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DORIAN/GAMBIT

# THE ROLES OF MAN IN MOL VOLUME II - ILLUSTRATIONS



MANNED ORBITING LABORATORY  
PROGRAM OFFICE  
WASHINGTON, D.C.

JUNE 1, 1969

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THE ROLES OF MAN IN MOL

(Volume II)

Manned Orbiting Laboratory  
Program Office

June 1, 1969



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Preface

This volume contains figures which are cited and discussed  
in Volume I of the report.

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Page 3 of 13 Pages  
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LIST OF ILLUSTRATIONS

Figures (Volume II)	<u>Page</u>
1. MOL Baseline System . . . . .	7
2.  . . . . .	8
3. Comparison of Resolution Achieved at Various Points on MOL 9-Inch Circular Format With and Without X-Format IMC, for Given Condi- tions of Photography. . . . .	9
4. MOL System Mean Static Resolution on Axis As Function of Focus Error. . . . .	10
5. MOL System Photography Resolution Loss As Function of Exposure-Setting Error . . . . .	11
6. Illustration of MOL System Diagnostic Technique. Problem: Targets Not Centered in Photographs . . . . .	12
7. Location of Acquisition Telescope Systems in MOL Laboratory Compartment. . . . .	13
8. MOL Mission Console - (Current Configuration) . . . . .	14
9. MOL Mission Console - (Early Configuration) . . . . .	15
10. Acquisition Telescope System Operating Concept. . . . .	16
11. Illustration of "Activity" at Airfield. . . . .	17
12. Time-Spatial Constraints for Astronauts While Performing in Active Target Indicator Mode (Typical Example) . . . . .	18
13. Actual Successful GAMBIT Photography Versus That Predicted Based on "Verified" Weather. . . . .	19
14. Actual Successful ADVANCED GAMBIT Photography Versus That Predicted Based on "Verified" Weather . . . . .	20

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Page 4 of ~~13~~ Pages  
Copy 1 of 3 Copies  
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	<u>Page</u>
15. Increase in Number of Clear Target Photographs Obtained Due to Man's Cloud-Avoidance Role in MOL . . . . .	21
16. Sky Coverage Conditions (U.S. Satellite Experience) . . . . .	22
17. Sky Coverage Conditions (GAMBIT Experience) . . . . .	23
18. Success of Photography Achieved Over Sino-Soviet Land Mass as Function of Cloud Cover Existing at Time of Photography. . . . .	24
19. Probability of Occurrence of "Activity" at Sino- Soviet Targets During MOL Overflights . . . . .	25
20. Acquisition Telescope System - View at 15X. . . . .	26
21. Acquisition Telescope System - View at 32X. . . . .	27
22. Acquisition Telescope System - View at 64X. . . . .	28
23. Acquisition Telescope System - View at 127X . . . . .	29
24. Main Visual Optics - View at [REDACTED] . . . . .	30
25. MOL Photograph Format . . . . .	31
26. Acquisition Telescope System Resolution Capability in Forward Scan Field. . . . .	32
27. Resolution Required to Detect Presence of Various Types of "Activity" at Targets of Interest. . . . .	33
28. Capability of MOL Astronauts to Identify "Active" Targets Correctly, as Function of Level of Activity Actually Present in Scene (Maximum Decision Time Allowed = 12 Seconds). . . . .	34
29. Accuracy Achieved by MOL Astronauts in Correctly Identifying "Active Targets" in Those Cases in Which Decision Time Was Six Seconds or Less . . . . .	35
30. MOL Mission-Enhancement Factor for Conditions Indicated, as Function of Man's Ability to Make Correct Decisions Concerning Presence of "Activity" at Alternate Targets (Simulation Results Superimposed) . . . . .	36

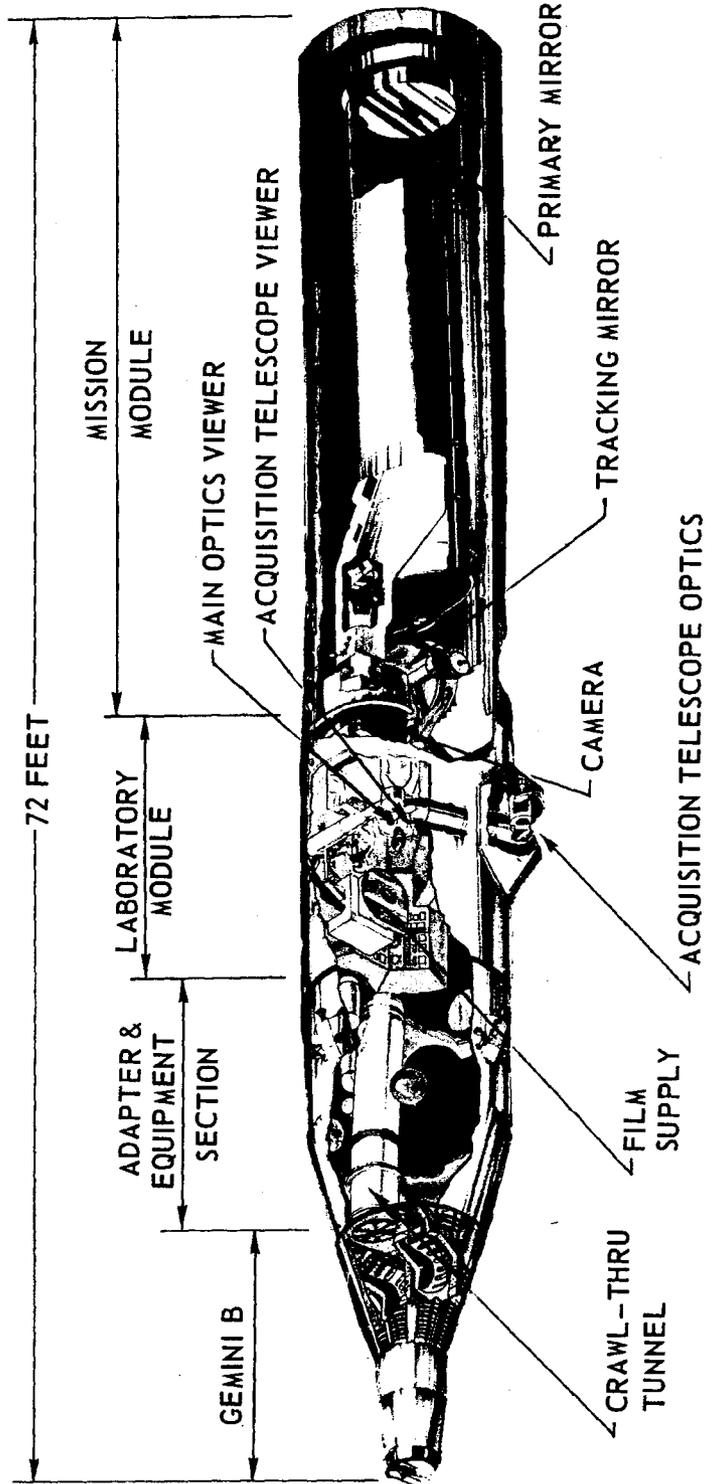
	<u>Page</u>
31. [REDACTED] . . . . .	37
32. [REDACTED] . . . . .	38
33. [REDACTED] . . . . .	39
34. [REDACTED] . . . . .	40
35. [REDACTED] . . . . .	41
36. MOL Systems Capability (Manned) for Accomplishment of Planetary Photography, Compared to Ground- Based Telescope Systems. . . . .	42

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BYEMAN Control System

Page 6 of 43 Pages  
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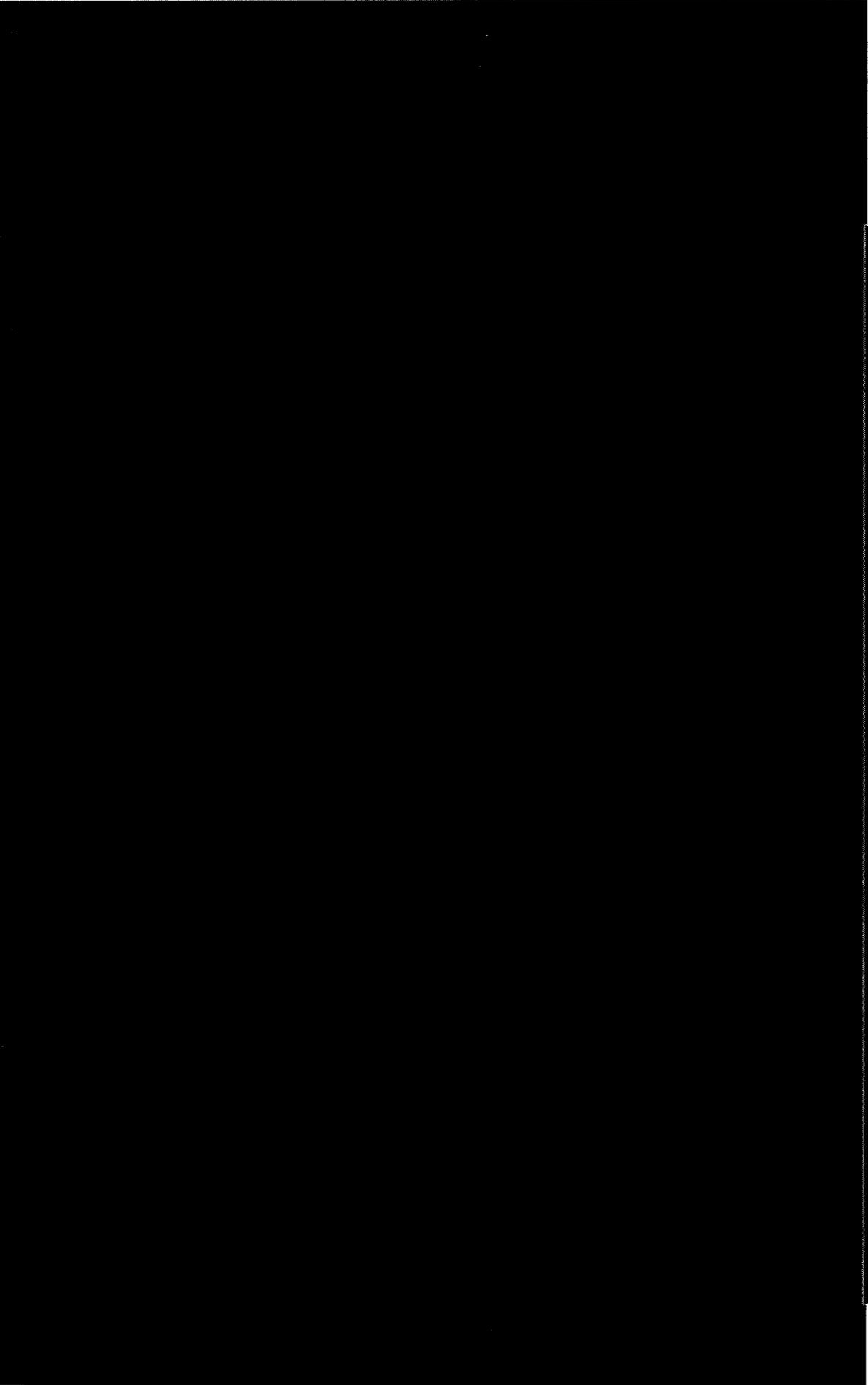
MOL BASELINE SYSTEM

FIGURE 1

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FIGURE 2  
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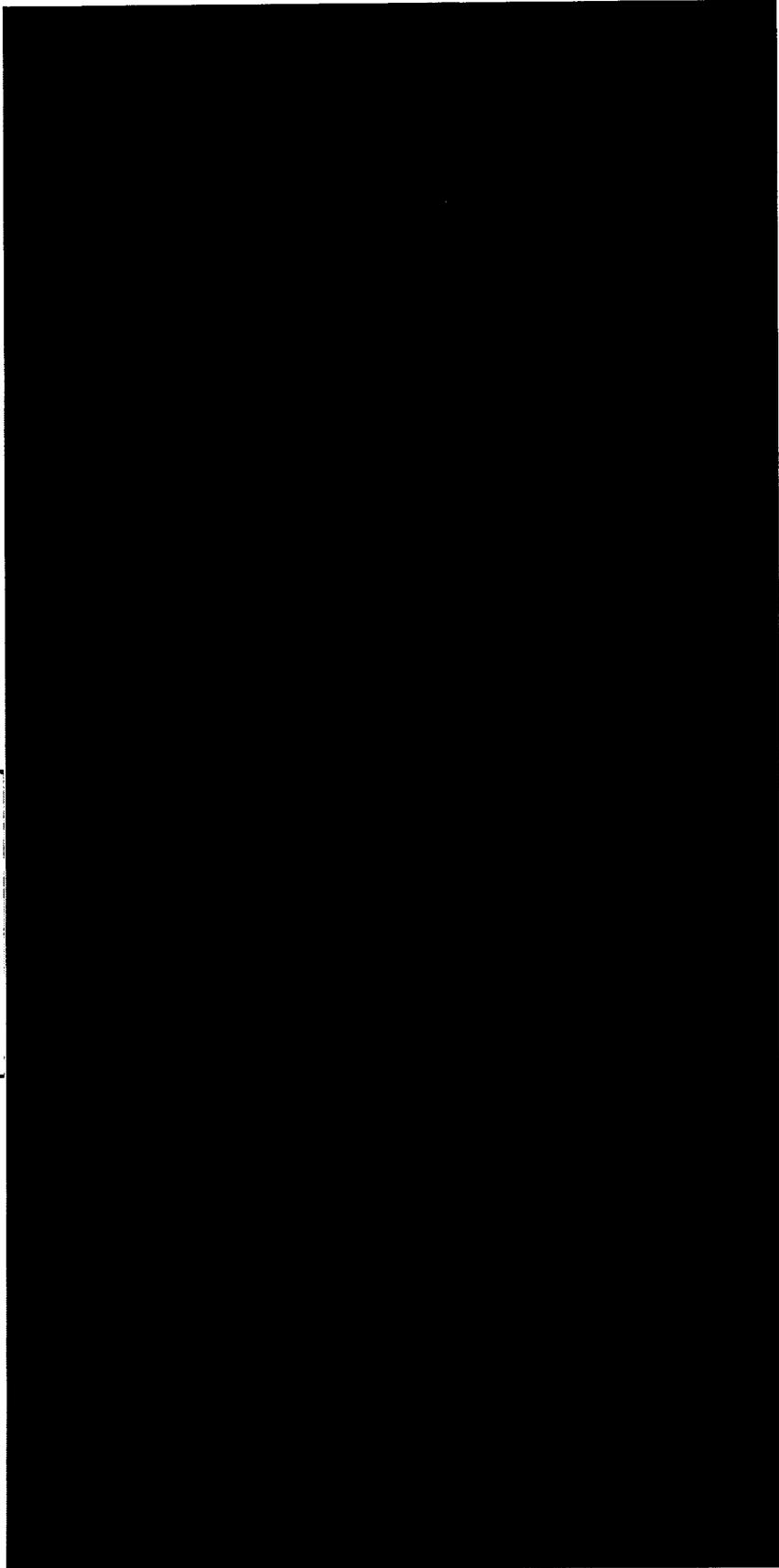
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DIRECTION  
OF FLIGHT



CONDITIONS:  
ALTITUDE 80 N.M.  
OBLIQUITY 20°  
FORWARD LOOK 15°

DIRECTION  
OF FLIGHT



WITH X-FORMAT IMC

WITHOUT X-FORMAT IMC

COMPARISON OF RESOLUTION ACHIEVED AT VARIOUS POINTS ON MOL  
9-INCH CIRCULAR-FORMAT PHOTOGRAPH, WITH AND WITHOUT X-FORMAT  
IMC, FOR GIVEN CONDITIONS OF PHOTOGRAPHY.

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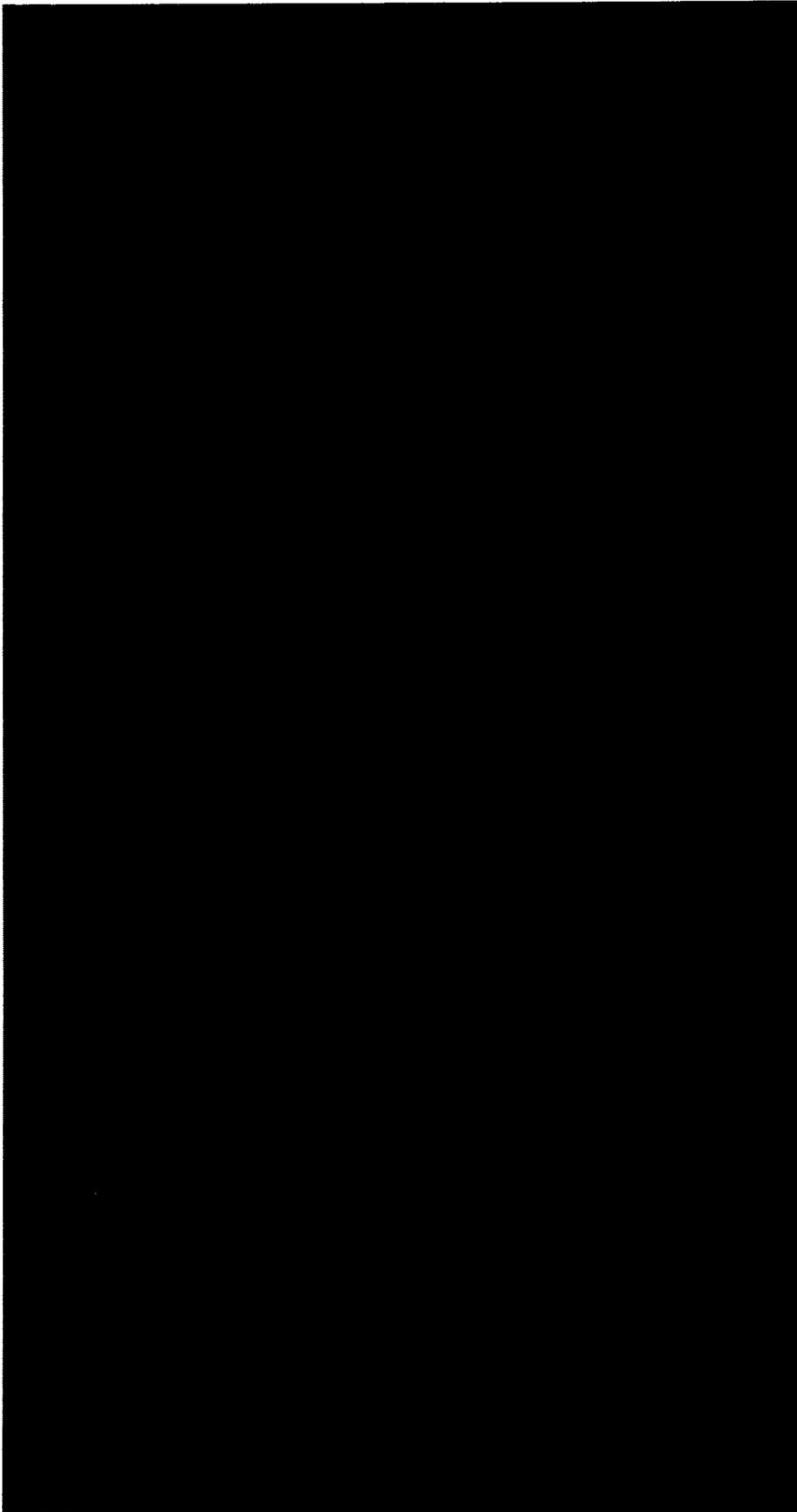
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FIGURE 3  
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GEOMETRIC  
MEAN  
RESOLUTION



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MOL SYSTEM MEAN STATIC RESOLUTION ON AXIS  
AS FUNCTION OF FOCUS ERROR

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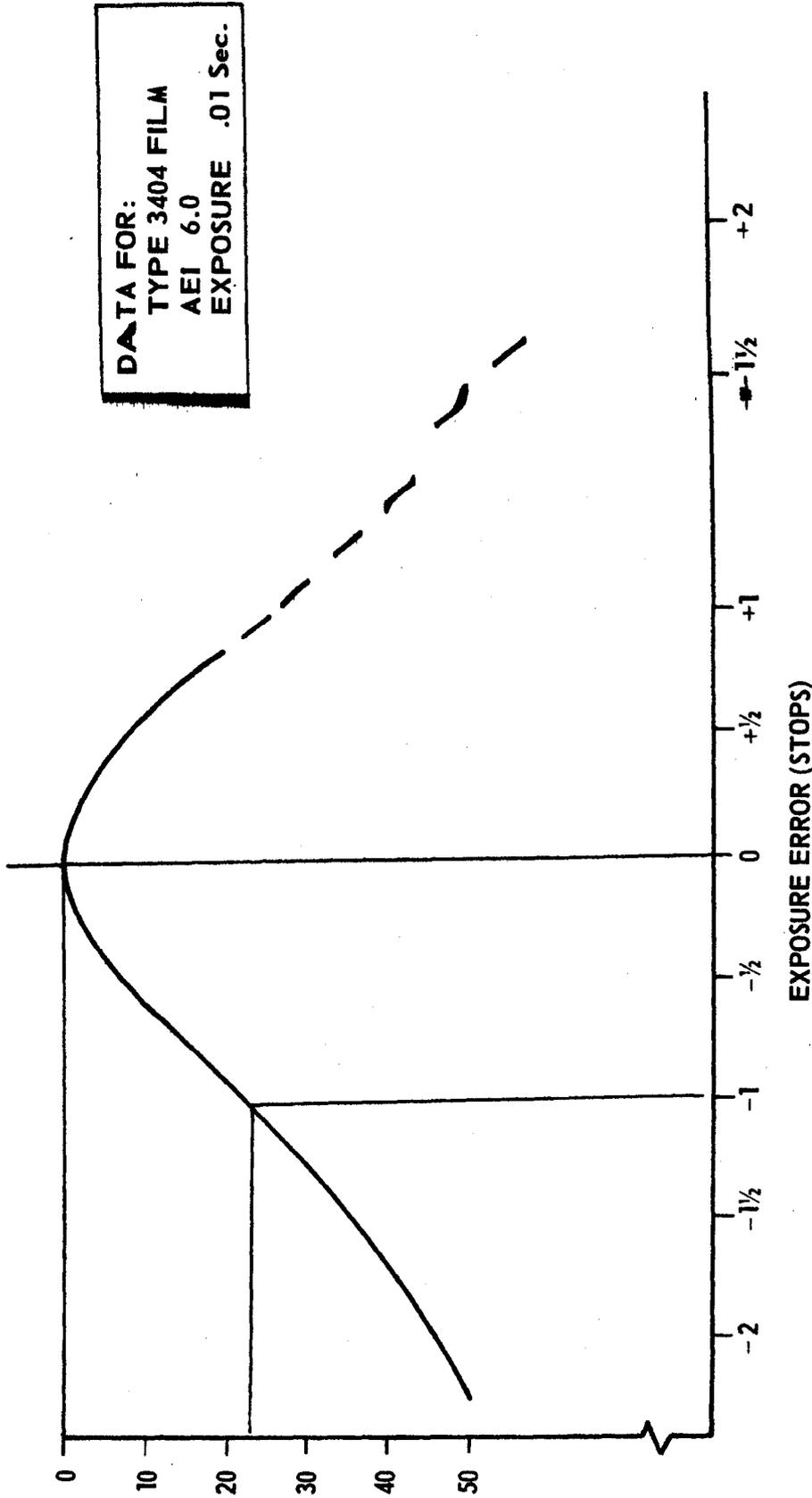
FIGURE 4

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MOL SYSTEM PHOTOGRAPHY RESOLUTION LOS S  
AS FUNCTION OF EXPOSURE - SETTING ERROR

FIGURE 5  
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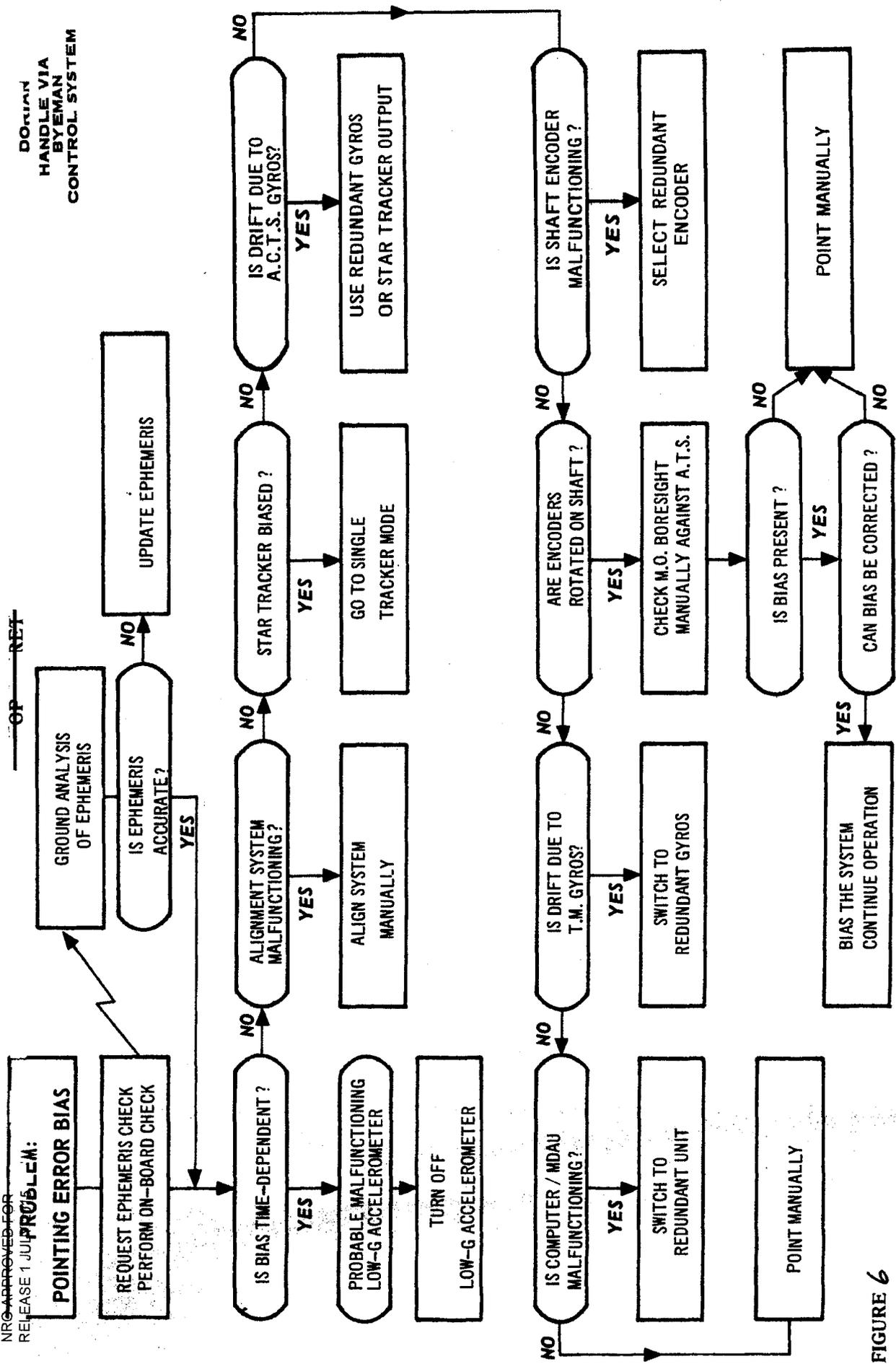


FIGURE 6

ILLUSTRATION OF MOL SYSTEM DIAGNOSTIC TECHNIQUE  
PROBLEM: TARGETS NOT CENTERED IN PHOTOGRAPHS

ASE1 201E

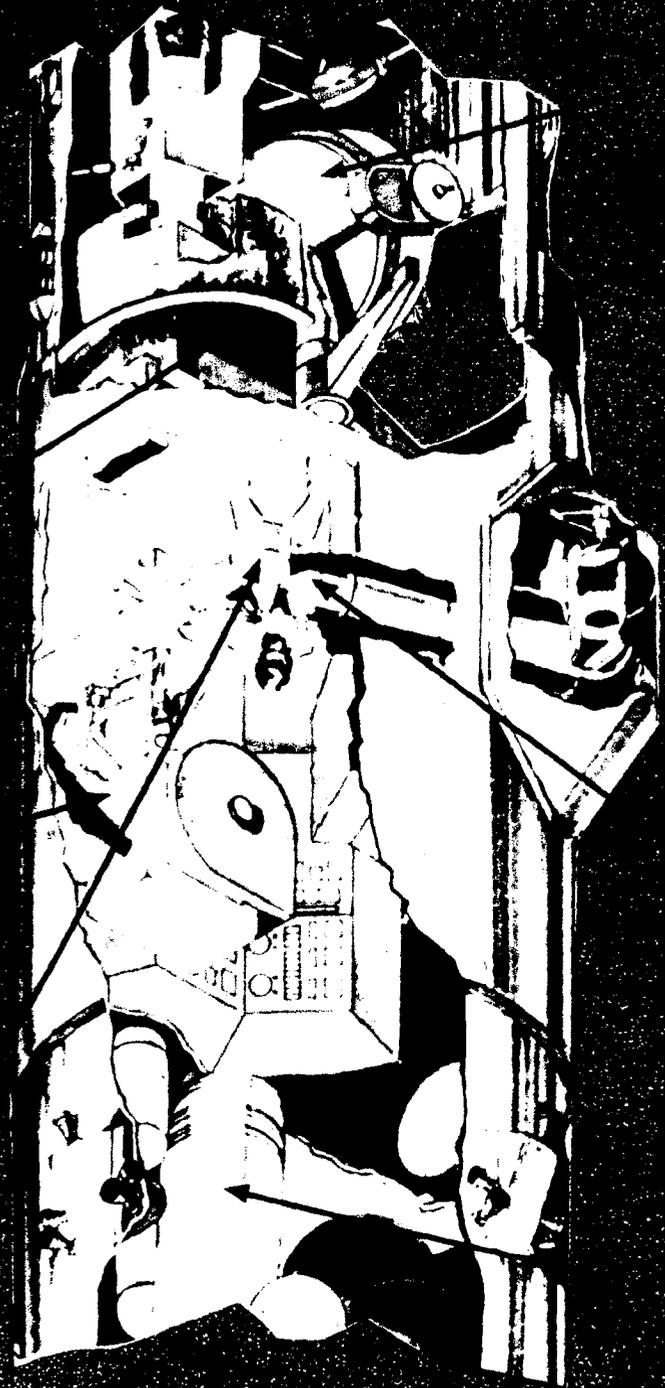
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ACQUISITION  
TELESCOPE No. 2

MAIN OPTICS

CAMERA



TO GEMINI B

CRAWL-THRU  
TUNNEL

ACQUISITION  
TELESCOPE No. 1

A.T.S. TRACKING  
MIRROR

MAIN OPTICS  
TRACKING MIRROR

LOCATION OF ACQUISITION TELESCOPE SYSTEMS  
IN MOL LABORATORY COMPARTMENT

Figure 7

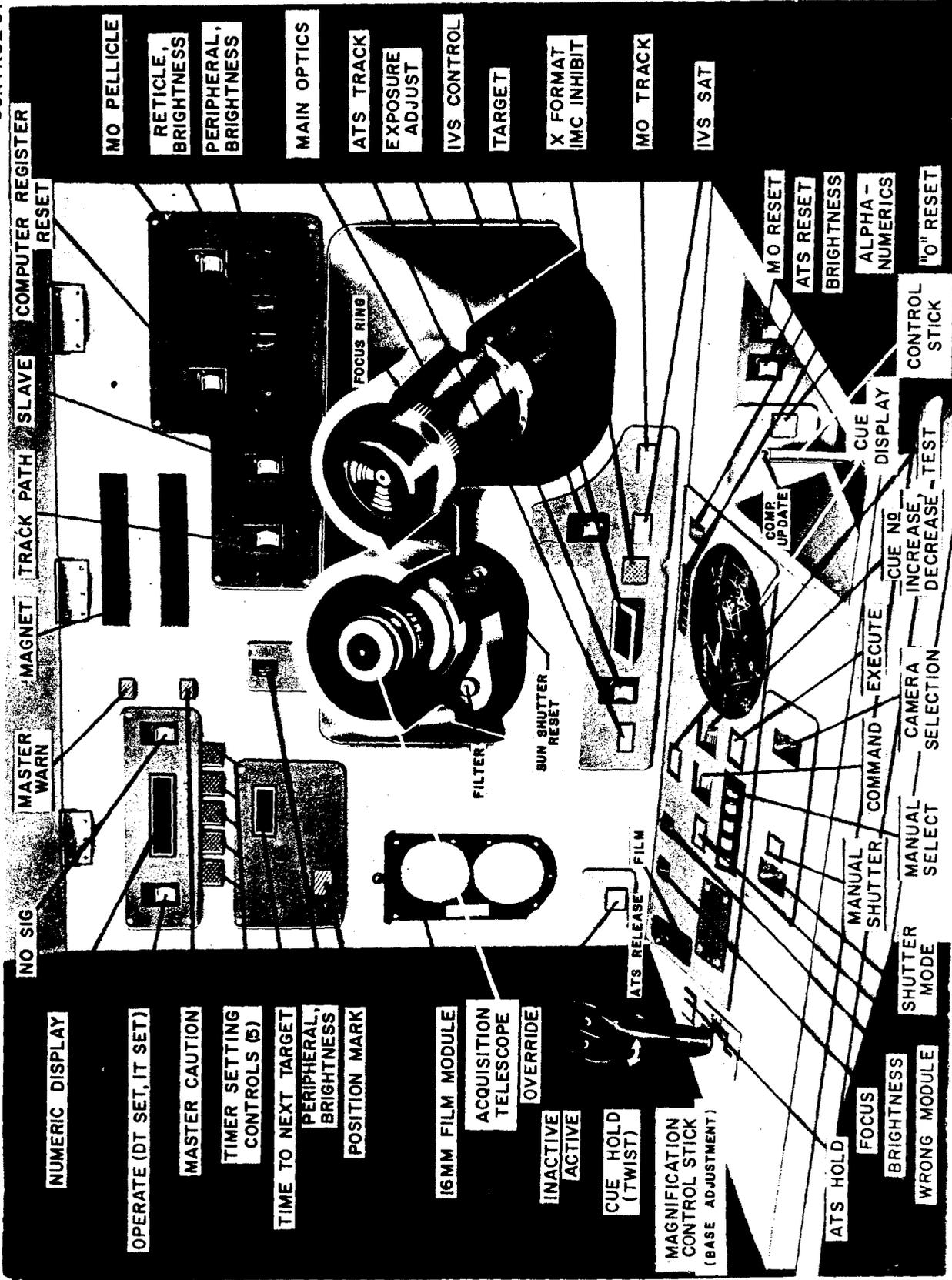
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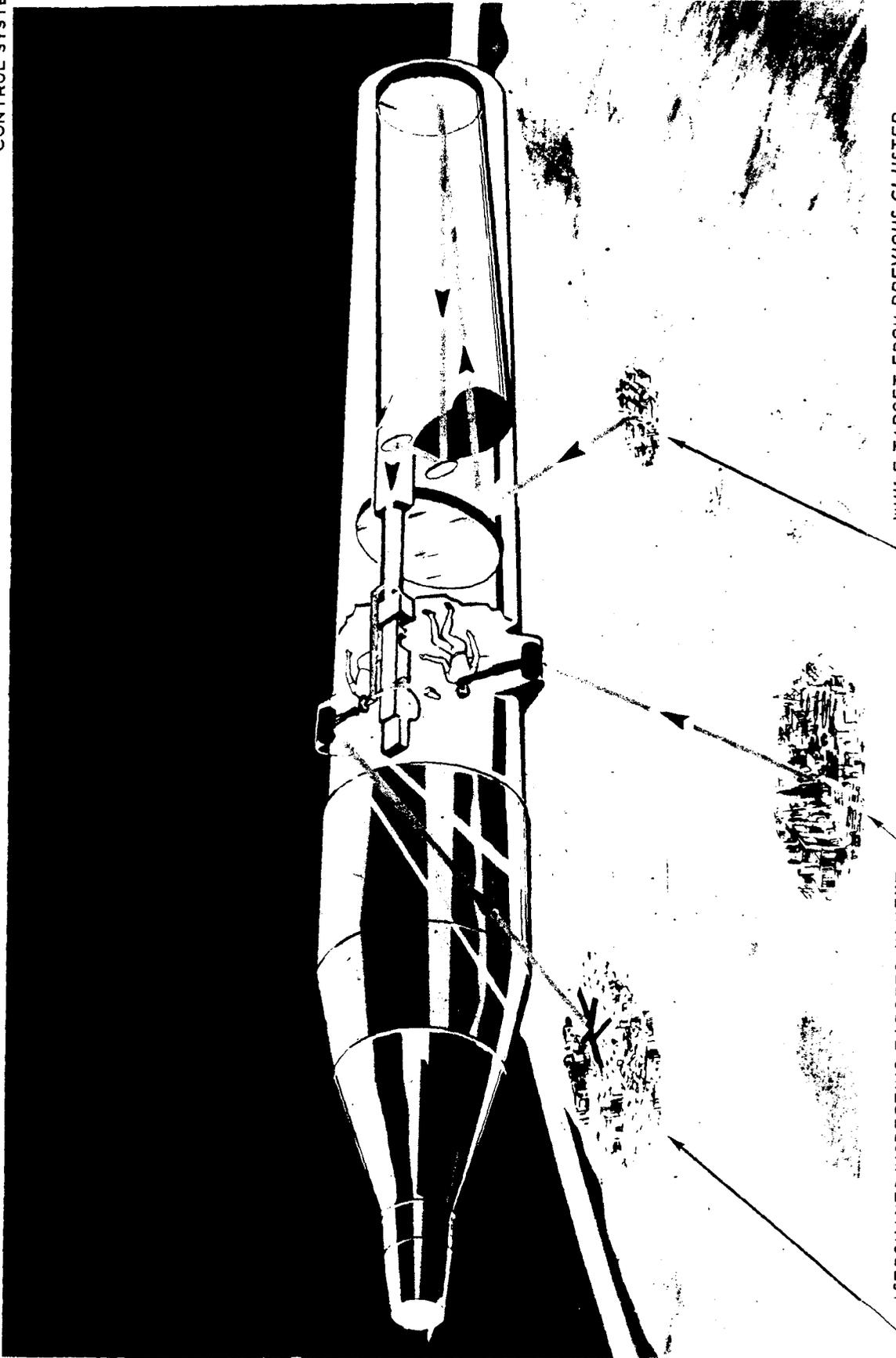
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FIGURE 3  
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— ASTRONAUTS INSPECTING TARGETS IN NEXT  
CLUSTER, FOR CLOUD COVER AND "ACTIVITY"

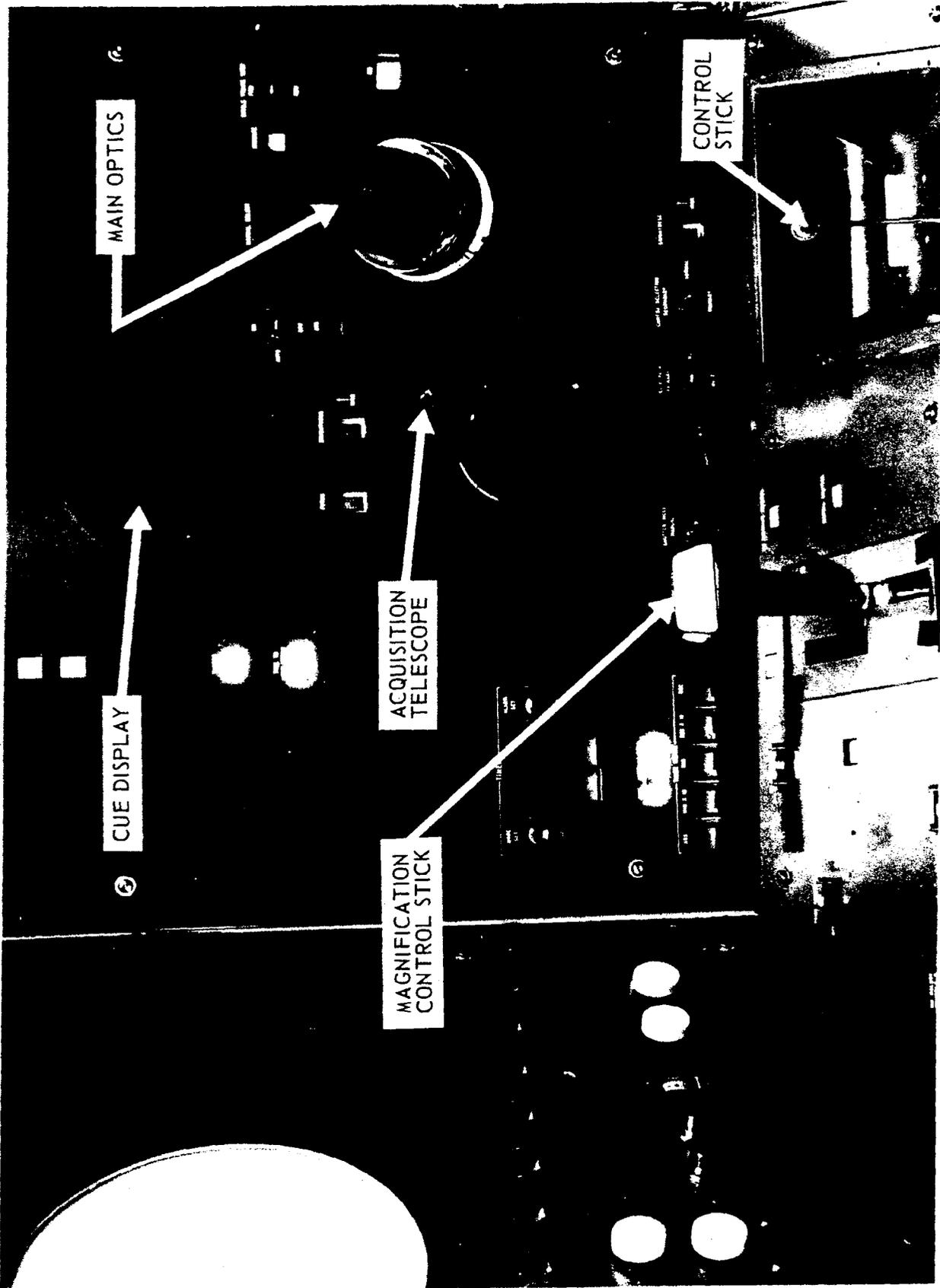
— WHILE TARGET FROM PREVIOUS CLUSTER  
IS BEING PHOTOGRAPHED

FIGURE 7

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ACQUISITION TELESCOPE SYSTEM OPERATING CONCEPT

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MOL MISSION CONSOLE (EARLY CONFIGURATION)

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FIGURE 1  
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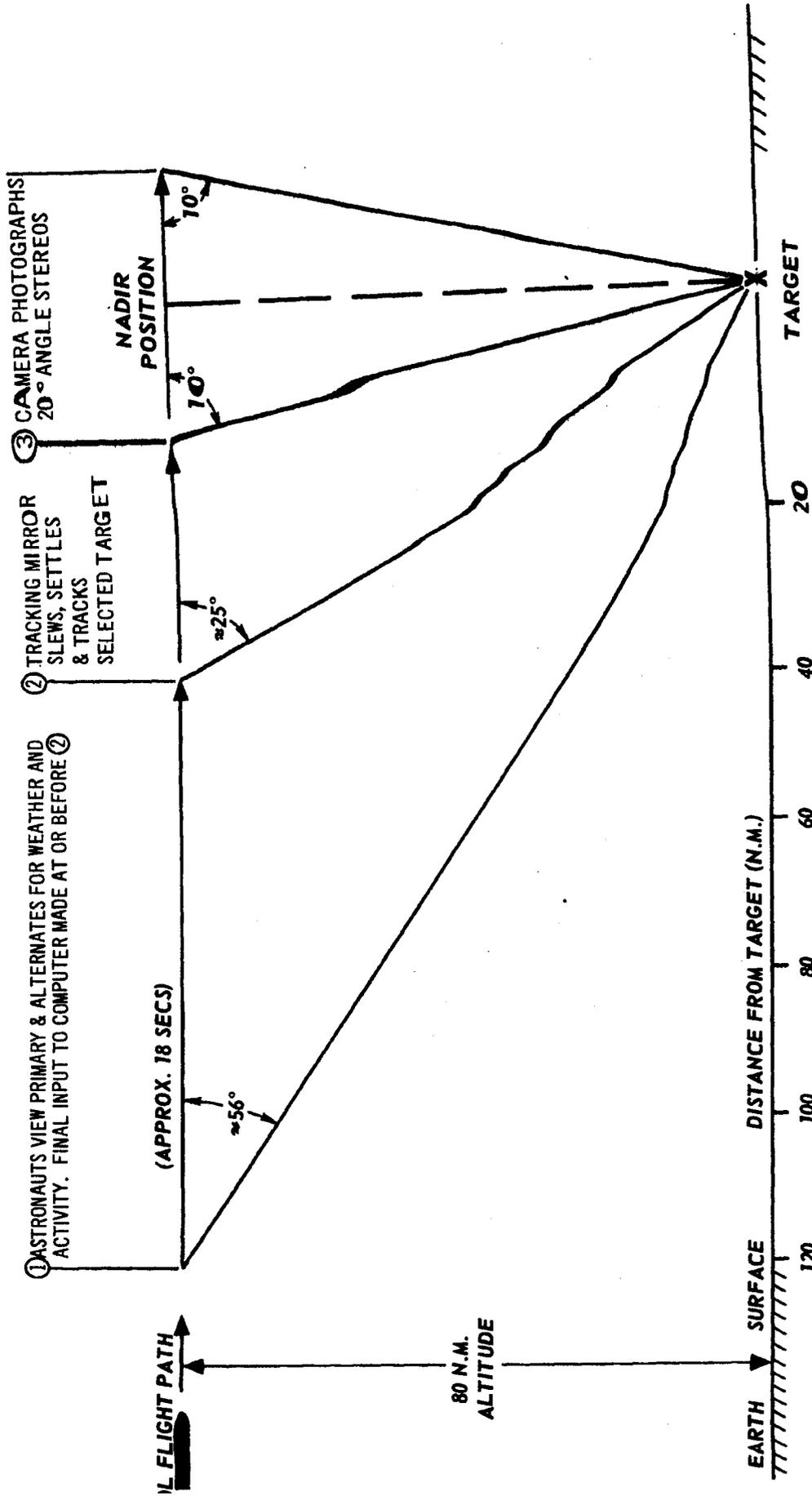
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FIGURE //  
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ILLUSTRATION OF "ACTIVITY" AT AIRFIELD

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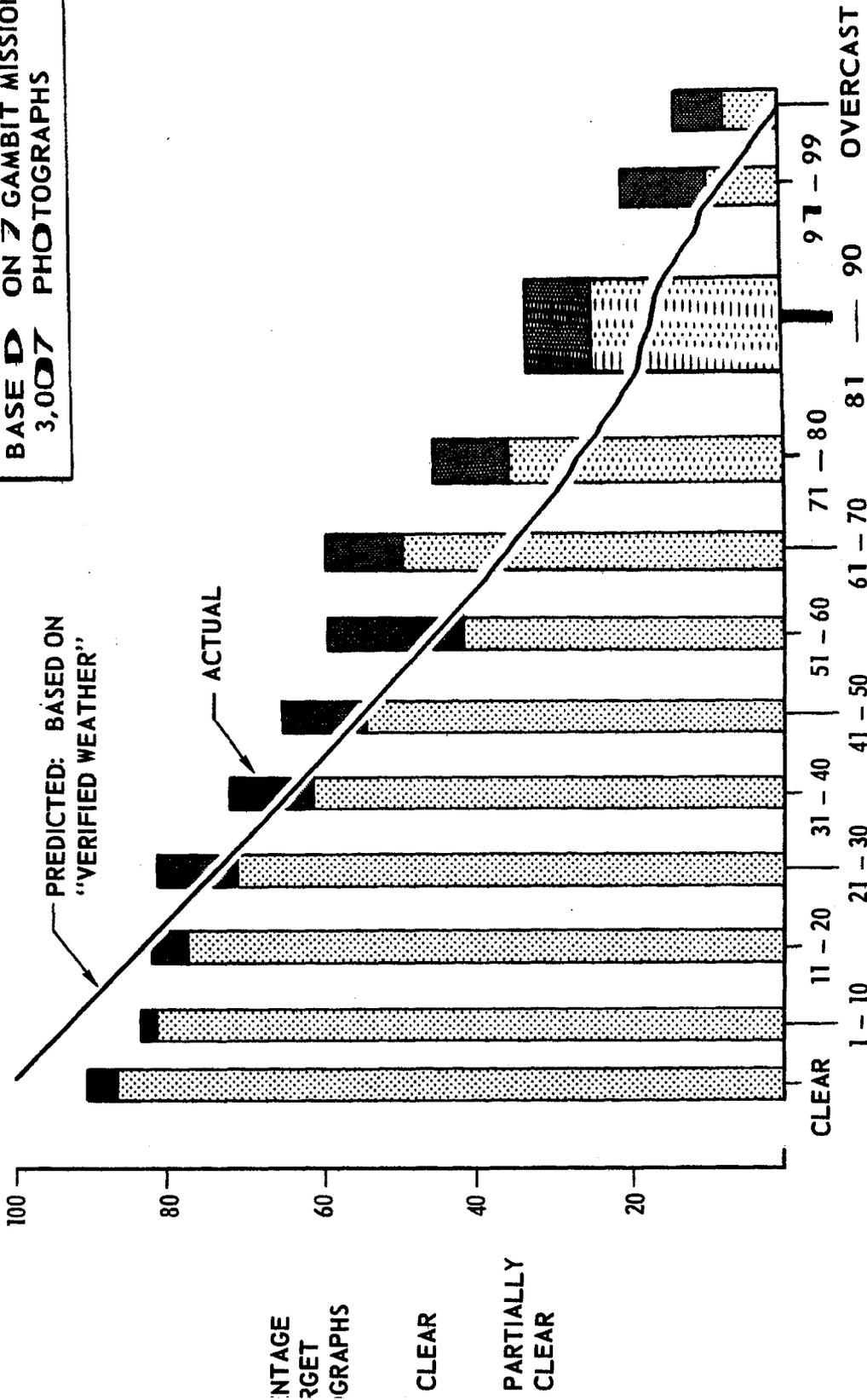
TIME - SPATIAL CONSTRAINTS FOR ASTRONAUTS WHILE  
PERFORMING IN ACTIVE TARGET INDICATOR MODE  
(TYPICAL EXAMPLE)

FIGURE 12

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BASE D ON 7 GAMBIT MISSIONS  
3,007 PHOTOGRAPHS



WEATHER CENTRAL "VERIFIED" CLOUD COVER (PERCENT)

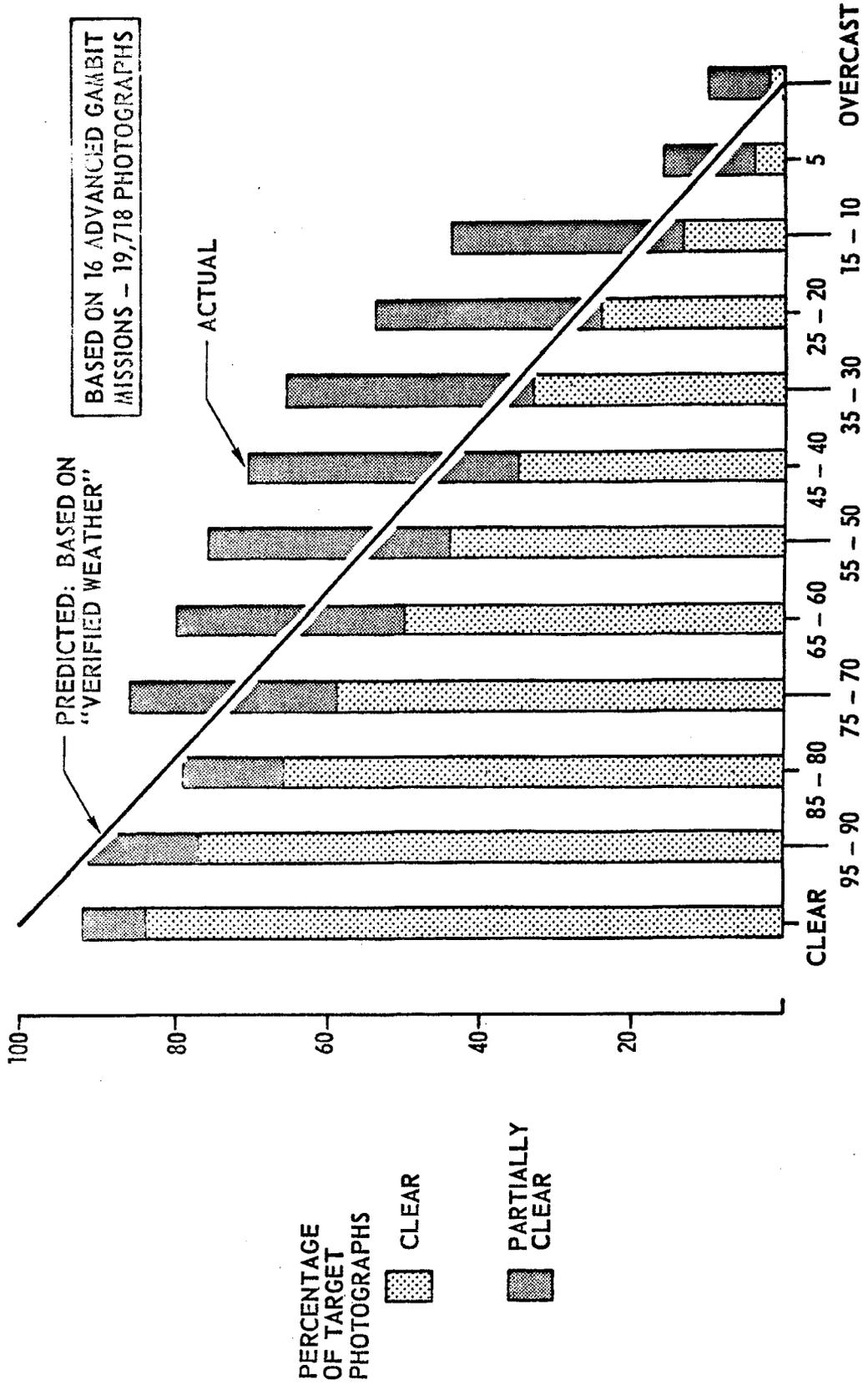
ACTUAL SUCCESSFUL GAMBIT PHOTOGRAPHY VERSUS  
THAT PREDICTED BASED ON "VERIFIED" WEATHER

FIGURE 13

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GAMBIT™  
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CONTROL SYSTEM



WEATHER CENTRAL "VERIFIED" PROBABILITY THAT TARGET WAS PHOTOGRAPHED CLEAR

**ACTUAL SUCCESSFUL ADVANCED GAMBIT PHOTOGRAPHY VERSUS THAT PREDICTED BASED ON "VERIFIED" WEATHER**

FIGURE A

GAMBIT  
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WEATHER MODEL	No. OF CLEAR PHOTOGRAPHS OBTAINED IN SIMULATED 30-DAY MISSION		% INCREASE DUE TO CLOUD AVOIDANCE ROLE PLAYED BY MAN
	AUTOMATIC OPERATION (PRIMARYES)	MANNED OPERATION (PRIMARYES & ALTERNATES)	
ANALYZED SINO-SOVIET WEATHER FOR PERIOD MARCH 7 - APRIL 5, 1960	2,019	2,533	25%
132,000 FRAMES OF SATELLITE PHOTOGRAPHY (WEATHER DISTRIBUTION SHOWN IN FIGURE 16)	2,209	2,584	17%
1,159 FRAMES OF GAMBIT PHOTOGRAPHY (SEE FIGURE 17)	2,023	2,365	17%
3,007 SEPARATE GAMBIT CAMERA OPERATIONS AGAINST PRIMARY TARGETS (FIG. 18)	2,153	2,592	20%
"VERIFIED" SINO-SOVIET WEATHER FOR PERIOD JULY-AUGUST 1966	1,150*	1,367*	22%

\* RESULTS SHOWN ARE FOR SIMULATED 15-DAY MISSION

INCREASE IN NUMBER OF CLEAR TARGET PHOTOGRAPHS OBTAINED  
DUE TO MAN'S CLOUD - AVOIDANCE ROLE IN MOL  
BASED ON SIMULATED AUTOMATIC VS. MANNED FLIGHT AGAINST TYPICAL  
SINO-SOVIET CLOUD COVERAGE

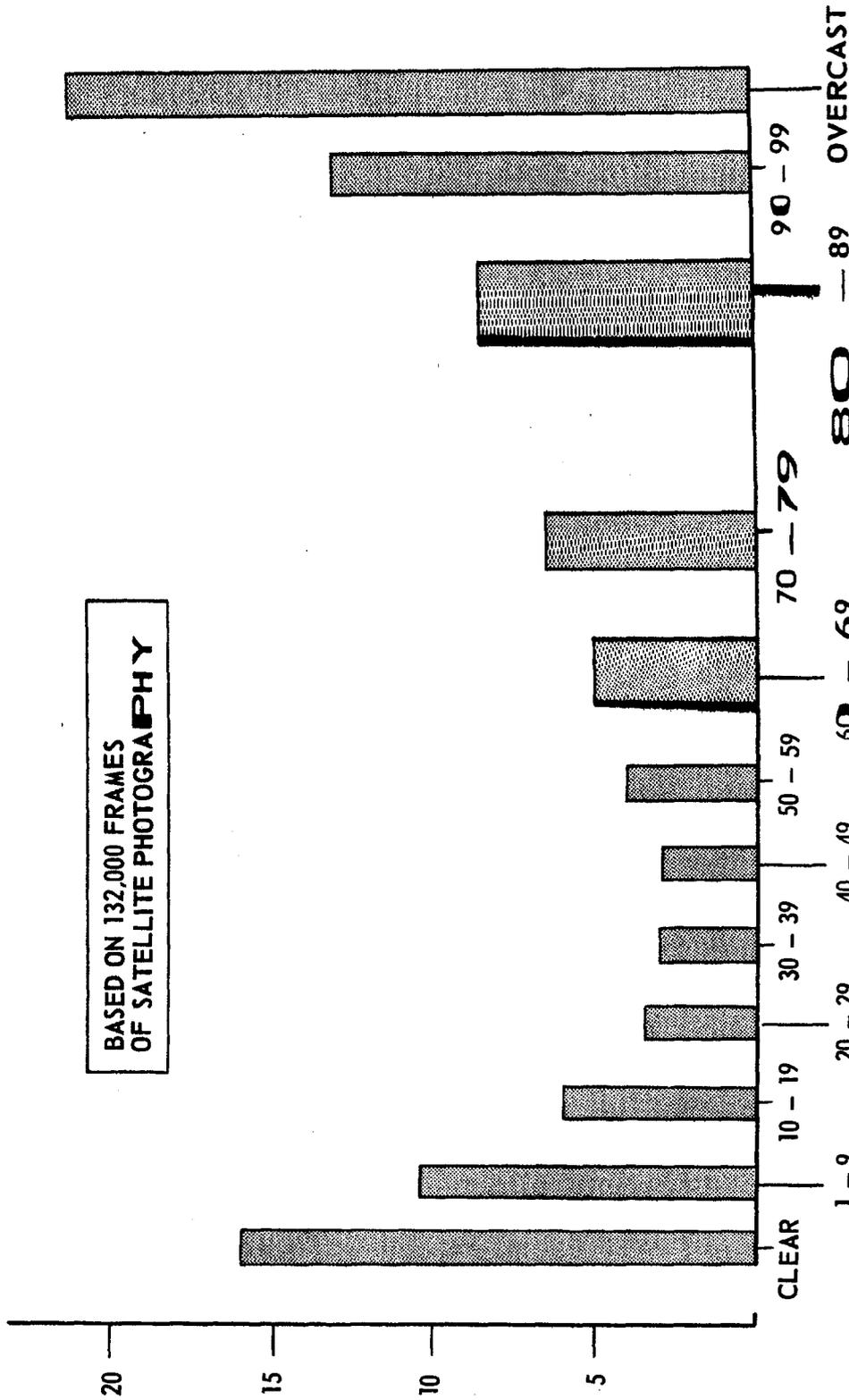
FIGURE /5

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PERCENTAGE OF SKY CLOUD COVERED

SKY COVERAGE CONDITIONS (U.S. SATELLITE EXPERIENCE)

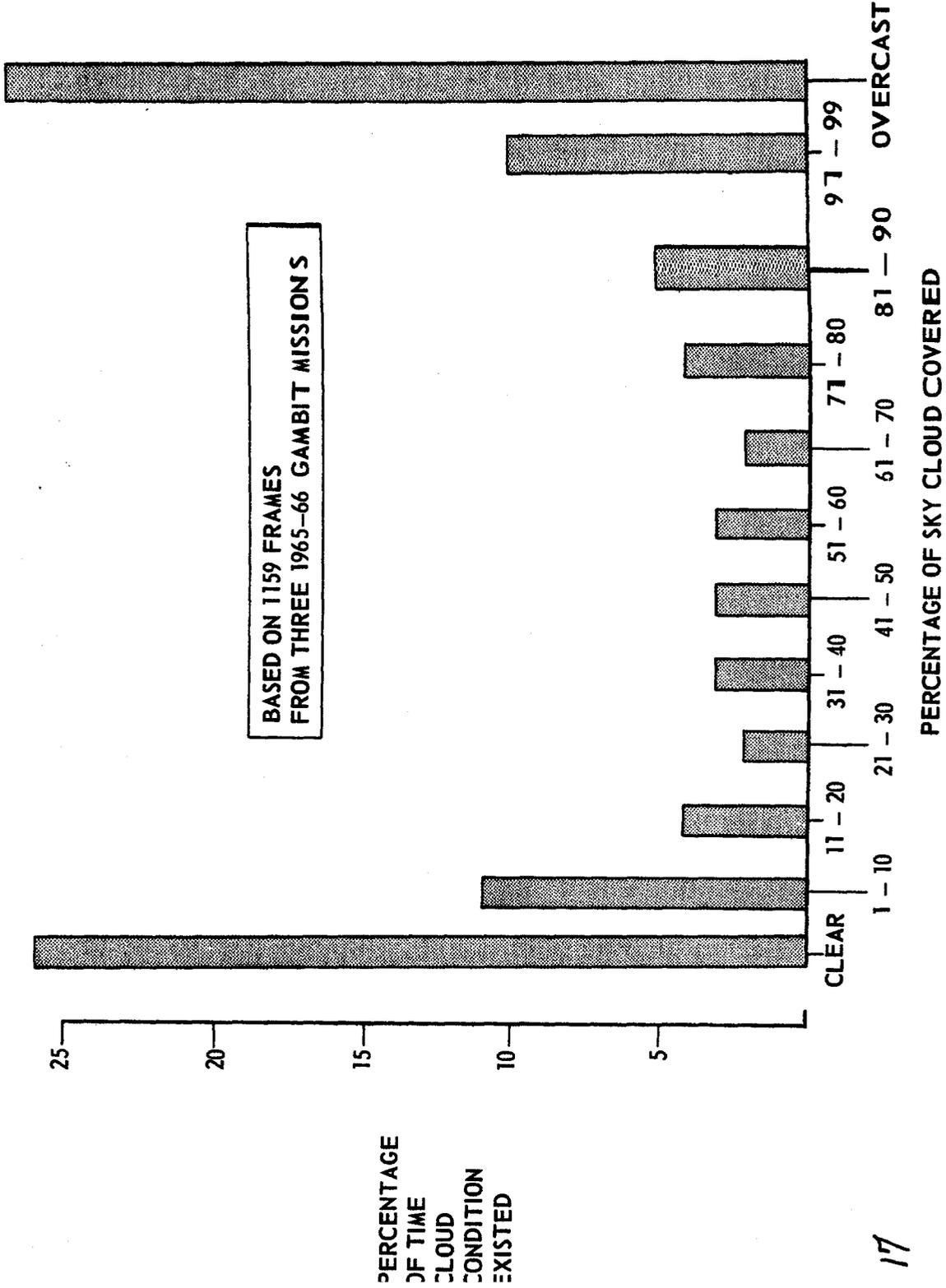
FIGURE 16

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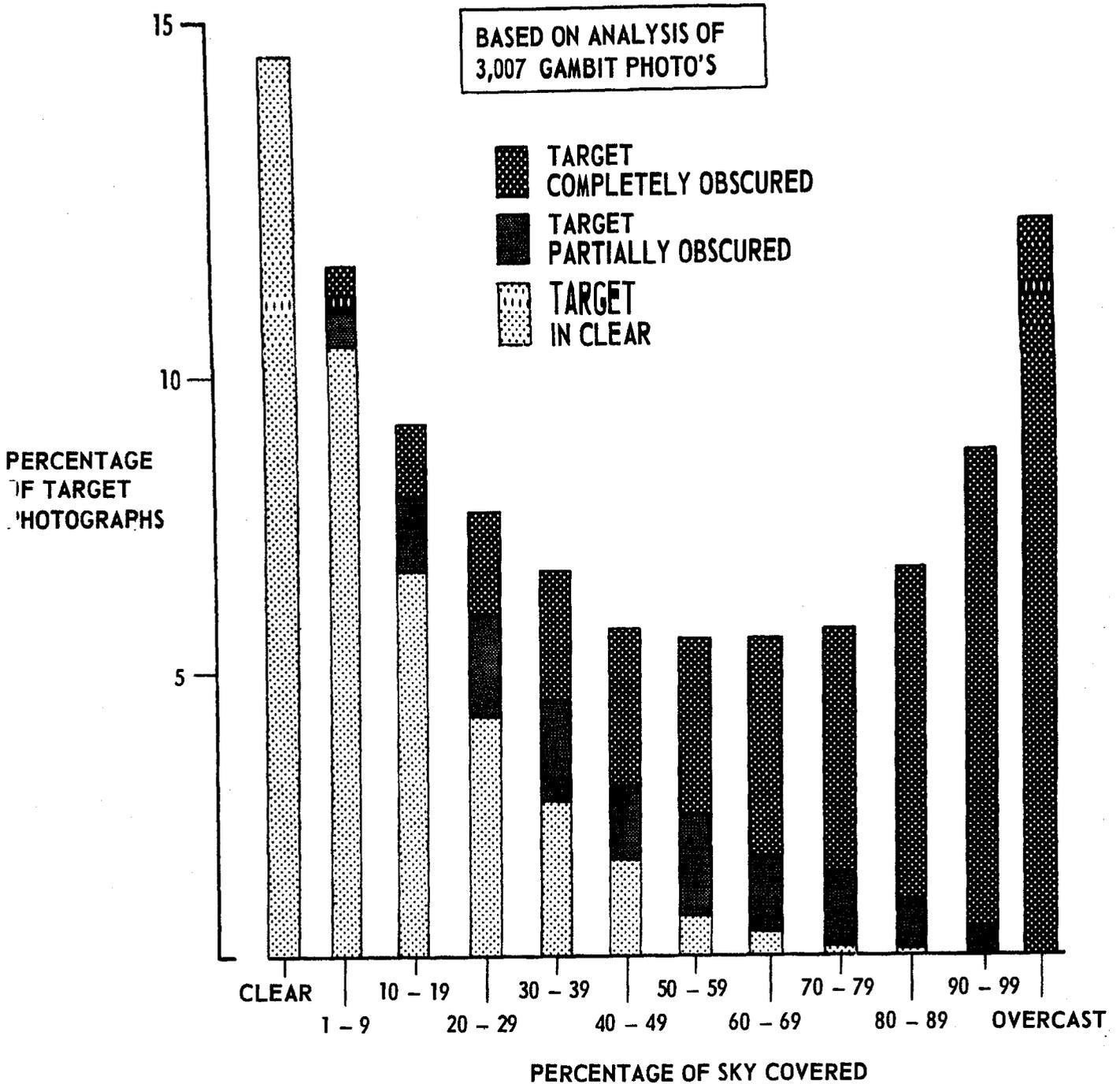
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### SKY COVERAGE CONDITIONS (GAMBIT EXPERIENCE)

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SUCCESS OF PHOTOGRAPHY ACHIEVED OVER SINO - SOVIET LAND MASS  
AS FUNCTION OF CLOUD COVER EXISTING AT TIME OF PHOTOGRAPHY

FIGURE 18

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TARGET CATEGORY	PERCENTAGE OF SITES AT WHICH "ACTIVITY" MAY OCCUR	PROBABILITY THAT ANY ONE SITE WILL BE "ACTIVE" DURING PAYLOAD PASS
MISSILE DEVELOPMENT & TEST	99	.07
GROUND FORCES	35	.11
AIRFIELDS	75	.18
RADAR/COMMUNICATIONS DEPLOYMENT	35	.04
INDUSTRY	5	.02
MISSILE PRODUCTION & LOGISTICS	65	.01
NUCLEAR WEAPONS	85	.05
BW / CW	85	.05
NUCLEAR MATERIALS	5	.03
AIRCRAFT PRODUCTION	75	.24
NAVAL ACTIVITY	65	.09
RADAR/COMMUNICATIONS (MAJ & R&D)	100	.25
AVERAGE:	70%	.06

FIGURE 19

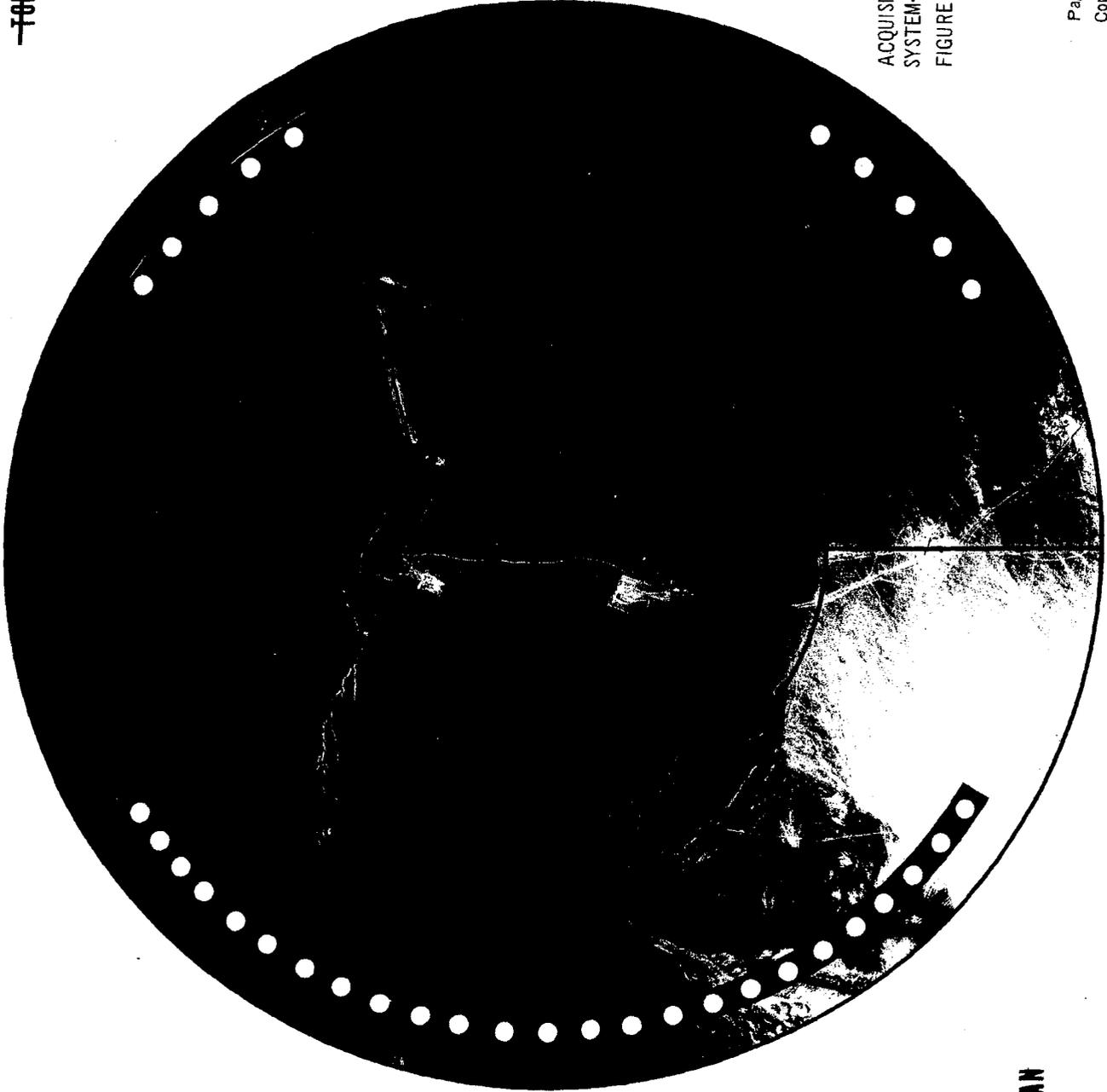
PROBABILITY OF OCCURRENCE OF "ACTIVITY"  
AT SINO-SOVIET TARGETS DURING MOL OVERFLIGHTS

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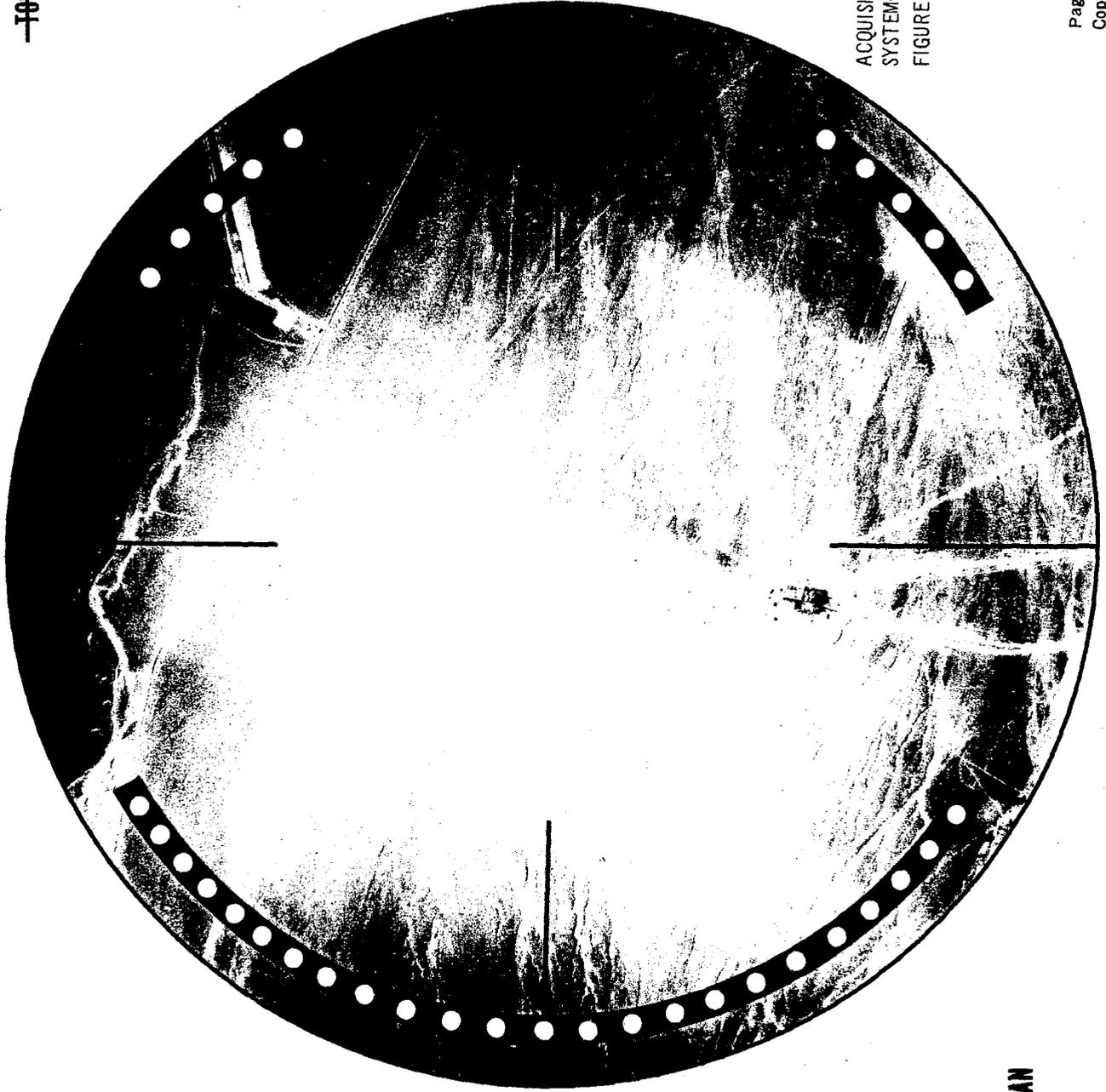
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ACQUISITION TELESCOPE  
SYSTEM-VIEW AT 15X  
FIGURE 1000

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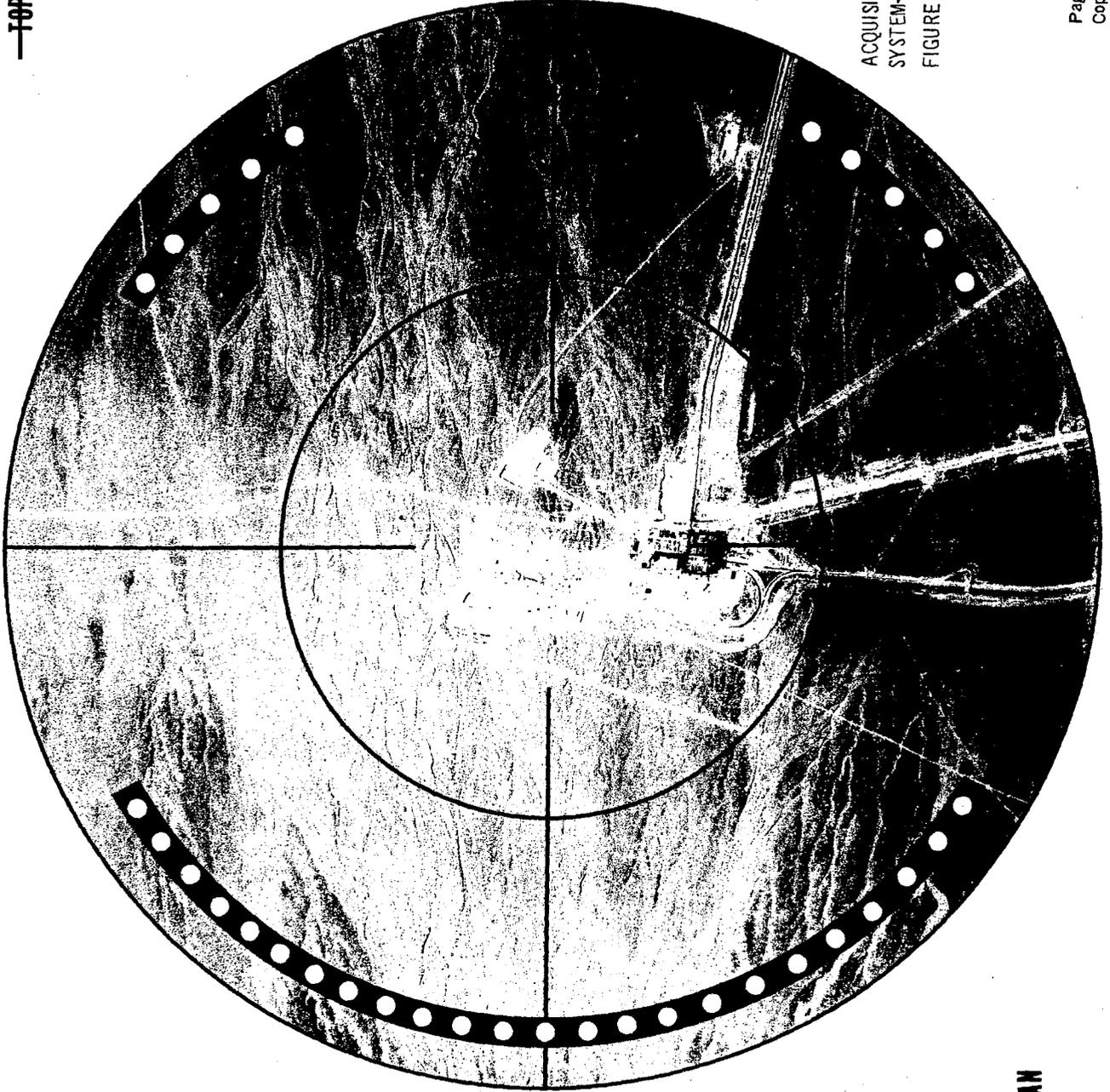
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ACQUISITION TELESCOPE  
SYSTEM-VIEW AT 32X  
FIGURE 1

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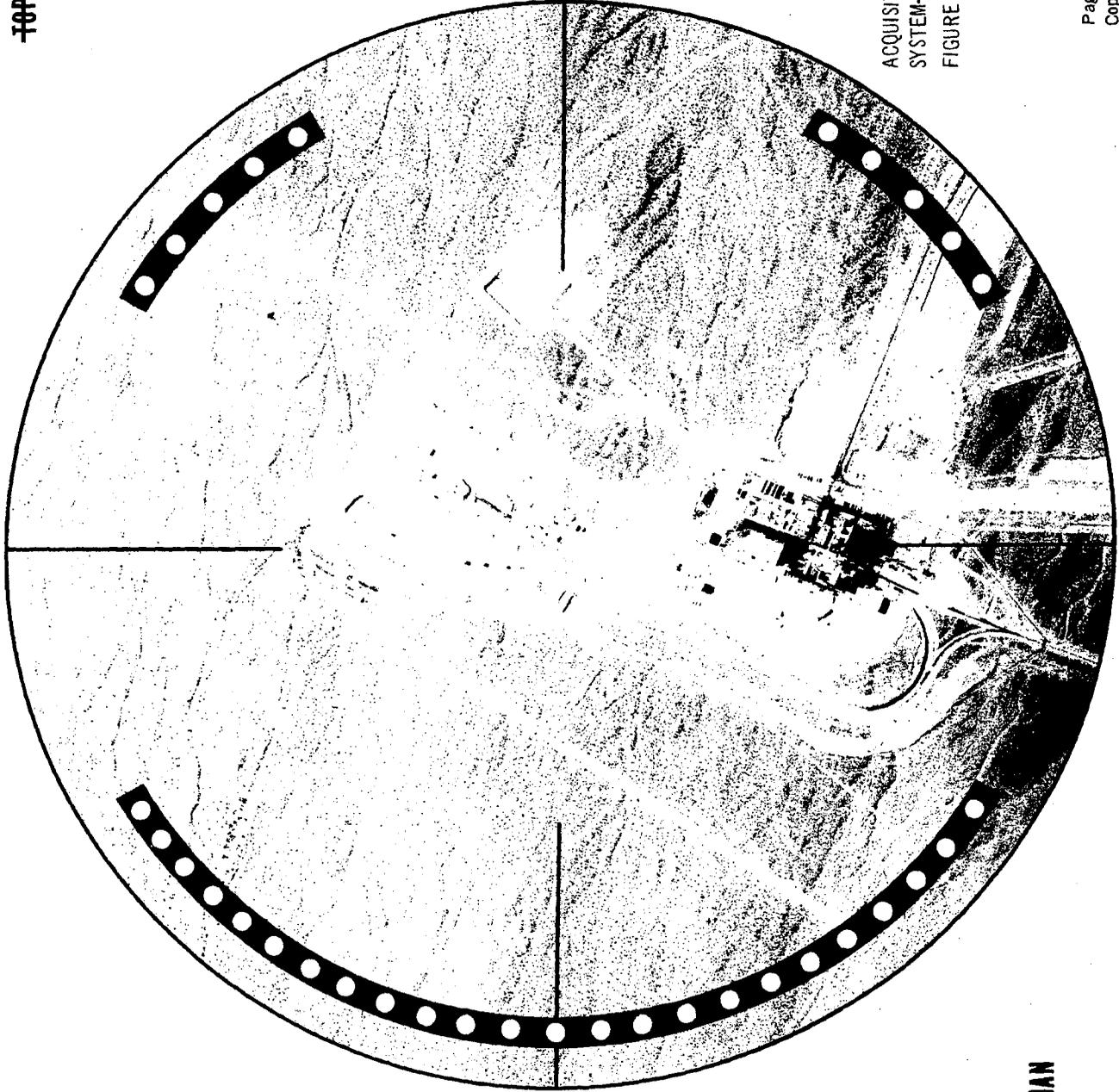
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ACQUISITION TELESCOPE  
SYSTEM-VIEW AT 64X  
FIGURE 100

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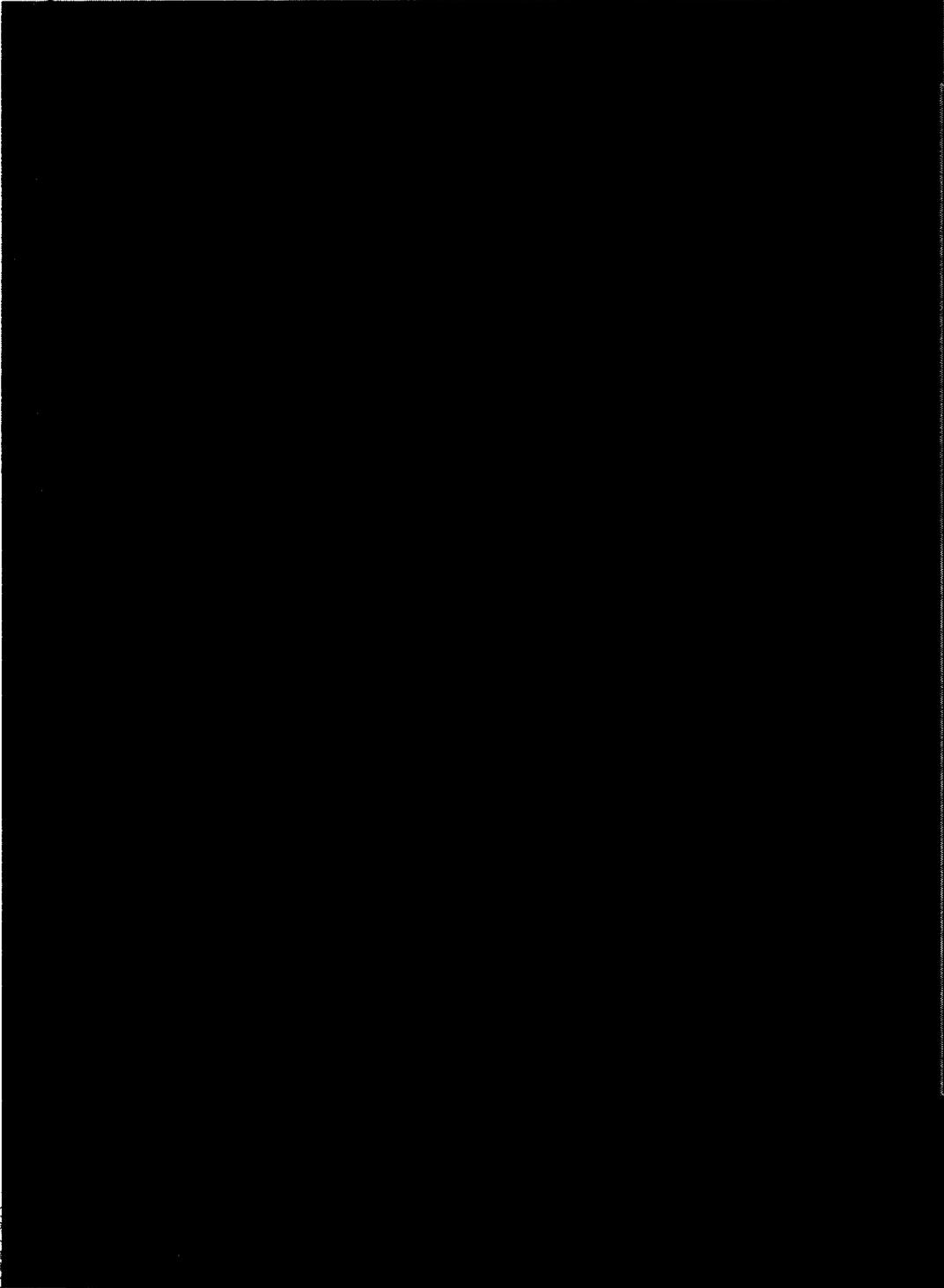


ACQUISITION TELESCOPE  
SYSTEM-VIEW AT 127X  
FIGURE 1

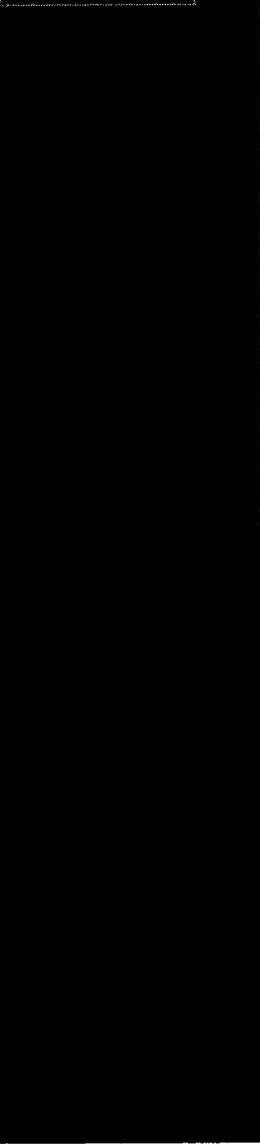
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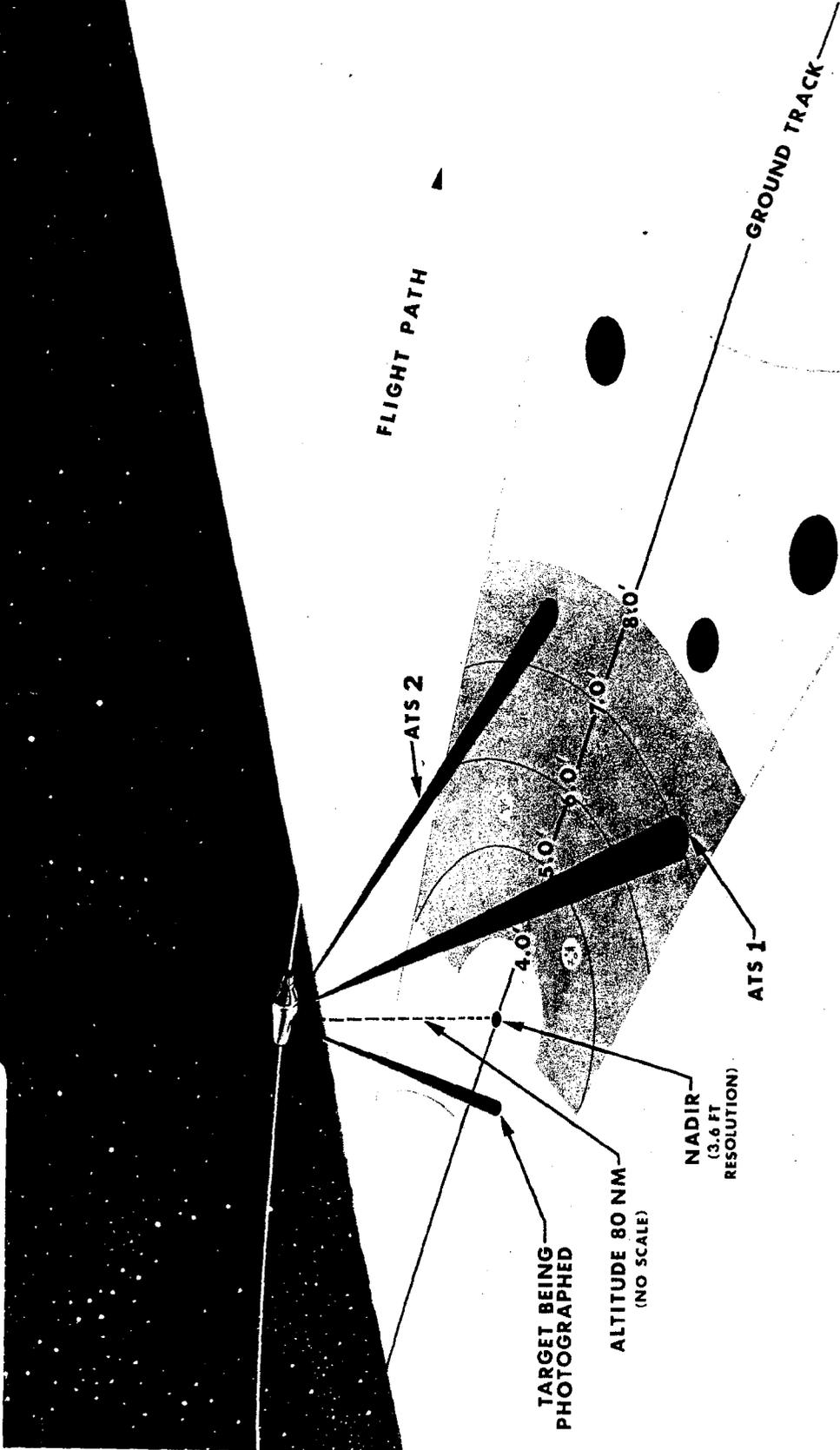


FIGURE 26 RESOLUTION IN ACQUISITION TELESCOPE SYSTEM  
CAPABILITY IN FORWARD SCAN FIELD

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BYEMAN/TALENT-KEYHOLE  
CONTROL SYSTEMS JOINTLY

DORIAN

TARGET TYPE	INDICATORS OF TRANSIENT INTELLIGENCE POTENTIAL	RESOLUTION REQUIRED FOR DETECTION (FEET)
OPERATIONAL MISSILE SITES	MISSILES EXPOSED	10
	ERECTION/LOADING EQUIPMENT EXPOSED	10
	VEHICULAR ACTIVITY	10
	INDICATION OF SNOW REMOVAL	10
	GROUND SUPPORT EQUIPMENT EXPOSED	5
	SILO DOOR OPEN	5
AIRFIELDS	PRESENCE OF SPECIAL VEHICLES	3
	AIRCRAFT IN UNUSUAL LOCATIONS	15
	NEW AIRCRAFT PRESENT	3 - 15
	UNUSUALLY CONFIGURED A/C PRESENT	3 - 10
	AIRCRAFT/GROUND EQUIPMENT IN WEAPONS LOADING AREA	10
	AIRCRAFT IN MAINTENANCE AREAS	10
	DISASSEMBLED AIRCRAFT	5
	VEHICULAR ACTIVITY AROUND AIRCRAFT	5
	AIRCRAFT SUBSYSTEMS EXPOSED	3
	GROUND FORCES	VEHICULAR ACTIVITY
VEHICLES PRESENT		10
SPECIFIC MODEL VEHICLE PRESENT		3

RESOLUTION REQUIRED TO DETECT PRESENCE OF VARIOUS  
TYPES OF "ACTIVITY" AT TARGETS OF INTEREST

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FIGURE 27

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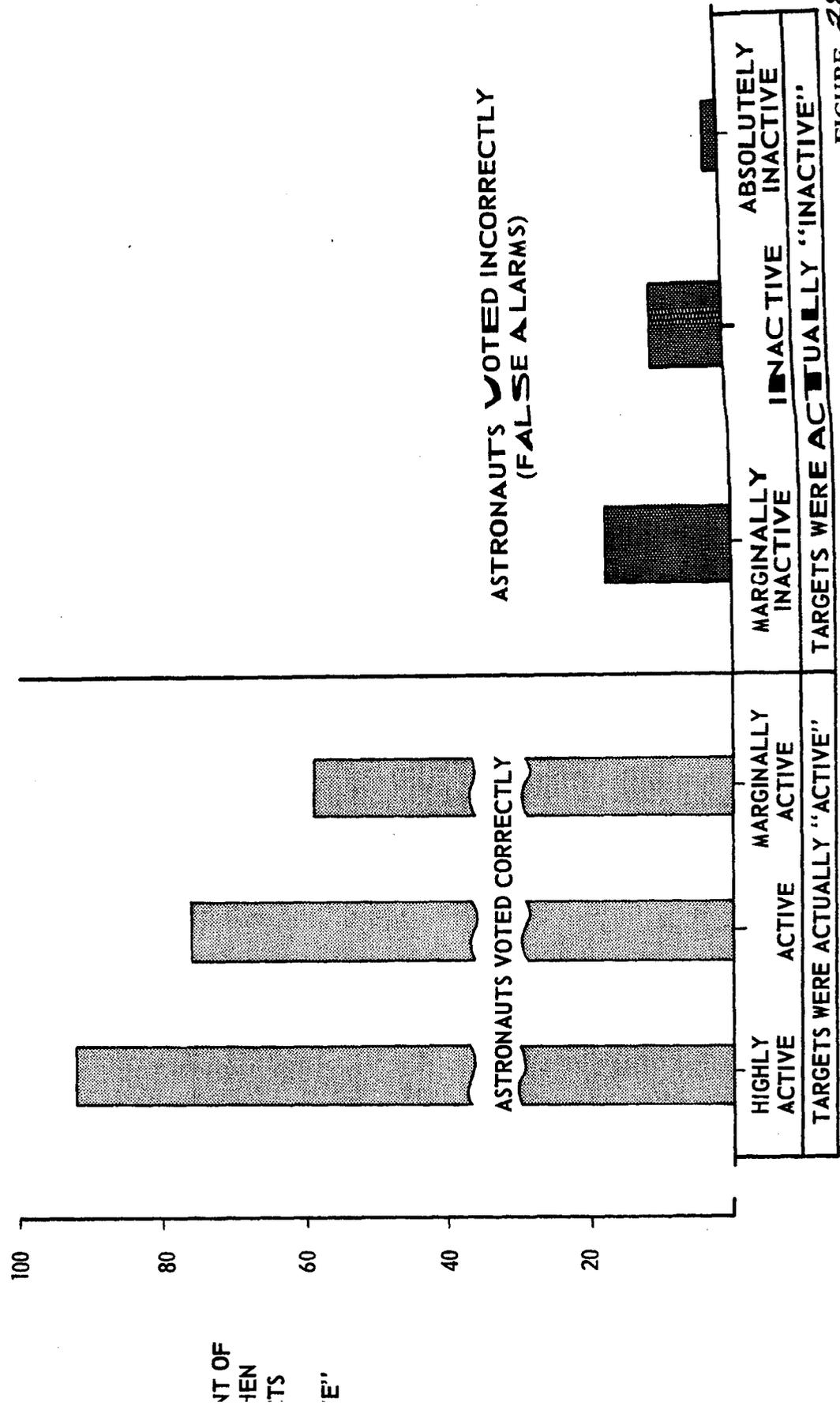


FIGURE 28

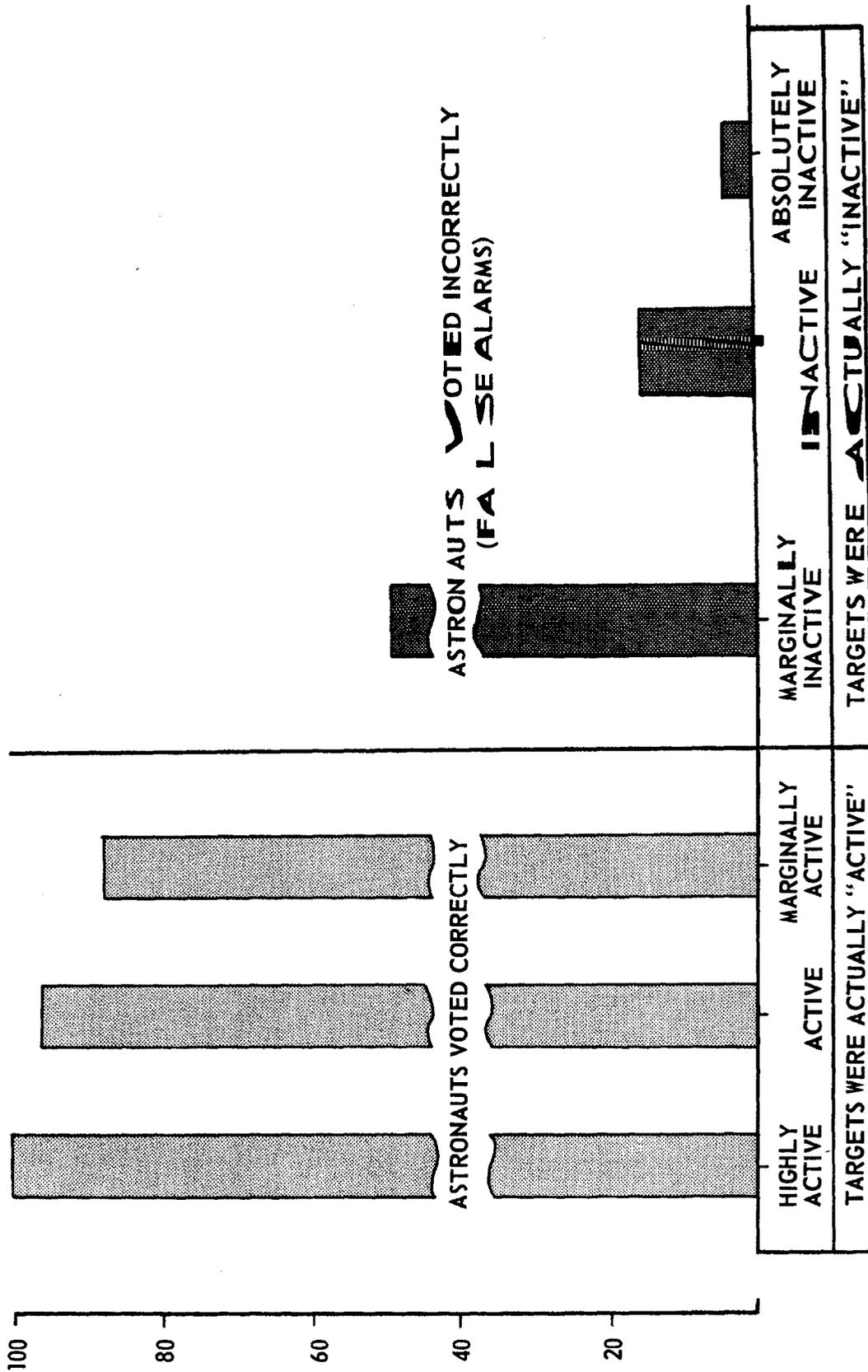
CAPABILITY OF MOL ASTRONAUTS TO IDENTIFY "ACTIVE" TARGETS  
CORRECTLY, AS FUNCTION OF LEVEL OF ACTIVITY ACTUALLY PRESENT IN SCENE  
(MAXIMUM DECISION TIME ALLOWED = 12 SECONDS)

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ACTIVITY LEVEL OF TARGET SCENE

ACCURACY ACHIEVED BY MOL ASTRONAUTS IN CORRECTLY IDENTIFYING "ACTIVE"  
TARGETS IN THOSE CASES IN WHICH DECISION TIME WAS SIX SECONDS OR LESS

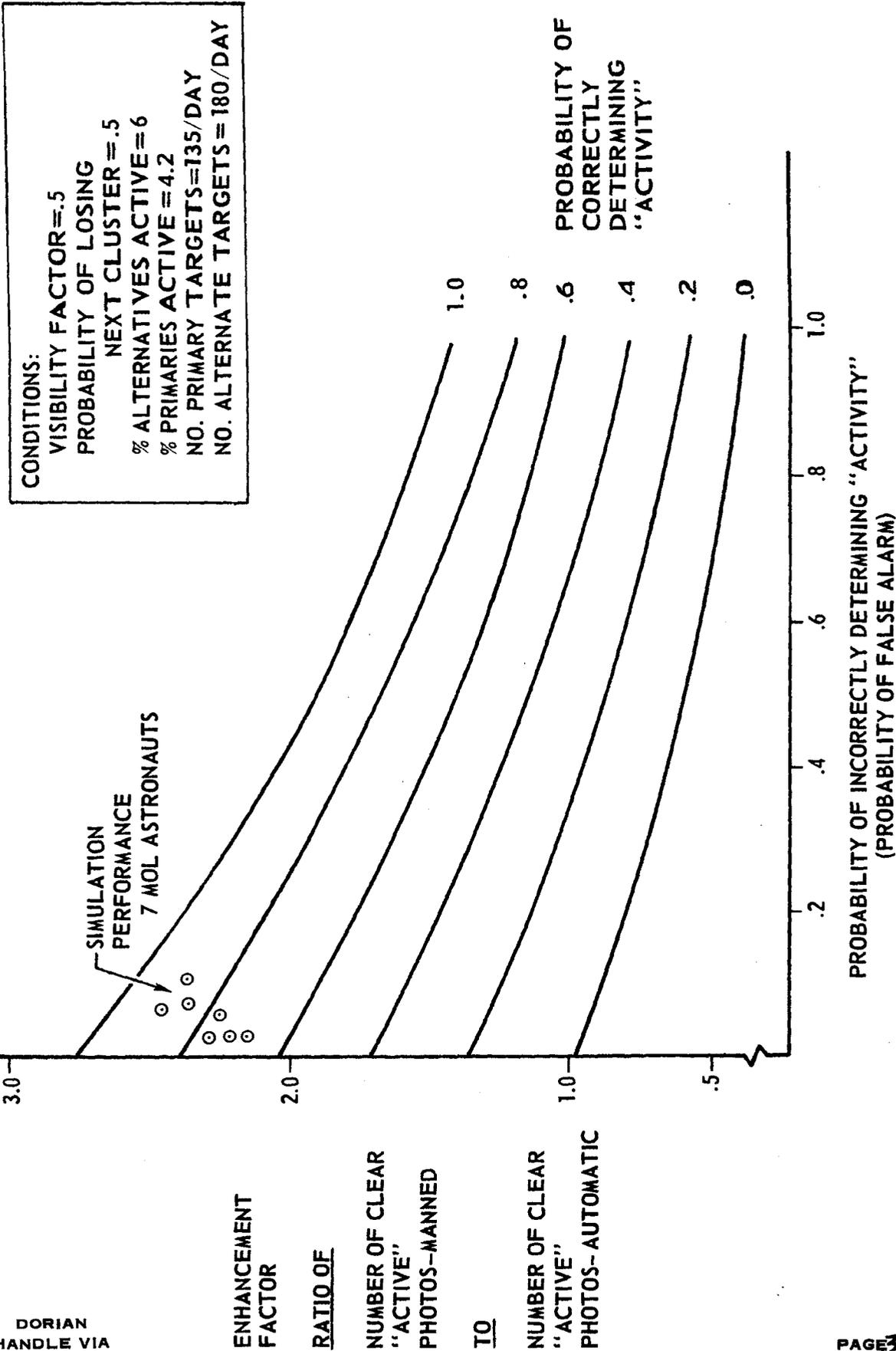
FIGURE 29

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MOL MISSION-ENHANCEMENT FACTOR, FOR CONDITIONS INDICATED, AS FUNCTION OF MAN'S ABILITY TO MAKE CORRECT DECISIONS CONCERNING PRESENCE OF "ACTIVITY" AT ALTERNATIVE TARGETS. (SIMULATION RESULTS SUPERIMPOSED)

FIGURE 30

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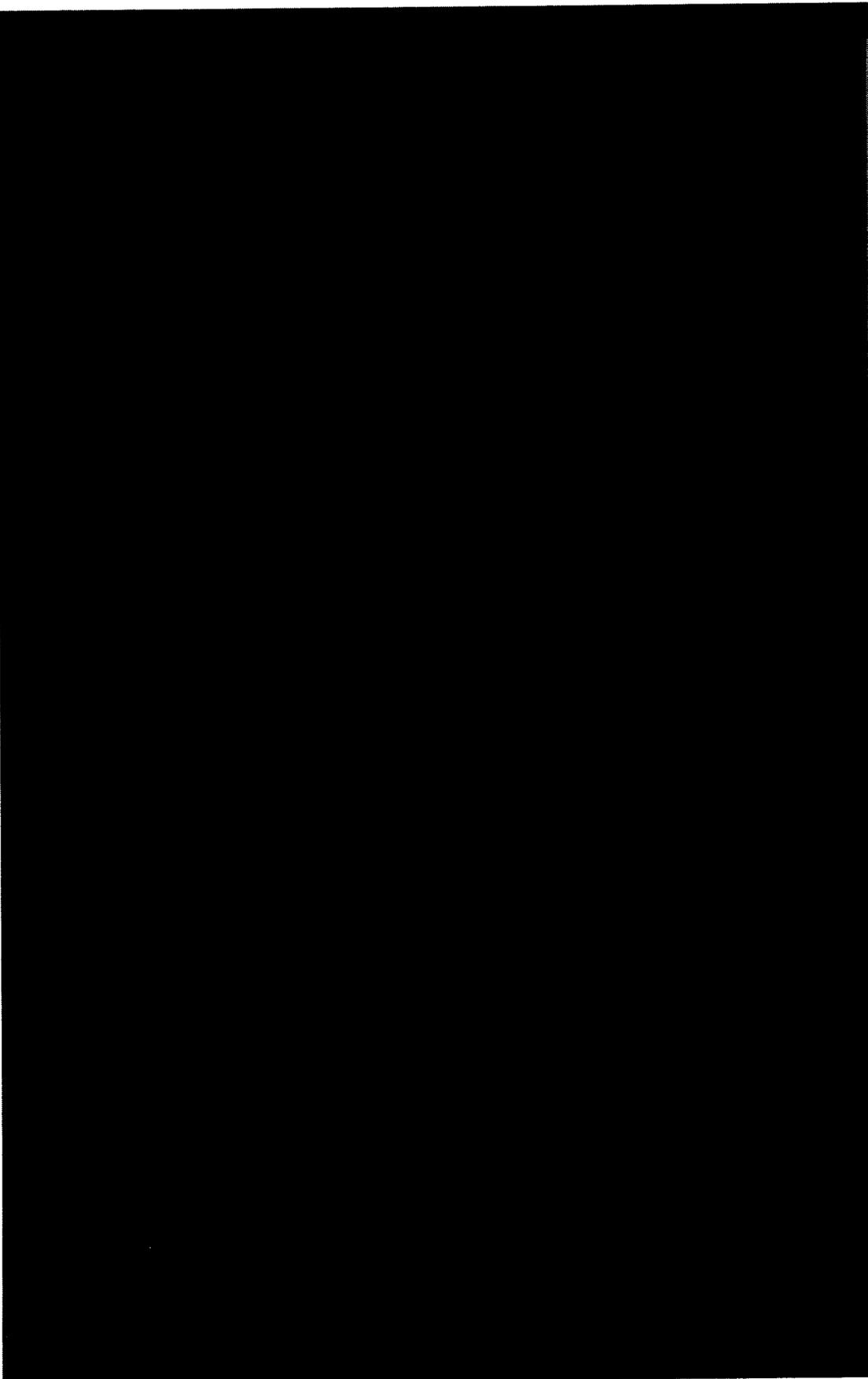


FIGURE 31

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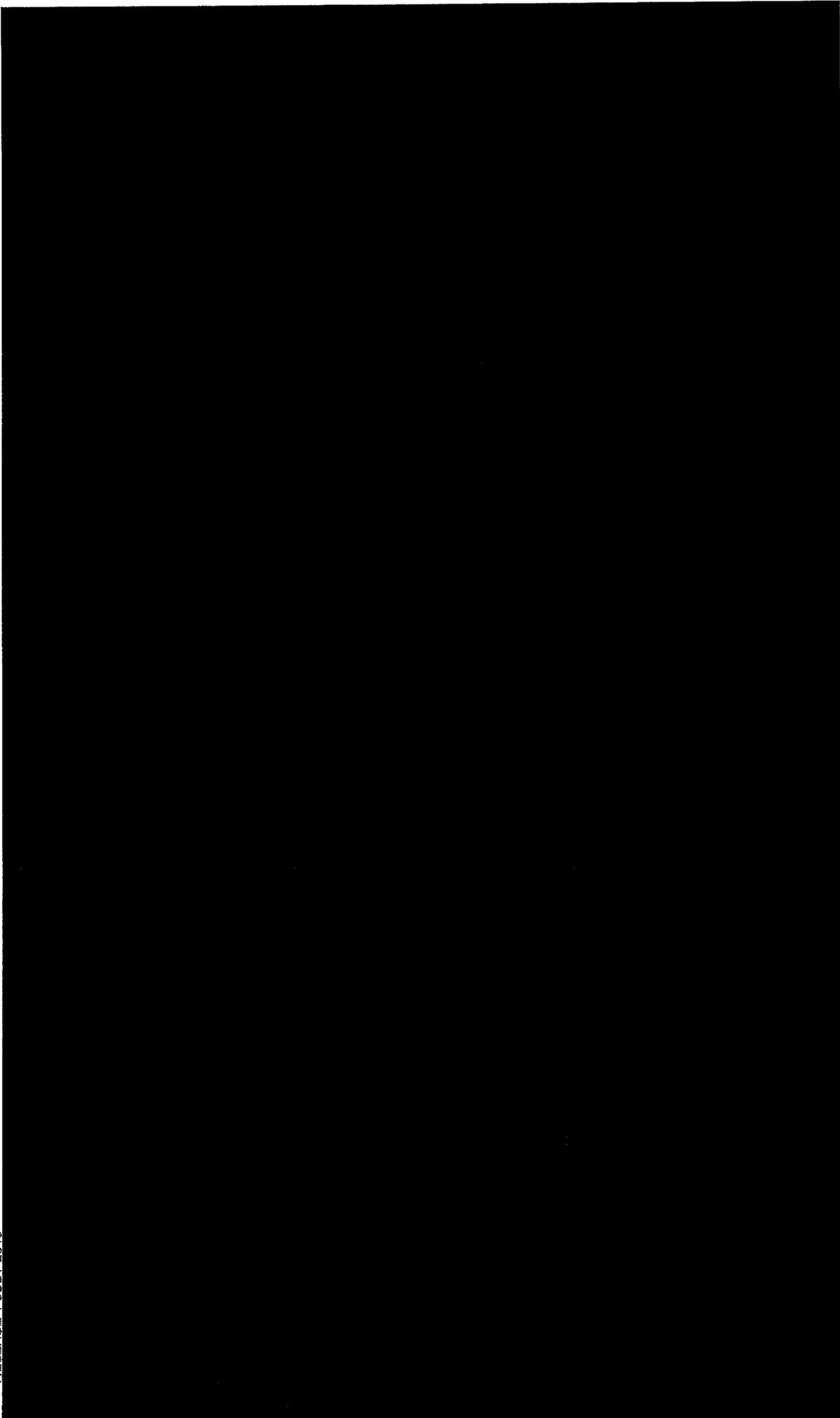
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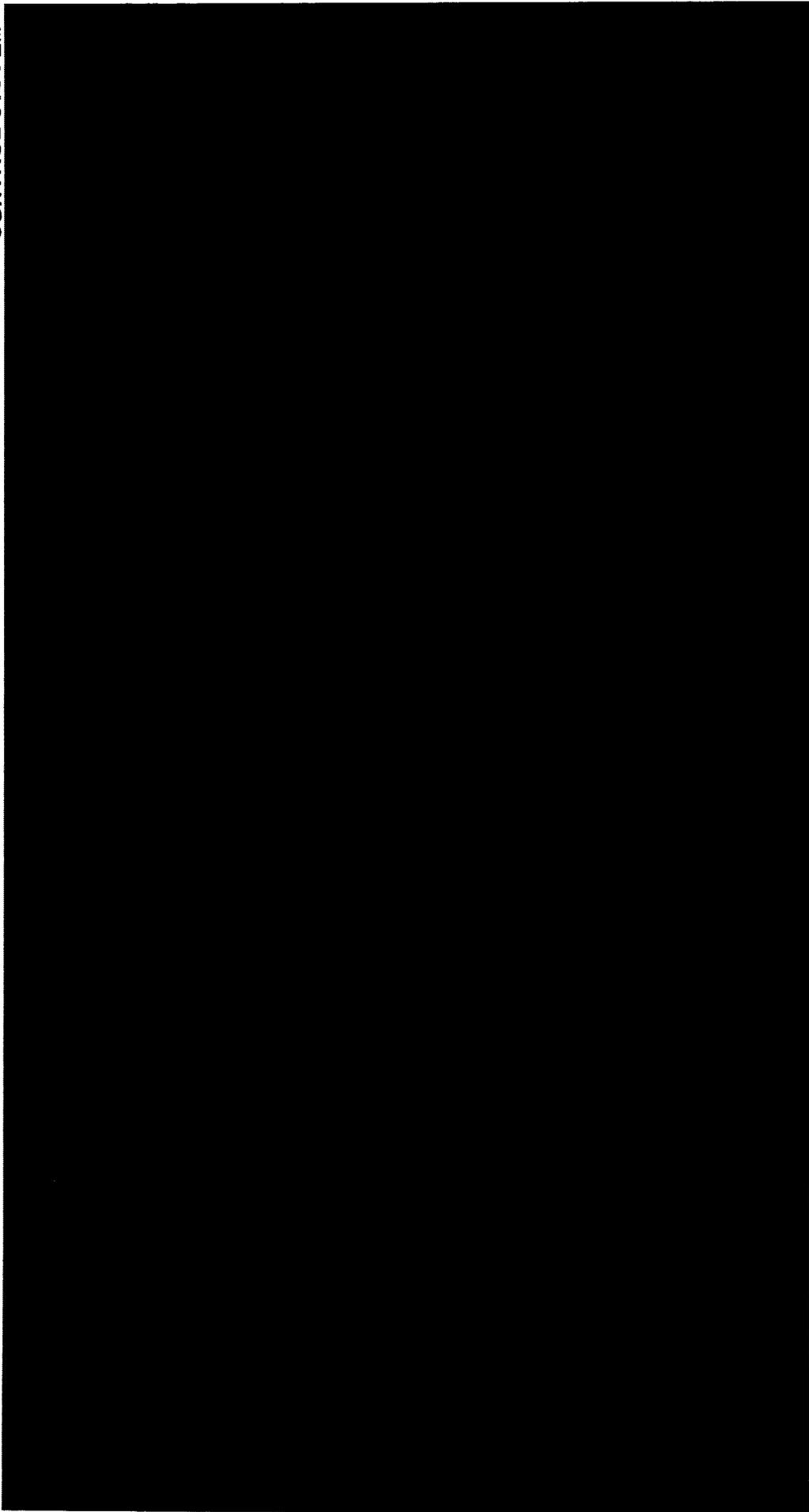
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BYEMAN  
CONTROL SYSTEM

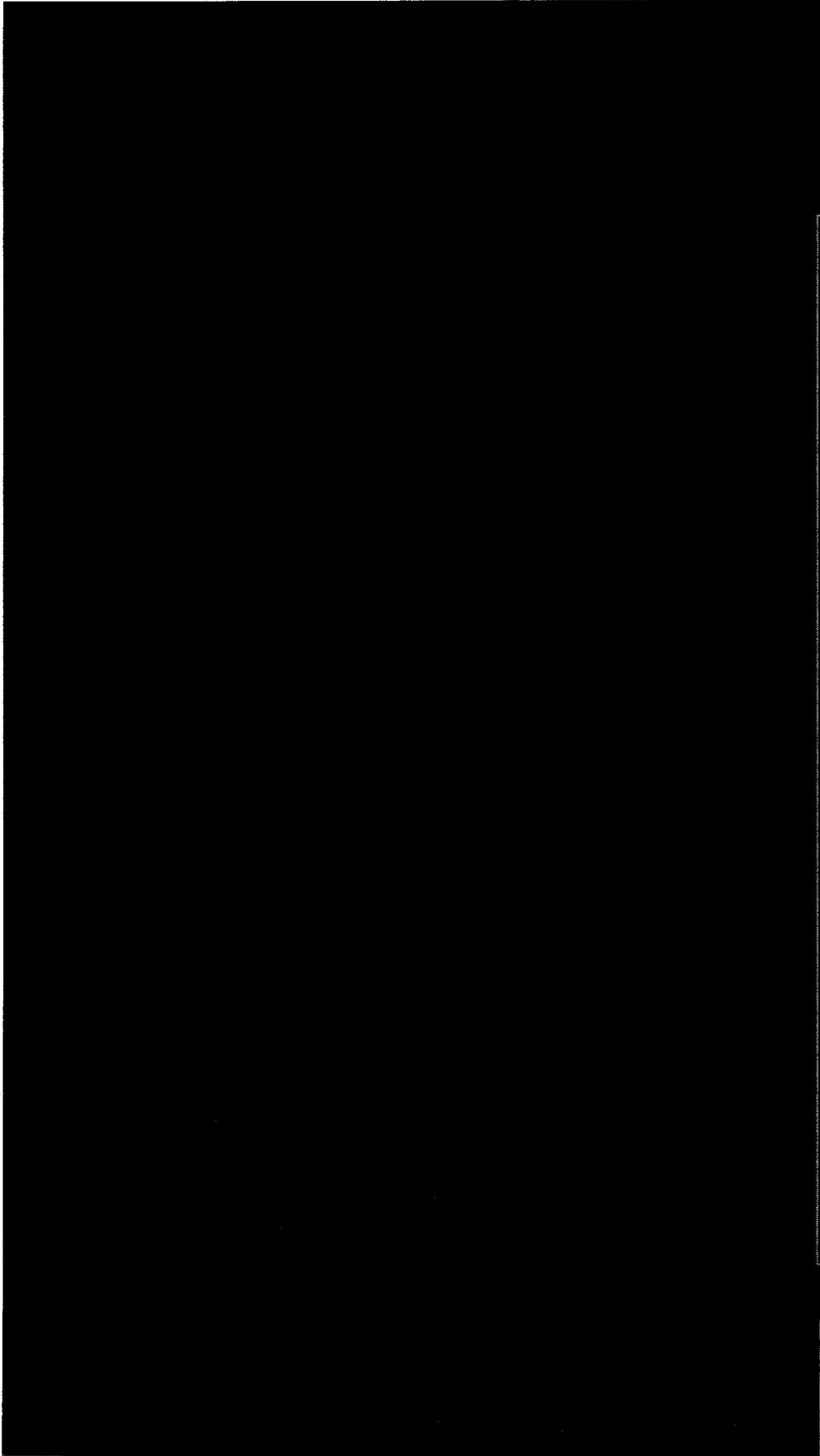
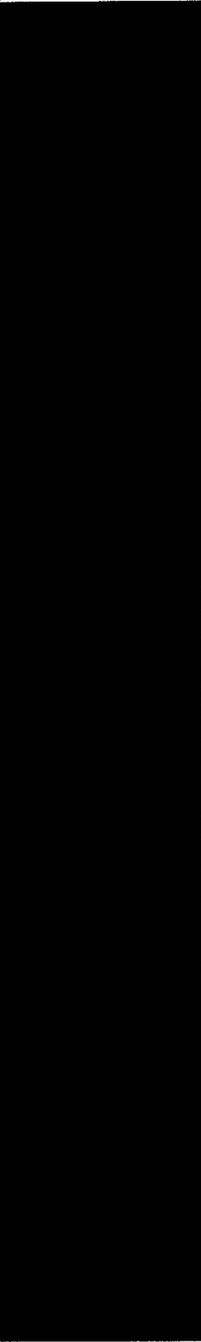


FIGURE 34

FORIAN  
HANDLE VIA  
BYEMAN  
CONTROL SYSTEM

PAGE 400 OF 423 PAGES  
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DORIAN  
HANDLE VIA  
BYEMAN  
CONTROL SYSTEM

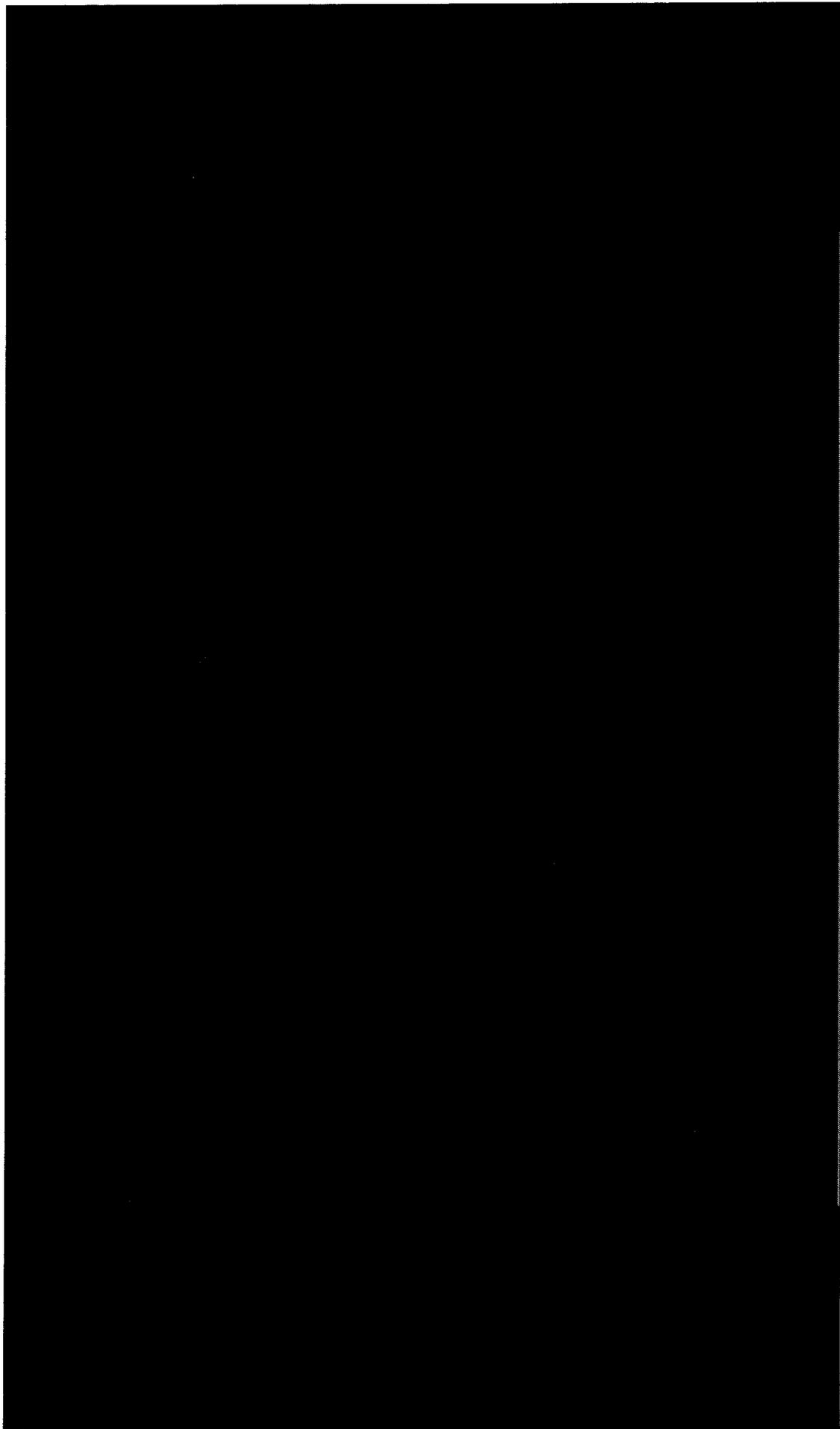


FIGURE 35

DORIAN  
HANDLE VIA  
BYEMAN  
CONTROL SYSTEM

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DORIAN  
HANDLE VIA  
BYEMAN  
CONTROL SYSTEM

PLANET	MOL SYSTEM RESOLUTION CAPABILITY*			GROUND-BASED TELESCOPE RESOLUTION CAPABILITY	
	LINES PER MILLIMETER	ANGULAR (ARC-SEC)	SURFACE (MILES)	ANGULAR (ARC-SEC)	SURFACE (MILES)
MERCURY	120	.13	52	1	405
VENUS	120	.13	39	1	301
MARS	106	.15	35	1	234
JUPITER	64	.25	440	1	1760
SATURN #	59	.27	975	1	3612
URANUS #	56	.28	2193	1	7831
NEPTUNE #	54	.29	3410	1	11756
PLUTO #	32	.50	8160	1	--

\* FOR OPTICAL QUALITY FACTOR .70

# REQUIRED EXPOSURE TIMES BEYOND CAPABILITY OF PRESENT MOL CAMERA

FIGURE 36

MOL SYSTEM CAPABILITY FOR ACCOMPLISHMENT OF PLANETARY  
PHOTOGRAPHY, COMPARED TO GROUND-BASED TELESCOPE SYSTEMS

DORIAN  
HANDLE VIA  
BYEMAN  
CONTROL SYSTEM

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~~BYEMAN~~  
Control System  
DORIAN/GAMBIT

DORIAN GAMBIT

Handle via  
BYEMAN  
Control System

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