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JULY 1968

STICK TRANSFER FUNCTION BRIEFING

J. R. BUYAN

HANDLE VIA BYEMAN
CONTROL SYSTEM
ONLY

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AEROSPACE PILOT STUDY BRIEFING

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o PROBLEM STATEMENT

/ GENERAL TRANSFER FUNCTION (LOS/STICK DEFLECTION, d)

$$K_1 + \frac{K_2}{s} + \frac{K_3}{s^2} + \frac{K_4}{s^2} u (d-D)$$

/ REQUIRED BY GE IN ORDER TO PERFORM OTHER STUDIES.

/ AEROSPACE TO DO PRELIMINARY WORK, GE TO VALIDATE *in digital environment*

o TASK DEFINITION - PRIMARY TASK IS RATE NULLING ^{the} FOLLOWING ERROR SOURCES.

/ ALTITUDE AND PITCH, GYRO SCALE FACTOR - \cos^2 EFFECT

/ SERVO RATE BIAS - CONSTANT RATE

/ NOISE - LOW FREQUENCY RANDOM MOTION (NOT IN BUDGET)

/ VIBRATION - NOT INCLUDED, DOESN'T AFFECT PERFORMANCE

/ POSITION - NOT INCLUDED, DOESN'T AFFECT RATE NULLING PERFORMANCE

o AEROSPACE SIMULATOR (UNCLASSIFIED)

/ DISPLAY - CRT, SQUARE SYMBOL, NON-ZOOM RETICLE, HOOD

/ CONTROLS - STICK: 30° HALF ANGLE CONE, ANALOG PROCESSING
GAIN CONTROL: 4 STEPS

/ TASK - RATE NULL, 14 SECOND RUNS, 4 SECOND RESET, 2 INITIAL CONDITIONS

/ SCORING - TIME TO GET BELOW RATE SPEC

- STEADY STATE AVERAGE RATE ERROR LESS NOISE ERROR

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AEROSPACE PILOT STUDY BRIEFING, CONT'D

o **PILOT STUDY RESULTS**

/ **START WITH:**

$$K_1 + \frac{K_2}{s} + \frac{K_3}{s^2} + \frac{K_4}{s^3} u (d-29^\circ); \text{ WITH AND WITHOUT GFM}$$

/ **MINIMIZE STICK TYPES**

$K_1 \neq 0$: **JUMPY RESPONSE, FINGER NOISE**

$K_3, K_4 \neq 0$: **REQUIRES $K_2 \neq 0$: OSCILLATORY RESPONSE**

NO GFM: REAL NOT APPARENT RATES DEFINE TASK

/ **REDUCE STICK GAIN COMBINATIONS**

$$\left[\frac{K_2}{s}, \frac{K_2 + K_3}{s}, \frac{K_2 + K_4}{s^2} u (d-29) \right]$$

K_2 ONLY: **MUST BE LARGE ENOUGH TO CATCH ALL EXPECTED INITIAL CONDITIONS. THEREFORE, $K_2 \approx 4000$ (240 ur/s)**

$K_2 + K_3$: **LARGE K_2 GIVES FASTER INITIAL NULLING BUT POORER STEADY STATE PERFORMANCE**

LARGE K_3 GIVES FASTER NULLING BUT INCREASES OVERSHOOTS

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AEROSPACE PILOT STUDY BRIEFING, CONT'D

SET OF FINAL CANDIDATES:

K_2

K_3

2500 (150ur)	600 (36ur)
2000 (120ur)	800 (48ur)
1500 (90ur)	1000 (60ur)
1000 (60ur)	1200 (72ur)
500 (30ur)	1400 (84ur)

$K_2 + K_4$ u (d-29°): LARGE K_2 INCREASES STABILITY BUT REDUCES STEADY STATE ² PERFORMANCE

LARGE K_4 GIVES FASTER TIME BUT REDUCES STABILITY

SET OF FINAL CANDIDATES:

K_2

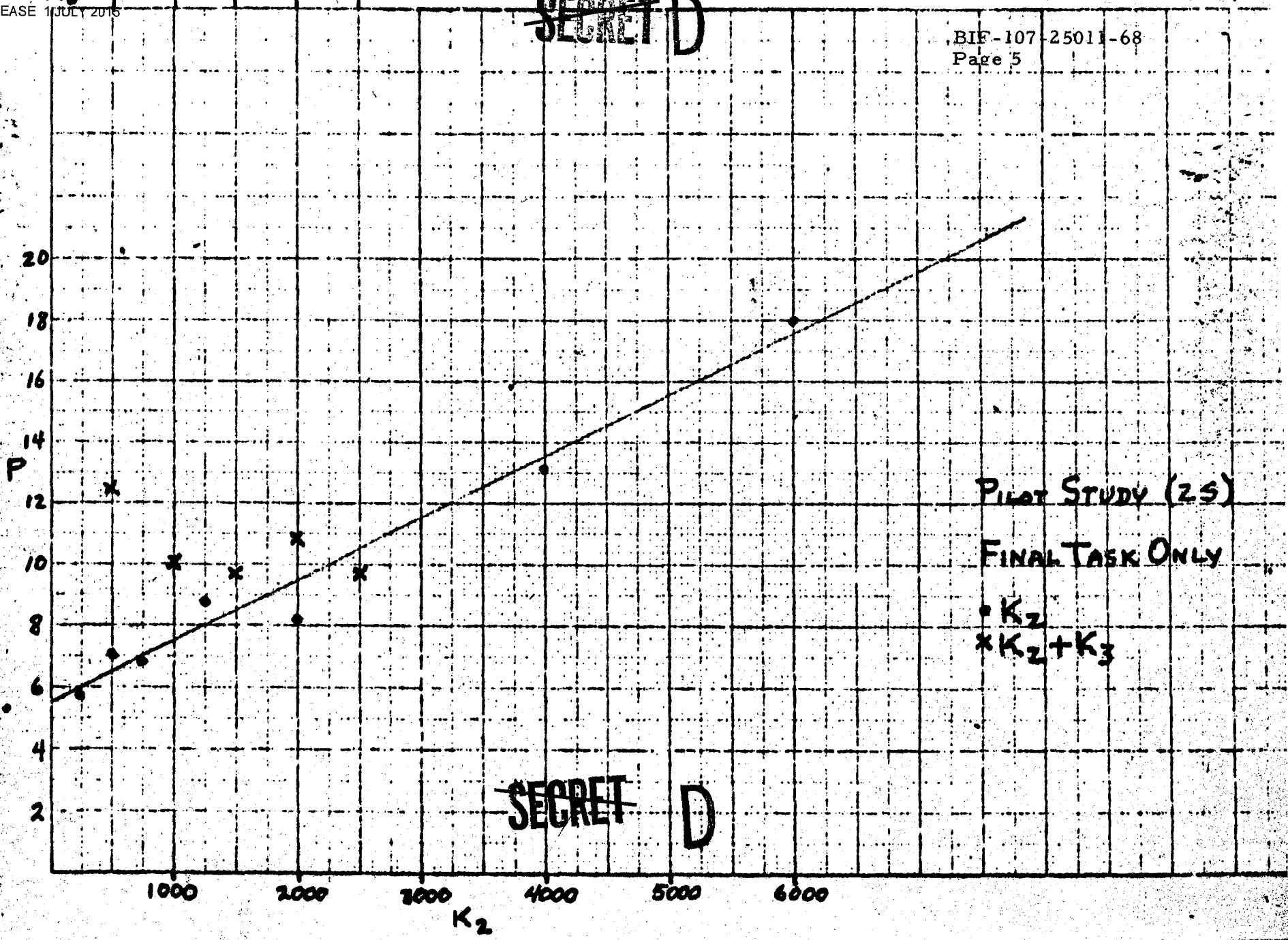
K_3

750 (45ur)	10,000 (600ur)
750	4000 (240ur)
750	2000 (120ur)
2000 (120ur)	10,000
2000	4000
2000	2000

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K₂ 1400 1200 1000 800 600

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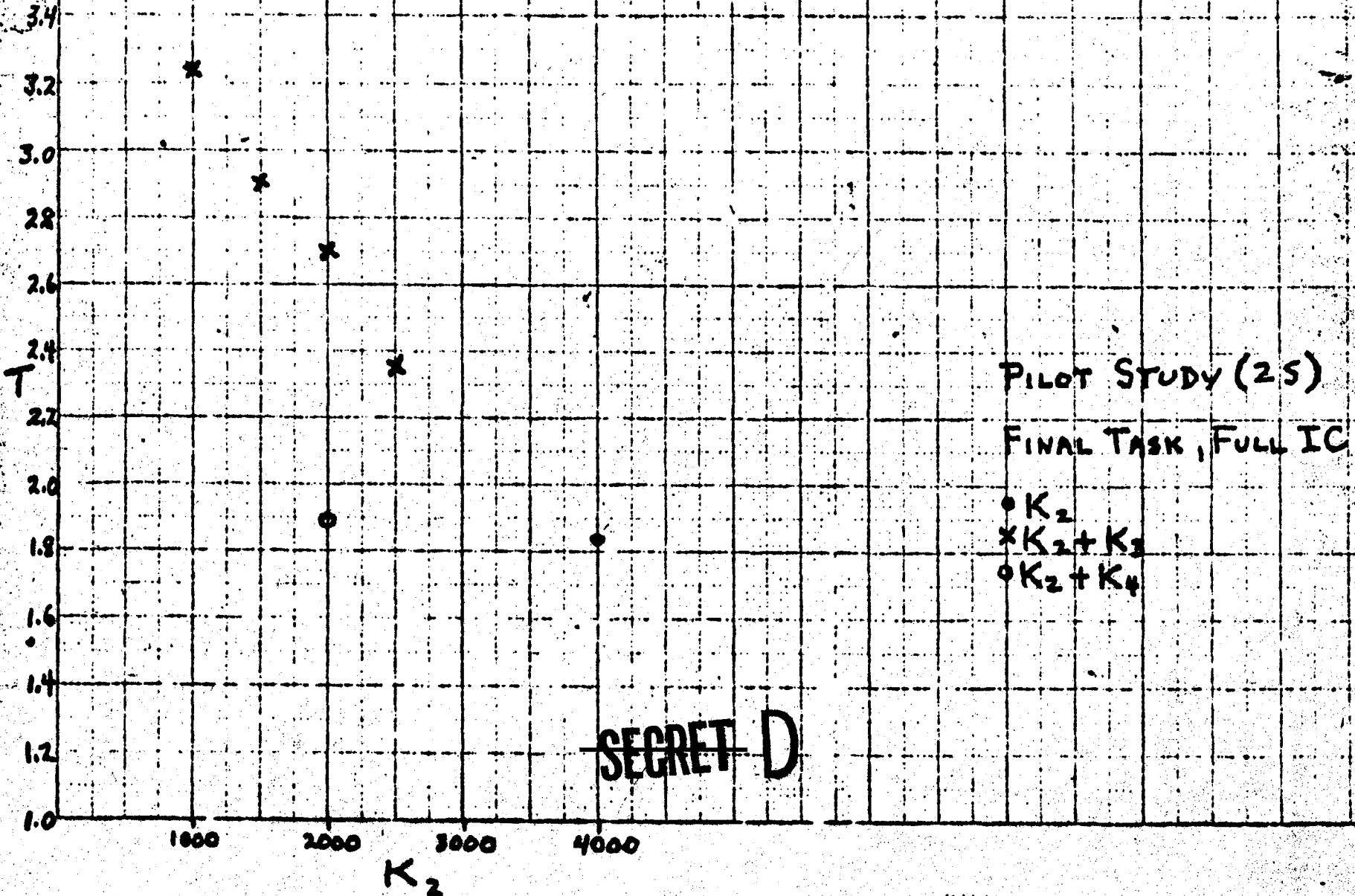
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28
26
24
22
20
18
16
14
12
10
8
6
4
2

PILOT STUDY (25)
FINAL TASK, FULL IC
• K_2
* $K_2 + K_3$
○ $K_2 + K_4$

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1000 2000 3000 4000 5000 6000

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PILOT STUDY (2S)

FINAL TASK ONLY

$K_2 = 2000$

14
12
10
8
6
4
2

1

2

3

LHC POSITION

4

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FORMAL STUDIES

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● EVALUATION

/ THREE TRANSFER FUNCTIONS (T)

(1) K_2 (240ur)

(2) $K_2 + K_3$ (120ur, 60ur)

(3) $K_2 + K_4$ (120ur, 240ur)

/ TWO LEVELS OF INITIAL CONDITIONS (D)

(1) NOMINAL LEVEL (52.1ur/s MAX)

(2) EXTREME LEVEL (215ur/s MAX)

/ THREE BLOCKS OF DATA (B)

(1) TEN RUNS EACH (CONTAINS BOTH IC LEVELS)

/ SIX SUBJECTS (S)

● SCHEDULING

/ TRAINING - 5-9 HOURS TOTAL, 1 1/2-2 1/2 SESSIONS

/ DATA RUNS - 1/2 SESSION, FOLLOWING PRACTICE

● DATA ANALYSIS

/ TIME

/ FINAL PERFORMANCE

● VALIDATION

/ R-38

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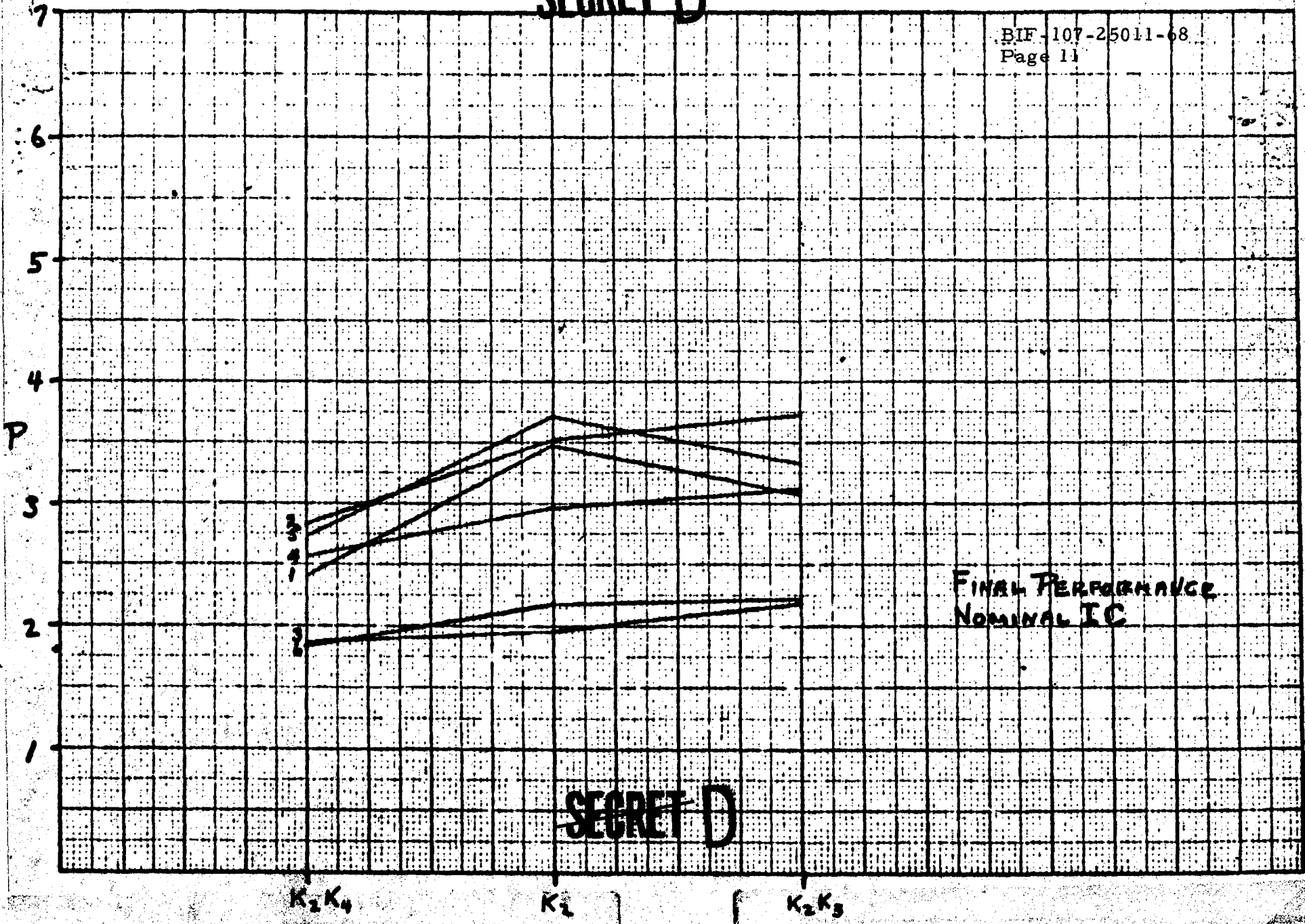
ANALYSIS OF VARIANCE (FINAL PERFORMANCE AND TIME)

<u>SOURCES OF VARIATION</u>	<u>DEGREE OF FREEDOM</u>	<u>F RATIO (p<.01)</u>
BETWEEN TRANSFER FUNCTIONS (T)	2	**
BETWEEN INITIAL CONDITIONS (D)	1	**
BETWEEN SUBJECTS (S)	5	**
INTERACTIONS:		
T x D	2	**
T x S	10	**
D x S	5	**
T x D x S	10	**
ERROR	504	
TOTAL	<hr/> 539	

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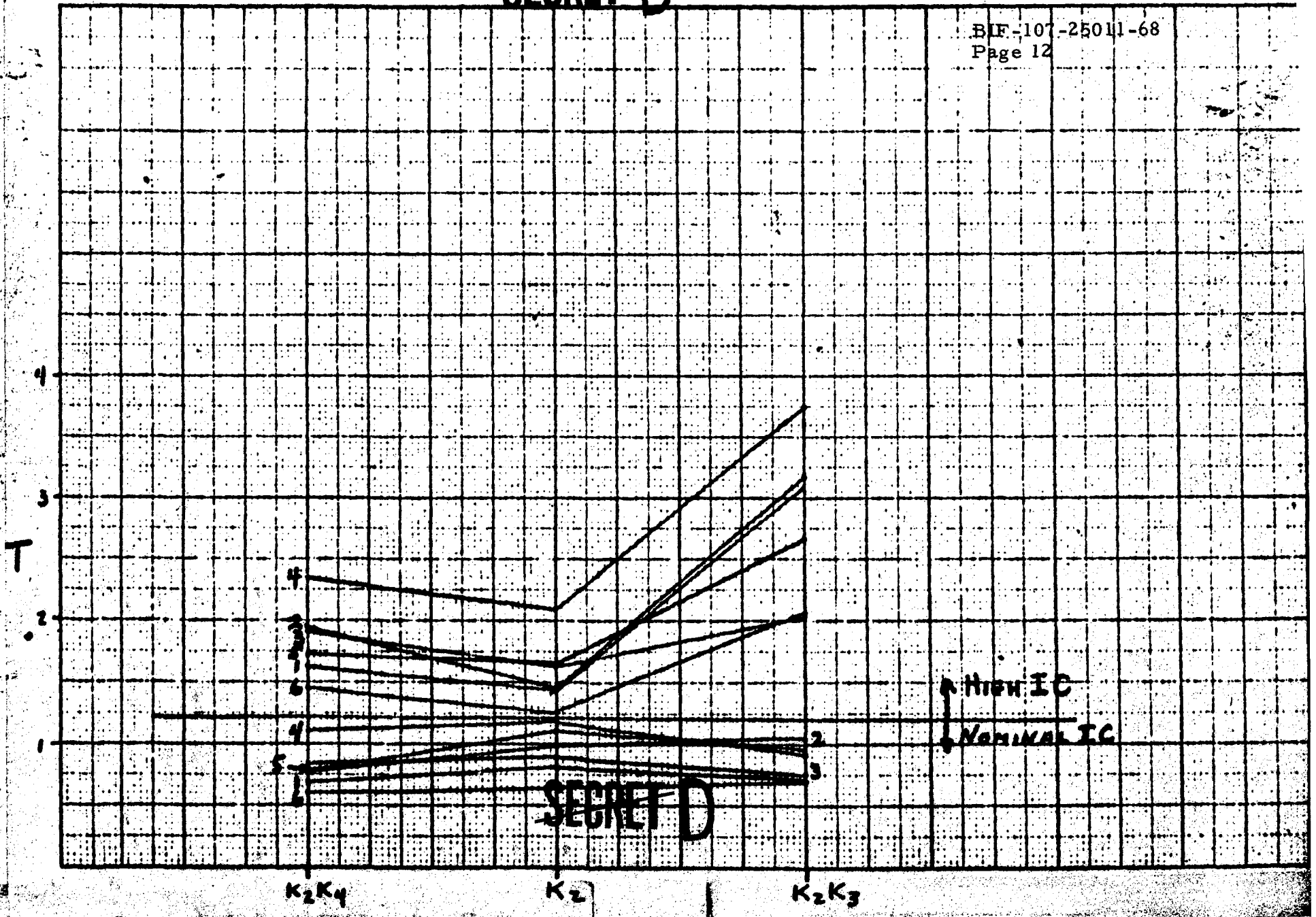
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FORMAL STUDY CONCLUSIONS

- o **RATE WITH END STOP ACCELERATION STICK HAS BEST OVERALL CAPABILITY AND FLEXIBILITY**
 - / **SIGNIFICANTLY BETTER RATE NULLING PERFORMANCE (INDEPENDENT OF INITIAL CONDITION MAGNITUDE)**
 - / **TIME TO RATE NULL IS VERY GOOD**
 - / **PREFERRED BY SUBJECTS**
 - / **RANDOM NOISE INTERACTION MINIMIZED**
 - / **HAS BEST TIME VERSUS RATE NULLING PERFORMANCE TRADEOFF FLEXIBILITY**
 - / **MOST EFFECTIVE PERFORMANCE AGAINST A WIDE RANGE OF INITIAL CONDITIONS**

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(D) ~~SECRET~~ SPECIAL HANDLING

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AEROSPACE EXTENTION TO MAXIMUM (SPECIFICATION) RATES

o STICK GAINS REOPTIMIZED FOR SPEC RATES (540 μ r/sec)

- / RATE STICK 600 μ r/sec max
- / RATE + ACC 480 μ r/sec + 240 μ r/sec² max (~~PRELIMINARY~~)
- / RATE WITH END STOP
ACC 240 μ r/sec + 600⁷²⁰ μ r/sec² max (~~PRELIMINARY~~)

o PRELIMINARY RESULTS

- / TIME TO NULL CONSISTENT WITH LOWER INITIAL CONDITION DATA
- / RATE NULLING PERFORMANCE SLIGHTLY POORER

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GE VALIDATION STUDY

o **SIMILARITIES**

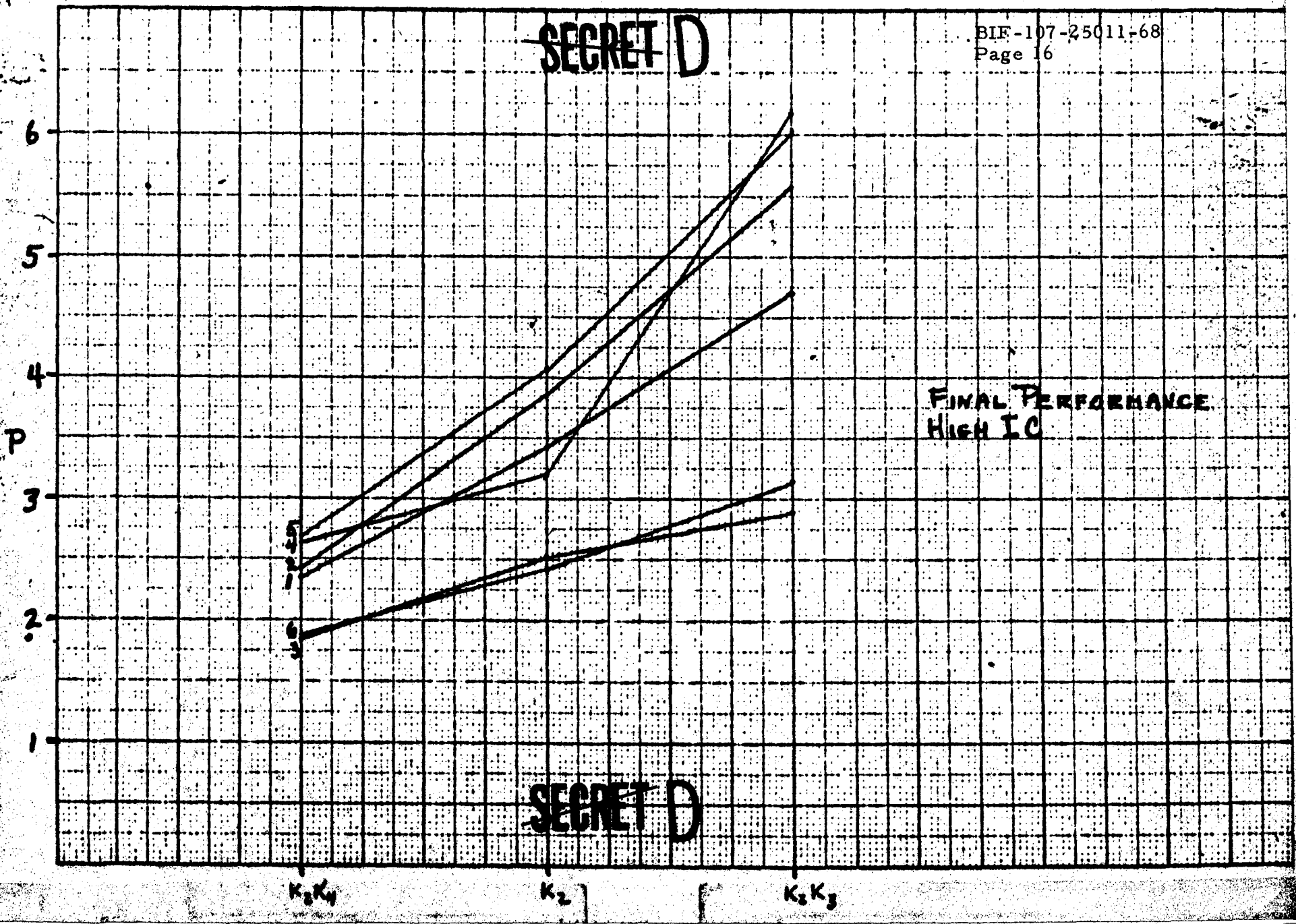
- / **THREE TRANSFER FUNCTIONS**
- / **MAGNIFICATION**
- / **SUBJECTS**
- / **REAL TIME ANALOG DATA**
- / **EXPERIMENTAL DESIGN**
- / **INITIAL CONDITIONS INCLUDING EXTENSION TO SPEC RATES**

o **DIFFERENCES**

- / **SCENE MATERIAL**
- / **ADDITIONAL DIGITAL SCORING CAPABILITY**
- / **AVE STICK SAMPLING RATE**
- / **AVE DIGITAL STICK QUANTIZATION**
- / **AVE EXTRAPOLATION (LINEAR)**
- / **AVE PROCESSING DELAYS**
- / **R-38 CAPSULE ENVIRONMENT**

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R-38 STATUS AND SCHEDULE

- o- **SIMULATOR UPGRADING (TO JULY 8)**
 - / **INCORPORATION OF AVE DIGITAL PROCESSING TECHNIQUES**
 - / **SYSTEM ERROR ANALYSES, SCALING, CALIBRATION**
 - / **ON LINE ANALOG SCORING**
 - / **SOFTWARE PACKAGE DEVELOPMENT**
- o **AF/AEROSPACE EVALUATION (WEEK OF JULY 8)**
- o **FORMAL EXPERIMENT (BEGINNING JULY 15)**

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AEROSPACE ATS STICK TRANSFER FUNCTION STUDY

- OBJECTIVES
 - / OPTIMIZATION OF CENTERING TASK (PRIMARY EMPHASIS)
 - / OPTIMIZATION OF RATE NULLING PERFORMANCE (SECONDARY EMPHASIS)
- STICK CANDIDATES (HIGHER GAIN REQUIRED THAN FOR RATE NULLING)
 - / RATE ONLY - GOOD BUT HAS SIGNIFICANT FINGER NOISE
 - / RATE WITH ADDITIONAL END-STOP RATE - MOST FLEXIBLE
 - / RATE WITH END-STOP ACCELERATION - NOT OPTIMUM FOR THIS TASK
 - / RATE PLUS ACCELERATION - POOR
- TASK INTERPRETATION DIFFICULTIES
 - / WHEN IS CENTERING PERFORMED?
 - / CENTERING TIME VERSUS ACCURACY TRADEOFF
 - / ACTIVITY DETECTION VERSUS CENTERING TRADEOFF
- RECOMMENDATIONS
 - / PERFORM PROCEDURES DEFINITION AND/OR EXPERIMENT
 - / MAKE RATE WITH END-STOP RATE BASELINE ATS STICK TRANSFER FUNCTION

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GENERAL AEROSPACE SIMULATOR RESULTS

GENERALIZED KNOWLEDGE OF STICK TRANSFER FUNCTION TRADEOFFS

REQUIREMENT FOR ON-LINE SCORING CAPABILITY

- / PERMITS RESPONSE TO DIFFERENTIAL LEARNING CHARACTERISTICS
- / PERMITS RAPID REDUCTION OF PARAMETER RANGES
- / IMMEDIATE RESULTS IMPROVE SUBJECT MOTIVATION
- / (PROVIDES KNOWLEDGE OF LEARNING STATUS)
- / SPEEDS OPTIMIZATION OF MOTOR SKILL TECHNIQUE
- / FATIGUE CAN BE QUICKLY DETECTED THROUGH PERFORMANCE DATA

BETTER UNDERSTANDING OF CREW MOTOR SKILL LEARNING TIME

IMPROVEMENT IN BASIS FOR TECHNICAL DIRECTION IN RELATED AREAS

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FUTURE

○ CURRENT FOLLOW-ON EFFORT

- / SIMULATION OF STICK SAMPLING CHARACTERISTICS ~~AVAILABLE~~
- / SIMULATION OF STICK QUANTIZATION - UNDER DEVELOPMENT
- ~~FURTHER ATS STICK TRANSFER FUNCTION STUDIES AS REQUIRE~~

○ POTENTIAL EXPANSION TO HYBRID CAPABILITY

- / HYBRID HARDWARE ~~TO BE~~ INSTALLED
- / POSSIBLE USES: EXTRAPOLATION TECHNIQUES, OTHER AVE
DIGITAL PROCESSING CHARACTERISTICS

○ FUTURE STUDY POSSIBILITIES

- ~~/ STICK COUPLING~~
- ~~/ DEROTATION EFFECTS~~



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