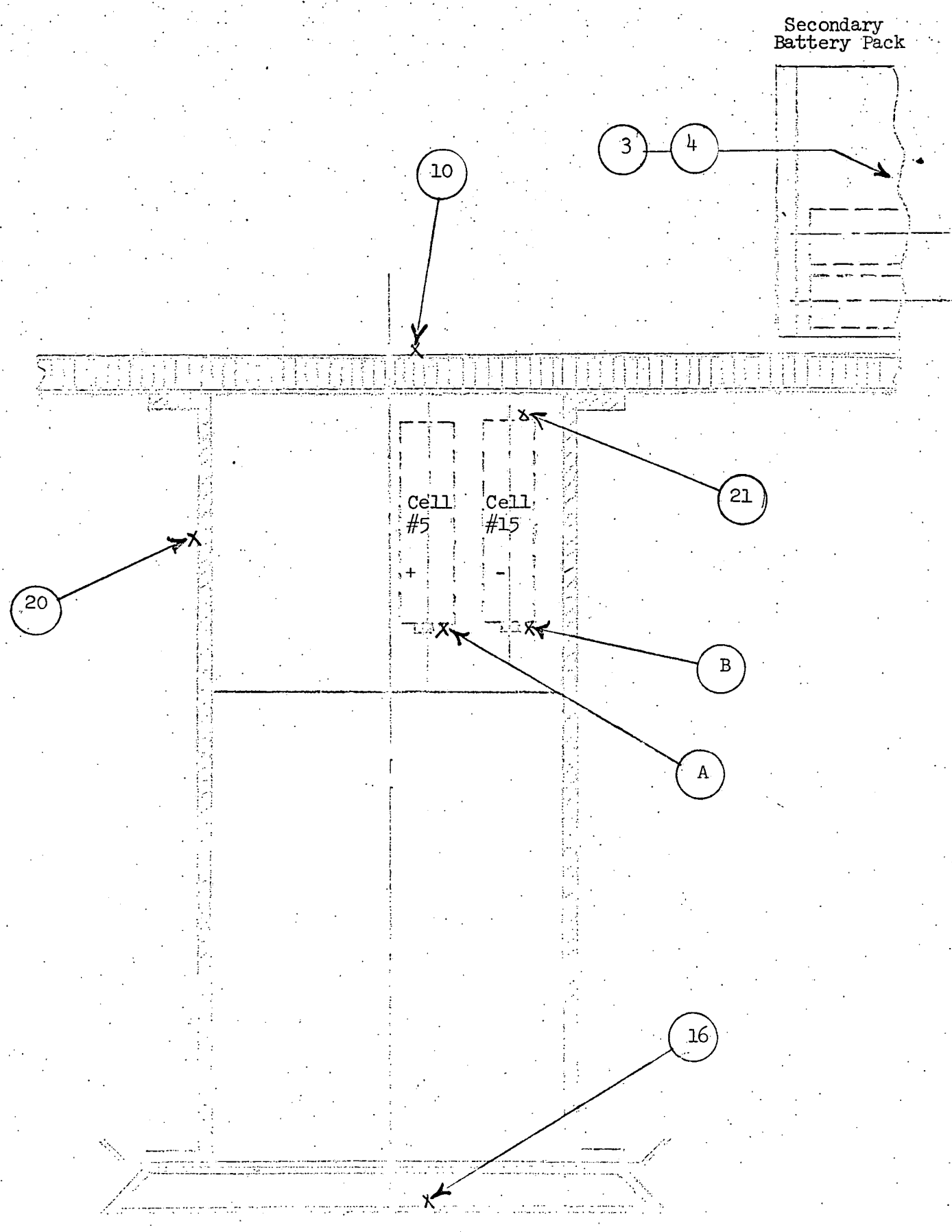


Fig. 3

I.9.



3.3(b)(1)

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I.10. QUICK LOOK DISPLAY

FORMATS

II.1. TELEMETRY FORMATS

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170 Series Programs Magnetic Tape Format

C B A 8 4 2 1

0	1	2	X	X	X	_____	10's of Seconds
6	7	X	X	X	X	_____	Units of Seconds
12	13	14	15	16	17		
0	1	2	X	X	X	_____	10's of Minutes
6	7	X	X	X	X	_____	Units of Minutes
12	13	14	15	16	17		
0	1	2	3	X	X	_____	10's of Hours
6	7	X	X	X	X	_____	Units of Hours
12	13	14	15	16	17		
0	1	X	X	X	X	_____	10's of Days
6	7	X	X	X	X	_____	Units of Days
12	13	14	15	16	17		
0	1	2	3	4	5	_____	100's of Days
6	7	8	9	X	X		
12	13	14	15	16	17		
1	1	1	0	1	0	_____	-frame sync
1	1	1	0	0	1		
0	0	0	0	16	17		
0	0	0	1	0	1	_____	Sub-
0	0	0	1	1	0	_____	Frame sync
1	1	1	1	16	17		
X	X	X	X	X	X	_____	Data words
X	X	X	X	X	X		
X	X	X	X	16	17		

MSB →

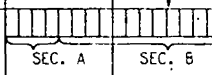
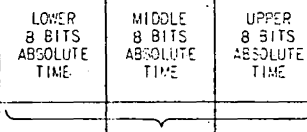
↑
LSB

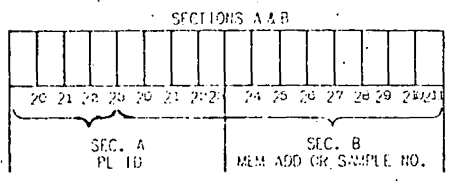
Frame Content:

Five time words followed by sub-frame sync, frame sync, frame sync, twelve eight bit data words, sub-frame sync, fourteen data words, sub-frame sync, fourteen data words---to a total of sixty nine sixteen bit words. per magnetic tape record.

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	SYNC LBB 1110 1011	SYNC U&B 1001 0000	SF SYNC LBB 0001 0100	SF SYNC U&B 0110 1111	+ CELL MON. 2	- CELL MON. 10	DIG WD EXP 1	DIG WD EXP 2	+ BATT V ABSTIM	- BATT V ABSTIM	RW TACH ABSTIM	MAG X	MAG Y	MAG Z	DIG WD AUCOLE A	DIG WD AUCOLE B
1			DIGITAL WORD ADD	VERNIER .TIME	+ CELL 3	11	DIG WD EXP 3	DIG WD EXP 4	5V CAL	REC 1- ACC	REC 2- ACC	BOOM LENGTH	+ CELL MON 1	- CELL MON 18	DIG WD SPRO	DIG WD SPRJ
2			DIG WD CMD	DIG WD MEM	4	12	5 A, B	6 A, B	TEMP 19 SCP	TEMP 24 BAT BYP	PRESS TH 1 CONTROL	PRESS TH 2 CONTROL	DL TIMER CMD 1	DL TIMER CMD 2	DIG WD BOOM CTL	DIG WD RA CTL
3			DIG WD PCM	DIG WD CMD	5	13	7 A, B	8 A, B	+ SEC V MON	- SEC V MON	TEMP 2 PKG.	TEMP 15 SCP 1	TEMP 3 + SEC BATT	TEMP 4 - SEC BATT	DIG WD THRUSTER CTL	SPARE
4			DIG WD BAT	SPARE	6	14	9 A, B	10 A, B	+ BAT V	- BAT V	TEMP + BAT T 25	TEMP - BAT T 26	+ CHG 1	+ DISC 1	- CHG 1	- DISC 1
5			RED DIG WD SAME AS 1-2	RED DIG WD SAME AS 2-2	7	15	11 A, B	12	TEMP + BAT T 25	TEMP - BAT T 26	TEMP 10 HC 1	TEMP 16 SCP 2	TEMP 20 S TUBE	TEMP 21 BAT 3	TEMP 22 CHG CTL	TEMP 23 V CTL
6			DIG WD EXP 17	DIG WD EXP 17	8	16	13 A, B	14 A, B	TEMP 8 SKIN 1	TEMP 9 SKIN 2	TEMP 17 INNER SC 2	TEMP 12 B BAND	TEMP 13 INR. SC 1 NON STD	TEMP 14 OUTR. SC NON STD	+ SC CHG 1 MON	- SC CHG 1 MON
7			DIG WD EXP 17	DIG WD PAR	9	17	15 A, B	16	TEMP 5 TANK	TEMP 6 NOZ 1	TEMP 7 RW 2	TEMP 18 BB SC 2	TEMP 11 DL BOOM	TEMP 1 PCW PK	PRESS TH 2 PLENUM	PRESS TH 1 PLENUM

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	SYNC LBR 1110 1011	SYNC UBB 1001 0000	SF SYNC LBR 0001 0100	SF SYNC UBB 0110 1111	+ CELL MON. 2	- CELL MON. 10	DIG WD EXP 1	DIG WD EXP 2	+ BATT V ABSTIM	- BATT V ABSTIM	RW TACH ABSTIM	MAG X	MAG Y	MAG Z	DIG WD ADCOLE A	DIG WD ADCOLE B
1			DIGITAL WORD ADD	VERNIER TIME	+ CELL 3	11	DIG WD EXP 3	DIG WD EXP 4	5V CAL	REC 1- ACC	REC 2- ACC	BOOM LENGTH	+ CELL MON 1	- CELL MON 18	DIG WD SPRO	DIG WD SPRO
2			DIG WD CMD	DIG WD MEM	4	12	5 A, B	6 A, B	TEMP 19 SCP	TEMP 24 BAT BYP	PRESS TH 1 CONTROL	PRESS TH 2 CONTROL	DL TIMER CMD 1	DL TIMER CMD 2	DIG WD BOOM CTL	DIG WD RA CTL
3			DIG WD PCM	DIG WD CMD	5	13	7 A, B	8 A, B	+ SEC V MON	- SEC V MON	TEMP 2 PKG.	TEMP 15 SCP 1	TEMP 3 + SEC BATT	TEMP 4 - SEC BATT	DIG WD THRUSTER CTL	SPARE
4			DIG WD BAT	EXP 17 A, B	6	14	9 A, B	10	+ BAT V	- BAT V	TEMP + BAT T 25	TEMP - BAT T 26	+ CHG 1	+ DISC 1	- CHG 1	- DISC 1
5			EXP 18	EXP 19	7	15	11 A, B	12	TEMP + BAT T 25	TEMP - BAT T 26	TEMP 10 HC 1	TEMP 16 SCP 2	TEMP 20 S TUBE	TEMP 21 BAT 3	TEMP 22 CHG CTL	TEMP 23 V CTL
6			EXP 20	EXP 21	8	16	13 A, B	14 A, B	TEMP 8 SKIN 1	TEMP 9 SKIN 2	TEMP 17 INNER SC 2	TEMP 12 B BAND	TEMP 13 INR. SC 1 NON STD	TEMP 14 OUTR. SC NON STD	+ SC CHG 1 MON	- SC CHG 1 MON
7			RLTEP	PAR	9	17	15 A, B	16	TEMP 5 TANK	TEMP 6 NOZ 1	TEMP 7 RW 2	TEMP 18 BB SC 2	TEMP 11 DL BOOM	TEMP 1 PCM PK	PRESS TH 2 PLENUM	PRESS TH 1 PLENUM

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
0	SYNC L8B	SYNC U6B	SF SYNC L8B	SF SYNC U8B	+ CELL MON 2	- CELL MON 10	PLID	MEM. ADD (SAMPLE NUM)									
1			DIG WD ADD	VERNIER TIME	3	11	↓	TO 512									
2			DIG WD CMD	DIG WD MEM	4	12											
3			DIG WD PCM	DIG WD CMD	5	13			THIS 8 BIT COUNTER IS THE SAME AS THE VERNIER TIME-WORD 1-4								
4			DIG WD BAT	SPARE	6	14											
5			DIG WD RED. 1-2	DIG WD RED. 2-2	7	15	THESE 3-8 BIT WORDS REPLACE THE NORMAL 3-8 BIT WORDS OF PART OF ANY SUBFRAME THAT IS STORED AS THE FIRST MEMORY SAMPLE AFTER A MEMORY READ OUT.										
6			DIG WD EXP 17	DIG WD EXP 17	8	16											
7			DIG WD EXP 17	DIG WD PAR	9	17											

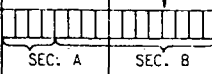
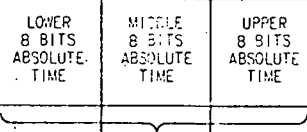


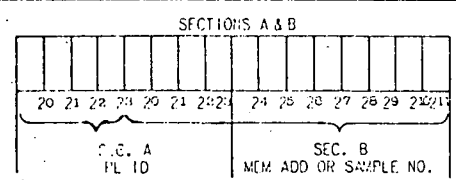
171 - 172

ID PART

DATA PART OF SUBFRAME 0-7 STORED IN MEM. SAME AS PART OF PCM SUBFRAME 0-7 WORD FOR WORD EXCEPT FOR THE FIRST MEM. SAMPLE AND WHERE A DIFFERENT SUBFRAME IS COMMANDED TO BE STORED

MEMORY READ OUT DATA

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	SYNC LBB	SYNC UBB	SF SYNC LBB	SF SYNC UBB	+ CELL MON 2	- CELL MON 10	PLID	MEM. ADD (SAMPLE NUM)								
1			DIG WD ADD	VERNIER TIME	3	11		TO 512								
2			DIG WD CMD	DIG WD MEM	4	12										
3			DIG WD PCM	DIG WD CMD	5	13	 <p>THIS 8 BIT COUNTER IS THE SAME AS THE VERNIER TIME-WORD 1-4</p>									
4			DIG WD BAT	EXP. 17 A, B	6	14	 <p>LOWER 8 BITS ABSOLUTE TIME MIDDLE 8 BITS ABSOLUTE TIME UPPER 8 BITS ABSOLUTE TIME</p>									
5			EXP. 18	EXP. 19	7	15	<p>THESE 3-8 BIT WORDS REPLACE THE NORMAL 3-8 BIT WORDS OF PART OF ANY SUBFRAME THAT IS STORED AS THE FIRST MEMORY SAMPLE AFTER A MEMORY READ OUT.</p>									
6			EXP. 20	EXP. 21	8	16										
7			RETEP	PAR	9	17										



ID PART

DATA PART OF SUBFRAME 0-7 STORED IN MEM. SAME AS PART OF PCM SUBFRAME 0-7 WORD FOR WORD EXCEPT FOR THE FIRST MEM. SAMPLE AND WHERE A DIFFERENT SUBFRAME IS COMMANDED TO BE STORED

MEMORY READ OUT DATA

II.2. PCM ANALOG INPUTS

170 SERIES POM PCM ANALOG INPUTS

FUNCTION	LOCATION				CURVE NO.
	ENCODER		DECODE		
	SF	WD	SF	WD	
PLUS 5 VOLT CALIBRATE	1	8	1	9	
RECEIVER 1 AGC	1	9	1	10	14
RECEIVER 2 AGC	1	10	1	11	14
TIMER COMMAND 1 IND	2	12	2	13	
TIMER COMMAND 2 IND	2	13	2	14	
PLUS VOLTAGE SENSOR	0	8	0	9	3
MINUS VOLTAGE SENSOR	0	9	0	10	3
PLUS VOLTAGE SENSOR	4	8	4	9	3
MINUS VOLTAGE SENSOR	4	9	4	10	3
PLUS SEC VOLTAGE MON	3	8	3	9	4
MINUS SEC VOLTAGE MON	3	9	3	10	3
PLUS SOLAR CELL CUR MON	6	14	6	15	5
PLUS CHARGE CUR MON	4	12	4	13	6
PLUS DISCHARGE CUR MON	4	13	4	14	6
MINUS SOLAR CELL CUR MON	6	15	7	0	5
MINUS CHARGE CUR MON	4	14	4	15	6
MINUS DISCHARGE CUR MON	4	15	5	0	6
CELL 1	1	12	1	13	
CELL 2	0	4	0	5	
CELL 3	1	4	1	5	
CELL 4	2	4	2	5	
CELL 5	3	4	3	5	
CELL 6	4	4	4	5	
CELL 7	5	4	5	5	
CELL 8	6	4	6	5	
CELL 9	7	4	7	5	
CELL 10	0	5	0	6	
CELL 11	1	5	1	6	
CELL 12	2	5	2	6	
CELL 13	3	5	3	6	
CELL 14	4	5	4	6	
CELL 15	5	5	5	6	
CELL 16	6	5	6	6	
CELL 17	7	5	7	6	
CELL 18	1	13	1	14	

PRIM. PLUS

PRIM. MINUS

170 SERIES POM PCM ANALOG INPUTS (Cont'd)

FUNCTION		LOCATION				COMMENT	CURVE NO.
		ENCODER		DECOM			
		SF	WD	SF	WD		
RW TACHOMETER		0	10	0	11		12
BOOM LENGTH INDICATOR		1	11	1	12		11
X AXIS MAGNETOMETER		0	11	0	12	—	
Y		0	12	0	13	—	
Z		0	13	0	14	—	
THRUSTER 1 PRESS (CONTROL)		2	10	2	11		9
1 (POT)		7	15	0	0		9
2 (CONTROL)		2	11	2	12		9
2 (POT)		7	14	7	15		9
PCM PACKAGE TEMP	T1	7	13	7	14		1
PACKAGE TEMP	T2	3	10	3	11		1
PLUS SEC. BATT TEMP	T3	3	12	3	13		1
MINUS SEC. BATT TEMP	T4	3	13	3	14		1
THRUSTER TANK TEMP	T5	7	8	7	9		1
THRUSTER 1 NOZ. TEMP	T6	7	9	7	10		1
THRUSTER 2 NOZ. TEMP	T7	-	-	-	-	NOT MONITORED	1
UPPER SKIN TEMP NO. 1	T8	6	8	6	9		1
UPPER SKIN TEMP. NO.2	T9	6	9	6	10		1
HONEY COMB TEMP	T10	5	10	5	11		1
DL BOOM TEMP.	T11	7	12	7	13		1
BELLY BAND TEMP.	T12	6	11	6	12		1
SOLAR CELL PANEL TEMP. NO.1	T13	6	12	6	13		2
SOLAR CELL PANEL TEMP. NO. 2	T14	6	13	6	14		1
SOLAR CELL PADDLE TEMP. No. 1	T15	3	11	3	12		1
LOWER PLATE TEMP.	T16	5	11	5	12		1
SOLAR CELL PANEL TEMP. NO. 3	T17	6	10	6	11		2
BB SOLAR CELL PANEL TEMP. NO.1	T18	7	11	7	12		1
SOLAR CELL PADDLE TEMP. NO. 2	T19	2	8	2	9		1
SUPPORT TUBE TEMP.	T20	5	12	5	13		1
PRIM. BATT. TEMP. NO. 3	T21	5	13	5	14		1
CHARGE CONTROL H.S. TEMP	T22	5	14	5	15		1
VOLT	T23	5	15	6	0		1
BATT. BYP.	T24	2	9	2	10		1
PRIM PLUS BATT TEMP.	T25	5	8	5	9		1
PRIM MINUS BATT TEMP.	T26	5	9	5	10		1
RW BEARING TEMP	T27	7	10	7	11		13
PRIM PLUS BATT TEMP.	T25	4	10	4	11		1
PRIM MINUS BATT TEMP.	T26	4	11	4	12		1

II.3. COMMAND SYSTEM

II.4. PCM DIGITAL INPUTS

17
17
17

170 SERIES PCM
PCM TM DIGITAL INPUTS

FUNCTION	LOCATION						LOGIC STATE	
	ENCODER			DECOM			1	0
	SF	WD	BIT	SF	WD	BIT		
ADDRESS 1A.	1	2	1	1	3	1	RESET	ADDRESS
2A		2			2		or DIG "1"	or DIG "0"
3A		3			3		↓	↓
4A		4			4			
1B		5			5			
2B		6			6			
3B		7			7			
4B		8			8			
CMD ENABLE	2	2	1	2	3	1	OFF	ON
BACK UP CMD SYSTEM		2			2		ON	OFF
DL ENABLE ON-OFF		3			3		OFF	ON
RESET TIMER ON-OFF		4			4		ON	OFF
DL SYSTEM ON-OFF		5			5		ON	OFF
BACKUP DL SYSTEM		6			6		ON	OFF
EXECUTE ON-OFF		7			7		OFF	ON
EXECUTE BACK UP		8			8		ON	OFF
PCM TIMING CHAIN A-B	3	2	1	3	3	1	A ✓	B
PCM MIPX A-B		2			2		A	B ✓
MEMORY ON-OFF		3			3		ON ✓	OFF
PCM POWER A-B		4			4		A ✓	B
PCM DATA SEL ON-OFF		5			5		ON	OFF
PCM TO DL ON-OFF		6			6		ON	OFF
		7			7			
		8			8			
CHARGE/VOLT CON ON-OFF	4	2	1	4	3	1	ON	OFF
CHARGE CON HI-LO		2			2		HI	LO
BATT BYP ON-OFF		3			3		ON	OFF
BATT BYP ENAB ON-OFF		4			4		ON	OFF
PRIM-SEC PLUS BATT SEL		5			5		PRIM	SEC
PRIM-SEC MINUS BATT SEL		6			6		PRIM	SEC
UNDERVOLTAGE ON-OFF		7			7		ON	OFF
		8			8			
SUBFRAME 1 SEL	2	3	1	2	4	1	ON	OFF
SUBFRAME 2 SEL		2			2		ON	OFF

170 SERIES POM PCM TM DIGITAL INPUTS (Con't)

0
1
3
1
0
0
1
0

FUNCTION	LOCATION		LOGIC STATE		
	ENCODER	DECOM	1	0	
	SF WD BIT	SF WD BIT			
SUB FRAME 3 SEL	3	3	ON	OFF	
PCM BIT RATE FAST-SLO	4	4	SLO	FAST	
MEMORY A1 - AO SAMPLE	2 3 5	2 4 5	A1	AO	
MEMORY B1 - BO SAMPLE	6	6	B1	BO	
PCM A/D A-B	7	7	A	B	
PCM OSC A-B	8	8	A	B	
ORDNANCE ENABLE ON-OFF	3 3 1	3 4 1	ON	OFF	
ALT. ORD. ENABLE ON-OFF	2	2	ON	OFF	
HK SENSORS ON-OFF	3	3	ON	OFF	
ANALOG TM ON-OFF	4	4	ON	OFF	
TIMER 20-50 MIN	5	5	50 MIN	20 MIN	
PL ID BIT 1	6	6			171 000
PL ID BIT 2	7	7			172 100
PL ID BIT 3	8	8			173 010
BOOM ON-OFF	2 14 1	2 15 1	ON	OFF	174 110
BOOM IN-OUT	2	2	OUT	IN	
BOOM FULL RETRACT IND	3	3	RET	RET	
BOOM MID IND	4	4	MID	MID	
BOOM FULL EXTENSION IND	5	5	EXT	EXT	
BOOM TIP MASS RELEASE IND	6	6	REL	REL	
DL BOOM RELEASE IND	7	7	REL	REL	
	8	8			
THRUSTER 1 ON-OFF	3 14 1	3 15 1	ON	OFF	
THRUSTER 2 ON-OFF	2	2	ON	OFF	
TH 1 HEATER ON-OFF	3	3	ON	OFF	
TH 2 HEATER ON-OFF	4	4	ON	OFF	
THRUSTER HI-LO	5	5	LO	HI	
	6	6			
	7	7			
	8	8			
RW SPEED MON. ON-OFF	2 15 1	3 0 1	ON	OFF	
RW ON-OFF	2	2	ON	OFF	
RW FWD-REV	3	3	REV	FWD	
RW PRIM-SEC POWER AMP	4	4	PRIM	SEC	
RW PRIM-SEC CONTROL	5	5	SEC	PRIM	
RW FWD-REV IND	6	6	REV	FWD	
	7	7			
	8	8			

II.5. DATA REDUCTION TABLES

ANALOG

170 SERIES POM DATA REDUCTION TABLES

CURVE NO.	1	2	3	4 ✓	5 ✓	6	9	12	✓ 13	
%	VOLTS	STD TEMP SENSOR	INST S.C. TEMP SENSOR	+VOLT SEC -BATT	SEC +BATT	+ S.C. I MON	+CH DISCH I MON	THRUST PRESS	TW TACH	FW BEARING TEMP
		°C	°C	VOLTS	VOLTS	AMPS	AMPS	PSI	RPS	°C
0	0			10.00		0	0	0	0	
2	.1	153		10.08		.03	.02	1	.6	
4	.2	119		10.16		.06	.04	2	1.2	
6	.3	101		10.24		.09	.06	3	1.7	
8	.4	89		10.32		.12	.08	4	1.9	
10	.5	81	99.7	10.40		.15	.10	5	2.3	70
12	.6	73		10.48		.18	.12	6	2.6	62.8
14	.7	67		10.56		.21	.14	7	3.0	57
16	.8	62		10.64		.24	.16	8	3.4	52.2
18	.9	58		10.72		.27	.18	9	3.7	48
20	1.0	54	70.7	10.80		.30	.20	10	4.0	44
22	1.1	50		10.88		.33	.22	11	4.4	40
24	1.2	47		10.96		.36	.24	12	4.7	37
26	1.3	44		11.04		.39	.26	13	5.0	34.2
28	1.4	41		11.12		.42	.28	14	5.5	31.5
30	1.5	38	54	11.20		.45	.30	15	5.9	29
32	1.6	36		11.28		.48	.32	16	6.3	26.5
34	1.7	34		11.36		.51	.34	17	6.7	24
36	1.8	31		11.44		.54	.36	18	7.0	21.8
38	1.9	29		11.52		.57	.38	19	7.4	19.5
40	2.0	27	41.6	11.60		.60	.40	20	7.8	17.2
42	2.1	25		11.68		.63	.42	21	8.2	15
44	2.2	23		11.76		.66	.44	22	8.6	13
46	2.3	21		11.84		.69	.46	23	9.0	11
48	2.4	19		11.92		.72	.48	24	9.4	8.8
50	2.5	17	31.1	12.00		.75	.50	25	9.8	6.8
52	2.6	15		12.08		.78	.52	26	10.3	5
54	2.7	14		12.16		.81	.54	27	10.7	3
56	2.8	12		12.24		.84	.56	28	11.1	1
58	2.9	10		12.32	8.10	.87	.58	29	11.5	-1.5

170 SERIES POM DATA REDUCTION TABLES

CURVE NO.	1	2	3	4	5	6	9	12	13	
%	VOLTS	STD TEMP SENSOR	INST S.C. TEMP SENSOR	+VOLT SEC -BATT	SEC +BATT	+ S.C. I MON	+CH DISCH I MON	THRUST PRESS	<i>RW</i> TACH	FW BEARING TEMP
		°C	°C	VOLTS	VOLTS	AMPS	AMPS	PSI	RPS	°C
60	3.0	8	21.6	12.40	8.40	.90	.60	30	11.9	-4
62	3.1	7		12.48	8.70	.93	.62	31	12.5	-7.2
64	3.2	5		12.56	8.95	.96	.64	32	13.0	
66	3.3	3		12.64	9.20	.99	.66	33	13.5	
68	3.4	1		12.72	9.45	1.02	.68	34	14.0	
70	3.5	-1	12.1	12.80	9.80	1.05	.70	35	14.4	
72	3.6	-2		12.88	10.05	1.08	.72	36	14.9	
74	3.7	-4		12.96	10.30	1.11	.74	37	15.4	
76	3.8	-6		13.04	10.55	1.14	.76	38	15.9	
78	3.9	-8		13.12	10.90	1.17	.78	39	16.4	
80	4.0	-10	2.0	13.20	11.15	1.20	.80	40	16.9	
82	4.1	-12		13.28	11.40	1.23	.82	41	17.5	
84	4.2	-14		13.36	11.70	1.26	.84	42	18.1	
86	4.3	-17		13.44	12.00	1.29	.86	43	18.7	
88	4.4	-19		13.52	12.25	1.32	.88	44	19.3	
90	4.5	-22	-10.2	13.60	12.50	1.35	.90	45	19.9	
92	4.6	-25		13.68	12.77	1.38	.92	46	20.6	
94	4.7	-28		13.76	13.05	1.41	.94	47	21.3	
96	4.8	-32		13.84	13.32	1.44	.96	48	22	
98	4.9	-36		13.92	13.60	1.47	.98	49		
100	5.0			14.00	13.90	1.50	1.0	50		

II.6. TABLE OF CURVES

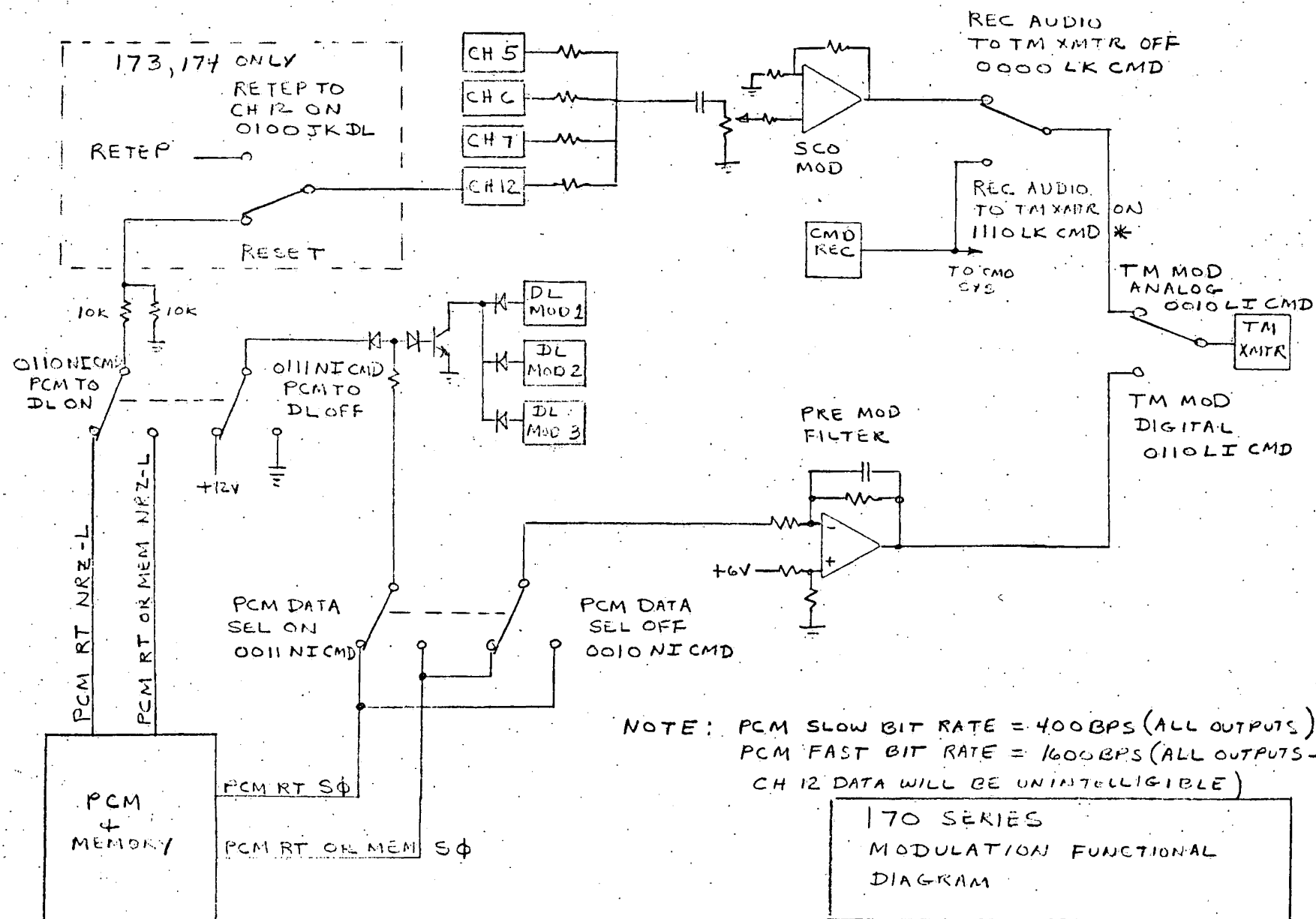


Figure 1

170 SERIES COMMAND SYSTEM TONE PAIRS

PAYLOAD	171	172	173	174
ADDRESS	PL, PI, PK, PJ	QK, QL, QI, QJ	RJ, RK, RI, RL	SL, SJ, SI, SK
Address Complement	ML, MI, MK, MJ	MK, ML, MI, MJ	MJ, MK, MI, ML	ML, MJ, MI, MK
Command Enable	PN	QN	RN	SN
Execute	KI	KI	KI	KI
✓ DL Reset	MQ	MP	MS	MR
Advance	NK	NK	NK	NK
Backup Enable	NJ	NJ	NJ	NJ
Command Reset	MN	MN	MN	MN

EXP NO. 171-172

COMMANDS

10/15/71

TONE PAIR →	MTX BOX 1	MTX BOX 2	MTX BOX 1	MTX BOX 2	MTX BOX 1
	LK(DL)	JL(DL)	LI(DL)	JK(DL)	JI(CMD)
0000	DL1 1	DL16 # 1		DL CONV ON 1	PCM TM ON PCM POWER A 1
0001	DL2 2	DL11 # 2		DL CONV BYP * # 2	PCM TM OFF 2
0011	DL3 3	DL9 # 3	DL CONV BYP * 3	DL CONV 1 SEL 3	PCM OSC A 3
0010	DL4 4	DL10 # 4	DL17 ENABLE 4	DL CONV 2 SEL 4	PCM OSC B 4
0110	DL5 5	DL13 # 5	DL17 GRP 1 5	SIM ON 5	PCM A-D A 5
0111	DL6 6	DL14 # 6	DL17 GRP 2 6		PCM A-D B 6
0101	DL7 7	DL12 # 7	DL17 GRP 3 7	ADJ. THRESH. ON 7	MEMORY READ OUT 7
0100	DL8 8	DL15 # 8	DL17 GRP 4 8		PCM POWER B 8
1100	DL9 9	DL3 # 9	DL17 (1-3) 9	DL MOD 1 OFF * 9	PCM MIPLEX A 9
1101	DL10 10	DL4 # 10	DL17 (4-6) 10	DL MOD 2 OFF * 10	PCM MIPLEX B 10
1110	DL11 11	DL2 # 11	DL17 (7-9) 11	DL MOD 3 OFF * 11	PCM TIMING CHAIN A 11
1010	DL12 12	DL7 # 12	DL17 (10-12) 12	DL MODS ON * 12	PCM TIMING CHAIN B 12
1001	DL13 13	DL5 # 13	DL17 (13-15) 13	BU DL SYS ON 13	MEM A 1 SAMP 13
1000	DL14 14	DL6 # 14	DL17 (16-18) 14	BU DL SYS OFF 14	MEM AO SAMP 14
1011	DL15 15	DL8 # 15	DL17 (19-20) 15	20 MIN TIMER 15	MEM B1 SAMP 15
1111	DL16 16	DL1 # 16	TIMER CMD 1 16	TIMER CMD 2 16	MEM B0 SAMP 16

* - ORDNANCE ENABLE

- BACK UP CMD

SAMPLE RATE	FB	FA
1	0	0
4	0	1
32	1	0
64	1	1

EXP NO. 173-174

COMMANDS

10/15/71

TONE PAIR	MTX BOX 1	MTX BOX 2	MTX BOX 1	MTX BOX 2	MTX BOX 1
	LK(DL)	JL(DL)	LI(DL)	JK(DL)	JI(CMD)
0000	DL1 1	DL16 # 1		DL CONV ON 1	PCM TM ON PCM POWER A 1
0001	DL2 2	DL11 # 2		DL CONV BYP # * 2	PCM TM OFF 2
0011	DL3 3	DL9 # 3		DL CONV 1 SEL 3	PCM OSC A 3
0010	DL4 4	DL10 # 4	DL CONV BYP * 4	DL CONV 2 SEL 4	PCM OSC B 4
0110	DL5 5	DL13 # 5	DL 17 5	SLM ON 5	PCM A-D A 5
0111	DL6 6	DL14 # 6	DL 18 6		PCM A-D B 6
0101	DL7 7	DL12 # 7	DL 19 7	ADJ.THRESH.ON 7	MEMORY READ OUT 7
0100	DL8 8	DL15 # 8	DL 20 8	RETEP TO CH 12 ON 8	PCM POWER B 8
1100	DL9 9	DL3 # 9	DL 21 9	DL MOD 1 OFF * 9	PCM MIPLX A 9
1101	DL10 10	DL4 # 10	RETEP ON 10	DL MOD 2 OFF * 10	PCM MIPLX B 10
1110	DL11 11	DL6 # 11		DL MOD 3 OFF * 11	PCM TIMING CHAIN A 11
1010	DL12 12	DL7 # 12		DL MODS ON * 12	PCM TIMING CHAIN B 12
1001	DL13 13	DL5 # 13		BU DL SYS ON 13	MEM A1 SAMP 13
1000	DL14 14	DL8 # 14		BU DL SYS OFF 14	MEM A0 SAMP 14
1011	DL15 15	DL8 # 15		20 MIN TIMER 15	MEM B1 SAMP 15
1111	DL16 16	DL1 # 16	TIMER CMD 1 16	TIMER CMD 2 16	MEM B0 SAMP 16

* - ORDNANCE ENABLE

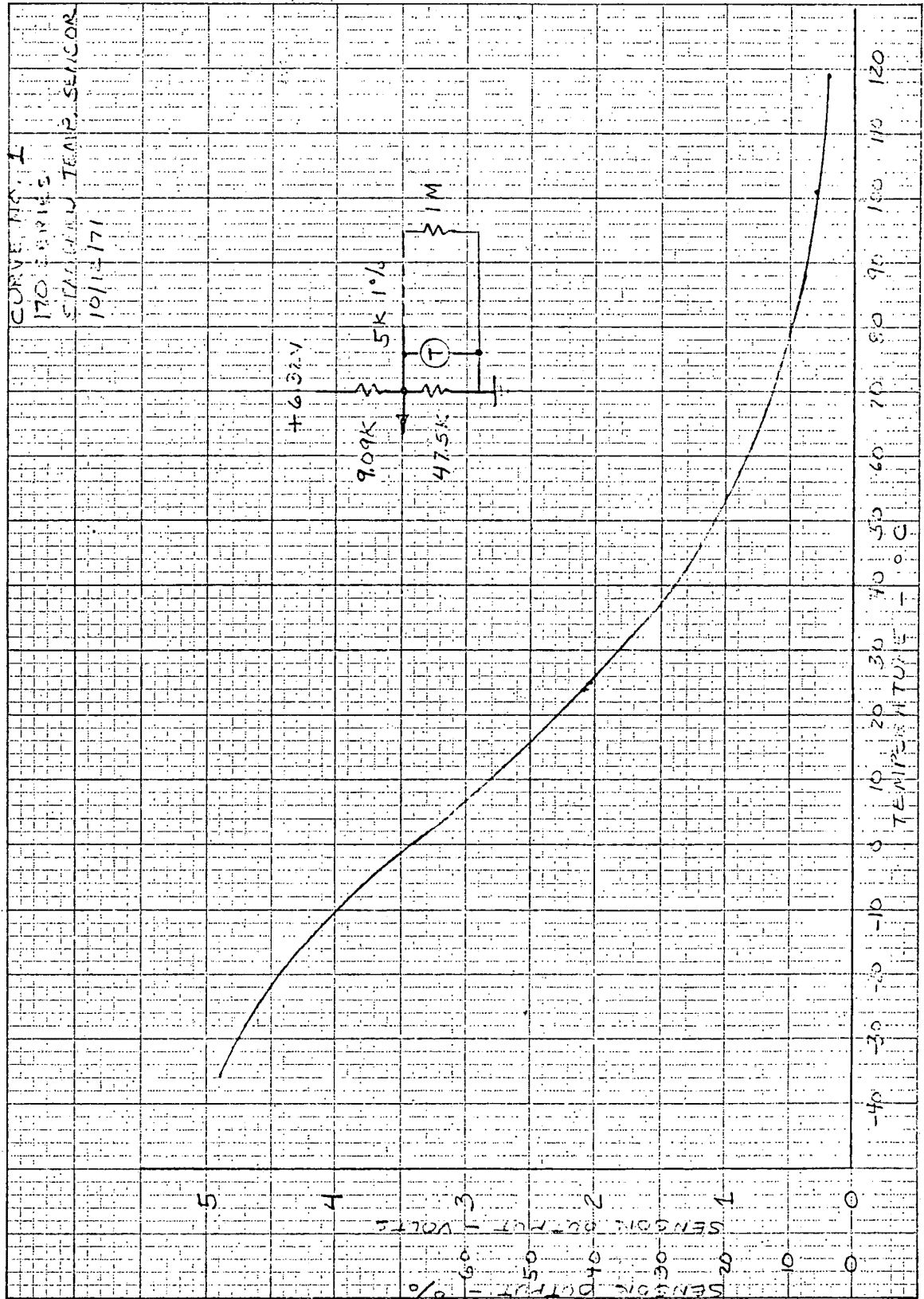
- BACK UP CMD

170 SERIES POM

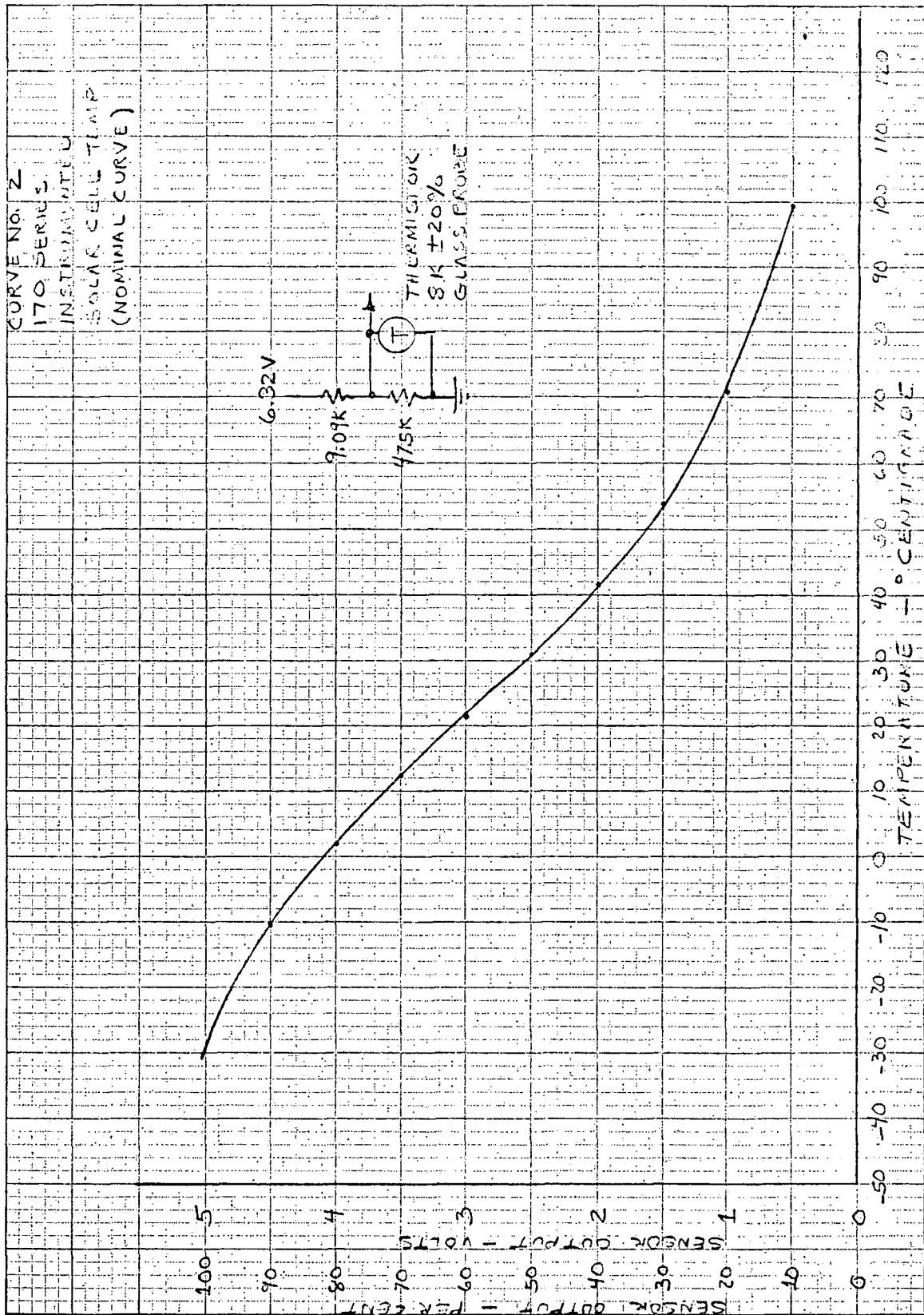
TABLE OF CURVES

1. STANDARD TEMP SENSOR
2. INSTRUMENTED SOLAR CELL TEMP SENSOR
3. PLUS and MINUS VOLTAGE SENSOR
SECONDARY MINUS BATT VOLTAGE
4. SECONDARY PLUS BATT VOLTAGE
5. PLUS and MINUS SOLAR CELL CURRENT MONITOR
6. PLUS and MINUS CHARGE and DISCHARGE CURRENT MONITOR
7. CHARGE CURRENT VS. SOLAR CELL CURRENT HI CHARGE
8. CHARGE CURRENT VS. SOLAR CELL CURRENT LO CHARGE
9. THRUSTER PRESSURE
10. MODULATION INDEX VS. POWER
11. GG BOOM LENGTH INDICATOR
12. REACTION WHEEL TACHOMETER
13. REACTION WHEEL BEARING TEMP
14. RECEIVER AGC

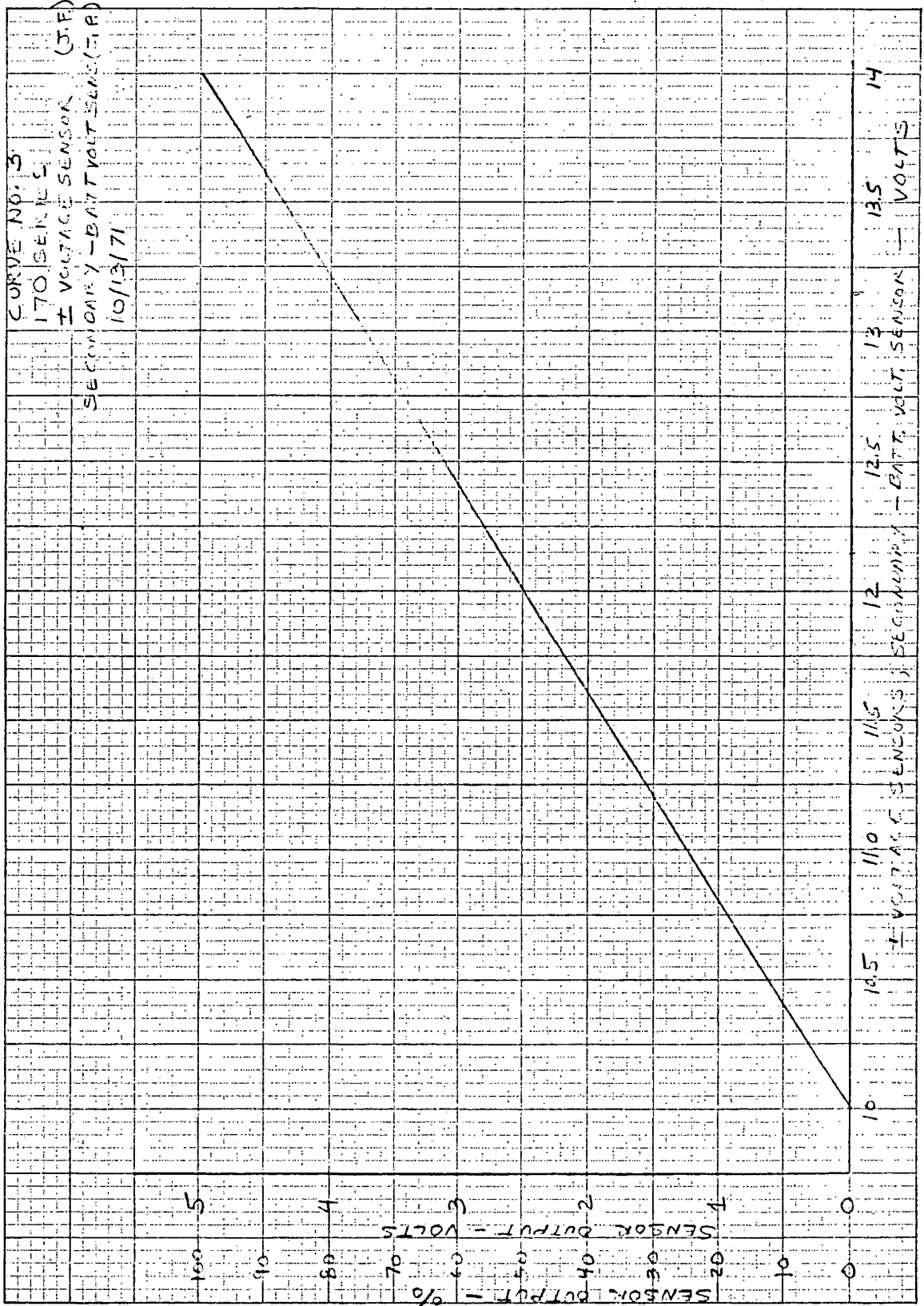
5 X 5 TO 1/2 INCH 46 0860
7 X 10 INCHES
NEUPPEL & ESSIGER CO.
MADE IN U.S.A.



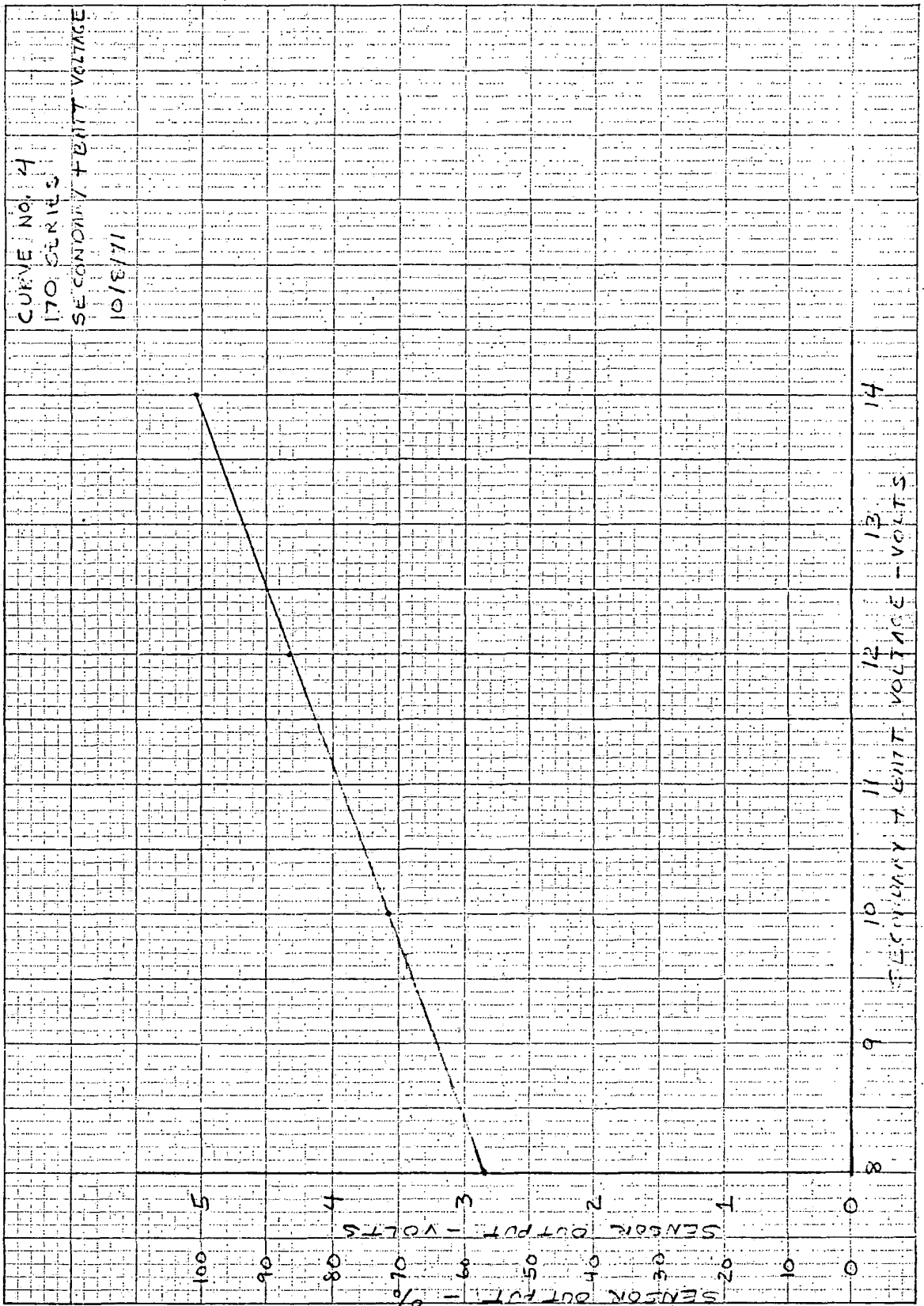
1 1/2" x 5" x 5" INCH 46 CR60
7 x 10 INCH'S PART IN U.S.A.
KALDI ELA & COOPER CO.



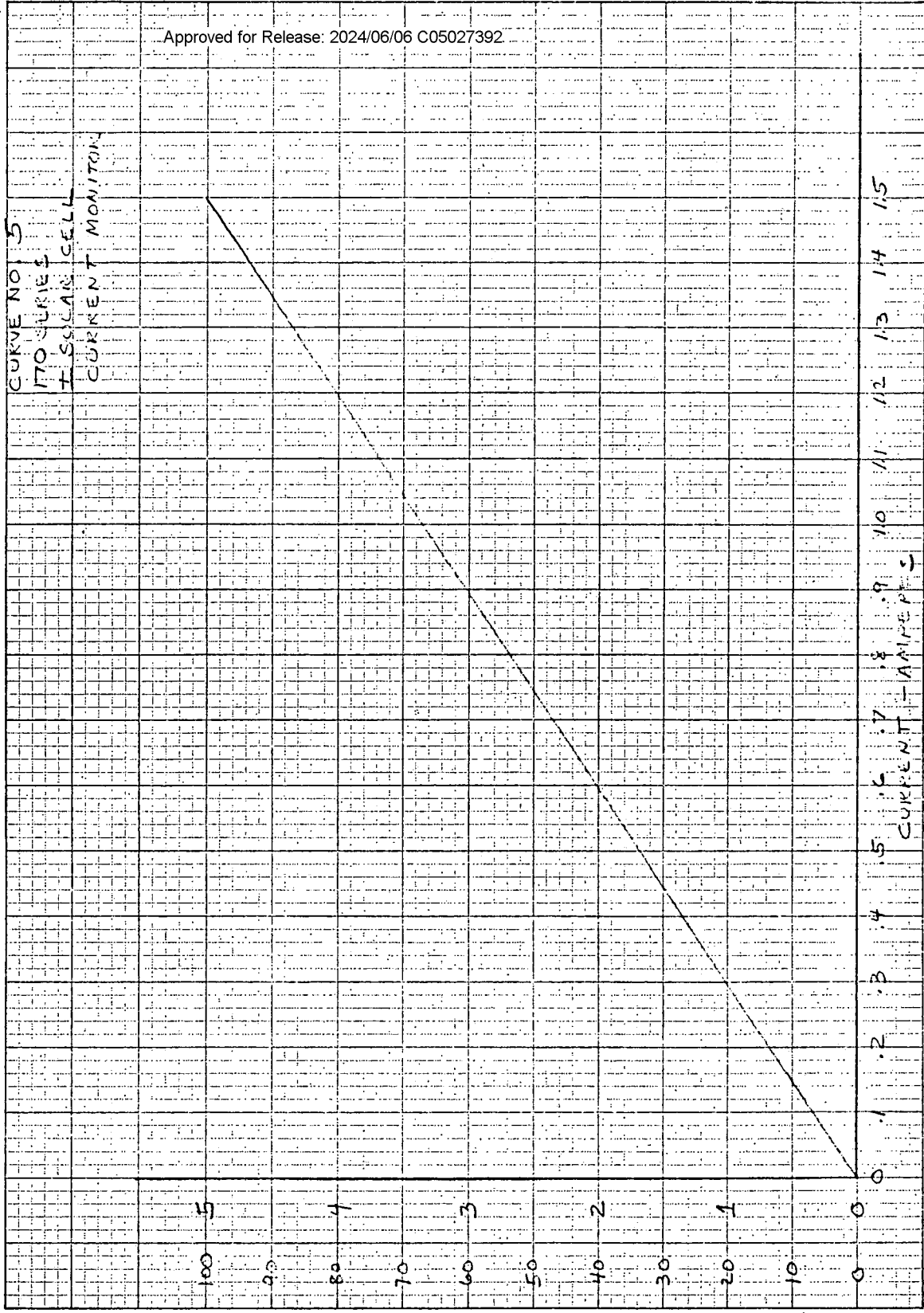
5 X 5 TO 1/2 INCH 46 0800
7 X 10 INCH
MADE IN U.S.A.
NATIONAL B. ECHER CO.



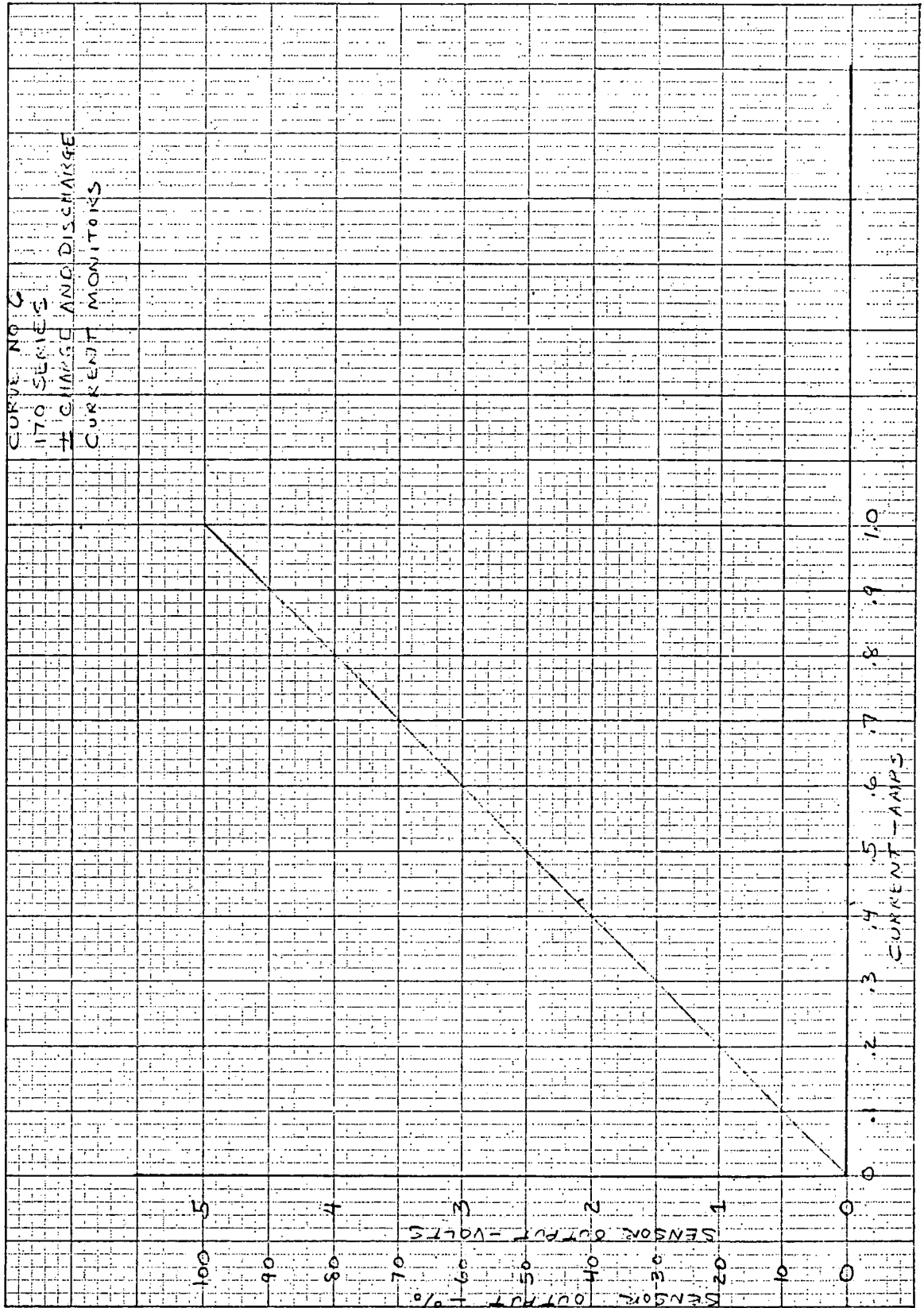
5 X 5 TO 15 INCH 46 0860
7 X 10 INCHES
MADE IN U.S.A.
MURPHY, A. J. & SONS CO.

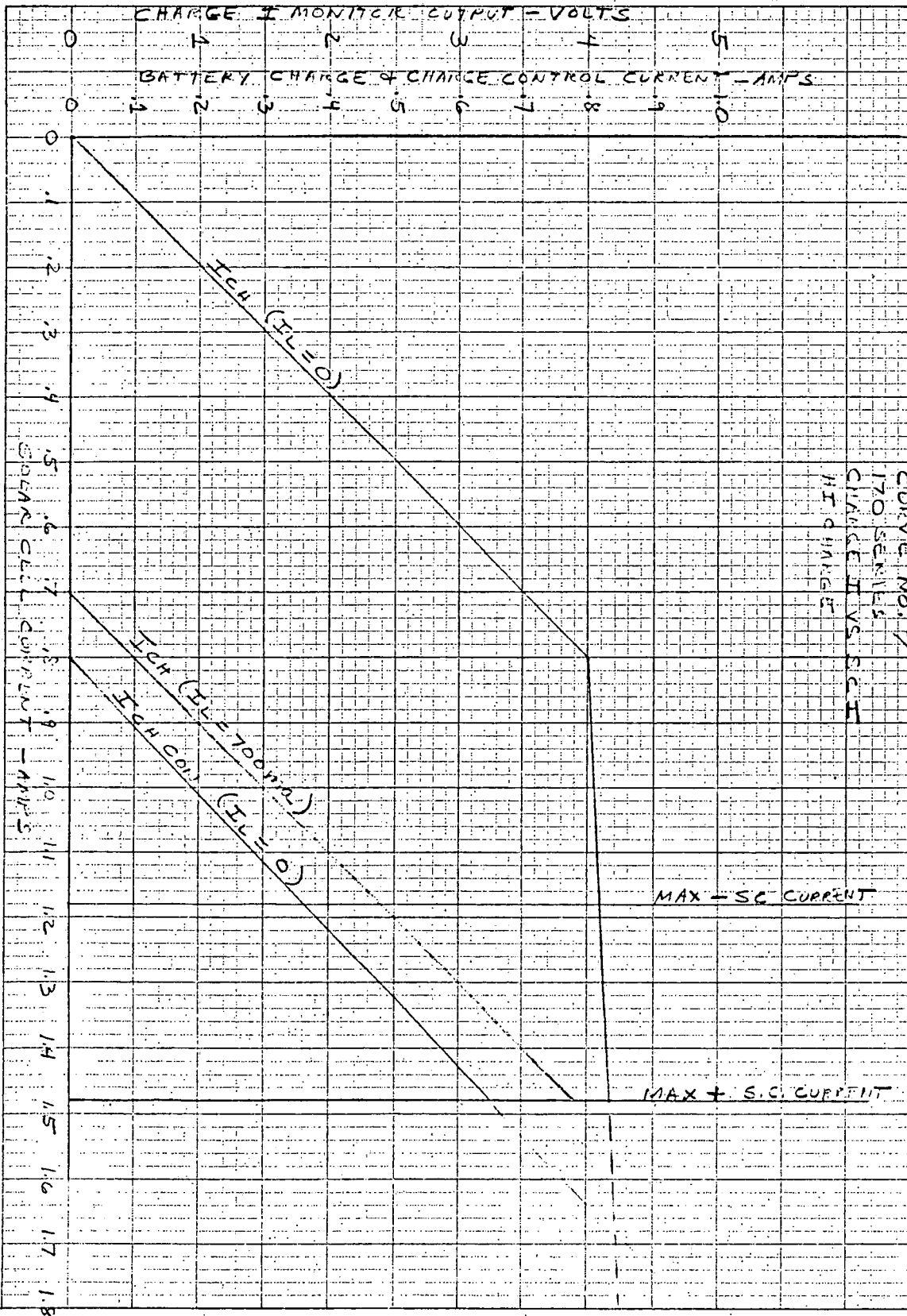


5 X 5 TO 1 1/2 INCH 46 OREGO
7 X 10 IRRIGALS MADE IN U.S.A.
KEUFFEL & ESSER CO.



5 X 5 TO 1/2 INCH 4G ORGO
7 X 10 INCHES
MADE IN U.S.A.
KUFFEL & ESSERT CO.



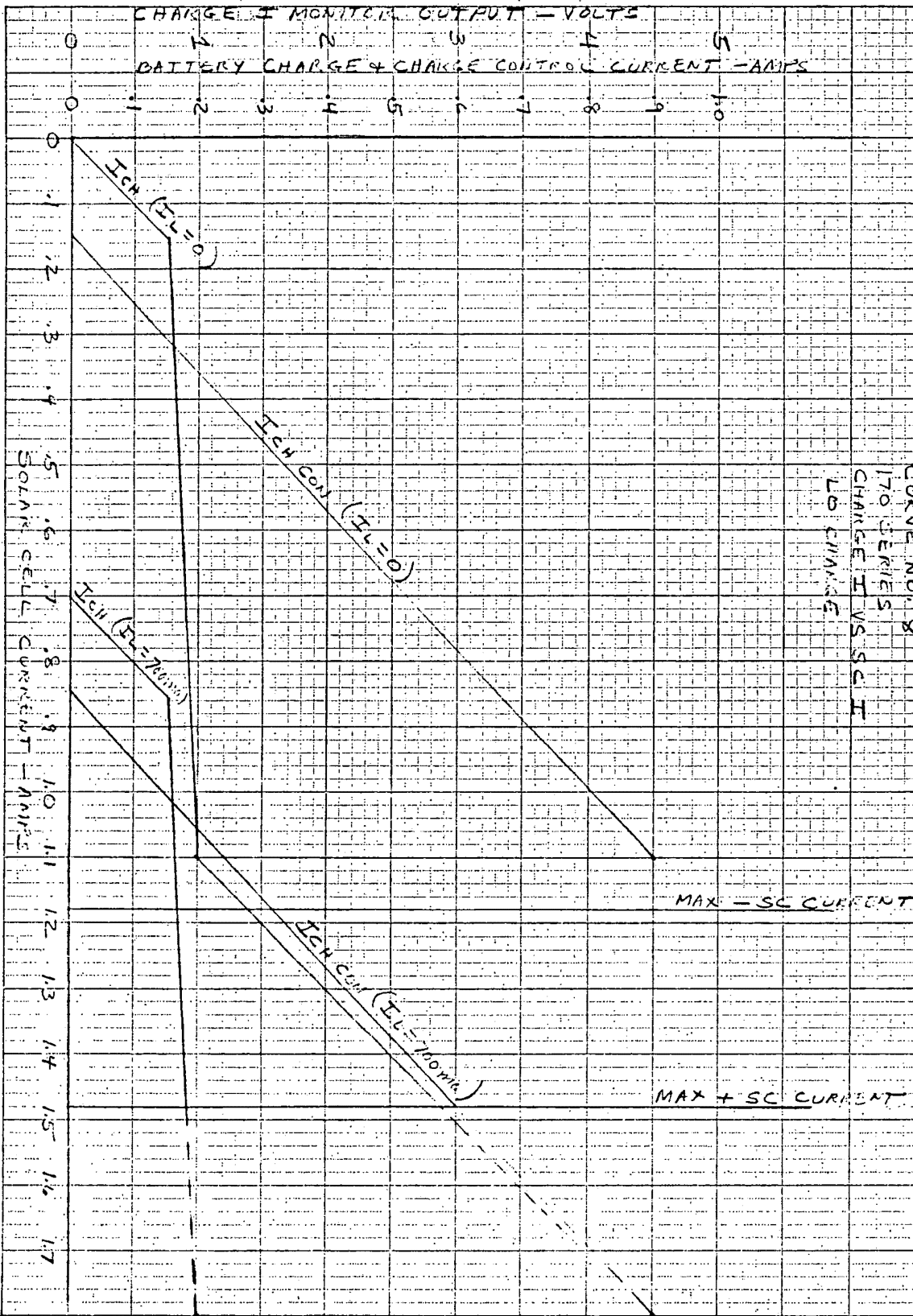


5 X 5 TO 1/2 INCH
 7 X 10 INCHES
 46 0800
 MADE IN U.S.A.
 NUPTEL & LESLER CO.

CURVE NO. 17
 170 SENN
 CHARGE IVS SCCT
 HINDINGE

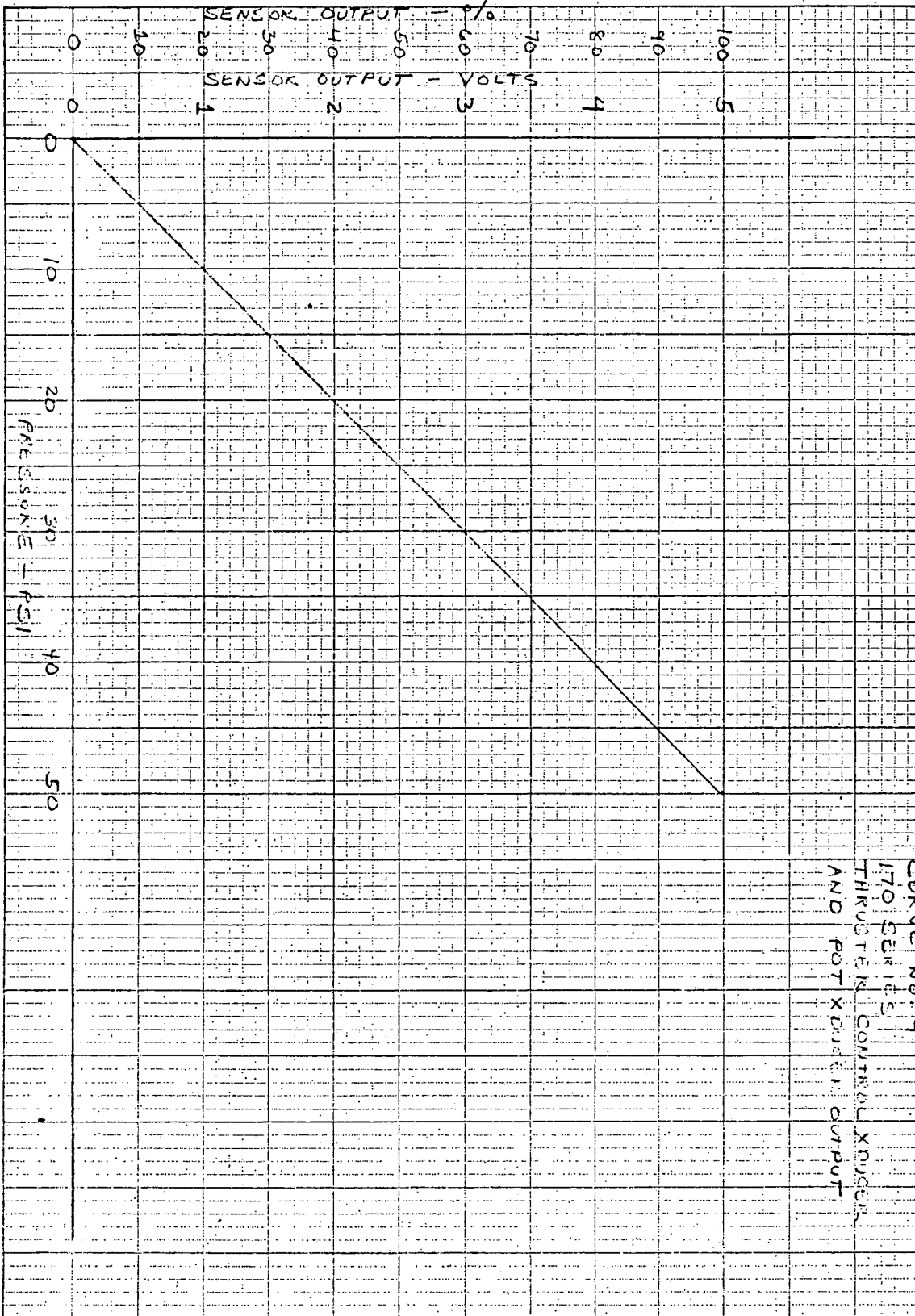
MAX - S.C. CURRENT

MAX + S.C. CURRENT



1 1/2" x 5 3/8" TO 1 1/2" INCH
 7 X 10 INCHES
 46 0360
 MADE IN U.S.A.
 ELECTRONIC RESEARCH CO.

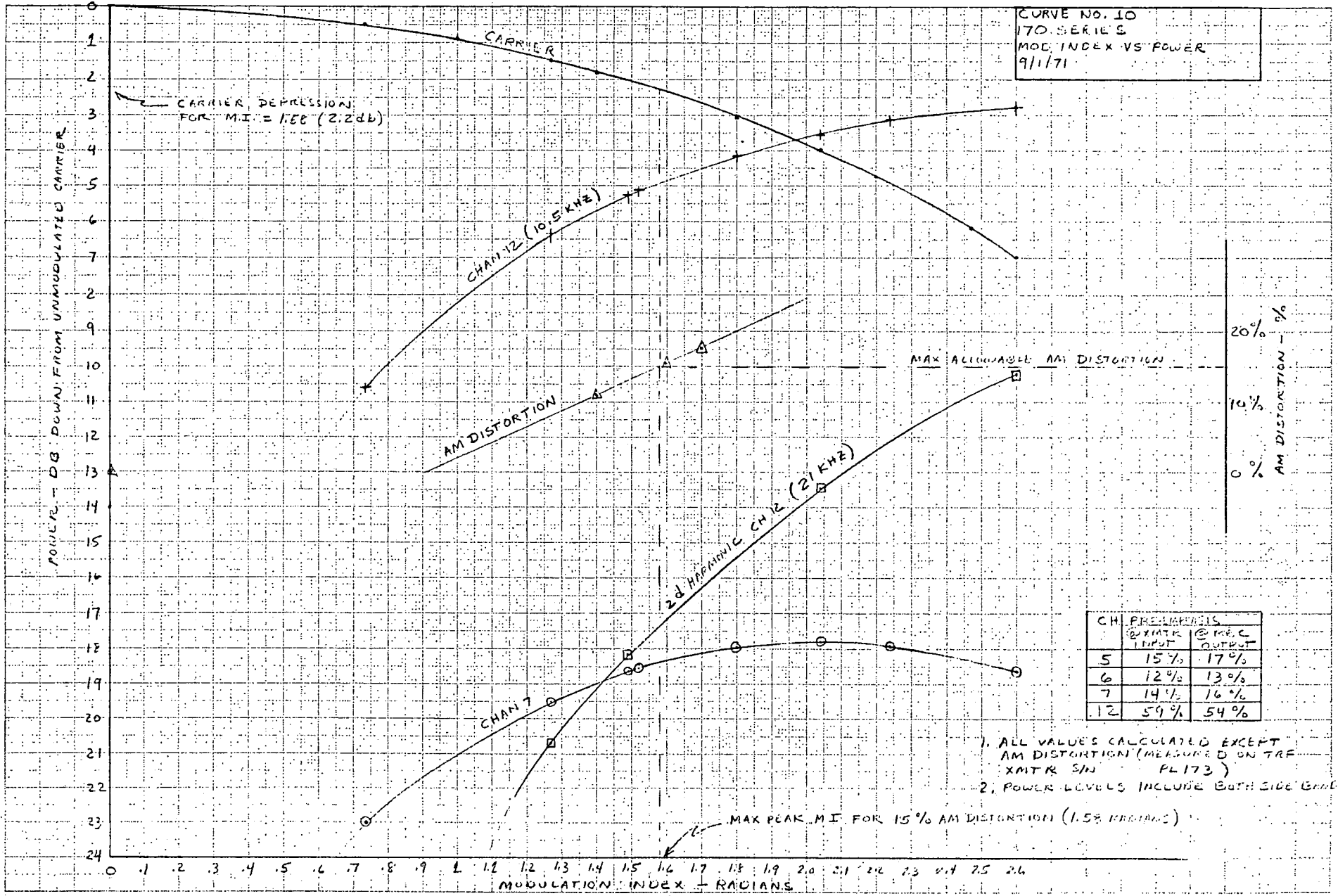
CURVE NO. 8
 I70 SERIES
 CHARGE I VS SC I
 LB CHANGE



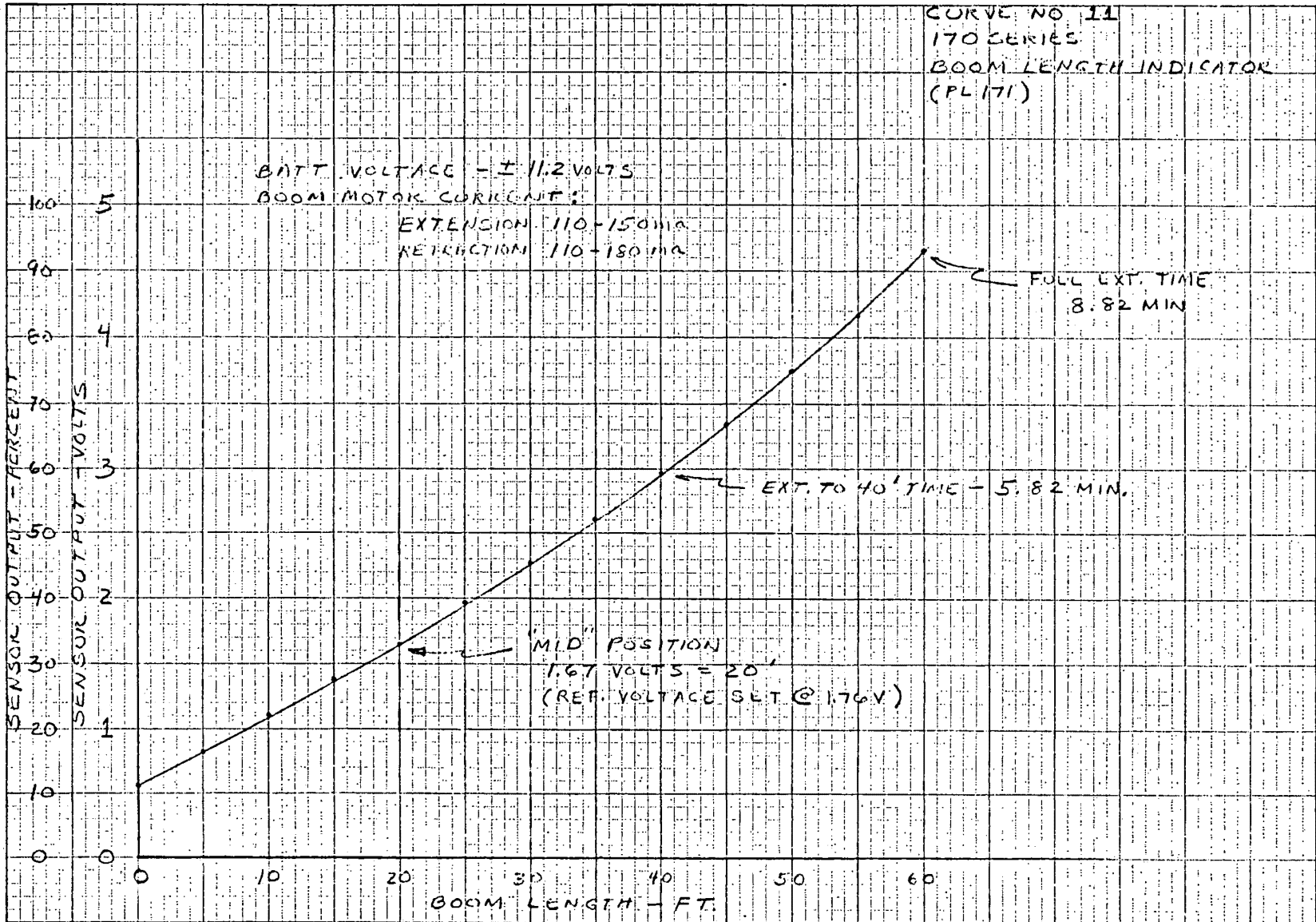
1 1/2" x 5 1/2" TO 1 1/2" INCH
 7 X 10 PROJECT
 MADE IN U.S.A.
 W. UFFEL & ESSER CO.

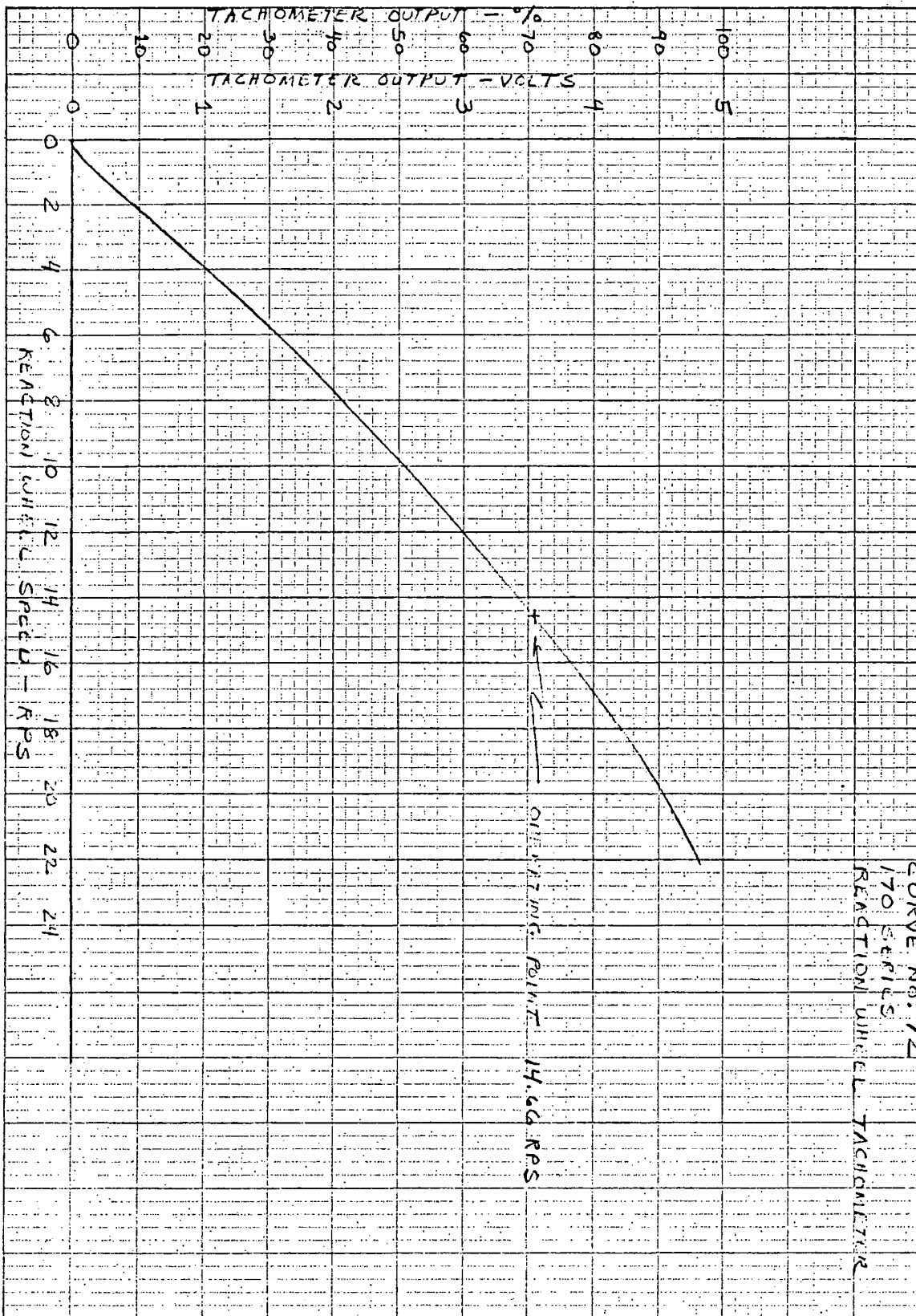
CURVE NO. 9
 I70 SERIES
 THRUSTER CONTROL XINGEN
 AND POT XINGEN OUTPUT

FORM NO. 210
 APR 68
 GPO WASHINGTON, D.C.



5 X 5 TO 1/2 INCH 46 0860
7 X 10 INCHES MADE IN U.S.A.
MUEHLE & ESSER CO.

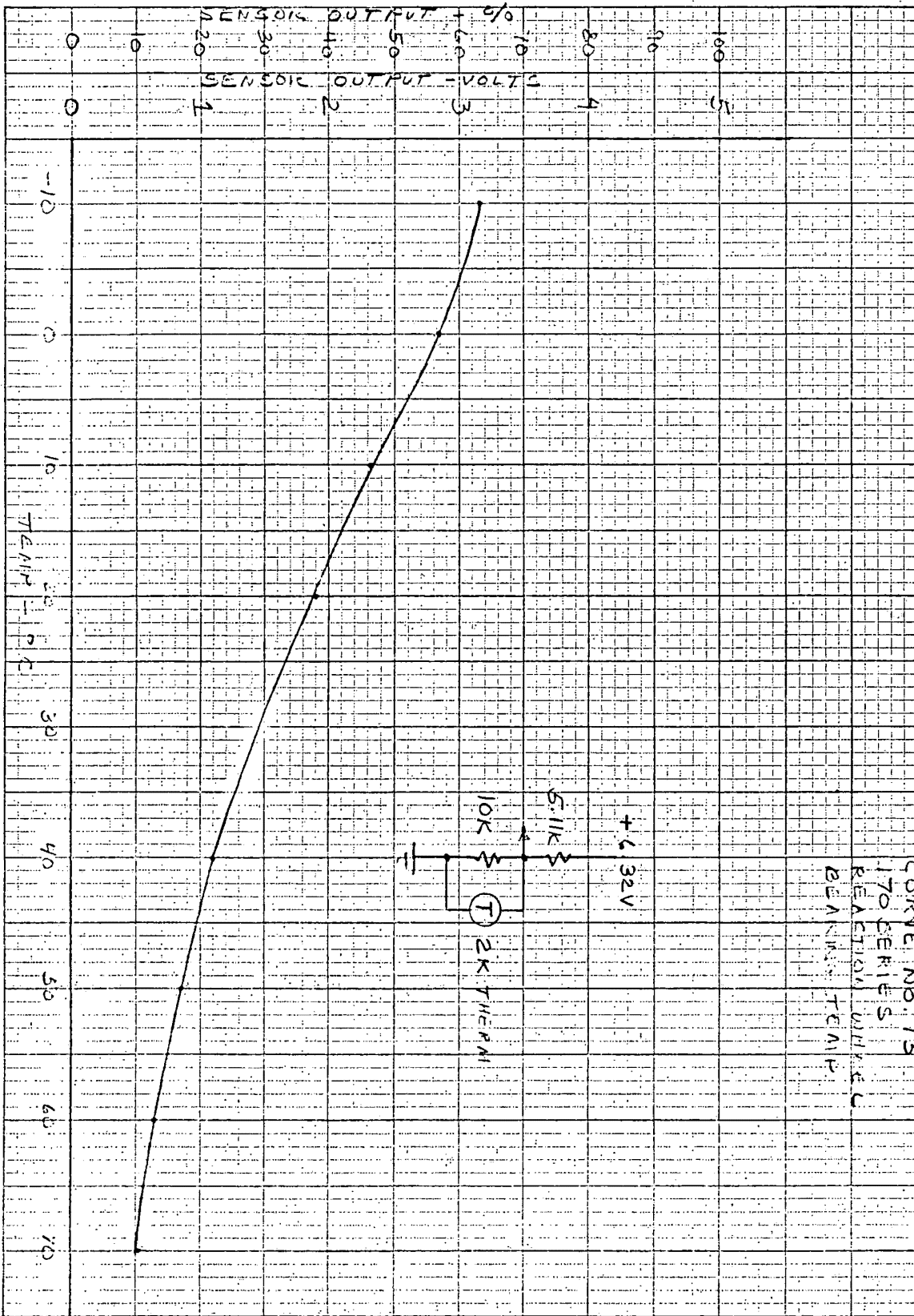




1 1/2" x 5" x 10" INCH
 MADE IN U.S.A.
 KUTUPITTL & ESSER CO. 46 0860

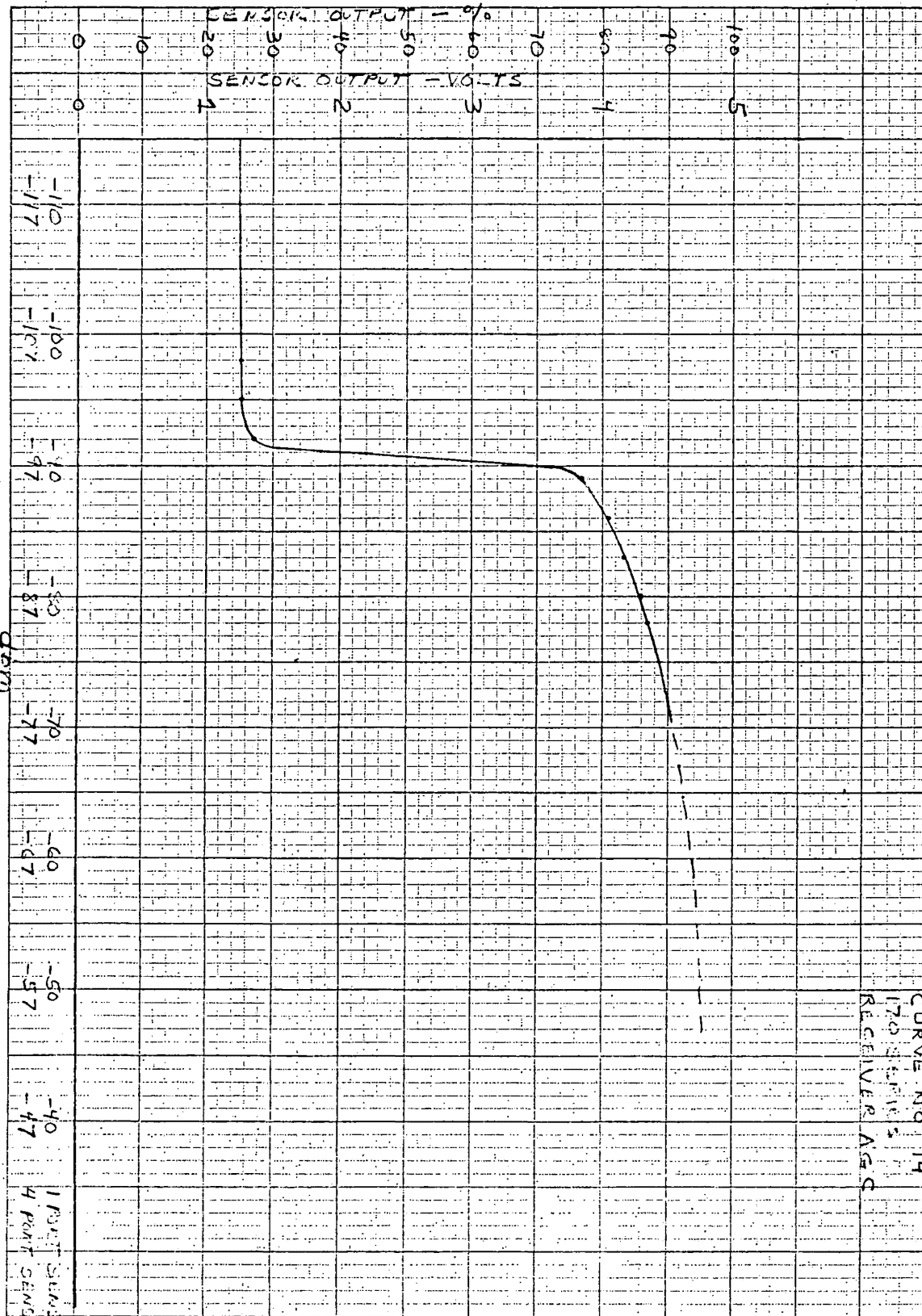
CURVE NO. 72
 170 SERIES
 REACTION WHEEL TACHOMETER

OILY POINT 14.6 RES



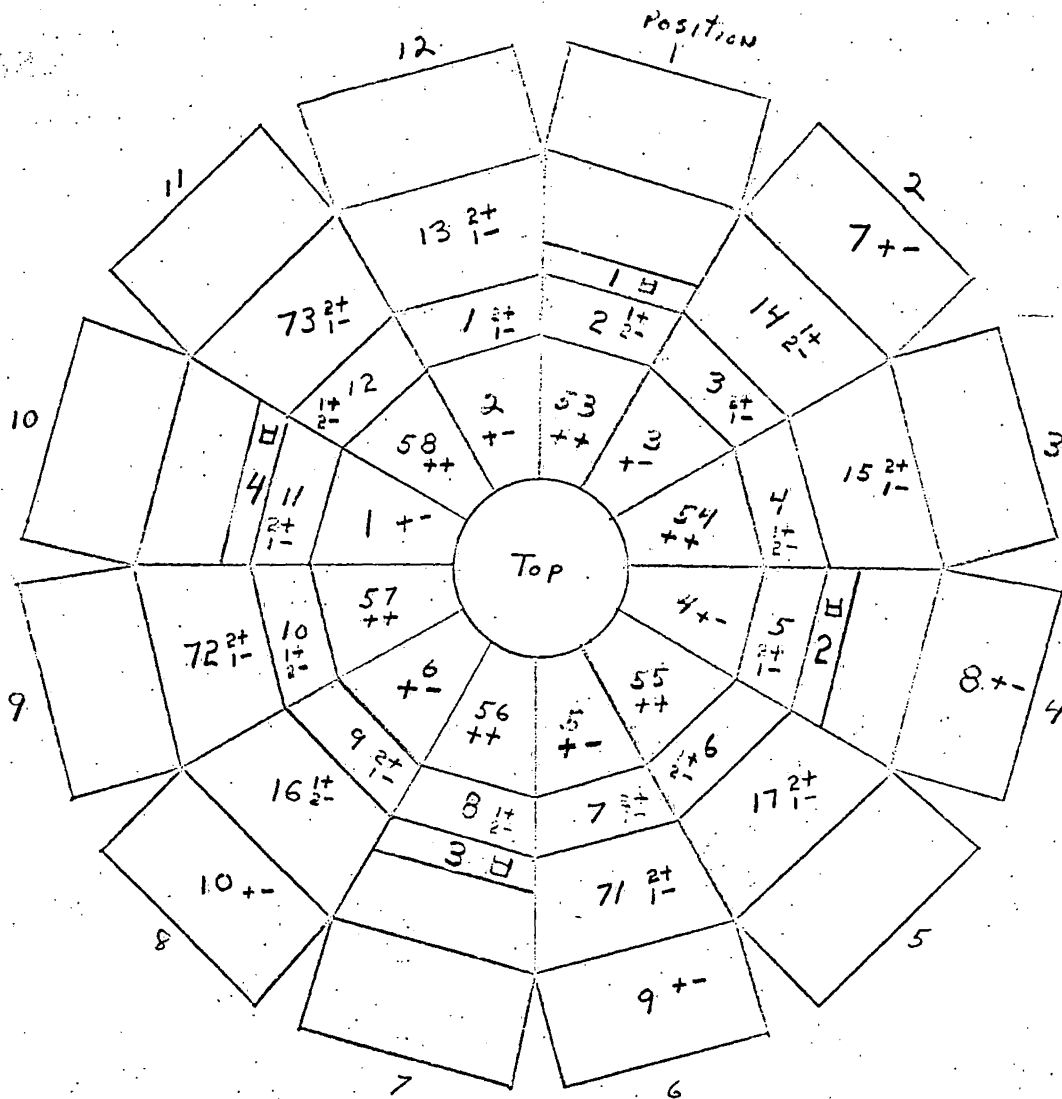
170 5 X 5 TO 1/2 INCH
 7 X 10 INCHES
 MADE IN U.S.A.
 46 0860
 KNUFFEL & ESSER CO.

SCALE 5 X 5 TO 1/2 INCH · 46 0860
7 X 10 INCHES
KIMMEL & ESSER CO. MADE IN U.S.A.



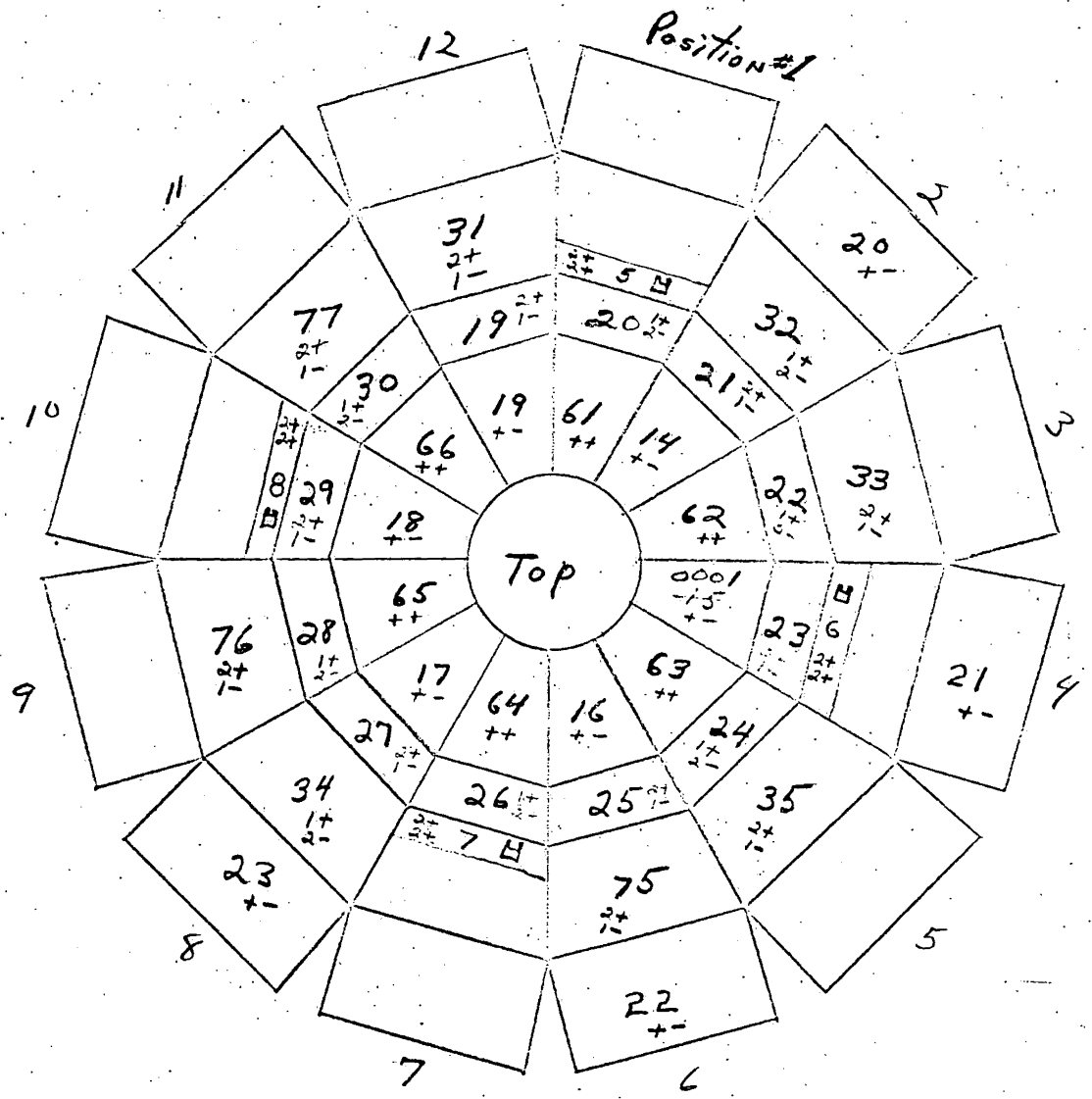
II.7. PANEL IDENTIFICATION

BY Shepherd DATE 10-18-71 SUBJECT Pl. 171 SHEET NO. _____ OF _____
 CHKD. BY _____ DATE _____ Panel Positions JOB NO. _____



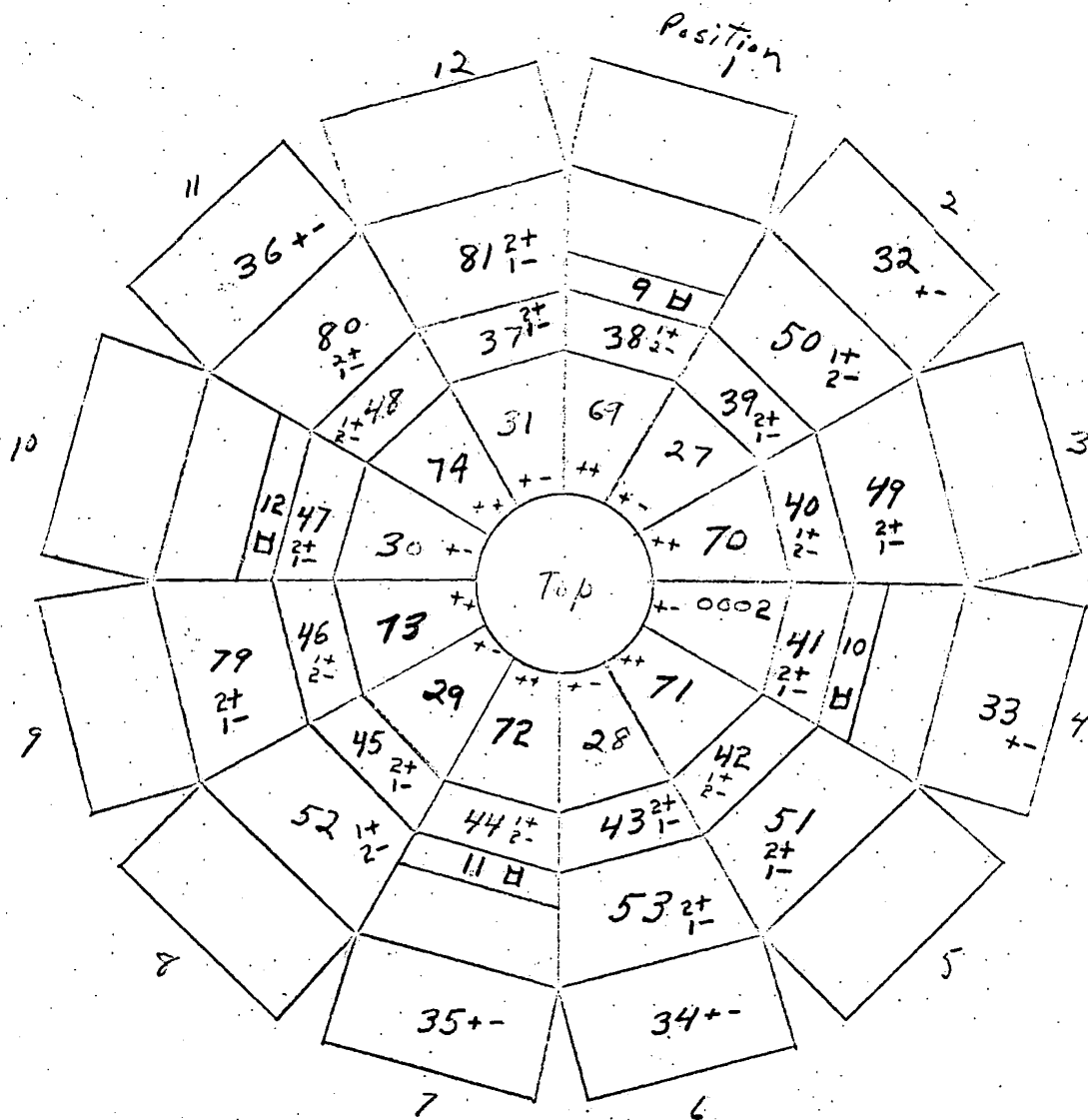
Paddle #1 Brown Dot

BY _____ DATE 10-23 SUBJECT PL 172 Panel Positions SHEET NO. _____ OF _____
 CHKD. BY Jm. [Signature] DATE _____ JOB NO. _____



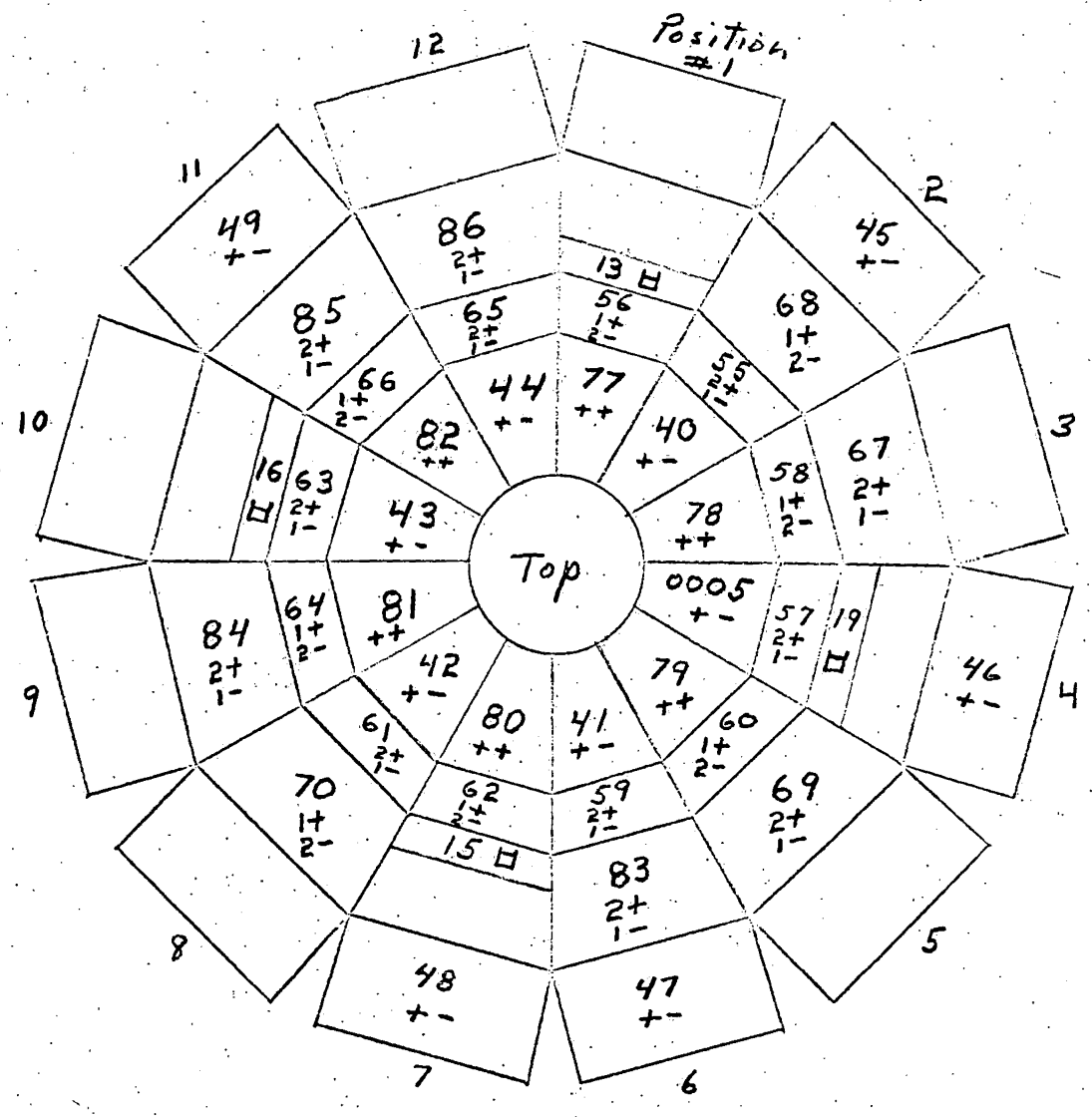
Panel - in of No. 1

BY _____ DATE _____ SUBJECT PL 173 SHEET NO. _____ OF _____
 CHKD. BY _____ DATE _____ Panel 1 Partitions 5 JOB NO. _____
Shepherd



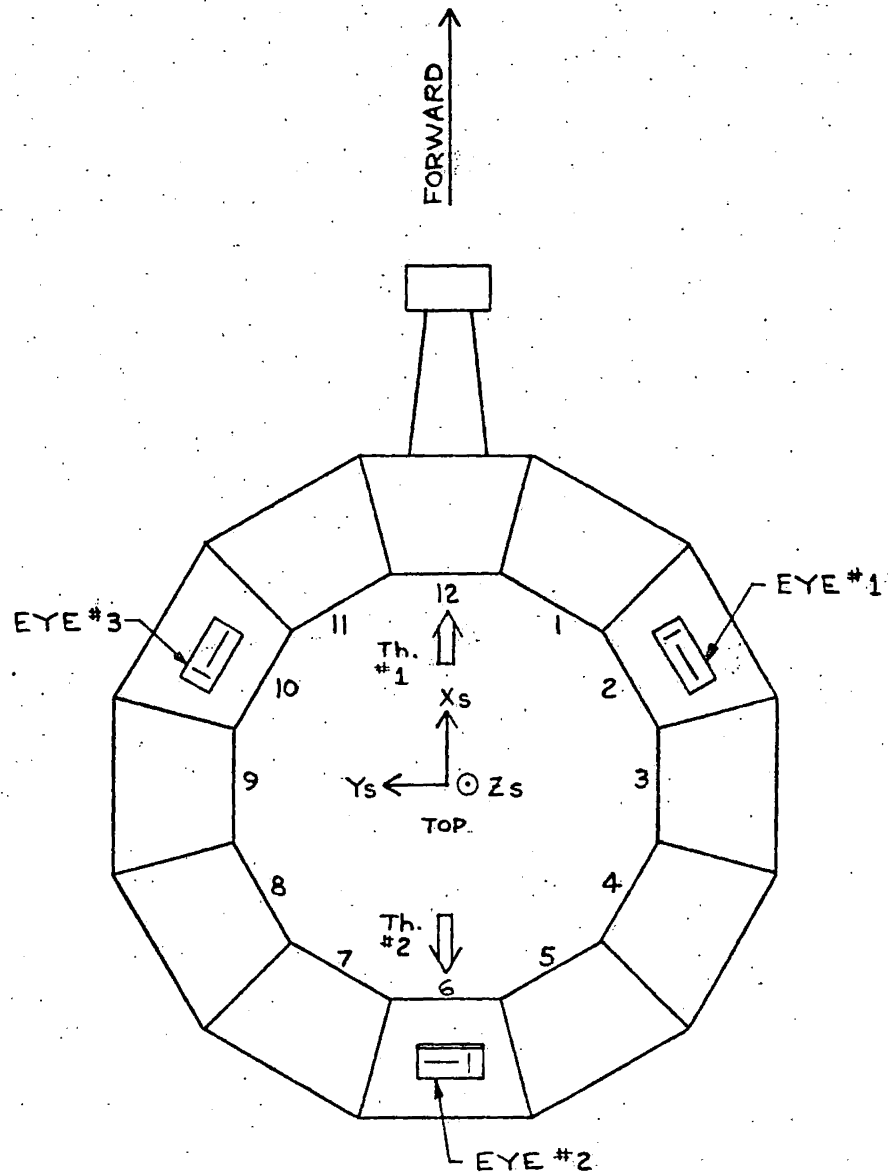
Puzzle = 3 orange dot

BY _____ DATE _____ STRATEGY PL 174 SHEET NO. _____
 CHG'D. BY _____ DATE _____ Panel Position JOB NO. _____
Shepherd



Paddle #4 Yellow Dot

II.8. FUNCTIONAL DIAGRAMS

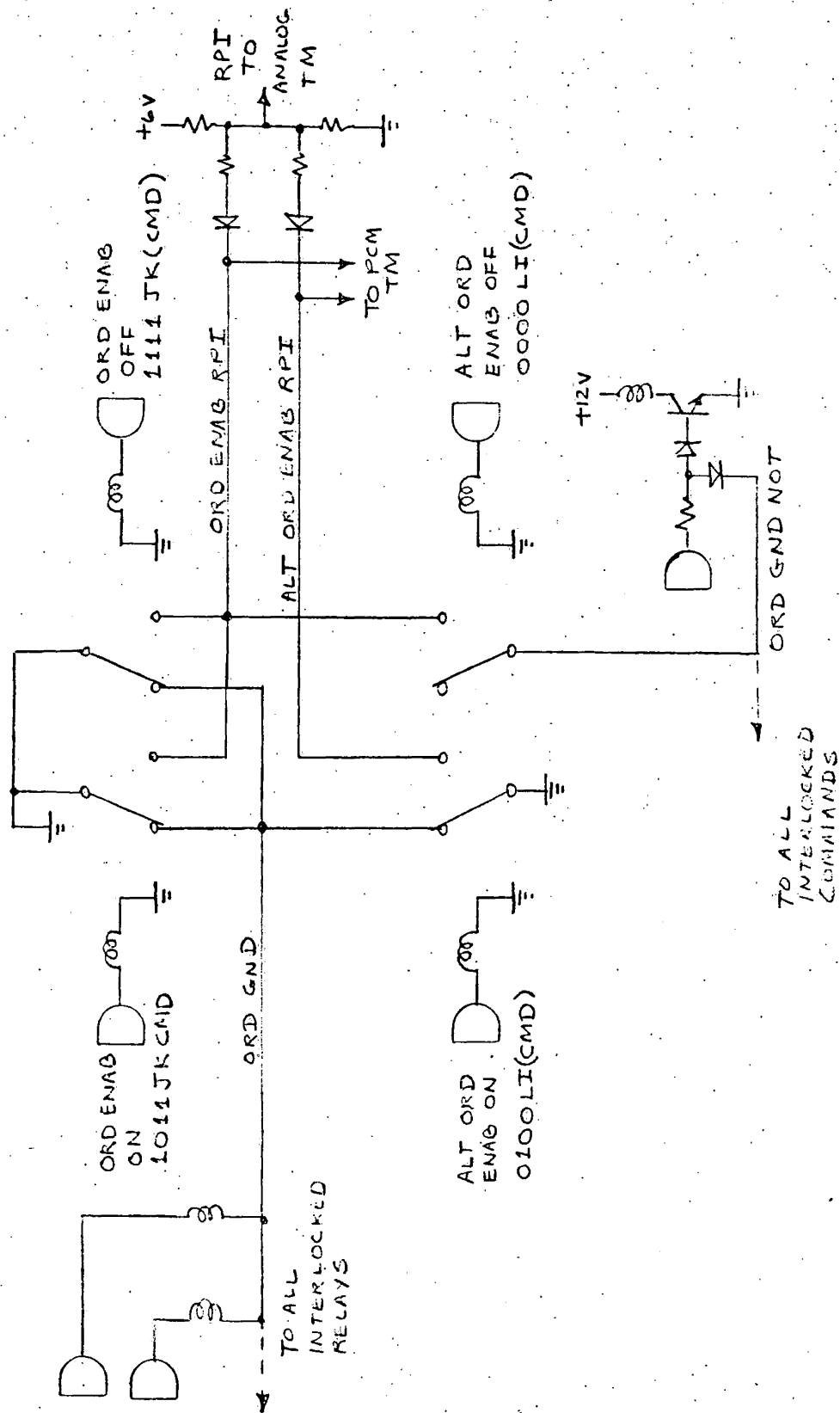


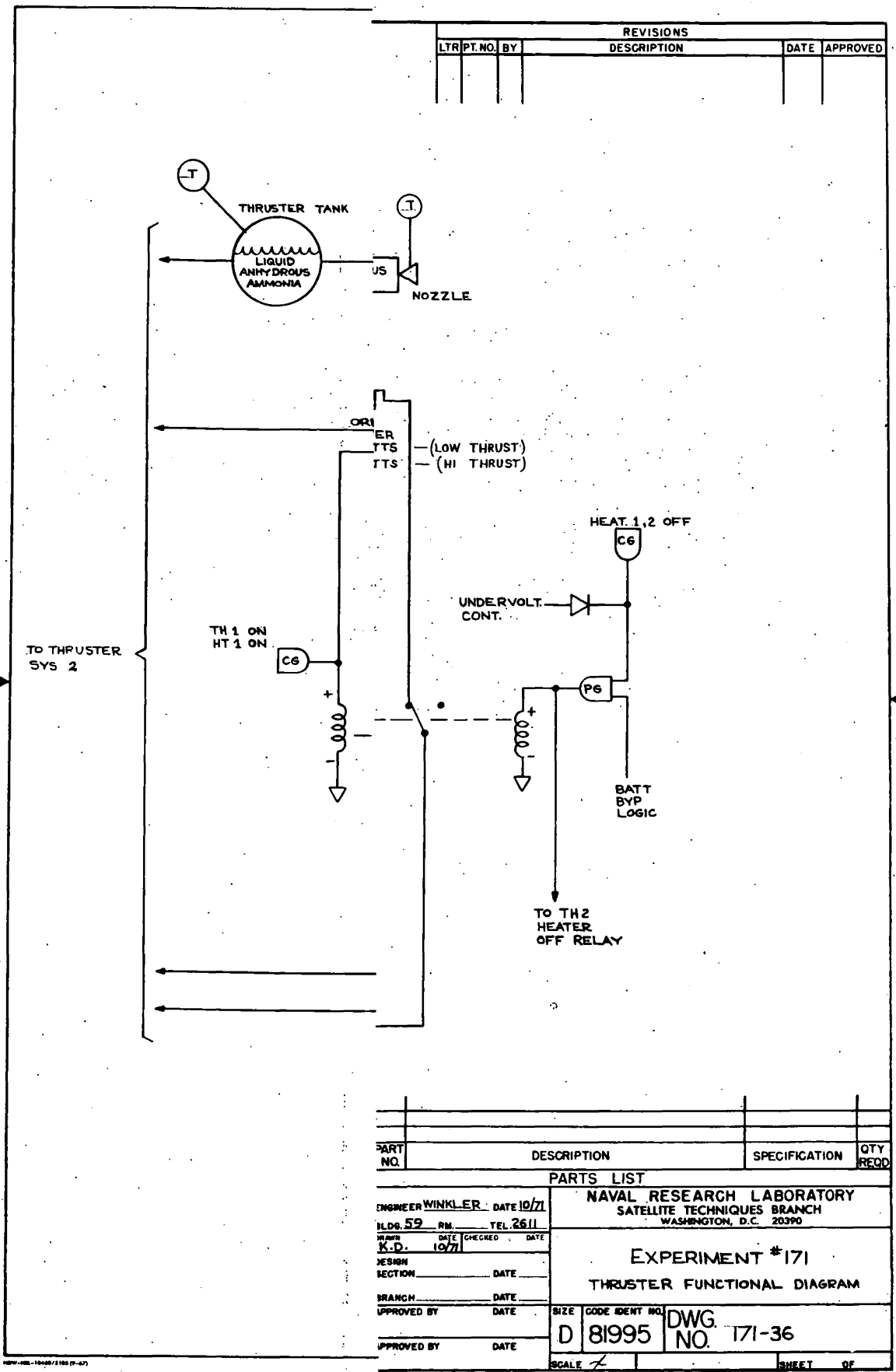
CMD FORWARD - MOMENTUM VECTOR OF WHEEL POINTS TO FLAT #9 (ie WHEEL TURNS CW LOOKING FROM SIDE OF CONNECTOR)

CMD BACKWARD - CONVERSE OF ABOVE

170 SERIES POM

ORDNANCE ENABLE SYSTEM

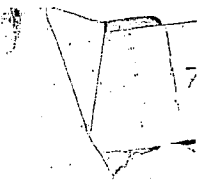




PART NO.	DESCRIPTION	SPECIFICATION	QTY REQD.
PARTS LIST			
ENGINEER WINKLER DATE 10/71 DLDG. 59 RM TEL 2611 WINKER K.D. DATE CHECKED DATE 10/71			
NAVAL RESEARCH LABORATORY SATELLITE TECHNIQUES BRANCH WASHINGTON, D.C. 20390			
EXPERIMENT #171 THRUSTER FUNCTIONAL DIAGRAM			
APPROVED BY	DATE	SIZE	CODE IDENT NO.
APPROVED BY	DATE	D 81995	DWG. NO. 171-36
SCALE		SHEET OF	

170 SERIES DDP-116 PROGRAMS

- F170R - Raw data is presented in octal or binary on the CRT and/or the Line Printer in the standard frame format.
- F170P - Processed PCM data is presented on the line Printer in the standard frame format.
- F170C - Processed PCM data is presented on the CRT in the standard frame format.
- F170MS - Processed memory data is presented on the CRT and/or the Line Printer.
- F170CS - Processed command system data is presented on the CRT and/or the Line Printer. Included are: address indicators, PCM control (word 2-2), PCM status (word 3-2), battery/power control (word 4-2), battery/power control (word 4-2), oscillator and A/D (word 2-3).
- F170ES - Processed experiment data is presented on CRT and/or the Line Printer.
- F170PS - Processed power system data is presented on the CRT and/or the Line Printer. Included are: cell voltages, 5 volt calibrate, voltage sensors, battery temperatures, charge currents, discharge currents, sec volt monitors, and battery power control (word 4-2).
- F170S - Processed reaction wheel, boom, and thrusters data is presented on the CRT and/or the Line Printer.
- F170M1 - Raw group sync data is channelled; PCM to mag tape one, MRO to mag tape two.
- F170M2 - Compares two tape generated by F170M1 above. Compares data sent to memory with data actually in memory.
- PLOT - FORTRAN plot subroutine allows line printer plotting of any word or bit in data stream. Limits and plot character to be determined by the user. TCT time is printed with plot. Plot image is Cols. 21 - 120.
- PLOT - FORTRAN M Plot frame words or bits vs. time.
- PSD-PLOT 70 - Plot frame words or bits vs. time
- PLOT - FORTRAN G Plot frame words or bits vs. time.
- F170AS - List attitude system vs. time.
- F170T - List temperatures vs. time.
- F170 H - Health program to check payload.



III.1. F170 R

DEC	OCT	BIN	DEC	OCT	BIN	DEC	OCT	BIN	DEC	OCT	BIN
000	000	00000000	064	100	01000000	128	200	10000000	192	300	11000000
001	001	00000001	065	101	01000001	129	201	10000001	193	301	11000001
002	002	00000010	066	102	01000010	130	202	10000010	194	302	11000010
003	003	00000011	067	103	01000011	131	203	10000011	195	303	11000011
004	004	00000100	068	104	01000100	132	204	10000100	196	304	11000100
005	005	00000101	069	105	01000101	133	205	10000101	197	305	11000101
006	006	00000110	070	106	01000110	134	206	10000110	198	306	11000110
007	007	00000111	071	107	01000111	135	207	10000111	199	307	11000111
008	010	00001000	072	110	01001000	136	210	10001000	200	310	11001000
009	011	00001001	073	111	01001001	137	211	10001001	201	311	11001001
010	012	00001010	074	112	01001010	138	212	10001010	202	312	11001010
011	013	00001011	075	113	01001011	139	213	10001011	203	313	11001011
012	014	00001100	076	114	01001100	140	214	10001100	204	314	11001100
013	015	00001101	077	115	01001101	141	215	10001101	205	315	11001101
014	016	00001110	078	116	01001110	142	216	10001110	206	316	11001110
015	017	00001111	079	117	01001111	143	217	10001111	207	317	11001111
016	020	00010000	080	120	01010000	144	220	10010000	208	320	11010000
017	021	00010001	081	121	01010001	145	221	10010001	209	321	11010001
018	022	00010010	082	122	01010010	146	222	10010010	210	322	11010010
019	023	00010011	083	123	01010011	147	223	10010011	211	323	11010011
020	024	00010100	084	124	01010100	148	224	10010100	212	324	11010100
021	025	00010101	085	125	01010101	149	225	10010101	213	325	11010101
022	026	00010110	086	126	01010110	150	226	10010110	214	326	11010110
023	027	00010111	087	127	01010111	151	227	10010111	215	327	11010111
024	030	00011000	088	130	01011000	152	230	10011000	216	330	11011000
025	031	00011001	089	131	01011001	153	231	10011001	217	331	11011001
026	032	00011010	090	132	01011010	154	232	10011010	218	332	11011010
027	033	00011011	091	133	01011011	155	233	10011011	219	333	11011011
028	034	00011100	092	134	01011100	156	234	10011100	220	334	11011100
029	035	00011101	093	135	01011101	157	235	10011101	221	335	11011101
030	036	00011110	094	136	01011110	158	236	10011110	222	336	11011110
031	037	00011111	095	137	01011111	159	237	10011111	223	337	11011111
032	040	00100000	096	140	01100000	160	240	10100000	224	340	11100000
033	041	00100001	097	141	01100001	161	241	10100001	225	341	11100001
034	042	00100010	098	142	01100010	162	242	10100010	226	342	11100010
035	043	00100011	099	143	01100011	163	243	10100011	227	343	11100011
036	044	00100100	100	144	01100100	164	244	10100100	228	344	11100100
037	045	00100101	101	145	01100101	165	245	10100101	229	345	11100101
038	046	00100110	102	146	01100110	166	246	10100110	230	346	11100110
039	047	00100111	103	147	01100111	167	247	10100111	231	347	11100111
040	050	00101000	104	150	01101000	168	250	10101000	232	350	11101000
041	051	00101001	105	151	01101001	169	251	10101001	233	351	11101001
042	052	00101010	106	152	01101010	170	252	10101010	234	352	11101010
043	053	00101011	107	153	01101011	171	253	10101011	235	353	11101011
044	054	00101100	108	154	01101100	172	254	10101100	236	354	11101100
045	055	00101101	109	155	01101101	173	255	10101101	237	355	11101101
046	056	00101110	110	156	01101110	174	256	10101110	238	356	11101110
047	057	00101111	111	157	01101111	175	257	10101111	239	357	11101111
048	060	00110000	112	160	01110000	176	260	10110000	240	360	11110000
049	061	00110001	113	161	01110001	177	261	10110001	241	361	11110001
050	062	00110010	114	162	01110010	178	262	10110010	242	362	11110010
051	063	00110011	115	163	01110011	179	263	10110011	243	363	11110011
052	064	00110100	116	164	01110100	180	264	10110100	244	364	11110100
053	065	00110101	117	165	01110101	181	265	10110101	245	365	11110101
054	066	00110110	118	166	01110110	182	266	10110110	246	366	11110110
055	067	00110111	119	167	01110111	183	267	10110111	247	367	11110111
056	070	00111000	120	170	01111000	184	270	10111000	248	370	11111000
057	071	00111001	121	171	01111001	185	271	10111001	249	371	11111001
058	072	00111010	122	172	01111010	186	272	10111010	250	372	11111010
059	073	00111011	123	173	01111011	187	273	10111011	251	373	11111011
060	074	00111100	124	174	01111100	188	274	10111100	252	374	11111100
061	075	00111101	125	175	01111101	189	275	10111101	253	375	11111101
062	076	00111110	126	176	01111110	190	276	10111110	254	376	11111110
063	077	00111111	127	177	01111111	191	277	10111111	255	377	11111111

170 Series Program Magnetic Tape Format

C B A 8 4 2 1

0	1	2	X	X	X		10's of Seconds
6	7	X	X	X	X		Units of Seconds
12	13	14	15	16	17		
0	1	2	X	X	X		10's of Minutes
6	7	X	X	X	X		Units of Minutes
12	13	14	15	16	17		
0	1	2	3	X	X		10's of Hours
6	7	X	X	X	X		Units of Hours
12	13	14	15	16	17		
0	1	X	X	X	X		10's of Days
6	7	X	X	X	X		Units of Days
12	13	14	15	16	17		
0	1	2	3	4	5		
6	7	8	9	X	X		100's of Days
12	13	14	15	16	17		
1	1	1	0	1	0		
1	1	1	0	0	1		Sub-frame sync
0	0	0	0	16	17		
0	0	0	1	0	1		
0	0	0	1	1	0		Frame sync
1	1	1	1	16	17		
X	X	X	X	X	X		
X	X	X	X	X	X		Data words
X	X	X	X	16	17		

MSB →

↑
LSB

Frame Content:

Five time words followed by subframe sync, frame sync, twelve eight bit data words, subframe sync, fourteen data words, subframe sync, fourteen data words---to a total of sixty nine sixteen bit words per magnetic tape record.

III.2. F170 P

BLEN	000076	000000	000000	303 15 43 47	RWTP	0.0315	RWTO	000000	MAGX	1.3400	+CM2	001.23	-C10	001.23	EXP1	000077	EXP2	000077
5VCL	*****	R1AG	*****	R2AG	0.0200	000068	VTIM	000057	MAGY	1.7600	+CM3	001.21	+C11	001.24	EXP3	000077	EXP4	000077
T19S	-040.9	T24B	0028.7	TH1P	000102	000076	MEMD	000310	CEL1	001.21	+CM4	001.22	+C12	001.22	SPRO	000377	SPR1	000377
+SVM	*****	-SVM	2.7400	T2PK	0030.5	000102	TH2P	000000	DLT1	000000	+CM5	001.22	+C13	001.22	EXP5	000077	EXP6	000077
+VSR	1.5200	-VSR	1.8200	+BTM	0.0211	000237	T15S	-040.9	T3+B	0021.1	+CM6	001.22	+C14	001.23	BBS7	000228	RW15	000105
+BAT	0021.1	-BAT	0021.5	T10H	0024.3	000363	-BTM	0.0215	+CIM	0.0000	+CM7	001.22	+DIM	0.5031	THHH	000245	EXP8	000077
T8S1	0045.0	T9S2	0045.5	E171	000377	000104	T16S	0130.0	+CM8	001.22	+CM7	0012.2	+C15	0012.3	EXP9	000077	EX10	000077
T5TK	002.23	N1TP	-04.09	E171	000377	000104	T171	0032.5	+CM9	001.23	+CM8	001.22	+C16	001.22	EXP11	000077	EX12	000077
BLEN	000076	000001	000001	E173	000377	000104	T12B	0035.0	+CM9	001.23	+CM9	001.23	+C17	001.23	T22C	0028.7	T23V	0028.7
5VCL	*****	R1AG	*****	E173	000377	000104	E174	000377	+CM9	001.23	+CM9	001.23	+C17	001.23	EXP15	000077	EXP16	000077
T19S	-040.9	T24B	0028.7	T72N	004.55	000104	T18B	004.45	+CM9	001.23	+CM9	001.23	+C17	001.23	EXP15	000077	EXP16	000077
+SVM	*****	-SVM	2.7400	303 15 43 50	RWTP	0.0315	RWTO	000000	+CM2	001.23	+CM2	001.23	-C10	001.23	EXP1	000077	EXP2	000077
+VSR	1.5200	-VSR	1.8200	000068	RWTP	0.0315	RWTO	000000	MAGX	1.3400	MAGY	1.7800	MAGZ	*****	AB1A	000000	AB1B	000000
+BAT	0021.5	-BAT	0021.5	000076	R1AG	*****	R2AG	0.0200	VTIM	000058	GM3	001.21	+C11	001.24	EXP3	000077	EXP4	000077
T8S1	0045.0	T9S2	0045.5	000076	R1AG	*****	R2AG	0.0200	MEMD	000310	CEL1	001.21	CL18	001.21	SPRO	000377	SPR1	000377
T5TK	002.27	N1TP	-04.09	000102	TH1P	000102	TH2P	000000	DLT1	000000	+CM4	001.22	+C12	001.22	EXP5	000077	EXP6	000077
BLEN	000076	000002	000002	000102	TH1P	000102	TH2P	000000	DLT1	000000	+CM4	001.22	+C12	001.22	EXP5	000077	EXP6	000077
5VCL	*****	R1AG	*****	000237	TH1P	000102	TH2P	000000	DLT1	000000	+CM4	001.22	+C12	001.22	EXP5	000077	EXP6	000077
T19S	-040.9	T24B	0028.7	000237	TH1P	000102	TH2P	000000	DLT1	000000	+CM4	001.22	+C12	001.22	EXP5	000077	EXP6	000077
+SVM	*****	-SVM	2.7400	000363	T2PK	0030.5	T15S	-040.9	+CM5	001.22	+CM5	001.22	+C13	001.22	BBS7	000228	RW15	000105
+VSR	1.5200	-VSR	1.8000	000363	T2PK	0030.5	T15S	-040.9	+CM5	001.22	+CM5	001.22	+C13	001.22	EXP7	000077	EXP8	000077
+BAT	0021.1	-BAT	0021.9	000104	+BTM	0.0211	-BTM	0.0215	+CIM	0.0000	+CIM	0.0000	+DIM	0.5031	THHH	000245	EXP8	000077
T8S1	0045.0	T9S2	0045.5	000104	T10H	0024.3	T16S	0130.0	+CM7	0012.2	+CM7	0012.2	+C15	0012.3	EXP9	000077	EX10	000077
T5TK	002.23	N1TP	-04.09	000104	E171	000377	E172	000377	+CM8	001.22	+CM8	001.22	+C16	001.22	EXP9	000077	EX10	000077
BLEN	000076	000003	000003	000104	E171	000377	E172	000377	+CM8	001.22	+CM8	001.22	+C16	001.22	EXP9	000077	EX10	000077
5VCL	*****	R1AG	*****	000104	E171	000377	E172	000377	+CM8	001.22	+CM8	001.22	+C16	001.22	EXP9	000077	EX10	000077
T19S	-040.9	T24B	0028.7	000104	E171	000377	E172	000377	+CM8	001.22	+CM8	001.22	+C16	001.22	EXP9	000077	EX10	000077
+SVM	*****	-SVM	2.7400	000104	E171	000377	E172	000377	+CM8	001.22	+CM8	001.22	+C16	001.22	EXP9	000077	EX10	000077
+VSR	1.5200	-VSR	1.8200	000104	E171	000377	E172	000377	+CM8	001.22	+CM8	001.22	+C16	001.22	EXP9	000077	EX10	000077
+BAT	0021.1	-BAT	0021.5	000104	E171	000377	E172	000377	+CM8	001.22	+CM8	001.22	+C16	001.22	EXP9	000077	EX10	000077
T8S1	0045.0	T9S2	0045.5	000104	E171	000377	E172	000377	+CM8	001.22	+CM8	001.22	+C16	001.22	EXP9	000077	EX10	000077

171
 Processed
 THUR
 VAC
 CHAMBER

EL70P CRT DISPLAY

SPED	OFF	STAT	ON	FORS	REVS
PRSC	PRIM	CONT	PRIM	DIRT	FORN
SPCT	SLOW	SPRO	021845		
RETL	0.0006	RWTO	008.50		
-VSR	07.990		+VSR		07.990
BCIO	OUT	BFRI	NRET	B MID	N MID
BFEI	NEXT	BMTR	REL	DLRI	NREL
PTCL	33.320		PTC2	33.320	
PTTI	33.320		PTT2	33.320	
BLEN	050.19		BTEM	000.06	
+DIM	0.6630		-DIM	0.6630	
+CIM	0.6630		BCOF	ON	
-CIM	0.6630		OREB	ON	
-PBS	SECD		+PBS	PRIM	
PCM	VTIM	170	P170S		
SAMPLE	00000	BIRD	173		
HKSR	OFF		OREN	OFF	REV
DLSS	OFF	316 19 11 28			000000

Boom, Thrusters, Reaction Wheel

170 Series Programs

170 SERIES DDP-116. RAW/PROCESSED TABLES

5 NOV 71

PROCESS AMPS 5 NOV 71

$$PD(n) = UD(n) * 40$$

000	0.0000	050	0.2000	100	0.4000	150	0.6000	200	0.8000
001	0.0040	051	0.2040	101	0.4040	151	0.6040	201	0.8040
002	0.0080	052	0.2080	102	0.4080	152	0.6080	202	0.8080
003	0.0120	053	0.2120	103	0.4120	153	0.6120	203	0.8120
004	0.0160	054	0.2160	104	0.4160	154	0.6160	204	0.8160
005	0.0200	055	0.2200	105	0.4200	155	0.6200	205	0.8200
006	0.0240	056	0.2240	106	0.4240	156	0.6240	206	0.8240
007	0.0280	057	0.2280	107	0.4280	157	0.6280	207	0.8280
008	0.0320	058	0.2320	108	0.4320	158	0.6320	208	0.8320
009	0.0360	059	0.2360	109	0.4360	159	0.6360	209	0.8360
010	0.0400	060	0.2400	110	0.4400	160	0.6400	210	0.8400
011	0.0440	061	0.2440	111	0.4440	161	0.6440	211	0.8440
012	0.0480	062	0.2480	112	0.4480	162	0.6480	212	0.8480
013	0.0520	063	0.2520	113	0.4520	163	0.6520	213	0.8520
014	0.0560	064	0.2560	114	0.4560	164	0.6560	214	0.8560
015	0.0600	065	0.2600	115	0.4600	165	0.6600	215	0.8600
016	0.0640	066	0.2640	116	0.4640	166	0.6640	216	0.8640
017	0.0680	067	0.2680	117	0.4680	167	0.6680	217	0.8680
018	0.0720	068	0.2720	118	0.4720	168	0.6720	218	0.8720
019	0.0760	069	0.2760	119	0.4760	169	0.6760	219	0.8760
020	0.0800	070	0.2800	120	0.4800	170	0.6800	220	0.8800
021	0.0840	071	0.2840	121	0.4840	171	0.6840	221	0.8840
022	0.0880	072	0.2880	122	0.4880	172	0.6880	222	0.8880
023	0.0920	073	0.2920	123	0.4920	173	0.6920	223	0.8920
024	0.0960	074	0.2960	124	0.4960	174	0.6960	224	0.8960
025	0.1000	075	0.3000	125	0.5000	175	0.7000	225	0.9000
026	0.1040	076	0.3040	126	0.5040	176	0.7040	226	0.9040
027	0.1080	077	0.3080	127	0.5080	177	0.7080	227	0.9080
028	0.1120	078	0.3120	128	0.5120	178	0.7120	228	0.9120
029	0.1160	079	0.3160	129	0.5160	179	0.7160	229	0.9160
030	0.1200	080	0.3200	130	0.5200	180	0.7200	230	0.9200
031	0.1240	081	0.3240	131	0.5240	181	0.7240	231	0.9240
032	0.1280	082	0.3280	132	0.5280	182	0.7280	232	0.9280
033	0.1320	083	0.3320	133	0.5320	183	0.7320	233	0.9320
034	0.1360	084	0.3360	134	0.5360	184	0.7360	234	0.9360
035	0.1400	085	0.3400	135	0.5400	185	0.7400	235	0.9400
036	0.1440	086	0.3440	136	0.5440	186	0.7440	236	0.9440
037	0.1480	087	0.3480	137	0.5480	187	0.7480	237	0.9480
038	0.1520	088	0.3520	138	0.5520	188	0.7520	238	0.9520
039	0.1560	089	0.3560	139	0.5560	189	0.7560	239	0.9560
040	0.1600	090	0.3600	140	0.5600	190	0.7600	240	0.9600
041	0.1640	091	0.3640	141	0.5640	191	0.7640	241	0.9640
042	0.1680	092	0.3680	142	0.5680	192	0.7680	242	0.9680
043	0.1720	093	0.3720	143	0.5720	193	0.7720	243	0.9720
044	0.1760	094	0.3760	144	0.5760	194	0.7760	244	0.9760
045	0.1800	095	0.3800	145	0.5800	195	0.7800	245	0.9800
046	0.1840	096	0.3840	146	0.5840	196	0.7840	246	0.9840
047	0.1880	097	0.3880	147	0.5880	197	0.7880	247	0.9880
048	0.1920	098	0.3920	148	0.5920	198	0.7920	248	0.9920
049	0.1960	099	0.3960	149	0.5960	199	0.7960	249	0.9960
250	1.0000								

Approved for Release: 2024/06/06 C05027392

PROCESS VOLTS 5 NOV 71

PD(n) = UD(n)*200

000	0.0000	050	1.0000	100	2.0000	150	3.0000	200	4.0000
001	0.0200	051	1.0200	101	2.0200	151	3.0200	201	4.0200
002	0.0400	052	1.0400	102	2.0400	152	3.0400	202	4.0400
003	0.0600	053	1.0600	103	2.0600	153	3.0600	203	4.0600
004	0.0800	054	1.0800	104	2.0800	154	3.0800	204	4.0800
005	0.1000	055	1.1000	105	2.1000	155	3.1000	205	4.1000
006	0.1200	056	1.1200	106	2.1200	156	3.1200	206	4.1200
007	0.1400	057	1.1400	107	2.1400	157	3.1400	207	4.1400
008	0.1600	058	1.1600	108	2.1600	158	3.1600	208	4.1600
009	0.1800	059	1.1800	109	2.1800	159	3.1800	209	4.1800
010	0.2000	060	1.2000	110	2.2000	160	3.2000	210	4.2000
011	0.2200	061	1.2200	111	2.2200	161	3.2200	211	4.2200
012	0.2400	062	1.2400	112	2.2400	162	3.2400	212	4.2400
013	0.2600	063	1.2600	113	2.2600	163	3.2600	213	4.2600
014	0.2800	064	1.2800	114	2.2800	164	3.2800	214	4.2800
015	0.3000	065	1.3000	115	2.3000	165	3.3000	215	4.3000
016	0.3200	066	1.3200	116	2.3200	166	3.3200	216	4.3200
017	0.3400	067	1.3400	117	2.3400	167	3.3400	217	4.3400
018	0.3600	068	1.3600	118	2.3600	168	3.3600	218	4.3600
019	0.3800	069	1.3800	119	2.3800	169	3.3800	219	4.3800
020	0.4000	070	1.4000	120	2.4000	170	3.4000	220	4.4000
021	0.4200	071	1.4200	121	2.4200	171	3.4200	221	4.4200
022	0.4400	072	1.4400	122	2.4400	172	3.4400	222	4.4400
023	0.4600	073	1.4600	123	2.4600	173	3.4600	223	4.4600
024	0.4800	074	1.4800	124	2.4800	174	3.4800	224	4.4800
025	0.5000	075	1.5000	125	2.5000	175	3.5000	225	4.5000
026	0.5200	076	1.5200	126	2.5200	176	3.5200	226	4.5200
027	0.5400	077	1.5400	127	2.5400	177	3.5400	227	4.5400
028	0.5600	078	1.5600	128	2.5600	178	3.5600	228	4.5600
029	0.5800	079	1.5800	129	2.5800	179	3.5800	229	4.5800
030	0.6000	080	1.6000	130	2.6000	180	3.6000	230	4.6000
031	0.6200	081	1.6200	131	2.6200	181	3.6200	231	4.6200
032	0.6400	082	1.6400	132	2.6400	182	3.6400	232	4.6400
033	0.6600	083	1.6600	133	2.6600	183	3.6600	233	4.6600
034	0.6800	084	1.6800	134	2.6800	184	3.6800	234	4.6800
035	0.7000	085	1.7000	135	2.7000	185	3.7000	235	4.7000
036	0.7200	086	1.7200	136	2.7200	186	3.7200	236	4.7200
037	0.7400	087	1.7400	137	2.7400	187	3.7400	237	4.7400
038	0.7600	088	1.7600	138	2.7600	188	3.7600	238	4.7600
039	0.7800	089	1.7800	139	2.7800	189	3.7800	239	4.7800
040	0.8000	090	1.8000	140	2.8000	190	3.8000	240	4.8000
041	0.8200	091	1.8200	141	2.8200	191	3.8200	241	4.8200
042	0.8400	092	1.8400	142	2.8400	192	3.8400	242	4.8400
043	0.8600	093	1.8600	143	2.8600	193	3.8600	243	4.8600
044	0.8800	094	1.8800	144	2.8800	194	3.8800	244	4.8800
045	0.9000	095	1.9000	145	2.9000	195	3.9000	245	4.9000
046	0.9200	096	1.9200	146	2.9200	196	3.9200	246	4.9200
047	0.9400	097	1.9400	147	2.9400	197	3.9400	247	4.9400
048	0.9600	098	1.9600	148	2.9600	198	3.9600	248	4.9600
049	0.9800	099	1.9800	149	2.9800	199	3.9800	249	4.9800
250	5.0000	251	5.0200	252	5.0400	253	5.0600	254	5.0800
255	5.1000								

PROCESS PSI 5 NOV 71

$$PD(n)=UD(n)*196/10$$

000	00.000	050	00.980	100	01.960	150	02.940	200	03.920
001	00.019	051	00.999	101	01.979	151	02.959	201	03.939
002	00.039	052	01.019	102	01.999	152	02.979	202	03.959
003	00.058	053	01.038	103	02.018	153	02.998	203	03.978
004	00.078	054	01.058	104	02.038	154	03.018	204	03.998
005	00.098	055	01.078	105	02.058	155	03.038	205	04.018
006	00.117	056	01.097	106	02.077	156	03.057	206	04.037
007	00.137	057	01.117	107	02.097	157	03.077	207	04.057
008	00.156	058	01.136	108	02.116	158	03.096	208	04.076
009	00.176	059	01.156	109	02.136	159	03.116	209	04.096
010	00.196	060	01.176	110	02.156	160	03.136	210	04.116
011	00.215	061	01.195	111	02.175	161	03.155	211	04.135
012	00.235	062	01.215	112	02.195	162	03.175	212	04.155
013	00.254	063	01.234	113	02.214	163	03.194	213	04.174
014	00.274	064	01.254	114	02.234	164	03.214	214	04.194
015	00.294	065	01.274	115	02.254	165	03.234	215	04.214
016	00.313	066	01.293	116	02.273	166	03.253	216	04.233
017	00.333	067	01.313	117	02.293	167	03.273	217	04.253
018	00.352	068	01.332	118	02.312	168	03.292	218	04.272
019	00.372	069	01.352	119	02.332	169	03.312	219	04.292
020	00.392	070	01.372	120	02.352	170	03.332	220	04.312
021	00.411	071	01.391	121	02.371	171	03.351	221	04.331
022	00.431	072	01.411	122	02.391	172	03.371	222	04.351
023	00.450	073	01.430	123	02.410	173	03.390	223	04.370
024	00.470	074	01.450	124	02.430	174	03.410	224	04.390
025	00.490	075	01.470	125	02.450	175	03.430	225	04.410
026	00.509	076	01.489	126	02.469	176	03.449	226	04.429
027	00.529	077	01.509	127	02.489	177	03.469	227	04.449
028	00.548	078	01.528	128	02.508	178	03.488	228	04.468
029	00.568	079	01.548	129	02.528	179	03.508	229	04.488
030	00.588	080	01.568	130	02.548	180	03.528	230	04.508
031	00.607	081	01.587	131	02.567	181	03.547	231	04.527
032	00.627	082	01.607	132	02.587	182	03.567	232	04.547
033	00.646	083	01.626	133	02.606	183	03.586	233	04.566
034	00.666	084	01.646	134	02.626	184	03.606	234	04.586
035	00.686	085	01.666	135	02.646	185	03.626	235	04.606
036	00.705	086	01.685	136	02.665	186	03.645	236	04.625
037	00.725	087	01.705	137	02.685	187	03.665	237	04.645
038	00.744	088	01.724	138	02.704	188	03.684	238	04.664
039	00.764	089	01.744	139	02.724	189	03.704	239	04.684
040	00.784	090	01.764	140	02.744	190	03.724	240	04.704
041	00.803	091	01.783	141	02.763	191	03.743	241	04.723
042	00.823	092	01.803	142	02.783	192	03.763	242	04.743
043	00.842	093	01.822	143	02.802	193	03.782	243	04.762
044	00.862	094	01.842	144	02.822	194	03.802	244	04.782
045	00.882	095	01.862	145	02.842	195	03.822	245	04.802
046	00.901	096	01.881	146	02.861	196	03.841	246	04.821
047	00.921	097	01.901	147	02.881	197	03.861	247	04.841
048	00.940	098	01.920	148	02.900	198	03.880	248	04.860
049	00.960	099	01.940	149	02.920	199	03.900	249	04.880
250	04.900	251	04.919	252	04.939	253	04.958	254	04.978
255	04.998								

$$PD(n)=UD(n)*47$$

000	00.000	050	02.350	100	04.700	150	07.050	200	09.400
001	00.047	051	02.397	101	04.747	151	07.097	201	09.447
002	00.094	052	02.444	102	04.794	152	07.144	202	09.494
003	00.141	053	02.491	103	04.841	153	07.191	203	09.541
004	00.188	054	02.538	104	04.888	154	07.238	204	09.588
005	00.235	055	02.585	105	04.935	155	07.285	205	09.635
006	00.282	056	02.632	106	04.982	156	07.332	206	09.682
007	00.329	057	02.679	107	05.029	157	07.379	207	09.729
008	00.376	058	02.726	108	05.076	158	07.426	208	09.776
009	00.423	059	02.773	109	05.123	159	07.473	209	09.823
010	00.470	060	02.820	110	05.170	160	07.520	210	09.870
011	00.517	061	02.867	111	05.217	161	07.567	211	09.917
012	00.564	062	02.914	112	05.264	162	07.614	212	09.964
013	00.611	063	02.961	113	05.311	163	07.661	213	10.011
014	00.658	064	03.008	114	05.358	164	07.708	214	10.058
015	00.705	065	03.055	115	05.405	165	07.755	215	10.105
016	00.752	066	03.102	116	05.452	166	07.802	216	10.152
017	00.799	067	03.149	117	05.499	167	07.849	217	10.199
018	00.846	068	03.196	118	05.546	168	07.896	218	10.246
019	00.893	069	03.243	119	05.593	169	07.943	219	10.293
020	00.940	070	03.290	120	05.640	170	07.990	220	10.340
021	00.987	071	03.337	121	05.687	171	08.037	221	10.387
022	01.034	072	03.384	122	05.734	172	08.084	222	10.434
023	01.081	073	03.431	123	05.781	173	08.131	223	10.481
024	01.128	074	03.478	124	05.828	174	08.178	224	10.528
025	01.175	075	03.525	125	05.875	175	08.225	225	10.575
026	01.222	076	03.572	126	05.922	176	08.272	226	10.622
027	01.269	077	03.619	127	05.969	177	08.319	227	10.669
028	01.316	078	03.666	128	06.016	178	08.366	228	10.716
029	01.363	079	03.713	129	06.063	179	08.413	229	10.763
030	01.410	080	03.760	130	06.110	180	08.460	230	10.810
031	01.457	081	03.807	131	06.157	181	08.507	231	10.857
032	01.504	082	03.854	132	06.204	182	08.554	232	10.904
033	01.551	083	03.901	133	06.251	183	08.601	233	10.951
034	01.598	084	03.948	134	06.298	184	08.648	234	10.998
035	01.645	085	03.995	135	06.345	185	08.695	235	11.045
036	01.692	086	04.042	136	06.392	186	08.742	236	11.092
037	01.739	087	04.089	137	06.439	187	08.789	237	11.139
038	01.786	088	04.136	138	06.486	188	08.836	238	11.186
039	01.833	089	04.183	139	06.533	189	08.883	239	11.233
040	01.880	090	04.230	140	06.580	190	08.930	240	11.280
041	01.927	091	04.277	141	06.627	191	08.977	241	11.327
042	01.974	092	04.324	142	06.674	192	09.024	242	11.374
043	02.021	093	04.371	143	06.721	193	09.071	243	11.421
044	02.068	094	04.418	144	06.768	194	09.118	244	11.468
045	02.115	095	04.465	145	06.815	195	09.165	245	11.515
046	02.162	096	04.512	146	06.862	196	09.212	246	11.562
047	02.209	097	04.559	147	06.909	197	09.259	247	11.609
048	02.256	098	04.606	148	06.956	198	09.306	248	11.656
049	02.303	099	04.653	149	07.003	199	09.353	249	11.703
250	11.750	251	11.797	252	11.844	253	11.891	254	11.938
255	11.985								

$$PD(n) = (UD(n)*200)/297$$

000	000.00	050	000.36	100	000.72	150	001.08	200	001.44
001	000.00	051	000.36	101	000.72	151	001.08	201	001.44
002	000.02	052	000.38	102	000.74	152	001.08	202	001.44
003	000.02	053	000.38	103	000.74	153	001.10	203	001.46
004	000.02	054	000.38	104	000.74	154	001.10	204	001.46
005	000.04	055	000.40	105	000.76	155	001.12	205	001.46
006	000.04	056	000.40	106	000.76	156	001.12	206	001.48
007	000.06	057	000.40	107	000.76	157	001.12	207	001.48
008	000.06	058	000.42	108	000.78	158	001.14	208	001.50
009	000.06	059	000.42	109	000.78	159	001.14	209	001.50
010	000.08	060	000.44	110	000.78	160	001.14	210	001.50
011	000.08	061	000.44	111	000.80	161	001.16	211	001.52
012	000.08	062	000.44	112	000.80	162	001.16	212	001.52
013	000.10	063	000.46	113	000.82	163	001.16	213	001.52
014	000.10	064	000.46	114	000.82	164	001.18	214	001.54
015	000.10	065	000.46	115	000.82	165	001.18	215	001.54
016	000.12	066	000.48	116	000.84	166	001.18	216	001.54
017	000.12	067	000.48	117	000.84	167	001.20	217	001.56
018	000.12	068	000.48	118	000.84	168	001.20	218	001.56
019	000.14	069	000.50	119	000.86	169	001.22	219	001.56
020	000.14	070	000.50	120	000.86	170	001.22	220	001.58
021	000.16	071	000.50	121	000.86	171	001.22	221	001.58
022	000.16	072	000.52	122	000.88	172	001.24	222	001.60
023	000.16	073	000.52	123	000.88	173	001.24	223	001.60
024	000.18	074	000.54	124	000.88	174	001.24	224	001.60
025	000.18	075	000.54	125	000.90	175	001.26	225	001.62
026	000.18	076	000.54	126	000.90	176	001.26	226	001.62
027	000.20	077	000.56	127	000.92	177	001.26	227	001.62
028	000.20	078	000.56	128	000.92	178	001.28	228	001.64
029	000.20	079	000.56	129	000.92	179	001.28	229	001.64
030	000.22	080	000.58	130	000.94	180	001.30	230	001.64
031	000.22	081	000.58	131	000.94	181	001.30	231	001.66
032	000.22	082	000.58	132	000.94	182	001.30	232	001.66
033	000.24	083	000.60	133	000.96	183	001.32	233	001.68
034	000.24	084	000.60	134	000.96	184	001.32	234	001.68
035	000.26	085	000.60	135	000.96	185	001.32	235	001.68
036	000.26	086	000.62	136	000.98	186	001.34	236	001.70
037	000.26	087	000.62	137	000.98	187	001.34	237	001.70
038	000.28	088	000.64	138	000.98	188	001.34	238	001.70
039	000.28	089	000.64	139	001.00	189	001.36	239	001.72
040	000.28	090	000.64	140	001.00	190	001.36	240	001.72
041	000.30	091	000.66	141	001.02	191	001.36	241	001.72
042	000.30	092	000.66	142	001.02	192	001.38	242	001.74
043	000.30	093	000.66	143	001.02	193	001.38	243	001.74
044	000.32	094	000.68	144	001.04	194	001.40	244	001.74
045	000.32	095	000.68	145	001.04	195	001.40	245	001.76
046	000.32	096	000.68	146	001.04	196	001.40	246	001.76
047	000.34	097	000.70	147	001.06	197	001.42	247	001.78
048	000.34	098	000.70	148	001.06	198	001.42	248	001.78
049	000.36	099	000.70	149	001.06	199	001.42	249	001.78
250	001.80	251	001.80	252	001.80	253	001.82	254	001.82
255	001.82								

$$PD(n) = UD(n) * 5 \quad \text{if } UD(n) \text{ less than } 198$$

$$PD(n) = (UD(n) - 196) / 2 + UD(n) * 5 \quad \text{if } UD(n) \text{ greater than } 197$$

000	000.00	050	002.50	100	005.00	150	007.50	200	010.10
001	000.05	051	002.55	101	005.05	151	007.55	201	010.15
002	000.10	052	002.60	102	005.10	152	007.60	202	010.25
003	000.15	053	002.65	103	005.15	153	007.65	203	010.30
004	000.20	054	002.70	104	005.20	154	007.70	204	010.40
005	000.25	055	002.75	105	005.25	155	007.75	205	010.45
006	000.30	056	002.80	106	005.30	156	007.80	206	010.55
007	000.35	057	002.85	107	005.35	157	007.85	207	010.60
008	000.40	058	002.90	108	005.40	158	007.90	208	010.70
009	000.45	059	002.95	109	005.45	159	007.95	209	010.75
010	000.50	060	003.00	110	005.50	160	008.00	210	010.85
011	000.55	061	003.05	111	005.55	161	008.05	211	010.90
012	000.60	062	003.10	112	005.60	162	008.10	212	011.00
013	000.65	063	003.15	113	005.65	163	008.15	213	011.05
014	000.70	064	003.20	114	005.70	164	008.20	214	011.15
015	000.75	065	003.25	115	005.75	165	008.25	215	011.20
016	000.80	066	003.30	116	005.80	166	008.30	216	011.30
017	000.85	067	003.35	117	005.85	167	008.35	217	011.35
018	000.90	068	003.40	118	005.90	168	008.40	218	011.45
019	000.95	069	003.45	119	005.95	169	008.45	219	011.50
020	001.00	070	003.50	120	006.00	170	008.50	220	011.60
021	001.05	071	003.55	121	006.05	171	008.55	221	011.65
022	001.10	072	003.60	122	006.10	172	008.60	222	011.75
023	001.15	073	003.65	123	006.15	173	008.65	223	011.80
024	001.20	074	003.70	124	006.20	174	008.70	224	011.90
025	001.25	075	003.75	125	006.25	175	008.75	225	011.95
026	001.30	076	003.80	126	006.30	176	008.80	226	012.05
027	001.35	077	003.85	127	006.35	177	008.85	227	012.10
028	001.40	078	003.90	128	006.40	178	008.90	228	012.20
029	001.45	079	003.95	129	006.45	179	008.95	229	012.25
030	001.50	080	004.00	130	006.50	180	009.00	230	012.35
031	001.55	081	004.05	131	006.55	181	009.05	231	012.40
032	001.60	082	004.10	132	006.60	182	009.10	232	012.50
033	001.65	083	004.15	133	006.65	183	009.15	233	012.55
034	001.70	084	004.20	134	006.70	184	009.20	234	012.65
035	001.75	085	004.25	135	006.75	185	009.25	235	012.70
036	001.80	086	004.30	136	006.80	186	009.30	236	012.80
037	001.85	087	004.35	137	006.85	187	009.35	237	012.85
038	001.90	088	004.40	138	006.90	188	009.40	238	012.95
039	001.95	089	004.45	139	006.95	189	009.45	239	013.00
040	002.00	090	004.50	140	007.00	190	009.50	240	013.10
041	002.05	091	004.55	141	007.05	191	009.55	241	013.15
042	002.10	092	004.60	142	007.10	192	009.60	242	013.25
043	002.15	093	004.65	143	007.15	193	009.65	243	013.30
044	002.20	094	004.70	144	007.20	194	009.70	244	013.40
045	002.25	095	004.75	145	007.25	195	009.75	245	013.45
046	002.30	096	004.80	146	007.30	196	009.80	246	013.55
047	002.35	097	004.85	147	007.35	197	009.85	247	013.60
048	002.40	098	004.90	148	007.40	198	009.95	248	013.70
049	002.45	099	004.95	149	007.45	199	010.00	249	013.75
250	013.85	251	013.90	252	014.00	253	014.05	254	014.15
255	014.20								

000	0000.0	050	0055.9	100	0027.5	150	0007.5	200	-010.2
001	0128.1	051	0055.1	101	0027.1	151	0007.1	201	-010.7
002	0126.2	052	0054.3	102	0026.7	152	0006.7	202	-011.2
003	0124.3	053	0053.5	103	0026.3	153	0006.3	203	-011.7
004	0122.4	054	0052.7	104	0025.9	154	0005.9	204	-012.2
005	0120.5	055	0051.9	105	0025.5	155	0005.5	205	-012.7
006	0118.6	056	0051.1	106	0025.1	156	0005.1	206	-013.2
007	0116.7	057	0050.3	107	0024.7	157	0004.7	207	-013.7
008	0114.8	058	0049.5	108	0024.3	158	0004.3	208	-014.2
009	0112.9	059	0048.7	109	0023.9	159	0003.9	209	-014.7
010	0111.0	060	0047.9	110	0023.5	160	0003.6	210	-015.2
011	0109.1	061	0047.1	111	0023.1	161	0003.3	211	-015.7
012	0107.2	062	0046.3	112	0022.7	162	0003.0	212	-016.2
013	0105.3	063	0045.5	113	0022.3	163	0002.7	213	-016.7
014	0103.4	064	0045.0	114	0021.9	164	0002.4	214	-017.2
015	0101.5	065	0044.5	115	0021.5	165	0002.1	215	-017.7
016	0099.6	066	0044.0	116	0021.1	166	0001.8	216	-018.2
017	0097.7	067	0043.5	117	0020.7	167	0001.5	217	-018.7
018	0095.8	068	0043.0	118	0020.3	168	0001.2	218	-019.2
019	0093.9	069	0042.5	119	0019.9	169	0000.9	219	-019.7
020	0092.0	070	0042.0	120	0019.5	170	0000.6	220	-020.2
021	0090.1	071	0041.5	121	0019.1	171	0000.3	221	-020.7
022	0088.2	072	0041.0	122	0018.7	172	0000.0	222	-021.2
023	0086.3	073	0040.5	123	0018.3	173	-000.3	223	-021.7
024	0084.4	074	0040.0	124	0017.9	174	-000.6	224	-022.3
025	0082.5	075	0039.5	125	0017.5	175	-000.9	225	-022.9
026	0080.6	076	0039.0	126	0017.1	176	-001.2	226	-023.5
027	0078.7	077	0038.5	127	0016.7	177	-001.5	227	-024.1
028	0076.8	078	0038.0	128	0016.3	178	-001.8	228	-024.7
029	0074.9	079	0037.5	129	0015.9	179	-002.1	229	-025.3
030	0073.0	080	0037.0	130	0015.5	180	-002.4	230	-025.9
031	0071.1	081	0036.5	131	0015.1	181	-002.7	231	-026.5
032	0070.3	082	0036.0	132	0014.7	182	-003.0	232	-027.1
033	0069.5	083	0035.5	133	0014.3	183	-003.3	233	-027.7
034	0068.7	084	0035.0	134	0013.9	184	-003.6	234	-028.3
035	0067.9	085	0034.5	135	0013.5	185	-003.9	235	-028.9
036	0067.1	086	0034.0	136	0013.1	186	-004.2	236	-029.5
037	0066.3	087	0033.5	137	0012.7	187	-004.5	237	-030.1
038	0065.5	088	0033.0	138	0012.3	188	-004.8	238	-030.7
039	0064.7	089	0032.5	139	0011.9	189	-005.1	239	-031.3
040	0063.9	090	0032.0	140	0011.5	190	-005.4	240	-031.9
041	0063.1	091	0031.5	141	0011.1	191	-005.7	241	-032.5
042	0062.3	092	0031.0	142	0010.7	192	-006.2	242	-033.1
043	0061.5	093	0030.5	143	0010.3	193	-006.7	243	-033.7
044	0060.7	094	0030.0	144	0009.9	194	-007.2	244	-034.3
045	0059.9	095	0029.5	145	0009.5	195	-007.7	245	-034.9
046	0059.1	096	0029.1	146	0009.1	196	-008.2	246	-035.5
047	0058.3	097	0028.7	147	0008.7	197	-008.7	247	-036.1
048	0057.5	098	0028.3	148	0008.3	198	-009.2	248	-036.7
049	0056.7	099	0027.9	149	0007.9	199	-009.7	249	-037.3
250	-037.9	251	-038.5	252	-039.1	253	-039.7	254	-040.3
255	-040.9								

PROCESS BOOM 11 Nov 71

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170 Series programs

000	-00.10	050	008.18	100	030.54	150	045.54	200	054.54
001	-00.10	051	008.64	101	030.84	151	045.84	201	054.69
002	-00.10	052	009.10	102	031.14	152	046.14	202	054.84
003	-00.10	053	009.56	103	031.44	153	046.44	203	054.99
004	-00.10	054	010.02	104	031.74	154	046.74	204	055.14
005	-00.10	055	010.48	105	032.04	155	047.04	205	055.29
006	-00.10	056	010.94	106	032.34	156	047.34	206	055.44
007	-00.10	057	011.40	107	032.64	157	047.64	207	055.59
008	-00.10	058	011.86	108	032.94	158	047.94	208	055.74
009	-00.10	059	012.32	109	033.24	159	048.24	209	055.89
010	-00.10	060	012.78	110	033.54	160	048.54	210	056.04
011	-00.10	061	013.24	111	033.84	161	048.69	211	056.19
012	-00.10	062	013.70	112	034.14	162	048.84	212	056.34
013	-00.10	063	014.16	113	034.44	163	048.99	213	056.49
014	-00.10	064	014.62	114	034.74	164	049.14	214	056.64
015	-00.10	065	015.08	115	035.04	165	049.29	215	056.79
016	-00.10	066	015.54	116	035.34	166	049.44	216	056.94
017	-00.10	067	016.00	117	035.64	167	049.59	217	057.09
018	-00.10	068	016.46	118	035.94	168	049.74	218	057.24
019	-00.10	069	016.92	119	036.24	169	049.89	219	057.39
020	-00.10	070	017.38	120	036.54	170	050.04	220	057.54
021	-00.10	071	017.84	121	036.84	171	050.19	221	057.69
022	-00.10	072	018.30	122	037.14	172	050.34	222	057.84
023	-00.10	073	018.76	123	037.44	173	050.49	223	057.99
024	-00.10	074	019.22	124	037.74	174	050.64	224	058.14
025	-00.10	075	019.68	125	038.04	175	050.79	225	058.26
026	-00.10	076	020.14	126	038.34	176	050.94	226	058.38
027	-00.10	077	020.60	127	038.64	177	051.09	227	058.50
028	-00.10	078	021.06	128	038.94	178	051.24	228	058.62
029	-00.10	079	021.52	129	039.24	179	051.39	229	058.74
030	-00.10	080	021.98	130	039.54	180	051.54	230	058.86
031	-00.10	081	022.44	131	039.84	181	051.69	231	058.98
032	-00.10	082	022.90	132	040.14	182	051.84	232	059.10
033	000.36	083	023.36	133	040.44	183	051.99	233	059.22
034	000.82	084	023.82	134	040.74	184	052.14	234	059.34
035	001.28	085	024.28	135	041.04	185	052.29	235	059.46
036	001.74	086	024.74	136	041.34	186	052.44	236	059.58
037	002.20	087	025.20	137	041.64	187	052.59	237	059.70
038	002.66	088	025.66	138	041.94	188	052.74	238	059.82
039	003.12	089	026.12	139	042.24	189	052.89	239	059.94
040	003.58	090	026.58	140	042.54	190	053.04	240	060.06
041	004.04	091	027.04	141	042.84	191	053.19	241	060.18
042	004.50	092	027.50	142	043.14	192	053.34	242	060.30
043	004.96	093	027.96	143	043.44	193	053.49	243	060.42
044	005.42	094	028.42	144	043.74	194	053.64	244	060.54
045	005.88	095	028.88	145	044.04	195	053.79	245	060.66
046	006.34	096	029.34	146	044.34	196	053.94	246	060.78
047	006.80	097	029.80	147	044.64	197	054.09	247	060.90
048	007.26	098	029.94	148	044.94	198	054.24	248	061.02
049	007.72	099	030.24	149	045.24	199	054.39	249	061.14
250	061.26	251	061.38	252	061.50	253	061.62	254	061.74
255	061.86								

WORD NUMBER	BIT	LABEL	DESCRIPTION	DECOM
0-0	-	SFS1	sub frame sync 1	1
0-1	-	SFS2	sub frame sync 2	2
0-2	-	FSS1	frame sync 1	3
0-3	-	FSS2	frame sync 2	4
0-4	-	+CM2	+ cell 2	5
0-5	-	-C10	- cell 10	6
0-6	(1)	EXP1	experiment 1	7
0-7	(1)	EXP2	experiment 2	8
0-8	-	+VSR	+volt sensor	9
0-9	-	-VSR	-volt sensor	10
0-10	-	RWTO	reaction wheel tachometer	11
0-11	-	MAGX	x axis magnetometer	12
0-12	-	MAGY	y axis magnetometer	13
0-13	-	MAGZ	z axis magnetometer	14
0-14	-	AB1A	* adcole bits 1a-7a	15
0-15	-	AB1B	* adcole bits 1b-7b	16
1-0	-	SFS3	sub frame sync 3	17
1-1	-	SFS4	sub frame sync 4	18
1-2	-	AD11	address indicator 1	19
1-2	1	AND1	40d 1a	
1-2	2	AND2	40d 2a	
1-2	3	AND3	40d 3a	
1-2	4	AND4	40d 4a	
1-2	5	AND5	40d 1b	
1-2	6	AND6	40d 2b	
1-2	7	AND7	40d 3b	
1-2	8	AND8	40d 4b	
1-3	-	VTIM	PCM vernier time	20
1-4	-	+CM3	+ cell 3	21
1-5	-	-C11	- cell 11	22
1-6	(1)	EXP3	experiment 3	23
1-7	(1)	EXP4	experiment 4	24
1-8	-	5VCL	5 volt calibrate	25
1-9	-	RLAG	agc receiver 1	26
1-10	-	R2AG	agc receiver 2	27
1-11	-	BLEN	boom length	28
1-12	-	+CM1	+ cell 1	29
1-13	-	-C18	- cell 18	30
1-14	-	RWS1	reaction wheel speed	31
1-15	-	RWS2	reaction wheel speed	32
1-14/15	-	SPRO	reaction wheel speed	
1-15	15	SPCT	reaction wheel speed control	
2-0	-	SFS5	sub frame sync 5	33
2-1	-	SFS6	sub frame sync 6	34
2-2	1	CMDE	command enable	35
2-2	2	CEBU	command enable backup	
2-2	3	DLEN	data link enable	
2-2	4	TRST	timer reset	
2-2	5	DLSS	data link system	
2-2	6	DLSB	data link system backup	
2-2	7	EXEC	execute	
2-2	8	EXBU	execute backup	

170 STANDARD LABELS 25 OCT 71

WORD NUMBER	BIT	LABEL	DESCRIPTION	DECOM
2-3	-	MEMD	memory control	36
2-3	1,2,3	MSUB	memory subframe	
2-3	4	MCLK	memory clock frequency	
2-3	5,6	MRTB	memory rate	
2-3	7	ANDI	a-d indicator	
2-3	8	OSCL	oscillator	
2-4	-	+CM4	+ cell 4	37
2-5	-	-C12	- cell 12	38
2-6	(1)	EXP5	experiment 5	39
2-7	(1)	EXP6	experiment 6	40
2-8	-	T19S	t19 scp temperature	41
2-9	-	T24B	t24 battery bypass temperature	42
2-10	-	PTC1	control 1 pressure transducer	43
2-11	-	PTC2	control 2 pressure transducer	44
2-12	-	DLT1	dl timer cmd1	45
2-13	-	DLT2	dl timer cmd2	46
2-14	-	BCON	boom control	47
2-14	1	BCOF	boom on-off	
2-14	2	BCIO	boom in-out	
2-14	3	BFRI	boom full retract indicator	
2-14	4	BMIN	boom mid indicator	
2-14	5	BFEI	boom full extension indicator	
2-14	6	BTMR	boom tip mass release indicator	
2-14	7	DLRI	dl boom release indicator	
2-14	8			
2-15	-	RWCT	reaction wheel control	48
2-15	1	SPED	speed on-off reaction wheel	
2-15	2	STAT	reaction wheel on-off	
2-15	3	FORS	forward-reverse reaction wheel	
2-15	4	PRSC	primary-secondary power amplifier	
2-15	5	CONT	control primary-secondary	
2-15	6	DIRT	forward-reverse indicator	
2-15	7			
2-15	8			
3-0	-	SFS7	subframe sync 7	49
3-1	-	SFS8	subframe sync 8	50
3-2	-	PCMS	pcm status	51
3-2	1	TMCH	PCM timing chain	
3-2	2	MODC	multiplexer	
3-2	3	PCMM	memory on-off	
3-2	4	PCMR	pcm power register	
3-2	5			
3-2	6	PCMD	pcm data link on-off	
3-2	7	TSM	time of first memory sample	
3-2	8			
3-4	-	+CM5	cell 5	53
3-5	-	-C13	- cell 13	54
3-6	(1)	EXP7	experiment 7	55
3-7	(1)	EXP8	experiment 8	56

WORD NUMBER	BIT	LABEL	DESCRIPTION	DECOM
3-8	-	+ SVM	+ sec volt monitor	57
3-9	-	-SVM	- sec volt monitor	58
3-10	-	T2PK	t2 peak temperature	59
3-11	-	T15S	t15 scpl temperature	60
3-12	-	T3+B	t3 battery temperature +sec	61
3-13	-	T4-B	t4 battery temperature -sec	62
3-14	-	THCO	thrusters control	63
3-14	1	THR1	thruster 1 on-off	
3-14	2	THR2	thruster 2 on-off	
3-14	3	TH1H	Thruster 1 heater on-off	
3-14	4	TH2H	thruster 2 heater on-off	
3-14	5	THHL	thruster hi-lo	
3-14	6			
3-14	7			
3-14	8			
3-15	-	SPA2	spare 2	64
4-0	-	SFS9	sub frame sync 9	65
4-1	-	SF10	sub frame sync 10	66
4-2	-	BACT	battery control	67
4-2	1	CCOF	charge control on-off	
4-2	2	CCHL	charge control hi-low	
4-2	3	BBOF	battery bypass on-off	
4-2	4	BBEN	battery bypass enable on-off	
4-2	5	P+BS	primary-secondary plus battery select	
4-2	6	P-BS	primary-secondary minus battery select	
4-2	7	UNVC	undervoltage on-off	
4-2	8			
4-3				68
4-4	-	+ CM6	+ cell 6	69
4-5	-	-C14	- cell 14	70
4-6	(1)	EXP9	experiment 9	71
4-7	(1)	EX10	experiment 10	72
4-8	-	+VSR	+ volt sensor	73
4-9	-	-VSR	- volt sensor	74
4-10	-	+BTM	+ battery temperature	75
4-11	-	-BTM	- battery temperature	76
4-12	-	+ CIM	+ charge current monitor	77
4-13	-	+ DIM	+ discharge current monitor	78
4-14	-	-CIM	- charge current monitor	79
4-15	-	-DIM	- discharge current monitor	80
5-0	-	SF11	sub frame sync 11	81
5-1	-	SF12	sub frame sync 12	82
5-2				83
5-3				84
5-4	-	+CM7	+ cell 7	85
5-5	-	-C15	- cell 15	86
5-6	(1)	EX11	experiment 11	87
5-7	(1)	EX12	experiment 12	88
5-8	-	+ BAT	+ battery temperature	89
5-9	-	-BAT	- battery temperature	90
5-10	-	T10H	T10 hcl temperature	91
5-11	-	T16S	t16 scp 2 temperature	92
5-12	-	T20S	t20 scp tube temperature	93

WORD NUMBER	BIT	LABEL	DESCRIPTION	DECOM
5-13	-	T21B	t21 battery 3 temperature	94
5-14	-	T22C	t22 ch con temperature	95
5-15	-	T23V	t23v con temperature	96
6-0	-	SF13	sub frame sync 13	97
6-1	-	SF14	sub frame sync 14	98
6-2	(2)	E171	experiment 17-1	99
6-3	(2)	E172	experiment 17-2	100
6-4	-	+CM8	+ cell 8	101
6-5	-	-C16	- cell 16	102
6-6	(1)	EX13	experiment 13	103
6-7	(1)	EX14	experiment 14	104
6-8	-	T8S1	t8 skin 1 temperature	105
6-9	-	T9S2	t9 skin 2 temperature	106
6-10	-	T17I	t17 inner sc2 temperature	107
6-11	-	T12B	t12 bb temperature	108
6-12	-	T13I	t13 inner sc1 temperature	109
6-13	-	T14O	t14 out sc temperature	110
6-14	-	+SCM	+ sci monitor	111
6-15	-	-SCM	- sci monitor	112
7-0	-	SF15	sub frame sync 15	113
7-1	-	SF16	sub frame sync 16	114
7-2	(2)	E173	experiment 17-3	115
7-3	(2)	E174	experiment 17-4	116
7-4	-	+CM9	+ cell 9	117
7-5	-	-C17	- cell 17	118
7-6	(1)	EX15	experiment 15	119
7-7	(1)	EX16	experiment 16	120
7-8	-	T5TK	t5 tank temperature	121
7-9	-	N1TP	nozzle 1 temperature	122
7-10	-	RWTP	reaction wheel temperature	123
7-11	-	T18B	t18 bb sc2 temperature	124
7-12	-	BTEM	boom temperature	125
7-13	-	T1PP	t1 pcm pk temperature	126
7-14	-	PTT1	tank 1 pressure transducer	127
7-15	-	PTT2	tank 2 pressure transducer	128
3-3	-	PLST	payload status	52
3-3	1	OREN	ordance enable on-off	
3-3	2	AOEN	altitude ordance enable on-off	
3-3	3	HKSR	housekeeping sensors on-off	
3-3	4	ATMS	analog tm on-Off	
3-3	5	TIMR	timer 20-50 min	
3-3	6,7,8	BIRD	spacecraft id	

170 STANDARD LABELS 25 OCT 71(1) Experiments 1 thru 16:

<u>Bit</u>	<u>Label</u>	<u>DESCRIPTION</u>
1	CPTA	option a on-off
2	OPTB	option b on-off
3	PAR	PAR on-off
4	EXPN	expon on-off
5	CPX1	option x1 on-off
6	OPX2	option x2 on-off
7		
8		

(2) Experiment 17:

<u>WORD NUMBER</u>	<u>BIT</u>	<u>LABEL</u>	<u>DESCRIPTION</u>	<u>DECOM</u>
6-2	1	E7-1	ex17-1	99
6-2	2	E7-2	ex17-2	
6-2	3	E7-3	ex17-3	
6-2	4	E7-4	ex17-4	
6-2	5	E7-5	ex17-5	
6-2	6	E7-6	ex17-6	
6-2	7	E7-7	ex17-7	
6-2	8	E7-8	ex17-8	
6-3	1	E7-9	ex17-9	100
6-3	2	E710	ex17-10	
6-3	3	E711	ex17-11	
6-3	4	E712	ex17-12	
6-3	5	E713	ex17-13	
6-3	6	E714	ex17-14	
6-3	7	E715	ex17-15	
6-3	8	E716	ex17-16	
7-2	1	E717	ex17-17	115
7-2	2	E718	ex17-18	
7-2	3	E719	ex17-19	
7-2	4	E720	ex17-20	
7-2	5	E7G4	ex17 group 4	
7-2	6	E7G3	ex17 group 3	
7-2	7	E7G2	ex17 group 2	
7-2	8	E7G1	ex17 group 1	

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(2) Experiment 17 (cont.)

WORD NUMBER	BIT	LABEL	DESCRIPTION	DECOM
7-3	-	SLM	thdt	116
	1	SLM1	slm1 on-off	
	2	SLM3	slm3 on-off	
	3	SLM2	slm2 on-off	
	4	AJX2	adj x2 on-off	
	5	AJX3	adj x3 on-off	
	6	ADJ	adj on-off	
	7	AJL3	adj l3 on-off	
	8	AJL2	adj l2 on-off	

III.3. F170 C

III.4. F170 MS

RATE = 01		FREQ = 1600		RESET TIME 000 00 00 00																
VER	NIER	COUNT	ER																	
000	000	00	00	00	00	064	000	00	02	43.84	128	000	00	05	27.68	192	000	00	08	11.52
001	000	00	00	02	05.56	065	000	00	02	46.40	129	000	00	05	30.24	193	000	00	08	14.08
002	000	00	00	05	12.12	066	000	00	02	48.96	130	000	00	05	32.80	194	000	00	08	16.64
003	000	00	00	07	18.68	067	000	00	02	51.52	131	000	00	05	35.36	195	000	00	08	19.20
004	000	00	00	10	25.24	068	000	00	02	54.08	132	000	00	05	37.92	196	000	00	08	21.76
005	000	00	00	12	31.80	069	000	00	02	56.64	133	000	00	05	40.48	197	000	00	08	24.32
006	000	00	00	15	38.36	070	000	00	02	59.20	134	000	00	05	43.04	198	000	00	08	26.88
007	000	00	00	17	44.92	071	000	00	03	01.76	135	000	00	05	45.60	199	000	00	08	29.44
008	000	00	00	20	51.48	072	000	00	03	04.32	136	000	00	05	48.16	200	000	00	08	32.00
009	000	00	00	23	58.04	073	000	00	03	06.88	137	000	00	05	50.72	201	000	00	08	34.56
010	000	00	00	25	64.60	074	000	00	03	09.44	138	000	00	05	53.28	202	000	00	08	37.12
011	000	00	00	28	71.16	075	000	00	03	12.00	139	000	00	05	55.84	203	000	00	08	39.68
012	000	00	00	30	77.72	076	000	00	03	14.56	140	000	00	05	58.40	204	000	00	08	42.24
013	000	00	00	33	84.28	077	000	00	03	17.12	141	000	00	06	00.96	205	000	00	08	44.80
014	000	00	00	35	90.84	078	000	00	03	19.68	142	000	00	06	03.52	206	000	00	08	47.36
015	000	00	00	38	97.40	079	000	00	03	22.24	143	000	00	06	06.08	207	000	00	08	49.92
016	000	00	00	40	103.96	080	000	00	03	24.80	144	000	00	06	08.64	208	000	00	08	52.48
017	000	00	00	43	110.52	081	000	00	03	27.36	145	000	00	06	11.20	209	000	00	08	55.04
018	000	00	00	46	117.08	082	000	00	03	29.92	146	000	00	06	13.76	210	000	00	08	57.60
019	000	00	00	48	123.64	083	000	00	03	32.48	147	000	00	06	16.32	211	000	00	09	00.16
020	000	00	00	51	130.20	084	000	00	03	35.04	148	000	00	06	18.88	212	000	00	09	02.72
021	000	00	00	53	136.76	085	000	00	03	37.60	149	000	00	06	21.44	213	000	00	09	05.28
022	000	00	00	56	143.32	086	000	00	03	40.16	150	000	00	06	24.00	214	000	00	09	07.84
023	000	00	00	58	149.88	087	000	00	03	42.72	151	000	00	06	26.56	215	000	00	09	10.40
024	000	00	00	01	156.44	088	000	00	03	45.28	152	000	00	06	29.12	216	000	00	09	12.96
025	000	00	00	04	163.00	089	000	00	03	47.84	153	000	00	06	31.68	217	000	00	09	15.52
026	000	00	00	06	169.56	090	000	00	03	50.40	154	000	00	06	34.24	218	000	00	09	18.08
027	000	00	00	09	176.12	091	000	00	03	52.96	155	000	00	06	36.80	219	000	00	09	20.64
028	000	00	00	11	182.68	092	000	00	03	55.52	156	000	00	06	39.36	220	000	00	09	23.20
029	000	00	00	14	189.24	093	000	00	03	58.08	157	000	00	06	41.92	221	000	00	09	25.76
030	000	00	00	16	195.80	094	000	00	04	00.64	158	000	00	06	44.48	222	000	00	09	28.32
031	000	00	00	19	202.36	095	000	00	04	03.20	159	000	00	06	47.04	223	000	00	09	30.88
032	000	00	00	21	208.92	096	000	00	04	05.76	160	000	00	06	49.60	224	000	00	09	33.44
033	000	00	00	24	215.48	097	000	00	04	08.32	161	000	00	06	52.16	225	000	00	09	36.00
034	000	00	00	27	222.04	098	000	00	04	10.88	162	000	00	06	54.72	226	000	00	09	38.56
035	000	00	00	29	228.60	099	000	00	04	13.44	163	000	00	06	57.28	227	000	00	09	41.12
036	000	00	00	32	235.16	100	000	00	04	16.00	164	000	00	06	59.84	228	000	00	09	43.68
037	000	00	00	34	241.72	101	000	00	04	18.56	165	000	00	07	02.40	229	000	00	09	46.24
038	000	00	00	37	248.28	102	000	00	04	21.12	166	000	00	07	04.96	230	000	00	09	48.80
039	000	00	00	39	254.84	103	000	00	04	23.68	167	000	00	07	07.52	231	000	00	09	51.36
040	000	00	00	42	261.40	104	000	00	04	26.24	168	000	00	07	10.08	232	000	00	09	53.92
041	000	00	00	44	267.96	105	000	00	04	28.80	169	000	00	07	12.64	233	000	00	09	56.48
042	000	00	00	47	274.52	106	000	00	04	31.36	170	000	00	07	15.20	234	000	00	09	59.04
043	000	00	00	50	281.08	107	000	00	04	33.92	171	000	00	07	17.76	235	000	00	10	01.60
044	000	00	00	52	287.64	108	000	00	04	36.48	172	000	00	07	20.32	236	000	00	10	04.16
045	000	00	00	55	294.20	109	000	00	04	39.04	173	000	00	07	22.88	237	000	00	10	06.72
046	000	00	00	57	300.76	110	000	00	04	41.60	174	000	00	07	25.44	238	000	00	10	09.28
047	000	00	00	00	307.32	111	000	00	04	44.16	175	000	00	07	28.00	239	000	00	10	11.84
048	000	00	00	02	313.88	112	000	00	04	46.72	176	000	00	07	30.56	240	000	00	10	14.40
049	000	00	00	05	320.44	113	000	00	04	49.28	177	000	00	07	33.12	241	000	00	10	16.96
050	000	00	00	08	327.00	114	000	00	04	51.84	178	000	00	07	35.68	242	000	00	10	19.52
051	000	00	00	10	333.56	115	000	00	04	54.40	179	000	00	07	38.24	243	000	00	10	22.08
052	000	00	00	13	340.12	116	000	00	04	56.96	180	000	00	07	40.80	244	000	00	10	24.64
053	000	00	00	15	346.68	117	000	00	04	59.52	181	000	00	07	43.36	245	000	00	10	27.20
054	000	00	00	18	353.24	118	000	00	05	02.08	182	000	00	07	45.92	246	000	00	10	29.76
055	000	00	00	20	359.80	119	000	00	05	04.64	183	000	00	07	48.48	247	000	00	10	32.32
056	000	00	00	23	366.36	120	000	00	05	07.20	184	000	00	07	51.04	248	000	00	10	34.88
057	000	00	00	25	372.92	121	000	00	05	09.76	185	000	00	07	53.60	249	000	00	10	37.44
058	000	00	00	28	379.48	122	000	00	05	12.32	186	000	00	07	56.16	250	000	00	10	40.00
059	000	00	00	31	386.04	123	000	00	05	14.88	187	000	00	07	58.72	251	000	00	10	42.56
060	000	00	00	33	392.60	124	000	00	05	17.44	188	000	00	08	01.28	252	000	00	10	45.12
061	000	00	00	36	399.16	125	000	00	05	20.00	189	000	00	08	03.84	253	000	00	10	47.68
062	000	00	00	38	405.72	126	000	00	05	22.56	190	000	00	08	06.40	254	000	00	10	50.24
063	000	00	00	41	412.28	127	000	00	05	25.12	191	000	00	08	08.96	255	000	00	10	52.80

RATE = 01		FREQ = 1600		RESET TIME 000 00 00 00			
HI	ORDER	COUNTER					
000	000	00	00	00	00	00	00
001	001	22	36	12	16	064	124
002	003	21	12	24	32	065	126
003	005	19	48	36	48	066	128
004	007	18	24	48	64	067	130
005	009	17	01	00	80	068	132
006	011	15	37	12	96	069	133
007	013	14	13	25	12	070	135
008	015	12	49	37	28	071	137
009	017	11	25	49	44	072	139
010	019	10	02	01	60	073	141
011	021	08	38	13	76	074	143
012	023	07	14	25	92	075	145
013	025	05	50	38	08	076	147
014	027	04	26	50	24	077	149
015	029	03	03	02	40	078	151
016	031	01	39	14	56	079	153
017	033	00	15	26	72	080	155
018	034	22	51	38	88	081	157
019	036	21	27	51	04	082	159
020	038	20	04	03	20	083	161
021	040	18	40	15	36	084	163
022	042	17	16	27	52	085	165
023	044	15	52	39	68	086	166
024	046	14	28	51	84	087	168
025	048	13	05	04	00	088	170
026	050	11	41	16	16	089	172
027	052	10	17	28	32	090	174
028	054	08	53	40	48	091	176
029	056	07	29	52	64	092	178
030	058	06	06	04	80	093	180
031	060	04	42	16	96	094	182
032	062	03	18	29	12	095	184
033	064	01	54	41	28	096	186
034	066	00	30	53	44	097	188
035	067	23	07	05	60	098	190
036	069	21	43	17	76	099	192
037	071	20	19	29	92	100	194
038	073	18	55	42	08	101	196
039	075	17	31	54	24	102	198
040	077	16	03	06	40	103	200
041	079	14	44	18	56	104	201
042	081	13	20	30	72	105	203
043	083	11	56	42	88	106	205
044	085	10	32	55	04	107	207
045	087	09	09	07	20	108	209
046	089	07	45	19	36	109	211
047	091	06	21	31	52	110	213
048	093	04	57	43	68	111	215
049	095	03	33	55	84	112	217
050	097	02	10	08	00	113	219
051	099	00	46	20	16	114	221
052	100	23	22	32	32	115	223
053	102	21	58	44	48	116	225
054	104	20	34	44	64	117	227
055	106	19	11	08	80	118	229
056	108	17	47	20	96	119	231
057	110	16	23	33	12	120	233
058	112	14	59	45	28	121	234
059	114	13	35	57	44	122	236
060	116	12	12	09	60	123	238
061	118	10	48	21	76	124	240
062	120	09	24	33	92	125	242
063	122	08	00	46	08	126	244
064	124	06	36	58	24	127	246
065	126	05	13	10	40	128	248
066	128	03	49	22	56	129	250
067	130	02	25	34	72	130	252
068	132	01	01	46	88	131	254
069	133	23	37	59	04	132	256
070	135	22	14	11	20	133	258
071	137	20	50	23	36	134	260
072	139	19	26	35	52	135	262
073	141	18	02	47	68	136	264
074	143	16	38	59	84	137	266
075	145	15	15	12	00	138	267
076	147	13	51	24	16	139	269
077	149	12	27	36	32	140	271
078	151	11	03	48	48	141	273
079	153	09	40	00	64	142	275
080	155	08	16	12	80	143	277
081	157	06	52	24	96	144	279
082	159	05	28	37	12	145	281
083	161	04	04	49	28	146	283
084	163	02	41	01	44	147	285
085	165	01	17	13	60	148	287
086	166	23	53	25	76	149	289
087	168	22	29	37	92	150	291
088	170	21	05	50	08	151	293
089	172	19	42	02	24	152	295
090	174	18	18	14	40	153	297
091	176	16	54	26	56	154	299
092	178	15	30	38	72	155	300
093	180	14	06	50	88	156	302
094	182	12	43	03	04	157	304
095	184	11	19	15	20	158	306
096	186	09	55	27	36	159	308
097	188	08	31	39	52	160	310
098	190	07	07	51	68	161	312
099	192	05	44	03	84	162	314
100	194	04	20	16	00	163	316
101	196	02	56	28	16	164	318
102	198	01	32	40	32	165	320
103	200	00	08	52	48	166	322
104	201	22	45	04	64	167	324
105	203	21	21	16	80	168	326
106	205	19	57	28	96	169	328
107	207	18	33	41	12	170	330
108	209	17	09	53	28	171	332
109	211	15	46	05	44	172	333
110	213	14	22	17	60	173	335
111	215	12	58	29	76	174	337
112	217	11	34	41	92	175	339
113	219	10	10	54	08	176	341
114	221	08	47	06	24	177	343
115	223	07	23	18	40	178	345
116	225	05	59	30	56	179	347
117	227	04	35	42	72	180	349
118	229	03	11	54	88	181	351
119	231	01	48	07	04	182	353
120	233	00	24	19	20	183	355
121	234	23	00	31	36	184	357
122	236	21	36	43	52	185	359
123	238	20	12	55	68	186	361
124	240	18	49	07	84	187	363
125	242	17	25	20	00	188	365
126	244	16	01	32	16	189	367
127	246	14	37	44	32	190	368
128	248	13	58	56	48	191	370
129	250	11	10	10	64	192	372
130	252	10	09	22	80	193	374
131	254	09	07	34	96	194	376
132	256	08	38	46	12	195	378
133	258	07	59	57	28	196	380
134	260	06	51	09	44	197	382
135	262	05	27	21	60	198	384
136	264	04	03	33	76	199	386
137	266	03	39	45	92	200	388
138	267	23	15	58	08	201	390
139	269	21	52	10	24	202	392
140	271	20	28	22	40	203	394
141	273	19	04	34	56	204	396
142	275	17	40	46	72	205	398
143	277	16	16	58	88	206	400
144	279	14	53	11	04	207	402
145	281	13	29	23	20	208	404
146	283	12	05	35	36	209	406
147	285	10	41	47	52	210	408
148	287	09	17	59	68	211	410
149	289	07	54	11	84	212	412
150	291	06	30	24	00	213	414
151	293	05	06	36	16	214	416
152	295	03	42	48	32	215	418
153	297	02	19	00	48	216	420
154	299	00	55	12	64	217	422
155	300	23	31	24	80	218	424
156	302	22	07	36	96	219	426
157	304	20	43	49	12	220	428
158	306	19	20	61	28	221	430
159	308	17	56	13	44	222	432
160	310	16	32	25	60	223	434
161	312	15	08	37	76	224	436
162	314	13	44	49	92	225	438
163	316	12	21	02	08	226	440
164	318	10	57	14	24	227	442
165	320	09	33	26	40	228	444
166	322	08	09	38	56	229	446
167	324	06	45	50	72	230	448
168	326	05	22	02	88	231	450
169	328	03	58	15	04	232	452
170	330	02	34	27	20	233	454
171	332	01	10	39	36	234	456
172	333	23	46	51	52	235	458
173	335	22	23	03	68	236	460
174	337	20	59	15	84	237	462
175	339	19	35	28	00	238	464
176	341	18	11	40	16	239	466
177	343	16	47	52	32	240	468
178	345	15	24	04	48	241	470
179	347	14	00	16	64	242	472
180	349	12	36	28	80	243	474
181	351	11	12	40	96	244	476
182	353	09	48	53	12	245	478
183	355	08	25	05	28	246	480
184	357	07	01	17	44	247	482
185	359	05	37	29	60	248	484
186	361	04	13				

III.5. F170 CS

F170CS

COMMAND SYSTEM

PREPARED AT NRL BY MCGINTY

2 NOV 71

INA=0, INPUT GROUP SYNC, OUTPUT MT1
 INA=1, INPUT GROUP SYNC, OUTPUT MT2
 INA=2, INPUT MT1
 INA=3, INPUT MT2
 INA=4, INPUT GROUP SYNC; PCM OUTPUT TO MAG TAPE UNIT 1,
 MRO OUTPUT TO MAG TAPE UNIT 2.

SPECIAL DECOM TO LPR/CRT
 WILL PRINT/DISPLAY : DECOM NUMBER, RAW DATA, PROCESSED DATA

"TNUM" = NUMBER OF DECOMS

"TCOM" = TABLE OF DECOMS

PRINTER

DIGIT=0, NORMAL PRINT

DIGIT=3, SPECIAL DECOM PRINT

CRT

PAGE=0, NORMAL DISPLAY

PAGE=8, SPECIAL DECOM DISPLAY

DECOM (16,64)

WORD NUMBER 1-9 1 RIAG RECEIVER 1 AGC

DECOM 201,8,CRT/DPR/LPR,RAW,0

WORD NUMBER 1-10 2 R2AG RECEIVER 2 AGC

DECOM 209,8,CRT/DPR/LPR,RAW,0

WORD NUMBER 1-2 3 AD(XX) ADDRESS INDICATOR A AND B

DECOM 145,8,CRT/DPR/LPR,RAW,0

WORD NUMBER 2-2 4 PCM CONTROL

CMDE - COMMAND ENABLE. CMBU - COMMAND ENABLE BACKUP.

DLEN - DL ENABLE. TMRS - TIMER RESET. DLSY - DL SYSTEM.

DLBU - DL SYSTEM BACKUP. EXEQ - EXECUTE. EXBU - EXECUTE BACKUP.

DECOM 273,8,CRT/DPR/LPR,RAW,0

WORD NUMBER 3-2 5 PCM CONTROL

TIMC - TIMING CHAIN. REGR - REGISTER. MODC - MODULATION CONTROL.

PCMR - PCM REG. PCMM - PCM MEM. PCDL - PCM DL. TSFM - TSFM.

DECOM 401,8,CRT/DPR/LPR,RAW,0

WORD NUMBER 4-2 6 BATTERY CONTROL

CHCT - CHARGE CONTROL. CHIL - CONROL HI/LO. BABY - BATTERY PYPASS.

BBEN - BATTERY BYPASS ENABLE. +BSL - + BATTERY SELECT.

-BSL - - BATTERY SELECT. UNVS - UNDER VOLTAGE ON/OFF.

DECOM 529,8,CRT/DPR/LPR,RAW,0

WORD NUMBER 2-3 7 A-D A-D

DECOM 287,1,CRT/DPR/LPR,RAW,0

WORD NUMBER 2-3 8 OSC OSC

DECOM 288,1,CRT/DPR/LPR,RAW,0

WORD NUMBER 1-3 1 9 VTIM PCM VERNIER TIME DECIMAL

DECOM 153,8,CRT/LPR/DPR,RAW,0

WORD NUMBER 10 HKSR HOUSKEEPING SENSOR (0=OFF, 1=ON)

DECOM 411,1,CRT/LPR/DPR,RAW,0

WORD NUMBER 3-3 5 11 OREN ORDANCE ENABLE (0=OFF, 1=ON)

DECOM 277,1,CRT/LPR/DPR,RAW,0

WORD NUMBER 2-2 6 12 DLSS DL SYSTEM (0=OFF, 1=ON)

F170CS

COMMAND SYSTEM

* F170CS COMMAND SYSTEM

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*   DECOM          409,1,CRT/LPR/DPR,RAW,0
*   WORD NUMBER   2-7          13      MEMORY ADDRESS COUNTER
*   DECOM          313,8,CRT/LPR/DPR,RAW,0
*   WORD NUMBER   0-7          14      MEMORY ADDRESS COUNTER
*   DECOM          57,8,CRT/LPR/DPR,RAW,0
*   WORD NUMBER   7-7          15      MEMORY ADDRESS COUNTER
*   DECOM          953,8,CRT/LPR/DPR,RAW,0
*   WORD NUMBER   5-7          16      MEMORY ADDRESS COUNTER
*   DECOM          697,8,CRT/LPR/DPR,RAW,0
*   WORD NUMBER   3-3          17      BIRD      SPACECRAFT IDNADD 171)
*   DECOM          415,2,CRT/LPR/DPR,RAW,0
      SIZE TCOM(64)
*   TEXT          S1(2,6)SAMPLE"REV"
      TEXT          DIG(2,4)0"1"
*   STANDARD DATA HEADER
      TEXT          HT(7,4)VTIM"BIRD"PCM"MRO"HKSR"OREN"DLSS"
      TEXT          ON(2,3)OFF"ON"
*   CRT BUFFER
      SIZE          M(40)
      TEXT          OFF(2,4)ON"OFF"
      TEXT          A(2,4)B"A"
      TEXT          MEM(2,4)PCM"MRO"
      TEXT          AGC(2,4)R1AG"R2AG"
      TEXT          AD(8,4)AND1"AND2"AND3"AND4"AND5"AND6"AND7"AND8"
      TEXT          COM(8,4)CMDE"CEBU"DLEN"TRST"DLSS"DLSB"EXEC"EXBU"
      TEXT          PCMS(8,4)TMCH"MODC"PCMM"PCMR"      "PCMD"TSFM"
      TEXT          BA(8,4)CCOF"CCHL"BBOF"BBEN"P+BS"P-BS"UNVO"
      TEXT          E2(2,4)F170CS"REV"
*   TEXT          PS(2,4)SECD"PRIM"
      TEXT          HI(2,4)LOW"HI"
      PROCESS VOLT
      PD(N)=UD(N)*200
      ENDP
      PROCESS RAW
      PD(N)=UD(N)
      ENDP
*   START OF PROGRAM
      START
*   RESET SAMPLE COUNTER
      SA=1
*   DETERMINE MAG TAPE UNIT AND CONFIG
      IF (INA.EQ.1.OR.INA.EQ.3)GOTO DOG1
      CONFIG          MT,1,BIN,HI,AS3,FR,1
      GOTO DOG3
DOG1 CONFIG          MT,2,BIN,HI,AS3,FR,1
DOG3 IF (INA.EQ.2.OR.INA.EQ.3)GOTO IN9
*   GROUP SYNC INPUT
      CONFIG          GRP,1,0,0,16,8,'165620,16,8,'012157
      INPUT=1
SID21 IF (INPUT.NE.1) GOTO IN9
      INPUT (GRP)TERM
*   OUTPUT TO MAG TAPE
      IF (INA.EQ.4)GOTO SY1
*   INA NOT EQUAL 4
      GOTO SY4

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C05027392
 ANDI PRI 05CL PRI THCH A RGST B MODC ON PCMR A PCMM P+M PCMD OFF TSFM ON MSDS ON CHCT ON
 CCHL HI BATB OFF BTBE OFF +BAT PRI -BAT SEC UVOL ON ATCS OFF
 296 18 07 03
 BIRD 172 VTIM 123 TYPE P+M OREN OFF HKSR OFF DLSS ON
 ADN1 RESET ADN2 ADDR3 ADDR4 ADDR5 ADDR6 ADDR7 ADDR8 ADDR9 RESET AGC1 135 AGC2266 CMDE ON
 CEBJ OFF DLEN ON TRST ON DLSS ON DLSB ON EXEC OFF EXBU OFF SFRM 006 BRCT OFF SCTA A0 SCTB B1
 ANDI PRI 05CL PRI THCH B RGST A MODC OFF PCMR B PCMM P+M PCMD ON TSFM ON MSDS ON CHCT ON
 CCHL HI BATB ON BTBE OFF +BAT SEC -BAT PRI UVOL OFF ATCS OFF
 296 18 07 05
 BIRD 173 VTIM 124 TYPE P+M OREN OFF HKSR OFF DLSS OFF
 ADN1 RESET ADN2 RESET ADN3 RESET ADN4 RESET ADN5 RESET ADN6 RESET ADN7 RESET ADN8 ADDR9 AGC1 235 AGC2006 CMDE OFF
 CEBJ OFF DLEN OFF TRST ON DLSS OFF DLSB OFF EXEC ON EXBU ON SFRM 004 BRCT OFF SCTA A0 SCTB B1
 ANDI PRI 05CL PRI THCH A RGST B MODC OFF PCMR B PCMM P+M PCMD ON TSFM OFF MSDS OFF CHCT ON
 CCHL HI BATB OFF BTBE ON +BAT PRI -BAT SEC UVOL OFF ATCS OFF
 296 18 07 06
 BIRD 174 VTIM 125 TYPE P+M OREN OFF HKSR OFF DLSS OFF
 ADN1 ADDR2 ADDR3 ADDR4 ADDR5 ADDR6 ADDR7 ADDR8 ADDR9 AGC1 055 AGC2102 CMDE OFF
 CEBJ ON DLEN OFF TRST ON DLSS OFF DLSB OFF EXEC OFF EXBU OFF SFRM 006 BRCT OFF SCTA A0 SCTB B1
 ANDI PRI 05CL PRI THCH B RGST A MODC ON PCMR A PCMM P+M PCMD OFF TSFM OFF MSDS OFF CHCT ON
 CCHL LO BATB ON BTBE ON +BAT SEC -BAT SEC UVOL OFF ATCS ON
 296 18 07 07
 BIRD 171 VTIM 112 TYPE P+M OREN ON HKSR OFF DLSS ON
 ADN1 RESET ADN2 RESET ADN3 RESET ADN4 RESET ADN5 RESET ADN6 RESET ADN7 RESET ADN8 RESET AGC1 123 AGC2055 CMDE ON
 CEBJ OFF DLEN ON TRST OFF DLSS ON DLSB ON EXEC OFF EXBU OFF SFRM 007 BRCT OFF SCTA A1 SCTB B1
 ANDI PRI 05CL PRI THCH B RGST B MODC OFF PCMR B PCMM P+M PCMD OFF TSFM OFF MSDS OFF CHCT ON
 CCHL HI BATB OFF BTBE ON +BAT PRI -BAT PRI UVOL ON ATCS ON
 296 18 07 09
 BIRD 176 VTIM 115 TYPE PCM OREN ON HKSR OFF DLSS ON
 ADN1 RESET ADN2 RESET ADN3 ADDR4 ADDR5 ADDR6 ADDR7 ADDR8 ADDR9 AGC1 130 AGC2045 CMDE ON
 CEBJ ON DLEN ON TRST OFF DLSS ON DLSB OFF EXEC ON EXBU ON SFRM 007 BRCT OFF SCTA A0 SCTB B0
 ANDI PRI 05CL PRI THCH B RGST B MODC ON PCMR A PCMM PCM PCMD OFF TSFM OFF MSDS OFF CHCT OFF
 CCHL HI BATB ON BTBE OFF +BAT PRI -BAT SEC UVOL OFF ATCS OFF
 296 18 07 10
 BIRD 177 VTIM 120 TYPE P+M OREN ON HKSR OFF DLSS ON
 ADN1 RESET ADN2 RESET ADN3 RESET ADN4 RESET ADN5 ADDR6 ADDR7 ADDR8 ADDR9 AGC1 366 AGC2347 CMDE ON
 CEBJ OFF DLEN OFF TRST ON DLSS ON DLSB ON EXEC ON EXBU ON SFRM 002 BRCT OFF SCTA A1 SCTB B0
 ANDI SEC 05CL PRI THCH B RGST A MODC ON PCMR A PCMM P+M PCMD ON TSFM OFF MSDS ON CHCT ON
 CCHL LO BATB OFF BTBE ON +BAT SEC -BAT SEC UVOL ON ATCS ON
 296 18 07 11
 BIRD 174 VTIM 127 TYPE PCM OREN ON HKSR OFF DLSS ON
 ADN1 ADDR2 ADDR3 ADDR4 ADDR5 ADDR6 ADDR7 ADDR8 ADDR9 AGC1 340 AGC2116 CMDE ON
 CEBJ ON DLEN OFF TRST OFF DLSS ON DLSB ON EXEC OFF EXBU OFF SFRM 007 BRCT OFF SCTA A1 SCTB B1
 ANDI SEC 05CL PRI THCH A RGST B MODC ON PCMR A PCMM PCM PCMD ON TSFM ON MSDS ON CHCT ON
 CCHL LO BATB ON BTBE ON +BAT PRI -BAT PRI UVOL ON ATCS ON
 296 18 07 13
 BIRD 178 VTIM 121 TYPE P+M OREN OFF HKSR OFF DLSS ON
 ADN1 ADDR2 ADDR3 ADDR4 ADDR5 ADDR6 ADDR7 ADDR8 ADDR9 AGC1 364 AGC2326 CMDE ON
 CEBJ ON DLEN OFF TRST ON DLSS ON DLSB ON EXEC OFF EXBU OFF SFRM 006 BRCT OFF SCTA A1 SCTB B1
 ANDI SEC 05CL PRI THCH A RGST B MODC ON PCMR B PCMM P+M PCMD OFF TSFM ON MSDS ON CHCT OFF
 CCHL LO BATB OFF BTBE ON +BAT SEC -BAT SEC UVOL ON ATCS OFF
 296 18 07 14
 BIRD 178 VTIM 115 TYPE PCM OREN OFF HKSR OFF DLSS OFF
 ADN1 ADDR2 ADDR3 ADDR4 ADDR5 ADDR6 ADDR7 ADDR8 ADDR9 AGC1 031 AGC2133 CMDE ON
 CEBJ ON DLEN OFF TRST ON DLSS OFF DLSB OFF EXEC OFF EXBU OFF SFRM 004 BRCT ON SCTA A0 SCTB B1
 ANDI SEC 05CL PRI THCH A RGST A MODC ON PCMR A PCMM PCM PCMD ON TSFM OFF MSDS ON CHCT OFF
 CCHL HI BATB ON BTBE OFF +BAT PRI -BAT PRI UVOL ON ATCS ON
 296 18 07 15
 BIRD 175 VTIM 124 TYPE P+M OREN OFF HKSR OFF DLSS OFF
 ADN1 RESET ADN2 RESET ADN3 ADDR4 ADDR5 ADDR6 ADDR7 ADDR8 ADDR9 AGC1 223 AGC2141 CMDE OFF
 CEBJ OFF DLEN OFF TRST ON DLSS OFF DLSB ON EXEC OFF EXBU ON SFRM 000 BRCT ON SCTA A0 SCTB B0
 ANDI SEC 05CL PRI THCH B RGST B MODC ON PCMR B PCMM P+M PCMD OFF TSFM ON MSDS OFF CHCT ON
 CCHL LO BATB OFF BTBE ON +BAT PRI -BAT PRI UVOL ON ATCS OFF
 296 18 07 17
 BIRD 175 VTIM 120 TYPE P+M OREN ON HKSR OFF DLSS ON
 ADN1 ADDR2 ADDR3 ADDR4 ADDR5 ADDR6 ADDR7 ADDR8 ADDR9 AGC1 235 AGC2311 CMDE ON
 CEBJ ON DLEN ON TRST OFF DLSS ON DLSB ON EXEC ON EXBU OFF SFRM 000 BRCT OFF SCTA A0 SCTB B1

COMMAND - F170CS

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0																
1			MON ADDRESS D	V. TIME A						REC 1 AGC A	REC 2 AGC A					
2			MON COMMAND D	MON MEMORY D									MON DL TIMER CMD 1 A	MON DL TIMER CMD 2 A	MON BOOM CTL D	MON R CTL D
3			MON PCM D	MON COMMAND D											MON THRUSTER CTL D	
4			MON BATTERY D						+ BAT A	- BAT A	+ BAT TEMP A	- BAT TEMP A	+ CG I A	+ DISCG I A	- CG I A	- DISCG I A
5																
6																
7																
8																
9																
10																
11																
12																
13																
14																
15																

Approved for Release: 2024/06/06 C05027392

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III.6. F170 ES

170 EXPERIMENT SYSTEM F170E5

PREPARED AT NRL BY MCGINTY

3 NOV 71

INA=0, INPUT GROUP SYNC, OUTPUT MT1

INA=1, INPUT GROUP SYNC, OUTPUT MT2

INA=2, INPUT MT1

INA=3, INPUT MT2

INA=4, INPUT GROUP SYNC; PCM OUTPUT TO MAG TAPE UNIT 1,

SPECIAL DECOM TO LPR/CRT

WILL PRINT/DISPLAY : DECOM NUMBER, RAW DATA, PROCESSED DATA

"TNUM" = NUMBER OF DECOMS

"TCOM" = TABLE OF DECOMS

PRINTER

DIGIT=0, NORMAL PRINT

DIGIT=3, SPECIAL DECOM PRINT

PAGE=0, NORMAL DISPLAY

PAGE=8, SPECIAL DECOM DISPLAY

MRO OUTPUT TO MAG TAPE UNIT 2.

PURPOSE - TO OUTPUT MESSAGE LABEL AND PROCESSED DATA TO
CRT/LPR - 170 EXPERIMENT SYSTEM

DECOM (16,64)

WORD NUMBER	0-6	1	1	EXP1	EXPERIMENT 1 DIGITAL
DECOM				49,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	0-7	2	2	EXP2	EXPERIMENT 2 DIGITAL
DECOM				57,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	1-6	3	3	EXP3	EXPERIMENT 3 DIGITAL
DECOM				177,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	1-7	4	4	EXP4	EXPERIMENT 4 DIGITAL
DECOM				185,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	2-6	5	5	EXP5	EXPERIMENT 5 DIGITAL
DECOM				305,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	2-7	6	6	EXP6	EXPERIMENT 6 DIGITAL
DECOM				313,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	3-6	7	7	EXP7	EXPERIMENT 7 DIGITAL
DECOM				433,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	3-7	8	8	EXP8	EXPERIMENT 8 DIGITAL
DECOM				441,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	4-6	9	9	EXP9	EXPERIMENT 9 DIGITAL
DECOM				561,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	4-7	10	10	EX10	EXPERIMENT 10 DIGITAL
DECOM				569,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	5-6	11	11	EX11	EXPERIMENT 11 DIGITAL
DECOM				689,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	5-7	12	12	EX12	EXPERIMENT 12 DIGITAL
DECOM				697,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	6-6	13	13	EX13	EXPERIMENT 13 DIGITAL
DECOM				817,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	6-7	14	14	EX14	EXPERIMENT 14 DIGITAL
DECOM				825,8,CRT/LPR/DPR,RAW,0	
WORD NUMBER	7-6	15	15	EX15	EXPERIMENT 15 DIGITAL
DECOM				945,8,CRT/LPR/DPR,RAW,0	

170 EXPERIMENT SYSTEM F170ES

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* WORD NUMBER 7-7 16 16 EX16 EXPERIMENT 16 DIGITAL
  DECOM 953,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER 6-2 17 17 E171 EXPERIMENT 17-1
  DECOM 785,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER 6-3 18 18 E172 EXPERIMENT 17-2
  DECOM 793,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER 7-2 19 19 E173 EXPERIMENT 71-3
  DECOM 913,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER 7-3 20 20 E174 EXPERIMENT 17-4
  DECOM 921,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER 1-3 1 21 VTIM PCM VERNIER TIME DECIMAL
  DECOM 153,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER 3-3 2 22 BIRD SPACECRAFT ID (ADD 171)
  DECOM 415,2,CRT/LPR/DPR,RAW,0
* WORD NUMBER 3-2 3 23 (MRO,PCM) TYPE OF DATA (0=PCM,1=MRO)
  DECOM 405,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER 3-3 4 24 HKSR HOUSEKEEPING SENSOR (0=OFF, 1=ON)
  DECOM 411,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER 3-3 5 25 OREN ORDANCE ENABLE (0=OFF, 1=ON)
  DECOM 277,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER 2-2 6 26 DLSS DL SYSTEM (0=OFF, 1=ON)
  DECOM 409,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER 2-7 27 MEMORY ADDRESS COUNTER
  DECOM 313,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER 0-7 28 MEMORY ADDRESS COUNTER
  DECOM 57,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER 7-7 29 MEMORY ADDRESS COUNTER
  DECOM 953,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER 5-7 30 MEMORY ADDRESS COUNTER
  DECOM 697,8,CRT/LPR/DPR,RAW,0
  SIZE TCOM(64)
  SIZE MT(8)
  TEXT S1(2,6)SAMPLE"REV"
* STANDARD DATA HEADER
  TEXT HT(7,4)VTIM"BIRD"PCM"MRO"HKSR"OREN"DLSS"
  TEXT ON(2,3)OFF"ON"
* CRT BUFFER
  SIZE M2(160)
  SIZE M(20)
  TEXT E1(21,4)EXP1"EXP2"EXP3"EXP4"EXP5"EXP6"EXP7"EXP8"EXP9"EX10"
  TEXTC EX11"EX12"EX13"EX14"EX15"EX16"E171"E172"E173"SLXA"SLXA"
  TEXT E2(2,4)F170ES"REV"
  TEXT E4(8,4)OPTA"OPTB"RPAREXPN"OPX1"OPX2"SLMA" "
  TEXT E5(2,3)ON"OFF"
  TEXT T7(24,4)E7-1"E7-9"E717"E7-2"E710"E718"E7-3"E711"E719"
  TEXTC E7-4"E712"E720"E7-5"E713"E7G4"E7-6"E714"E7G3"E7-7"E715"E7G2"
  TEXTC E7-8"E716"E7G1"
  TEXT E6(9,4)SLM1"SLM3"SLM2"AJX2"AJX3"ADJ"AJL3"AJL2"AJL4"
  PROCESS RAW
  PD(N)=UD(N)
  ENDP
  START OF PROGRAM
  START
* RESET SAMPLE COUNTER
  SA=1
* DETERMINE MAG TAPE UNIT AND CONFIG
  IF (MAG.EQ.1.OR.INA.EQ.3)GOTO DOG1

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MRO	VTIM	167	BIRD	174	HKSR	OFF	OREN	OFF	DLSS	ON	320	14	42	12	F170E5	REV	000000	SAMPLE	000000																																						
EXP1	000375	EXP2	000273	EXP3	000224	EXP4	000025	EXP5	000235	EXP6	000235	EXP7	000012	EXP8	000274	EXP9	000254	EXP10	000236	EXP11	000373	EXP12	000373	EXP13	000332	EXP14	000353	EXP15	000246	EXP16	000062																										
E171	000045	E172	000300	E173	000253	SLMA	000305																																																		
OPTA	OFF	OFF	OFF	ON	OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	E7-1	ON	E7-9	OFF	E717	OFF	OPTB	OFF	ON	ON	ON	ON	ON	ON	ON	E7-2	ON	E710	OFF	E718	ON																				
PAR	OFF	OFF	ON	ON	ON	ON	ON	OFF	OFF	ON	OFF	OFF	ON	OFF	OFF	OFF	E7-3	OFF	E711	ON	E719	OFF	EXPN	OFF	OFF	OFF	OFF	OFF	ON	OFF	E7-4	ON	E712	ON	E720	ON																					
OP1	OFF	OFF	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	E7-5	ON	E713	ON	E764	OFF	OP2	OFF	ON	OFF	OFF	OFF	ON	ON	ON	OFF	E7-6	OFF	E714	ON	E763	ON																			
OP2	OFF	ON	OFF	OFF	OFF	OFF	ON	OFF	OFF	OFF	OFF	ON	ON	ON	OFF	ON	E7-7	ON	E715	ON	E762	OFF	SLM	SLM1	SLM3	SLM2	SLM2	AJX2	AJX3	ADJ	AJL3	AJL2	E7-8	OFF	E716	ON	E761	OFF																			
PCM	VTIM	052	BIRD	172	HKSR	OFF	OREN	ON	DLSS	OFF	320	14	42	14	F170E5	REV	000000	SAMPLE	000007																																						
EXP1	000327	EXP2	000266	EXP3	000001	EXP4	000177	EXP5	000032	EXP6	000016	EXP7	000162	EXP8	000057	EXP9	000030	EXP10	000175	EXP11	000014	EXP12	000374	EXP13	000147	EXP14	000370	EXP15	000167	EXP16	000177																										
E171	000057	E172	000167	E173	000254	SLMA	000137																																																		
OPTA	OFF	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-1	ON	E7-9	ON	E717	OFF	OPTB	OFF	ON	ON	OFF	ON	ON	OFF	ON	ON	ON	ON	ON	E7-2	ON	E710	OFF	E718	ON																
PAR	ON	OFF	ON	OFF	ON	ON	OFF	ON	ON	OFF	ON	OFF	ON	OFF	OFF	OFF	E7-3	OFF	E711	OFF	E719	OFF	EXPN	OFF	OFF	ON	OFF	OFF	ON	OFF	ON	OFF	ON	OFF	E7-4	ON	E712	OFF	E720	ON																	
OP1	ON	ON	ON	OFF	OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	E7-5	OFF	E713	ON	E764	OFF	OP2	OFF	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	E7-6	OFF	E714	OFF	E763	OFF																		
OP2	OFF	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	OFF	ON	E7-7	OFF	E715	OFF	E762	ON	SLM	SLM1	SLM3	SLM2	SLM2	AJX2	AJX3	ADJ	AJL3	AJL2	E7-8	OFF	E716	OFF	E761	ON																			
PCM	VTIM	093	BIRD	172	HKSR	ON	OREN	ON	DLSS	OFF	320	14	42	17	F170E5	REV	000000	SAMPLE	000008																																						
EXP1	000156	EXP2	000267	EXP3	000165	EXP4	000116	EXP5	000022	EXP6	000327	EXP7	000377	EXP8	000337	EXP9	000126	EXP10	000217	EXP11	000306	EXP12	000302	EXP13	000276	EXP14	000223	EXP15	000342	EXP16	000047																										
E171	000152	E172	000004	E173	000317	SLMA	000047																																																		
OPTA	ON	OFF	ON	ON	ON	OFF	OFF	ON	ON	OFF	OFF	OFF	OFF	OFF	ON	E7-1	ON	E7-9	ON	E717	OFF	OPTB	OFF	ON	ON	OFF	ON	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	E7-2	OFF	E710	ON	E718	OFF														
PAR	OFF	OFF	OFF	ON	ON	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-3	OFF	E711	ON	E719	ON	EXPN	ON	OFF	OFF	ON	OFF	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-4	ON	E712	ON	E720	ON											
OP1	ON	ON	ON	OFF	ON	ON	OFF	ON	OFF	ON	OFF	ON	ON	ON	ON	ON	E7-5	OFF	E713	ON	E764	OFF	OP2	ON	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	E7-6	ON	E714	OFF	E763	OFF																	
OP2	ON	ON	OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	ON	E7-7	OFF	E715	ON	E762	OFF	SLM	SLM1	SLM3	SLM2	SLM2	AJX2	AJX3	ADJ	AJL3	AJL2	E7-8	ON	E716	ON	E761	OFF																			
PCM	VTIM	193	BIRD	174	HKSR	ON	OREN	ON	DLSS	ON	320	14	42	19	F170E5	REV	000000	SAMPLE	000009																																						
EXP1	000101	EXP2	000202	EXP3	000277	EXP4	000133	EXP5	000345	EXP6	000020	EXP7	000024	EXP8	000261	EXP9	000055	EXP10	000315	EXP11	000177	EXP12	000056	EXP13	000327	EXP14	000222	EXP15	000317	EXP16	000133																										
E171	000146	E172	000347	E173	000317	SLMA	000344																																																		
OPTA	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-1	ON	E7-9	OFF	E717	OFF	OPTB	OFF	ON	ON	OFF	ON	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-2	OFF	E710	OFF	E718	OFF											
PAR	ON	ON	OFF	ON	OFF	ON	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	E7-3	OFF	E711	OFF	E719	ON	EXPN	ON	ON	OFF	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-4	ON	E712	ON	E720	ON								
OP1	ON	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-5	ON	E713	ON	E764	OFF	OP2	ON	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	E7-6	OFF	E714	OFF	E763	OFF																	
OP2	ON	ON	OFF	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-7	OFF	E715	OFF	E762	OFF	SLM	SLM1	SLM3	SLM2	SLM2	AJX2	AJX3	ADJ	AJL3	AJL2	E7-8	ON	E716	OFF	E761	OFF																			
PCM	VTIM	009	BIRD	171	HKSR	ON	OREN	ON	DLSS	OFF	320	14	42	22	F170E5	REV	000000	SAMPLE	000010																																						
EXP1	000344	EXP2	000174	EXP3	000311	EXP4	000253	EXP5	000147	EXP6	000164	EXP7	000322	EXP8	000047	EXP9	000236	EXP10	000001	EXP11	000117	EXP12	000271	EXP13	000203	EXP14	000270	EXP15	000265	EXP16	000175																										
E171	000107	E172	000027	E173	000357	SLMA	000147																																																		
OPTA	OFF	ON	OFF	OFF	ON	ON	OFF	ON	OFF	ON	ON	OFF	ON	ON	ON	ON	E7-1	ON	E7-9	ON	E717	OFF	OPTB	OFF	OFF	OFF	ON	OFF	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-2	OFF	E710	ON	E718	OFF									
PAR	OFF	OFF	ON	OFF	OFF	OFF	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	E7-3	ON	E711	ON	E719	OFF	EXPN	ON	OFF	ON	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-4	ON	E712	OFF	E720	ON				
OP1	ON	OFF	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-5	ON	E713	ON	E764	OFF	OP2	OFF	OFF	ON	ON	OFF	ON	OFF	ON	OFF	ON	OFF	E7-6	OFF	E714	OFF	E763	OFF																	
OP2	OFF	OFF	ON	ON	OFF	OFF	ON	OFF	OFF	ON	OFF	ON	ON	ON	ON	ON	E7-7	OFF	E715	OFF	E762	OFF	SLM	SLM1	SLM3	SLM2	SLM2	AJX2	AJX3	ADJ	AJL3	AJL2	E7-8	ON	E716	OFF	E761	OFF																			
PCM	VTIM	009	BIRD	171	HKSR	ON	OREN	ON	DLSS	OFF	320	14	42	22	F170E5	REV	000000	SAMPLE	000010																																						
EXP1	000344	EXP2	000174	EXP3	000311	EXP4	000253	EXP5	000147	EXP6	000164	EXP7	000322	EXP8	000047	EXP9	000236	EXP10	000001	EXP11	000117	EXP12	000271	EXP13	000203	EXP14	000270	EXP15	000265	EXP16	000175																										
E171	000107	E172	000027	E173	000357	SLMA	000147																																																		
OPTA	OFF	ON	OFF	OFF	ON	ON	OFF	ON	OFF	ON	ON	OFF	ON	ON	ON	ON	E7-1	ON	E7-9	ON	E717	OFF	OPTB	OFF	OFF	OFF	ON	OFF	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-2	OFF	E710	ON	E718	OFF					
PAR	OFF	OFF	ON	OFF	OFF	OFF	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	E7-3	ON	E711	ON	E719	OFF	EXPN	ON	OFF	ON	ON	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-4	ON	E712	OFF	E720	ON
OP1	ON	OFF	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	E7-5	ON	E713	ON	E764	OFF	OP2	OFF	OFF	ON	ON	OFF	ON	OFF	ON	OFF	ON	OFF	E7-6	OFF	E714	OFF	E763	OFF																	
OP2	OFF	OFF	ON	ON	OFF	OFF	ON	OFF	OFF	ON	OFF	ON	ON	ON	ON	ON	E7-7	OFF	E715	OFF	E762	OFF	SLM	SLM1	SLM3	SLM2	SLM2	AJX2	AJX3	ADJ	AJL3	AJL2	E7-8	ON	E716	OFF	E761	OFF																			

EXPERIMENTS - COMPUTER PRO. F170ES

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0							EXP. 1 D	EXP. 2 D								
1			ADDRESS MON D	V. TIME A			EXP. 3 D	EXP. 4 D								
2			COMMAND CONTROL MON D	MEMORY D			EXP. 5 D	EXP. 6 D					DL TIMER CMD 1 D	DL TIMER CMD 2 D		
3			PCM CONTROL MON D	COMMAND CONTROL MON D			EXP. 7 D	EXP. 8 D								
4			MON BAT D	EXP. 17 AB			EXP. 9 D	EXP. 10 D								
5			EXP. 18	EXP. 19			EXP. 11 D	EXP. 12 D								
6			EXP. 20	EXP. 21			EXP. 13 D	EXP. 14 D								
7			RETEP	PAR			EXP. 15 D	EXP. 16 D					TEMP 11 DL BOOM A			

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III.7. F170 .PS

POWER SYSTEM PROCESSED DATA

POWER SYSTEM PROCESSED DATA
POWER SYSTEM PROCESSED DATA

19 OCT 71

3.3(b)(1)

PREPARED AT NRL BY

INA=0, INPUT GROUP SYNC, OUTPUT MT1
INA=1, INPUT GROUP SYNC, OUTPUT MT2
INA=2, INPUT MT1
INA=3, INPUT MT2
INA=4, INPUT GROUP SYNC; PCM OUTPUT TO MAG TAPE UNIT 1,
MRO OUTPUT TO MAG TAPE UNIT 2.

PDS

PURPOSE - TO OUTPUT POWER SYSTEM PROCESSED DATA.

64 16-BIT WORDS

DECOM (16,64)

WORD NUMBER	1-12	1	1	+CL1	+ CELL 1 MONITOR	
DECOM			225,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	0-4	2	2	+CM2	+ CELL 2 MONITOR	
DECOM			33,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	1-4	3	3	+CM3	+ CELL 3 MONITOR	
DECOM			161,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	2-4	4	4	+CM4	+ CELL 4 MONITOR	2
DECOM			289,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	3-4	5	5	+CM5	+ CELL 5 MONITOR	2
DECOM			417,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	4-4	6	6	+CM6	+ CELL 6 MONITOR	2
DECOM			545,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	5-4	7	7	+CM7	+ CELL 7 MONITOR	2
DECOM			673,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	6-4	8	8	+CM8	+ CELL 8 MONITOR	
DECOM			801,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	7-4	9	9	+CM9	+ CELL 9 MONITOR	
DECOM			929,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	0-5	10	10	-C10	- CELL 2 MONITOR	
DECOM			41,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	1-5	11	11	-C11	- CELL 11 MONITOR	
DECOM			169,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	2-5	12	12	-C12	- CELL 12 MONITOR	
DECOM			297,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	3-5	13	13	-C13	- CELL 13 MONITOR	
DECOM			425,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	4-5	14	14	-C14	- CELL 14 MONITOR	
DECOM			553,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	5-5	15	15	-C15	- CELL 15 MONITOR	
DECOM			681,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	6-5	16	16	-C16	- CELL 16 MONITOR	
DECOM			809,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	7-5	17	17	-C17	- CELL 17 MONITOR	
DECOM			937,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		
WORD NUMBER	1-13	18	18	-C18	- CELL 18 MONITOR	
DECOM			233,8	CRT/LPR/DPR,LINZ,4,2,0,3,3		

* POWER SYSTEM PROCESSED DATA

DECOM			531,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	4-2-4	20	20 BBEN BATTERY BYPASS ENABLE
DECOM			532,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	4-2-5	21	21 P+BS PRI-SEC + BATTERY SELECT
DECOM			533,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	4-2-6	22	22 P-BS PRI-SEC - BATTERY SELECT
DECOM			534,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	4-2-1	23	23 CCOF CHARGE CONTROL ON-OFF
DECOM			529,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	4-2-2	24	24 CCHL CHARGE CONTROL HI-LO
DECOM			530,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	1-8	25	25 5VCL 5 VOLT CALIBRATE
DECOM			193,8,CRT/LPR/DPR,VOLT,0
* WORD NUMBER	4-8	1	26 +VSR + VOLT SENSOR
DECOM			577,8,CRT/LPR/DPR,LOLT,0
* WORD NUMBER	4-9	2	27 -VSR - VOLT SENSOR
DECOM			585,8,CRT/LPR/DPR,LOLT,0
* WORD NUMBER	4-10	3	28 +BTM + BATTERY TEMPERATURE
DECOM			593,8,CRT/LPR/DPR,CURVE,0
* WORD NUMBER	4-11	4	29 -BTM - BATTERY TEMPERATURE
DECOM			601,8,CRT/LPR/DPR,CURVE,0
* WORD NUMBER	4-12	5	30 +CIM + CHARGE CURRENT MONITOR
DECOM			609,8,CRT/LPR/DPR,AMPS,0
* WORD NUMBER	4-13	6	31 +DIM + DISCHARGE CURRENT MONITOR
DECOM			617,8,CRT/LPR/DPR,AMPS,0
WORD NUMBER	4,14	7	32 -CIM - CHARGE CURRENT MONITOR
DECOM			625,8,CRT/LPR/DPR,AMPS,0
* WORD NUMBER	4-15	8	33 -DIM - DISCHARGE CURRENT MONITOR
DECOM			633,8,CRT/LPR/DPR,AMPS,0
* WORD NUMBER	3-8	9	34 +SVM +SEC VOLT MONITOR OUTPUT
DECOM			449,8,CRT/LPR/DPR,LOLT,0
* WORD NUMBER	3-9	10	35 -SVM -SEC VOLT MONITOR OUTPUT
DECOM			457,8,CRT/LPR/DPR,LOLT,0
* WORD NUMBER	3-12	11	36 T3+B T3 + SEC BATTERY TEM
DECOM			481,8,CRT/LPR/DPR,CURVE,0
* WORD NUMBER	3-13	12	37 T4-B T4 - SEC BATTERY TEMPERATURE
DECOM			489,8,CRT/LPR/DPR,CURVE,0
* WORD NUMBER	1-3	1	38 VTIM PCM VERNIER TIME DECIMAL
DECOM	153,8,CRT/LPR/DPR,RAW,0		
* WORD NUMBER	3-3	2	39 BIRD SPACECRAFT ID (ADD 171)
DECOM			415,2,CRT/LPR/DPR,RAW,0
* WORD NUMBER	3-2	3	40 (MRO,PCM) TYPE OF DATA (0=PCM,1=MRO)
DECOM			405,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	3-3	4	41 HKSR HOUSEKEEPING SENSOR (0=OFF, 1=ON)
DECOM			411,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	3-3	5	42 OREN ORDANCE ENABLE (0=OFF, 1=ON)
DECOM			277,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	2-2	6	43 DLSS DL SYSTEM (0=OFF, 1=ON)
DECOM			409,1,CRT/LPR/DPR,RAW,0
* WORD NUMBER	2-7		44 MEMORY ADDRESS COUNTER
DECOM			313,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER	0-7		45 MEMORY ADDRESS COUNTER
DECOM			57,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER	7-7		46 MEMORY ADDRESS COUNTER
DECOM			953,8,CRT/LPR/DPR,RAW,0
* WORD NUMBER	5-7		47 MEMORY ADDRESS COUNTER

FL70PS CRT DISPLAY

+CM1	001.32	+CM2	001.30
+CM3	001.30	+CM4	001.30
+CM5	001.30	+CM6	001.30
+CM7	001.30	+CM8	001.30
+CM9	001.32	-C10	001.28
-C11	001.30	-C12	001.28
-C13	001.26	-C14	001.30
-C15	001.30	-C16	001.30
-C17	001.28	-C18	001.30
+VSR	05.499	-VSR	05.969
+BTM	0059.1	-BTM	0059.9
+CIM	0.0000	+DIM	0.0000
-CIM	0.0000	-DIM	0.0000
+SVM	09.400	-SVM	0.0000
T3+B	0059.1	T4-B	0058.3
5VCL	5.0400	BBOF	OFF
BBEN	OFF	P+BS	OFF
P-BS	OFF	CCOF	OFF
CCHL	LO	FL70PS	
SAMPLE	000000		312 14 16 58

POWER - COMPUTER PRO. F170PS

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0					CELL 2 A	CELL 10 A										
1		MON ADDRESS D	V. TIME A		CELL 3 A	CELL 11 A							CELL 1 A	CELL 18 A		
2		MON COMMAND D	MEM D		CELL 4 A	CELL 12 A				TEMP 24 BAT BYP A						
3		MEM D	MON HK D		CELL 5 A	CELL 13 A			MON + SEC V A	MON - SEC V A			TEMP 3 + SEC BAT A	TEMP 4 - SEC BAT A		
4		MON BAT CONTROL D			CELL 6 A	CELL 14 A			MON + BAT V A	MON - BAT V A	TEMP 25 + BAT A	TEMP 26 - BAT A	MON + CG 1 A	MON + DISCG 1 A	MON - CG 1 A	MON - DISCG 1 A
5					CELL 7 A	CELL 15 A			TEMP 25 + BAT A	TEMP 26 - BAT A						
6					CELL 8 A	CELL 16 A									MON + SC CG 1 A	MON - SC CG 1 A
7					CELL 9 A	CELL 17 A										

III.8. F170 S

F170S REATION WHEEL/BOOM/THRUSTERS SYSTEM I124
F170S REATION WHEEL/BOOM/THRUSTERS SYSTEM I124

27 OCT 71

3.3(b)(1)

PREPARED AT NRL BY

INA=0, INPUT GROUP SYNC, OUTPUT MT1
INA=1, INPUT GROUP SYNC, OUTPUT MT2
INA=2, INPUT MT1
INA=3, INPUT MT2
INA=4, INPUT GROUP SYNC; PCM OUTPUT TO MAG TAPE UNIT 1,
MRO OUTPUT TO MAG TAPE UNIT 2.

SPECIAL DECOM TO LPR/CRT

WILL PRINT/DISPLAY : DECOM NUMBER, RAW DATA, PROCESSED DATA
"TNUM" = NUMBER OF DECOMS
"TCOM" = TABLE OF DECOMS
PRINTER
DIGIT=0, NORMAL PRINT
DIGIT=3, SPECIAL DECOM PRINT

CRT

PAGE=0, NORMAL DISPLAY
PAGE=1, BOOM
PAGE=8, SPECIAL DECOM DISPLAY
SELECTED DECOM TEST

DECOM (16,64)

WORD NUMBER	2-15	1	1	SPED	SPEED ON/OFF (1,0)
DECOM				377,1,CRT/LPR/DPR,RAW,0	
WORD NUMBER	2-15		2	STAT	REACTION WHEEL ON/OFF (1,0)
DECOM				378,1,CRT/LPR/DPR,RAW,0	
WORD NUMBER	2-15		3	FORS	FORWARD/REVERSE (1,0)
DECOM				379,1,CRT/LPR/DPR,RAW,0	
WORD NUMBER	2-15		4	PRSC	PRIMARY/SECONDARY (1,0)
DECOM				380,1,CRT/LPR/DPR,RAW,0	
WORD NUMBER	2-15		5	CONT	CONTROL PRIMARY/SECONDARY (0,1)
DECOM				381,1,CRT/LPR/DPR,RAW,0	
WORD NUMBER	2-15		6	DIRT	DIRECTION PRIMARY/SECONDARY (1,0)
DECOM				382,1,CRT/LPR/DPR,RAW,0	
WORD NUMBER	1-14,15		7	SPRO	REACTION WHEEL SPEED
DECOM				242,15,CRT/LPR/DPR,RAW,0	
WORD NUMBER	1-15-15		8	SPCT	REACTION WHEEL SPEED CONTROL
DECOM				248,1,CRT/LPR/DPR,RAW,0	
WORD NUMBER	0-9		9	RWTP	REACTION WHEEL TEMPERATURE
DECOM				977,8,CRT/LPR/DPR,CURVE,0	
WORD NUMBER	0-10		10	RWTO	REACTION WHEEL TACH OUT
DECOM				081,8,CRT/LPR/DPR,TACH,0	
WORD NUMBER	4-8		11	+VSR	+ VOLT SENSOR
DECOM				577,8,CRT/LPR/DPR,LOLT,0	
WORD NUMBER	4-9		12	-VSR	- VOLT SENSOR
DECOM				585,8,CRT/LPR/DPR,LOLT,0	

WORD NUMBER	4-	Approved for Release: 2024/06/06 C05027392	617,8,CRT/LPR/DPR,AMPS,0	+ DISCHARGE CURRENT MONITOR
DECOM				
* WORD NUMBER	4-15		14 -DIM	- DISCHARGE CURRENT MONITOR
DECOM			633,8,CRT/LPR/DPR,AMPS,0	
* WORD NUMBER	4-12		15 +CIM	+ CHARGE CURRENT MONITOR
DECOM			609,8,CRT/LPR/DPR,AMPS,0	
WORD NUMBER	4,14		16 -CIM	- CHARGE CURRENT MONITOR
DECOM			625,8,CRT/LPR/DPR,AMPS,0	
* WORD NUMBER	3-3-2		17 OREB	ORDANCE ENABLE BACKUP
DECOM			410,1,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	2-3		18 MSUB	MEMORY SUBFRAME
DECOM			281,3,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	2-3		19 MCLK	MEMORY CLOCK FREQ
DECOM			284,1,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	2-3		20 MRTE	MEMORY SAMPLE RATE
DECOM			285,2,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	4-2-5		21 +PBS	PRIMARY/SECONDARY + BATTERY SELECT
DECOM			533,1,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	4-2-6		22 -PBS	PRIMARY /SECONDARY -BATTERY SELECT
DECOM			534,1,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	1-3	1	23 VTIM	PCM VERNIER TIME DECIMAL
DECOM			153,8,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	3-3	2	24 BIRD	SPACECRAFT ID (ADD 171)
DECOM			415,2,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	3-2	3	25	(MRO,PCM) TYPE OF DATA (0=PCM,1=MRO)
DECOM			405,1,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	3-3	4	26 HKSR	HOUSEKEEPING SENSOR (0=OFF, 1=ON)
DECOM			411,1,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	3-3	5	27 OREN	ORDANCE ENABLE (0=OFF, 1=ON)
DECOM			277,1,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	2-2	6	28 DLSS	DL SYSTEM (0=OFF, 1=ON)
DECOM			409,1,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	2-7		29	MEMORY ADDRESS COUNTER
DECOM			313,8,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	0-7		30	MEMORY ADDRESS COUNTER
DECOM			57,8,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	7-7		31	MEMORY ADDRESS COUNTER
DECOM			953,8,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	5-7		32	MEMORY ADDRESS COUNTER
DECOM			697,8,CRT/LPR/DPR,RAW,0	
* WORD NUMBER	7-12	33	BTEM	BOOM TEMPERATURE
DECOM			993,8,CRT/LPR/DPR,CURVE,0	
* WORD NUMBER	1-11	34	BLEN	BOOM LENGTH
DECOM			217,8,CRT/LPR/DPR,RAW,1	
* WORD NUMBER	2-10	1	35 PTC1	CONTROL 1 PRESSURE TRANSDUCER
DECOM			337,8,CRT/LPR/DPR,PSI,0	
* WORD NUMBER	2-11	2	36 PTC2	CONTROL 2 PRESSURE TRANSDUCER

* WORD NUMBER	1-11	34	BLEN	BOOM LENGTH
DECOM				
* WORD NUMBER	2-10	1 35	PTC1	CONTROL 1 PRESSURE TRANSDUCER
DECOM				
* WORD NUMBER	2-11	2 36	PTC2	CONTROL 2 PRESSURE TRANSDUCER
DECOM				
* WORD NUMBER	7-4	3 37	PTT1	TANK 1 PRESSURE TRANSDUCER
DECOM				
* WORD NUMBER	7-5	4 38	PTT2	TANK 2 PRESSURE TRANSDUCER
DECOM				
* WORD NUMBER	2-14-1	39	BCOF	BOOM (ON=1, OFF=0)
DECOM				
* WORD NUMBER	2-14-2	40	BCIO	BOOM (IN=0, OUT=1)
DECOM				
* WORD NUMBER	2-14-3	41	BFRI	BOOM FULL RETRACT (RET=1, NRET=0)

* F1705 REACTION WHEEL/BOOM/THRUSTERS SYSTEM I124

THRUSTER

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0																
1			ADD D	V. TIM A						REC 1 AGC A	REC 2 AGC A					
2			CMD D	MEM D							PRES TH 1 CTL A	PRÉS TH 2 CTL A				
3			PCM D	PCM D											THRUS CTL D	
4			BAT D						+ BAT V A	- BAT V A	+ BAT TEMP A	- BAT TEMP A	+ CG I A	+ DISCG I A	- CG I A	- DISCG I A
5																
6																
7									TEMP 5 TANK A	T6 NOZ. 1 A					PRES TH 2 PLEN. A	PPES TH 1 PLEN. A

BOOM

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0									A							
1			ADD D	V TIM A					5V CAL A			BOOM LENGTH A				
2			CMD D	MEM D											MON BOOM CTL D	
3			PCM D	CMD D												
4			BAT D						+ BAT A	- BAT A	+ BAT TEMP A	- BAT TEMP A	+ CG I A	+ DISCG I A	- CG I A	- DISCG A
5																
6																
7													DL BOOM TEMP A			

Approved for Release: 2024/06/06 C05027392

Approved for Release: 2024/06/06 C05027392

III.9. FORTRAN PLOT M

PLOT - FORTRAN LINE PRINTER PLOT SUBROUTINE

* PLOT - FORTRAN LINE PRINTER PLOT SUBROUTINE

* PLOT - FORTRAN LINE PRINTER PLOT SUBROUTINE
* PLOT - FORTRAN LINE PRINTER PLOT SUBROUTINE

3.3(b)(1)

* PREPARED AT NRL BY

* I PURPOSE TO UTILIZE THE LINE PRINTER AS A PLOTTER

* II METHOD

* THE "PLOT" SUBROUTINE UTILIZES THE INPUTS: MODE(SUBROUTINE ACT
* CURRENT DATA VALUE, LOWER LIMIT, UPPER LIMIT, AND CURRENT SYMBO
* TO CLEAR PLOT IMAGE, STORE A POINT, OR PLOT CURRENT POINTS.

* THE "MODE" VARIABLE: EQUAL ZERO, CLEAR PRINT/PLOT BUFFER TO
* SPECIFIED SYMBOL; EQUAL ONE, ENTER CURRENT SYMBOL IN PRINT/PLOT
* BUFFER WITHOUT PRINTING; EQUAL TWO, ENTER CURRENT SYMBOL IN
* PRINT/PLOT BUFFER AND PRINT.

* THE VALUE PER PRINT CHARACTER POSITION IS DETERMINED BY
* SUBTRACTING THE LOWER LIMIT FROM THE UPPER LIMIT AND DIVIDING
* THE RESULT BY 100(THE MAXIMUM NUMBER OF PRINT POSITIONS).
* IF THE RESULTING SIGN IS NEGATIVE, THE SIGN IS CHANGED TO POSIT

* THE POSITION OF THE CURRENT SYMBO IN THE PRINT BUFFER LINE IS
* DETERMINED BY FIRST; SUBTRACTING THE CURRENT VALUE FROM THE
* UPPER LIMIT, SECOND; DIVIDING THE RESULT BY THE VALUE PER PRINT
* CHARACTER AND ADDING ONE. THE RESULT IS USED TO PLACE THE
* SYMBOL IN PROPER POSITION IN THE PRINT/PLOT BUFFER.

* III USE

* THE PLOT SUBROUTINE MAY BE USED BY A FORTRAN PROGRAM VIA:

* CALL PLOT(MODE,Y,R,Z,S)

* MODE - EQUAL ZERO, CLEAR PRINT/PLOT BUFFER WITH
* CHARACTER SPECIFIED BY "S".
* EQUAL ONE, PLACE CURRENT SYMBOL "S" IN PROPER
* EQUAL TWO, PLACE CURRENT SYMBOL "S" IN PRINT/
* BUFFER AND PRINT.

* Y CURRENT VALUE OF DATA

* R UPPER LIMIT

* Z LOWER LIMIT

* S SYMBOL

* IV PLOT IMAGE

* THE PLOT IMAGE IS ONE HUNDRED CHARACTER POSITIONS FROM 21-120.
* POSITIONS 1-20 CONTAIN TCT TIME.

COMMON ITCT(9)

```

COMMON ITCT(9)
DIMENSION REC(450)
DIMENSION          JTCT(9),KTCT(9)
INTEGER REC
DATA S1,S2,S3,S4,S5,S6/1H ,1HX,1HO,1H$,1H*,1H+/
REWIND 6
C PRINT LIMITS
WRITE(4,25)
25 FORMAT(1X,46HLIMITS? CURRENT=+-1@ ASPECT ANGLE=0-5 DEGREE@,
152H#VOLT SENSOR=10.03,-14.10@ -VOLT SENSOR=9.88,-13.95@,
218HTANK PRESSURE=8,16)
23 CALL BMTR(REC,1,450,IEOF,IPAR,IEOT)
IF(IEOF)45,45,55
55 CALL WEOF(2)
CALL WEOF(2)
REWIND 6
WRITE(4,824)
824 FORMAT1X,41HTCT TIME, CURRENT, ANGLE, VOLTS, PRESSURE)
455 READ(6,16)(ITCT(I),I=1,9),
1 IC,IP,IAA,IBB,IS,IZ,ITP,AX,AAA,AS,AT,ATP
WRITE(4,16)(ITCT(I),I=1,9),
1 IC,IP,IAA,IBB,IS,IZ,ITP,AX,AAA,AS,AT,ATP
GO TO 455
45 MQ=27
MZ=12
MP=29
MR=37
DO 166 MA=6,411,45
C PICK UP TCT TIME
DO 93 IX=1,9
93 ITCT(IX)=0
K=8
L=9
MX=MA-5
DO 94 IX=1,4
CALL BIT(REC(MX),3,6,ITCT(K),13,16)
CALL BIT(REC(MX),9,12,ITCT(L),13,15)
MX=MX+1
L=L-2
94 K=K-2
CALL BIT(REC(MX),11,12,ITCT(1),15,16)
C CLEAR PLOT BUFFER
MODE=0
S=S1
CALL PLOT(MODE,Y,R,Z,S)
C + AND - CHARGE CURRENT
R=-1.
Z=1.
MODE=1
S=S2
IC=0
IP=0
CALL BIT(REC(MQ),9,16,IC,9,16)

```

COMMON ITCT(9)

```

CALL BIT(REC(MQ),1,08,IP,9,16)
IF(IC)4,3,4
3 AX=-IP
GO TO 5
4 AX=IC
5 AX=AX*.0039
Y=AX
CALL PLOT(MODE,Y,R,Z,S)
C ASPECT ANGLE
R=-5.
Z=0.
S=S3
IAA=0
IBB=0
CALL BIT(REC(MZ),9,16,IAA,9,16)
CALL BIT(REC(MZ),1,08,IBB,9,16)
AAA=IAA-IBB
AAA=AAA/25.
Y=AAA
CALL PLOT(MODE,Y,R,Z,S)
C VOLT SENSOR
R=10.
Z=13.
S=S4
IS=0
IZ=0
CALL BIT(REC(MP),9,16,IS,9,16)
CALL BIT(REC(MP),1,08,IZ,9,16)
AT=IZ
AT=(AT*1635./1000.+10035./10.)/100.0
Y=AT
CALL PLOT(MODE,Y,R,Z,S)
S=S5
8 AS=IS
AS=(AS*1635./1000.+9885.0/10.)/100.0
Y=AS
CALL PLOT(MODE,Y,R,Z,S)
C SPIN AND ATT TANK PRESSURE
R=10.
Z=14.
S=S6
MODE=2
ITP=0
CALL BIT(REC(MR),9,16,ITP,9,16)
ATP=ITP
ATP=(ATP*8173./969.+0./969.)/100.
Y=ATP
CALL PLOT(MODE,Y,R,Z,S)
WRITE(6,16) (ITCT(I),I=1,9),
1 IC,IP,IAA,IBB,IS,IZ,ITP,AX,AAA,AS,AT,ATP
16 FORMAT(1X,3I1,3(1X,2I1),2X,
1 7(I3,2X),F11.4,2X,F8.1,2X,F9.2,2X,F9.2,2X,F9.2)
MQ=MQ+45

```

COMMON ITCT(9)

MZ=MZ+45

MP=MP+45

MR=MR+45

166

CONTINUE

GO TO 23

STOP

SO

END

VI

PLOT SUBROUTINE LISTING

C SUBROUTINE - PLOT A LINE ON THE LINE PRINTER

C SUBROUTINE - PLOT A LINE ON THE LINE PRINTER

C SUBROUTINE - PLOT A LINE ON THE LINE PRINTER

C 16 SEPT 71

C PREPARED AT NRL BY

3.3(b)(1)

C PURPOSE - TO PROVIDE A ROUTINE TO USE THE LINE PRINTER
C AS A PLOTTER, MULTIPLE SYMBOLS

C USE - CALL PLOT(MODE,Y,R,Z,S)

C MODE = 0 - CLEAR PRINT BUFFER TO DESIRED SYMBOL

C = 1 - ENTER A SYMBOL IN PLACE IN PRINT BUFFER

C = 2 - ENTER A SYMBOL AND PLOT POINTS

C Y = CURRENT DATA VALUE

C R = UPPER LIMIT

C Z = LOWER LIMIT

C S = CURRENT SYMBOL

C SUBROUTINE PLOT(MODE,Y,R,Z,S)

C PRINT LINE BUFFER

C COMMON ITCT(9)

C DIMENSION AP(100)

C DETERMINE INCREMENTS PER PRINT CHAR

C SA=(R-Z)/100.0

C CHANGE SIGN IF MINUS

C IF(SA)1,2,2

1 SA=-(SA)

C WHAT MODE

2 IF(MODE-1)3,4,4

C SYMBOL MODE- SUBTRACT CURRENT VALUE FROM UPPER LIMIT

4 AY=Z-Y

C CHANGE SIGN IF NEGATIVE

C IF(AY)6,7,7

6 AY=-(AY)

C DETERMINE POSITON OF CURRENT SYMBOL IN PRINT BUFFER LINE

7 IY=AY/SA+1.

C IF(IY-100)78,78,77

77 IY=100

C PLACE CURRENT SYMBOL IN PLACE IN PRINT BUFFER

78 AP(IY)=S

C CHECK MODE FOR PLOT

C IF(MODE-1)9,9,8

C MODE=28 PLOT

8 WRITE(4,10)

1 (ITCT(I),I=1,9),(AP(K),K=1,100)

10 FORMAT(1X,3I1,3(1X,2I1),8X,100A1)

C GO TO 9

C CLEAR PRINT BUFFER TO CURRENT SYMBOL

3 DO 11 I=1,100

C AP(I)=S

11 CONTINUE

```
C      SUBROUTINE - PLOT A LINE ON THE LINE PRINTER  
9      RETURN  
$0     END
```


III.10. PDS PLOT 70

PLOT 70

This plot program allows the operator to select from one to five pieces of data from the series 170 PCM data stream and plot those data simultaneously on the line printer. These data may be complete 8-bit data words or single bit digital indicators.

In the case of data words, 1) the processed data value is presented on the left side of the line printer paper, 2) the raw data value is plotted on a 50 division plot area and 3) the vernier time associated with that data value is presented on the right side of the paper.

In the case of single bit plotting, the bit is presented on the left side of the plot area if it is zero with a deflection to the right if the bit is a one. The vernier time is also presented with each data sample.

During the plotting, raw data is placed on digital magnetic tape if the program is being operated in real time. The program may also be operated from digital magnetic tape playback. The selected data may be changed at any time as may the upper and lower limits of the plot area for each piece of data.

III.11. FORTRAN PLOT G

User Instructions for PLOT1 Subroutine

The user must have his own main routine for feeding points to the Plot1 subroutine. The plot program has the capability of plotting 1 to 5 variables on any desired horizontal scale versus time on the Y-axis, with time increasing from the top of the page to the bottom. A maximum of 52 samples per variable can be passed at a time. When all samples are plotted, control will be returned to the main routine. Each time that the main routine has control it must assign new values to the variables or terminate.

The following cards must be in the main routine or calling routine:
col 7

```
COMMON/PLOT/IDAY,IHR,IMN,ISC,IRATE,IDVSOR,IXANS(5,52)
```

```
IPASS=0
```

NOVAR=the number of variables to be plotted, (1-5), and not to be confused with the number of samples.

IRATE=(i.e. 256), the sampling rate. times a constant to eliminate significant digits being in the decimal portion of the rate.

IDVSOR=the constant used to determine IRATE and will enable the plot routine to keep track of the decimal point.

IDAY=starting day

IHR=starting hour

IMN=starting minute

ISC=starting second

All variables passed to the plot routine are integer format. The order that the variables are passed in the common and the call are extremely critical and, if the program doesn't bomb as a result of variables being out of order, will give very questionable results.

One other card that the user must have in his calling program is:

col 7

```
CALL PLOT1(NOVAR,IPASS)
```

This card will be inserted in the calling program after the input variables are initialized and before it loops back to initialize the variables again.

Once the variables IDAY,IHR,IMN,ISC are initialized the user doesn't have to worry about them. PLOT1 will automatically update them. The only thing the user might do is to test to see if a termination point has been reached.

The array IXANS(I,J) contains the points to be plotted in the following manner:

I denotes the variable.

J denotes the sample of variable I and the value of J will be plotted.

The PLOT1 routine will expect to read in 5 data cards the first time that it is called and will be as follows:

CARD ONE

It will contain the units that the user wants assigned to the x-axis. The first variable on the card will be the absolute number of units(subtract 1 if scale passes through, begins with, or ends with the origin), and has to be in columns 1-6 and may or may not have a decimal point in it but if no decimal point the value must be right adjusted(be safe-always put a decimal point in). The second variable will be the minimum value of the x-axis in columns 7-12 and, again, may or may not have a decimal point.

PLOT1 cont.

CARD TWO

It will be the 4 character names that the users wishes to assign to the variables that are to be plotted. All five names are read in in consecutive columns.

col 1

uuuuvvvvwwwwxxxxyyyyzzzz

CARD THREE

It will contain the heading that the users wishes to appear at the top of the page. Anything that the users puts in column 1-52 will appear on the plot.

CARD FOUR

Will be the title that user wants displayed along the vertical axis and is the same format as card three.

CARD FIVE

Will be the title that user wants displayed along the horizontal axis and is the same format as card three.

If the title cards are not desired, blank cards must be inserted.

The plot routine will identify the symbol used for each variable at the bottom of the page by the name that was input on card two.

For further explanation or if particular questions arise contact
[redacted] Bldg 59 Room 320 ext. 2635.

3.3(b)(1)

11/02/71

III.12. F170 M1 - F170 M2

ATTITUDE - F170AS

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
										MON RW TEMP A	MON RW TAC A	MON MAG X A	MON MAG Y A	MON MAG Z A	MON ADCCLE A D	MON ADCCLE B D
		MON ADDRESS D	V. TIME A									BOOM LENGTH A			MON SPR O D	MON SPR O D
		MON COMMAND D	MON MEMORY D								MON TH 1 CTL A	MON TH 2 CTL A			MON BOOM CTL D	MON RW CTL D
		MON DCM D	MON COMMAND D												MON THRUSTER CONTROL D	
		MON BAT CTL D														
									TEMP 5 TANK A	TEMP 6 NOZ. 1 A	TEMP RW A				MON TH 2 PR PLENUM A	MON TH 1 PR PLENUM A

III.14. F170 T

TEMP

			V TIME A					SV CAL A							
								TEMP 19 S.C.P. A	TEMP 24 BAT BYP A						
									TEMP 2 PKG A	TEMP 15 SCP 1 A	TEMP 3 + SEC BAT A	TEMP 4 - SEC BAT A			
									TEMP 25 + BAT A	TEMP 26 - BAT A					
								TEMP 25 + BAT A	TEMP 26 - BAT A	TEMP 10 HC 1 A	TEMP 16 SCP 2 A	TEMP 20 S. TUBE A	TEMP 21 BAT 3 A	TEMP 22 CG CTL. A	TEMP 23 V CTL A
								TEMP 8 SKIN 1 A	TEMP 9 SKIN 2 A	TEMP 17 IN. S.C. 2 A	TEMP 12 B. BAND A	TEMP 13 IN. S.C. 1 A	TEMP 14 O.S.C. A		
								TEMP 5 TANK A	TEMP 6 NOZ. 1 A	TEMP RW A	TEMP 18 BB SC 2 A	TEMP 11 DL BOCM A	TEMP 1 PCM PK A		

HL 15. F170 H