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HISTORY OF THE PURPOS SATELLITE SYSTEM



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HISTORY OF THE POPPY SATELLITE SYSTEM

FOREWORD

This report describes the history of the POPPY project from its concept in 1958 through its termination on 30 September 1977. This history was compiled at the request of the Director, National Reconnaissance Office to the Director, Program C. Included in this report are the significant events during the nineteen years of the POPPY project, including the development and refinement of POPPY satellites, mission ground stations, ground readout equipment, analog analysis, and data processing. The impact of failures, problems and anomalies are evaluated. Successes of the POPPY project are measured against program objectives. Technical data, cost history, key contributions, a glossary of terms related to the POPPY project, and a bibliography are contained in annexes to the report.

Each of the chapters in the report is intended to be somewhat self-contained. Annex 1 contains a summary of mission characteristics and merges some information from the third through the seventh chapters in order to provide a chronological summary of the technological innovations in the order of the launches.

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I. CONCEPTION

During the second world war, lookouts on German submarines used a hand-held crystal video type radar receiver named ATMOSS to detect pulses emitted from search radar on allied warships and airplanes. This simple passive electronic countermeasure receiver enabled evasion before range had closed sufficiently for returning radar echoes to indicate the presence of the submarine to the searching warship or airplane. After the war, crystal video receiver technology was applied in the direction finding systems for use on American warships and airplanes because of its simplicity, its small size and wide open frequency detection characteristics. By the late fifties, a crystal video receiver was being fitted to type 8-A submarine periscope; the first three receiver prototypes were developed by the Naval Research Laboratory (NRL) in late 1957.

On 4 October 1957, the Union of Soviet Socialist Republics (U.S.S.R.) launched the first artificial satellite as part of the thirty-month International Geophysical Year. Thirty days later, the second Sputnik was launched with a live dog as a passenger.

About one month later on 6 December 1957, with the whole nation watching on National television, the United States (U.S.) attempted its first satellite launch on a totally new sophisticated Vanguard missile. The payload was the grapefruit sized Vanguard satellite weighing three pounds. The missile lost thrust after 2 seconds and crashed in a huge ball of flames. The tiny satellite fell out of the nose fairing and rolled away. Its antennas were bent and broken and charred black from the fire - yet it was still transmitting its signal. This national embarrassment triggered a number of things. The immediate results were a presidential decision to task the Army team, under Dr. Wernher von Braun at the Redstone Arsenal, to launch a satellité on the existing ICBM called Jupiter C. Fortunately, these efforts did meet with success and on 31 January 1958, the U.S. placed its first satellite, Explorer I, in orbit. This satellite discovered the Van Allen belt. The Navy Vanguard team succeeded on Saint Patrick's Day, 17 March 1958, by placing Vanguard I in a highly elliptical orbit. This satellite, powered by solar cells, transmitted its signal for over six years. This stable orbit with constant transmission from the satellite permitted the first long term observation of orbital dynamics. This resulted in the discovery of the "pear-shaped earth" and initiated a series of sophisticated modeling efforts of the earth's gravity field which is so important for predicting satellite positions vs time and for ballistic missile accuracy.

But the Vanguard initial failure also had other longer range effects. It caused the nation to re-evaluate its position in the newly arrived space age. We felt threatened in that we seemed to be falling behind in this new high technology area. A frantic call went out to better educate more engineers and scientists in our colleges and universities. The gauntlet had been laid down and America would

respond with a tremendous effort and close that gap. In retrospect the Vanguard program with its spectacular failure but subsequent success and its tremendous technology advances may have been the best thing that could have happened to the infant U.S. space program.

Also, of much more specific value to the Navy was the fact that Vanguard had developed a technology base in satellite design at NRL which formed the foundation for the subsequent POPPY program.

These first space exploration successes stimulated the Advanced Research Projects Agency (ARPA) to solicit other DOD elements for proposals for space related projects. The Chief of Naval Operations (CND) relayed the query to Navy scientific and technical organizations by asking, "All hands to consider how they could use space in their design ideas for the Navy."

NRL responded to the CNO query with the proposal to launch a satellite into a 500 NM circular orbit. The satellite would be equipped with an S band crystal-video receiver to detect signals of sufficient power density and would use an uncoded radar beacon to transpond them (pulse-for-pulse) down to cooperative ground stations for recording and subsequent analysis. The proposal was reviewed and approved through the Navy and DOD and was approved by the President in August 1959 as Project TATTLETALE.

order to tighten security. A special security system was then established by the Office of Naval Intelligence (CNI). Access was limited to individuals with a strict need-to-know and required the approval of CNI, ARPA, or the Office of the Special Assistant to the Secretary of Defense (Special Operations). Those individuals granted access were required to execute a project secrecy agreement.

NRL developed the concept and designed the ELINT satellite and ground readout equipment which was continued as the top secret Project Walnut. Additional security was provided by adding an NRL scientific cover experiment designed to telemeter measurements of solar activity in X-ray, Lyman-Alpha, and ultraviolet radiations above the earth's atmosphere. This cover experiment became the first of a series of SOLRAD satellite experiments designed and exploited by the Naval Research Laboratory. The cover name GRAM (Galactic Radiation and Background) was used for the intelligence and scientific satellite.

With the first launch pending, new importance was added to the project after the crash of a U-2 high-altitude reconnaissance aircraft in the U.S.S.R. on 1 May 1968. Subsequent cancellation of routine U-2 overflights ended the capability for deep interior surveillance of the U.S.S.R. Future overhead surveillance missions would require presidential approval.

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The first U.S. and reconnaissance satellite (photo or SIGINT) to become operational was successfully launched on 22 June 1960 from Cape Canaveral, Florida aboard a Thor-Able-Star. GRAB/Dyno 1, as this ELINT satellite was named, shared the launch vehicle with Transit 2A, the Navy's second navigation satellite. The purpose of the ELINT package, designated Dyno 1, was to collect ELINT data from the interior and infrequently covered maritime regions of the U.S.S.R. ELINT data is transponded by the Dyno 1 for a forty-minute period after interrogation. The mission ground station equipment was operated only when Dyno satellites were transmitting above their radio horizon; recorded data from the down link(s) on magnetic tape; and forwarded data recordings with collection logs to NSA via the Armed Forces Courier Service (ARPCOS).

The ELINT capability of Dyno 1 was successfully tested on 4 July 1960 at Wahiawa, Hawaii, well out of Soviet range. Tense political climate following the U-2 incident dictated that this satellite would be tasked only by specific presidential authority. Thus only 22 data collection passes across the SINO Soviet bloc were collected and processed during the three month useful lifetime of the GRAB/Dyno 1 satellite.

II. ORGANIZATION

Throughout its lifetime the POPPY project was managed, operated and supported by a number of DOD elements under overall Navy leader—ship. There were two distinct phases of organization, pre-NRO and the reorganization following establishment of the NRO in 1962. During both of these phases, multi-agency activities were coordinated by means of a Technical Operations Group (TOG).

A. PRE-NRO

Directorship of Project GRAB/Dyno (see Annex 3) was assigned to the Director of Naval Intelligence (DNI). The TOG acted as the steering committee or staff of the project director. The TOG members were drawn from designated DOD organizations and the National Security Agency (NSA). The participating organizations, their responsibilities, and the staff responsibilities of their representatives to the TOG were specified by the DNI.

- 1. The NRL developed the overall system concept; designed, constructed, deployed, and logistically supported electronic receiving, recording, and timing equipment at mission ground stations; designed, fabricated, tested, and calibrated the satellite systems from concept through launch injection into orbit, and provided engineering and technical direction through the operational exploitation phase; trained mission ground station personnel; controlled the satellite prior to launch; monitored the launch; and monitored on-orbit performance of the satellite. The NRL member of the TOG was designated as the project technical representative/project manager until January 1971.
- 2. The Naval Security Group (NSG) directed and coordinated all mission ground station operations; acted as the focal point for all electrical communications associated with the operations of the project; provided sites, support facilities and operating and maintenance personnel at the NSG mission ground stations. The NSG member of the TOG was designated as the project operational representative.
- 3. The NSA authorized the allocation of service cryptologic personnel to man and operate the mission ground stations; processed all ELINT data recordings and disseminated the ELINT product; interpreted national intelligence collection and processing requirements and made tasking recommendations; and furnished the magnetic tapes for recording data at the mission ground stations. The NSA representative to the TOG was designated as an advisor to the staff.
- 4. The INI had the authority to review and approve all aspects of the project. The Scientific and Technical Intelligence Center of CNI (STIC) provided intelligence requirements to the director; provided signal analysis support to NSA; monitored the signal analysis

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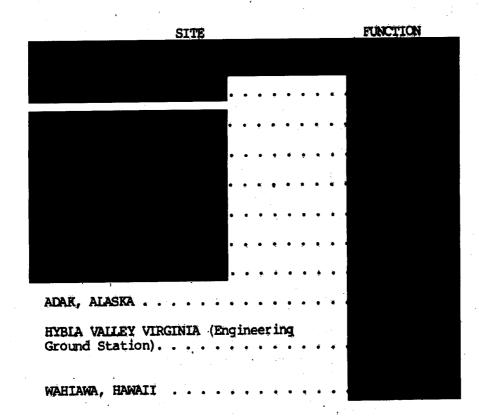
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program; and disseminated quality control technical data to mission ground stations. The STIC member of the TOG was designated as the product control representative.



- 6. As of 1962, the Army Security Agency (ASA) provided a site, support facilities and operating and maintenance personnel at the ASA mission ground station.
- 7. The sites where dedicated GRAB/Dyno collection and processing and spacecraft commanding systems were installed in the pre-NRO period are as follows:



B. NRO PROGRAM C

Upon consolidation of all U.S. overhead reconnaissance projects into a National Reconnaissance Program (NRP) in 1962, DNRO established NRO Program C as the organizational component to continue operation and management of the Dyno satellites. By December 1962, the Byeman

Control System was implemented throughout the project to govern security procedures. Byeman Project replaced the Project Walnut security clearance. The satellites became designated as POPPY satellites, and subsequent launches would receive NRO mission numbers in the series. The DNRO reviewed the organization and responsibilities within Program C as proposed by the DNI in the time frame July 1962 through January 1963. The following changes and additions to organizational responsibilities were implemented:

- 1. The NRO provided funding to support Program C based on annual program budget submissions by NRL beginning with fiscal year 1963. The Consolidated Cryptologic Program (CCP) continued to support mission ground station personnel, magnetic tape, and data processing.
- 2. The DNI became designated as Director, Program C. The CNI provided a POPPY project director responsible for supervising and administering all aspects of the project subject to the approval of Director, Program C.
- 3. The NRO Deputy Director for Operations prepared routine tasking schedules for the operational control of POPPY satellites with technical support from the TOG. Routine tasking was directed by the NRO Satellite Operations Center (SOC) through NSG. NSA directed quick reaction tasking of POPPY satellites through NSG following tip-off of Soviet space or missile activity:
- 4. Program A of the NRP provided the launch vehicle, launch vehicle/satellite integration, and launch services. The NRO separately funded this support.
- 5. The Naval Research Laboratory was designated the technical director responsible for design, development, and operational support.

C. LATER CHANGES

Program C and the POPPY project organization functioned in the same general manner as established under the NRO for the next fourteen years. Changes subsequent to 1963 were the result of realignments within the Navy, changes in capabilities leading to added responsibilities, and changes in participation. Significant changes and associated factors were the following:

1. Starting in April 1963, the requirement for detecting, electrically reporting and logging new and unusual signals was added to the responsibility of mission ground stations. The resulting on-line manual analysis produced the earliest possible recognition of

tion resources for exploitation

after it was couriered

back to CONUS for processing. Various site facilities were upgraded

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and changes made to the satellite designs in order to enhance the detection and recognition of the new emitters as they were added to the Soviet radar inventory during their rapid build-up during the 1960's. These Soviet radar changes started with original designs in the landbased early warning

almost all of which were initially detected gained from POPPY.

- 2. In 1967, ONI became redesignated as the Naval Intelligence Command (NIC). COMNAVINTOOM retained the responsibility of Director, Program C.
- 3. In response to the 1966 Presidents Scientific Advisory panel's urgent request to expoit overhead reconnaissance to determine if the Soviet Union was developing an antiballistic missile radar system the program site in was equipped with analog-to-digital data conversion and a small data processing computer. This on-site computer-aided manual analysis system was installed in and Adak, Alaska in late 1976.
- 4. AFSS participation ended in October 1969 with the closure of its last POPPY mission ground station at
- 5. ASA participation ended in August 1970 with the closure of its POPPY mission ground station at
- 6. On 14 January 1971, the Navy Space Project Office was established as PM-16 of the Naval Material Command. The Manager, Navy Space Project (FM-16) was designated as the Director, Program C. POPPY project director functions were performed within the System Project Office (SPO) of FM-16. Liaison with NIC continued.
- 7. In June 1973, PM-16 was redesignated as PME-106 of the Naval Electronic Systems Command with its manager continuing as Director, Program C.
- 8,
- 9. On 2 August 1977, the Director, Program C directed cessation of the POPPY Mission operations. However, the Engineering ground station at ment activities to sustain spacecraft operational capability.
- 10. On 30 September 1977, DNRO directed termination of the POPPY program as the

III. SATELLITES

All of the GRAB/Dyno ELINT satellites contained scientific cover experiments of the SOLRAD type. Engineering evolution and innovative refinement of the spacecraft and ground station subsystems were continued by NRL in the POPPY program following the transition from GRAB/Dyno to POPPY. The satellites were designed for long-life high-duty cycle operation. All satellites were designed for full utilization any time a satellite was in view of a ground station. Eight satellites provided useful intelligence for periods in excess of This combination provided a very efficient low-cost satellite system which continuously had continuously had operating satellites on-orbit from 1963 until 1977 when the program was terminated.

A. CLUSTER SIZE

The GRAB/Dyno satellites were launched pickaback with other scientific and navigation satellites. Two of the five attempts to orbit Dyno satellites were successful. The first POPPY launch Mission orbited a pair of ELINT satellites. The next two launches orbited POPPY Each of the final four launches carried satellites

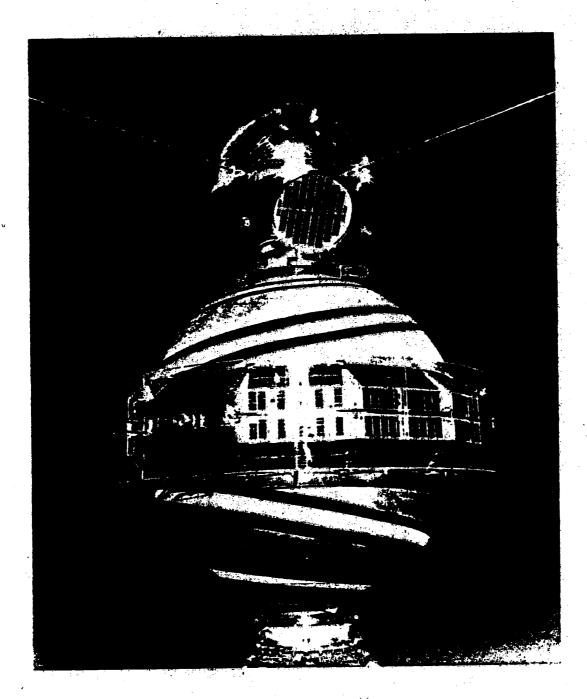
B. ORBITAL CHARACTERISTICS

C. PHYSICAL CHARACTERISTICS

The GRAB/Dyno satellites were of spherical configuration with a diameter of 20 inches. The first Dyno spacecraft weighed 42 pounds; later Dyno spacecraft weighed up to 55 pounds.

In the first POPPY launch, both of the satellites were composed of two 20-inch diameter hemispheres joined by a 4-inch wide equatorial band. The stretched sphere design was used for all satellites in the next three launches, either with 20-inch or 24-inch diameter configurations. These satellites weighed between 55 and 130 pounds.

The multiface design was first used on Mission in 1967, three of the four satellites being multiface. The fourth was a



First U.S. SIGINT Satellite, GRAB/Dyno 1 mounted above TRANSIT 2A

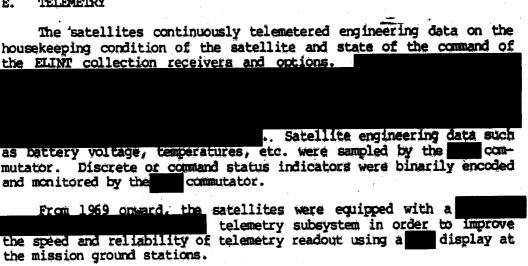
stretched sphere with a 9-inch equatorial band. The multiface satellite measured 27-inch diameter across flats at its 12-sided equator. Spacecraft equatorial bands varied in size to accommodate the increase in size and number of electronic and mechanical components necessary to satisfy the increasing mission requirements. The basic multiface structure was utilized on all POPPY satellites after The weights of the multiface satellites ranged from 162 Mission to 282 pounds.

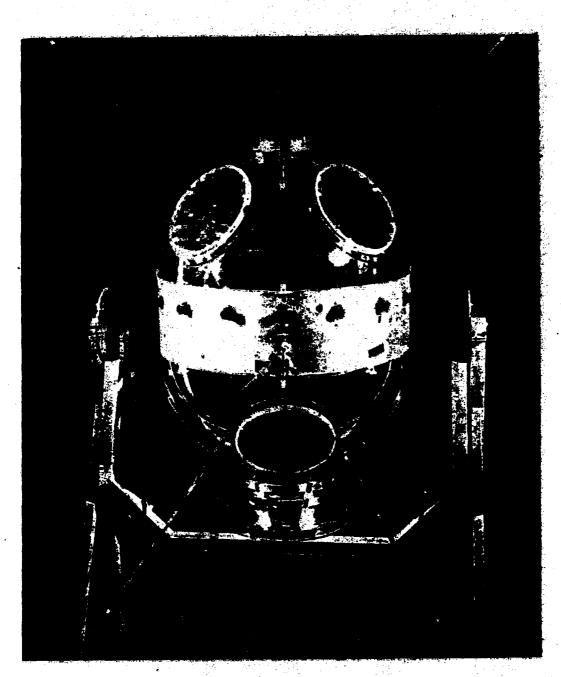
POWER D.

The first Dyno satellite was powered from a 12-volt storage battery consisting of nine D size cells in series. The battery was charged by silicon solar cells and was designed to provide useful life of one year in orbit. Six 9-inch diameter round patches of 156 cells were symmetrically located on the surface of the sphere so that approximately one watt of power would be available for any orientation of the satellite. In full sun, a single patch could provide about two watts of charging power to the chemical storage battery. From Dyno 2 onward, +12-volt and -12-volt storage batteries were included.

In the 24-inch diameter satellites, more solar cells of smaller size were placed on 11-inch diameter panels. The six symmetrically placed panels provided about four watts of charging power to an 18cell, nickel-cadmium battery pack. (NOTE: 9-inch diameter solar panels were used with the 20-inch diameter satellite and 11-inch diameters with the 24-inch satellite.)

TELEMETRY E.





Typical 24" Diameter Spherical Satellite with 9" high Equatorial Band

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The first GRAB/Dyno satellites transmitted telemetry signals at 108 MHz. In later years, frequencies in the neighborhood of 137 MHz were used to avoid interfering signals.

In the spheres and stretched spheres, the power output of both the telemetry transmitter and the ELIMT data transmitter(s) was fed into a single omni-directional, 4-element turnstile array. The same antenna served for reception of the command signals. The multifaces used two such turnstile arrays, one for command reception and telemetry transmission, the second for ELIMT data transmissions.

F. COMMAND

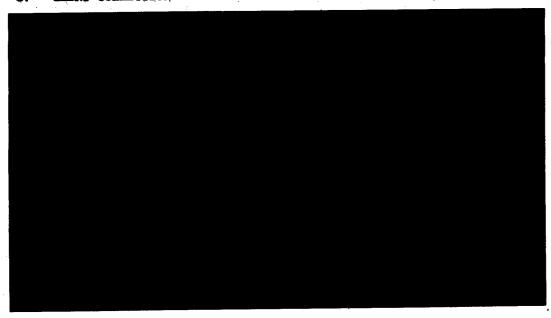
The command receiver in the GRAB/Dyno satellite was adapted from the system used with Vanquard.

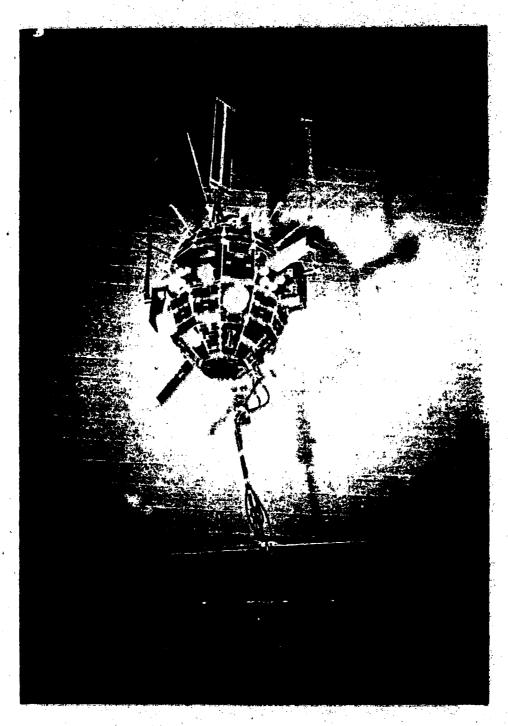
The receiver

was a double superheterodyne with crystal control on both the first and second oscillators to provide stability. Audio amplification of the proper tone activated the corresponding relay switches to turn on the data link transmitter and one of the two timers and to turn off telemetry at the end of useful life.

As command options increased to include more data receivers, data links, experiments, station keeping devices, etc. the basic command system was expanded from a simple tone system to a tone digital system utilizing ten frequency tones allowing over a hundred commands.

G. ELINT COLLECTION

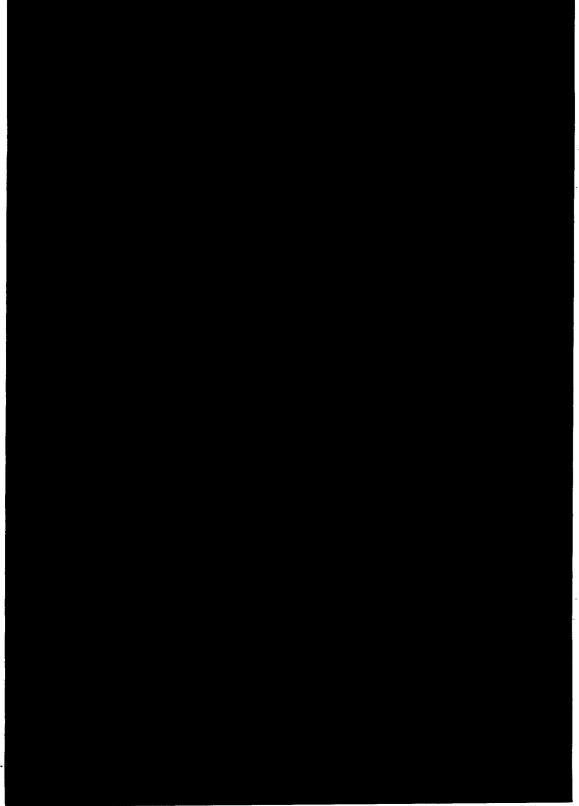




Typical 27th Multiface Satellite Mission

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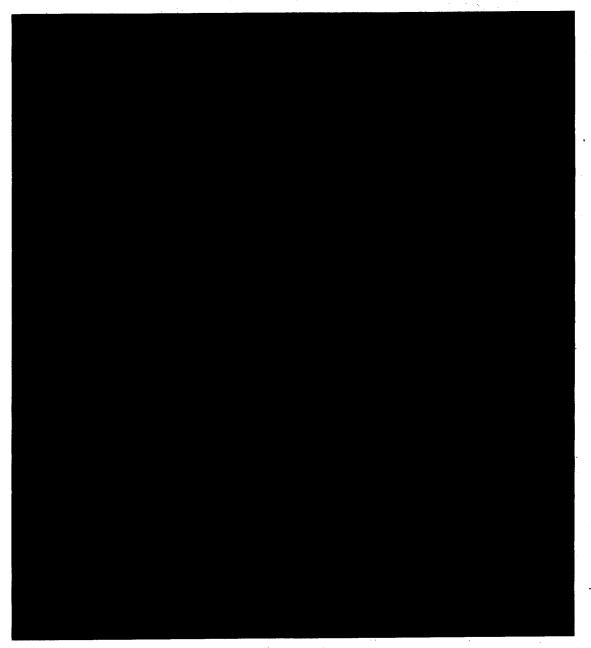
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H. ATTITUDE STABILIZATION AND STATION KEEPING

With refinements in the employment and placement of new directional antenna types, the orientation of the vertical axis of the satellites became a factor affecting performance. Satellites which tumbled or orbited upside down or sideways did not orient their ELINT antennas to produce optimum coverage in azimuth. To overcome this problem, a Gravity Gradient Stabilization Experiment (GGSE) was implemented in the eighth launch (Mission Come satellite was

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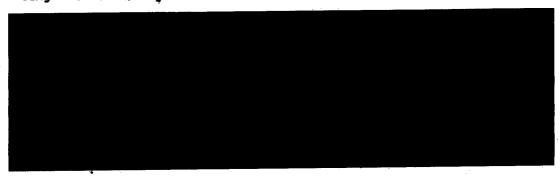
fitted with an extendable 28-foot at the end of the boom

boom. A tip mass

This

2-axis gravity gradient stabilization experiment succeeded in aligning the satellite's axis to within degrees of the local vertical and consumed no on-board power.

Gravity Gradient Stabilization was also implemented in Mission including 2-axis gravity gradient and 3-axis gravity gradient with two additional booms to provide yaw stabilization. In Mission two satellites were equipped with 2-axis gravity gradient stabilization, and two were equipped with the 3-axis system. One of the 3-axis stabilized satellites used additional booms; the other used a flywheel to provide active stabilization of the yaw axis. All satellites launched thereafter used the 3-axis, active system employing a single boom and flywheel.



Anhydrous ammonia was successfully used as the microthruster gas in one satellite in 1967 and in all satellites launched thereafter.

Three axis stabilization was a necessary prerequisite to the station keeping capability.

IV. MISSION GROUND STATIONS

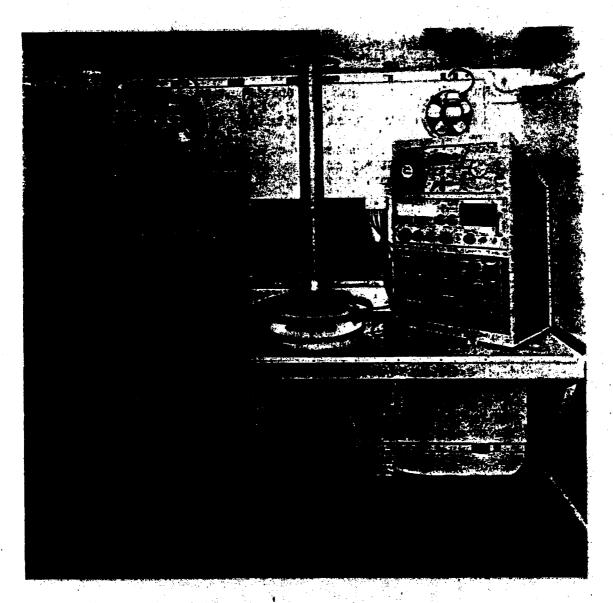
In addition, NRL operated an engineering data readout and interrogation site at Hybla Valley, Virginia until July 1967, when it was relocated to
The operation was relocated to Adak Island after Dyno 1 due to local interference 1962 to preserve operational security. Due to the scheduled closure of the SIGINT station at a mission ground station was established at in 1962.

Adak was the only one of the GRAB stations to continue POPPY operations until project termination. Adak ceased POPPY operations in August 1977.

During the initial operations collections were conducted in Earth Satellite Vehicle (ESV) shelter huts. After the system stabilized in the sixties, the transition was made to permanent buildings.

A. ESV HUTS

The ESV huts were procured from Craig Systems, Inc. of Lawrence, Massachusetts. These lightweight, aluminum shelters, designed for



First Generation GRAB/Dyno 1 Receiving, Timing, and Recording Position inside ESV Hut

POPPY Mission Ground Station Typical Earth Satellite Vehicle (ESV Hut Installation)

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POPPY Mission Ground Station Permanent Building

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worldwide service conditions, could be transported by helicopter, large aircraft, truck, rail, or ship. They were described as all-weather shelters constructed of lightweight rigid floor, roof, sidewall and end panels secured by two lifting-band assemblies. The panels were fire resistant and water proof. The ESV huts came equipped with two work benches, a spare parts cabinet, exhaust fans, a filtered air inlet, incandescent lighting, a power entrance and distribution cabinet, and an electric heater.

At NRL the ESV huts were fitted out for operations prior to deployment. NRL installed sheet-metal supporting racks to hold the electronic equipment, the necessary electronic equipment, an antenna mast, antennas, an antenna steering mechanism and brake assembly, and an air conditioner. The ESV huts were shipped as stand-alone assemblies requiring only minimal site support. At the mission ground stations, the ESV huts were placed on concrete pedestals, on pavement, or on elevated platforms equipped with carport-type canopy roof, provided with electrical power and they were ready to conduct operations. The ESV huts were only manned to prepare for and conduct scheduled collection operations. By 1962, in preparation for the first dual-satellite launch, each collection site was provided with two of the fully equipped ESV huts.

B. PERMANENT BUILDINGS

As the expanded exploitation and data collection roles placed increasing burdens on the site personnel, a move into permanent buildings was started in the early sixties when buildings housing the phased-out GRD-6 direction finding systems became available at Adak. These wooden buildings were adequate to replace the ESV huts and provided the necessary space to install the growing number of bays of electronic equipment.

At other sites different buildings or parts of buildings were made available for the POPPY installation. By 1967, the installations were in permanent buildings.

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V. GROUND READOUT EQUIPMENT

Mission ground station functions related to ELINT data collection included telemetry readout, satellite interrogation, and ELINT data monitoring and recording. All mission ground stations performed the telemetry readout and monitored and recorded ELINT data. Capability

A. TELEMETRY READOUT

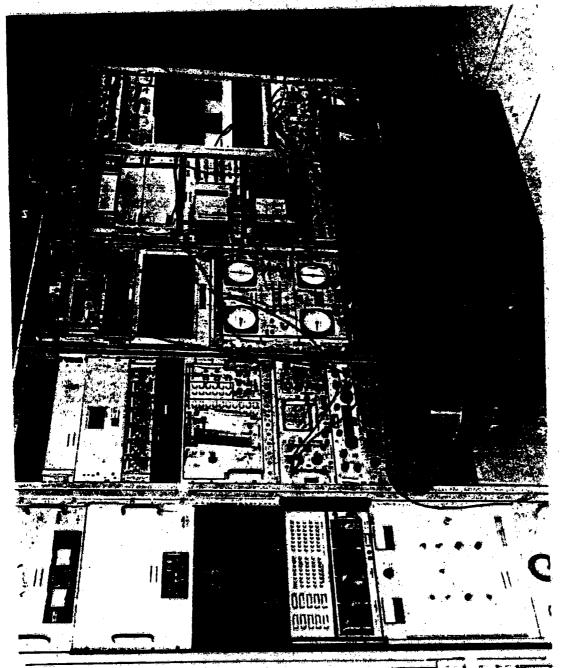


B. INTERROGATION

All satellites in 500 nautical mile orbits which came within 1750 nautical miles of an interrogation site could be commanded or interrogated upon acquisition and readout of the telemetry signal. The output of a command tone generator was fed into a transmitter with a 250-watt power output and propagated directionally on an array of four 10-element Yagi antennas fitted on the same mast as the telemetry antenna array. The satellite ELINT receiver(s) and data link transmitter(s) would be powered-up or activated when interrogated by the command signal from the ground station. The interrogation would be verified by interpreting state of command data in the telemetry stream.

With the move into permanent buildings, the manually steered antennas were replaced by remotely steerable, pedestal-mounted arrays consisting of two rows of four cross-polarized Yagi antennas. These antennas could be trained in both azimuth and elevation, permitting





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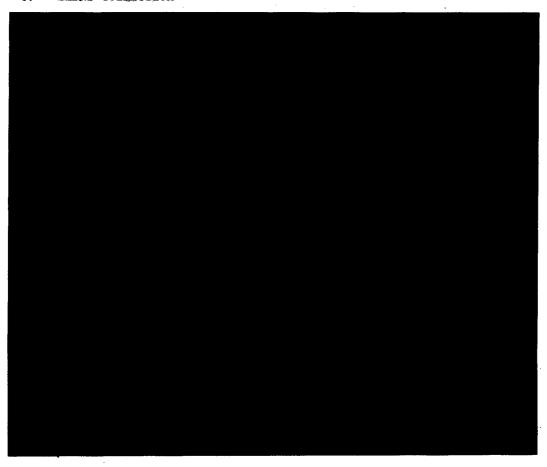
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uninterrupted telemetry and data collection as the satellites passed at high elevation angles. These antennas were fed by 50-watt output command transmitters.

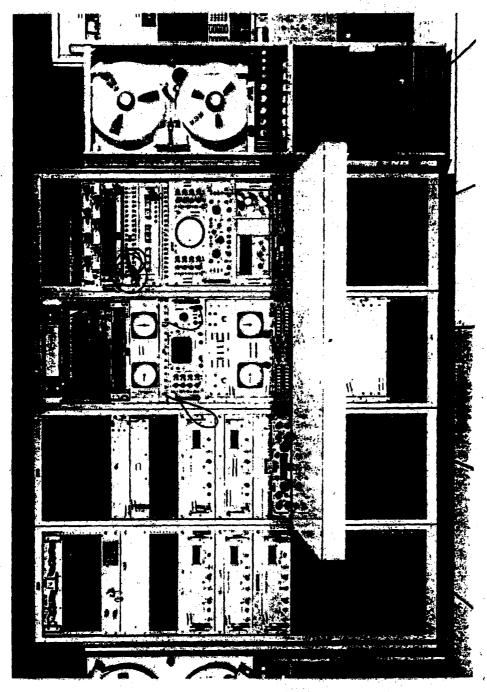
The interrogation position expanded into five bays of equipment manned by one operator. By 1967, the position included programmed command tone generators which read pre-punched cards prepared to implement the specific collection task groups authorized by the NRO Satellite Operations Center (SCC). The position also included an R-390A/URR receiver connected to a 25-foot whip antenna for the reception of the local standard time broadcast used to set the digital time generator. Solid state receivers replaced the R-390A/URR receivers used to copy telemetry.

All satellite interrogation except for ELINT data collection operations, (such as thrusting and power/attitude management, etc.) was performed at the NRL engineering ground station in Hybla Valley, Virginia

C. ELINT COLLECTION



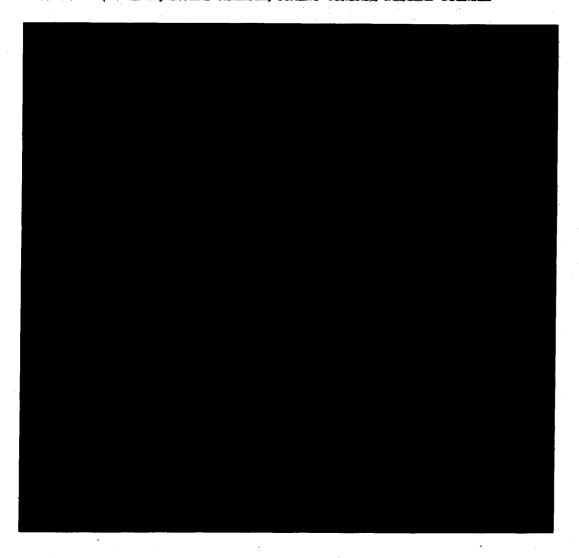
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PPY MGS Collection Position - 1972

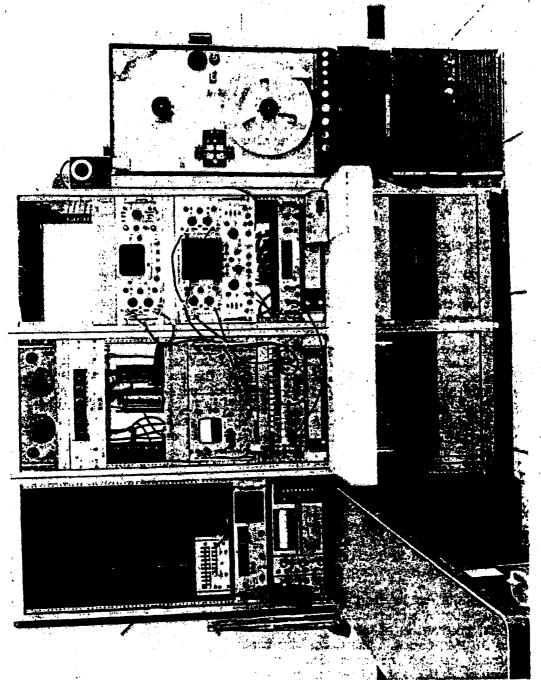
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VI. ANALOG ANALYSIS

Analog analysis of the GRAB and POPPY data was performed at NSA with some analytic support from NRL and STIC. A



POPPY MGS - Analog Analysis Position for Off-Line QC Function

-28-

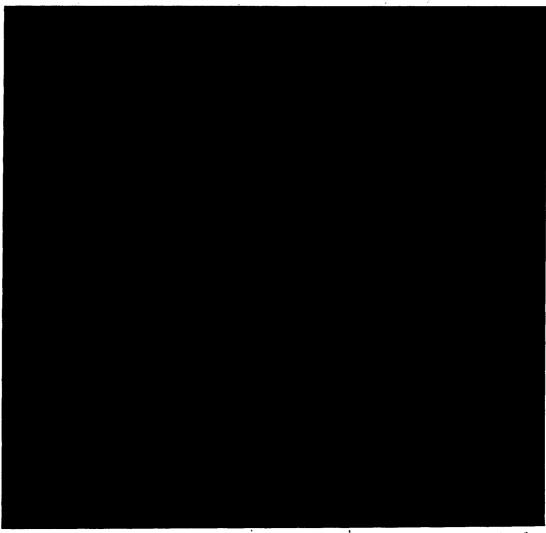
Collection operators noted in their logs occurrences of NSA specified signals of high interest as well as new, unique or unidentified signals. After a pass, analog analysts played back the tapes at their analysis and quality-control positions and performed aural and visual scans of each of the recorded data links. Parameters of these signals of interest and unidentified signals were measured and tabulated. After verification of the parameters of unidentified signals, leading analysts prepared a daily signal of interest tipoff report for transmission to NSA and to other POPPY sites.

In the early seventies, pulse width selectors were added to the analog analysis positions to isolate and display the data collected from a single RF band in the satellite(s).

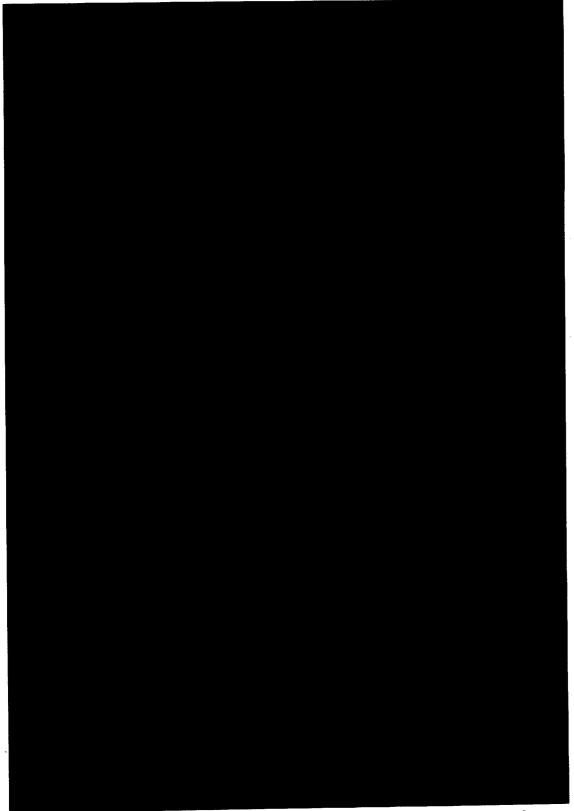
As the reliability in detecting and reporting signals of interest at the mission ground stations became established, the requirement for forwarding all analog tapes to NSA diminished to a requirement to forward only those tapes containing unidentified signals or tapes specifically requested by NSA. Recordings not forwarded were retained for a specified period, then degaussed and recycled.

VII. DATA PROCESSING

A. GRAB DATA PROCESSING



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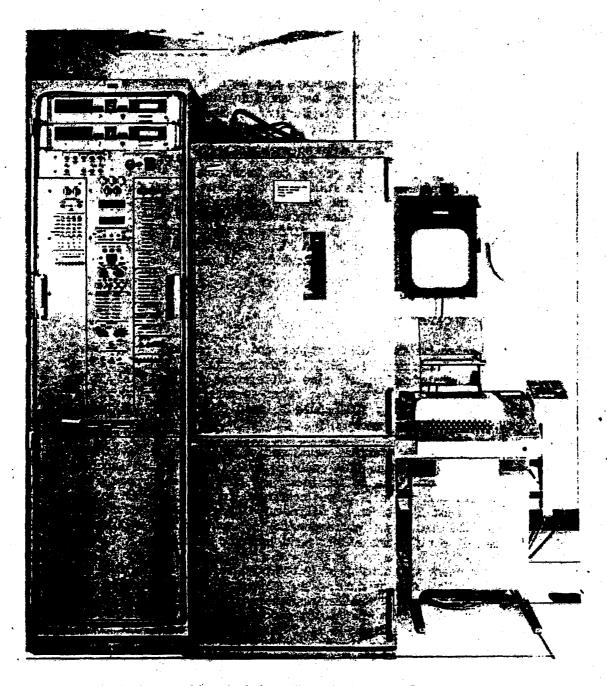


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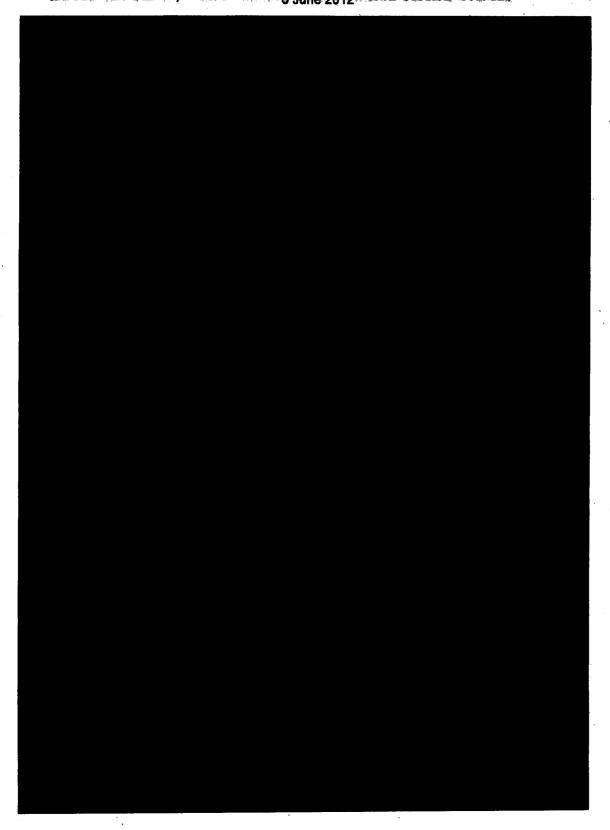
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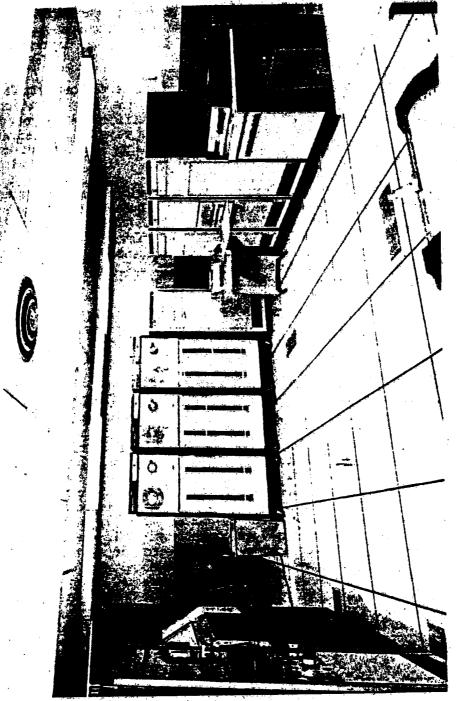
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POPPY MGS - Buffered Digital Tape System - 1972

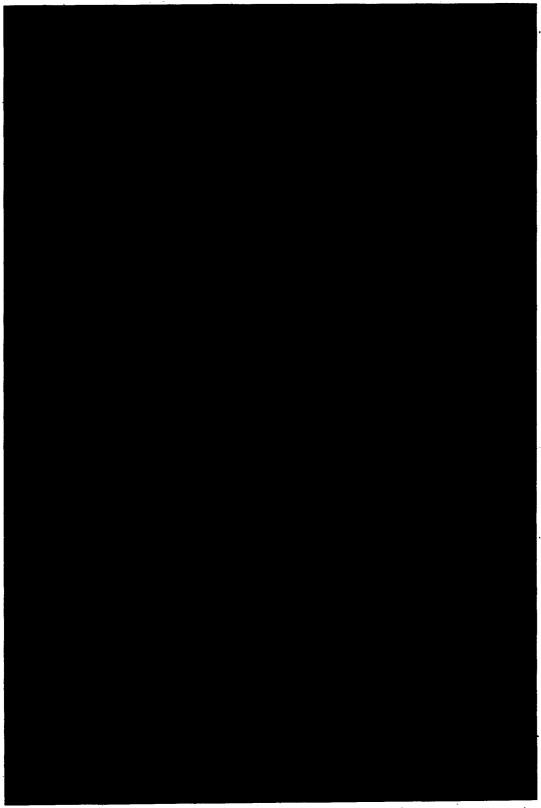




POPPY MGS - SEL-810 CPU Digital Data Processor - 1972

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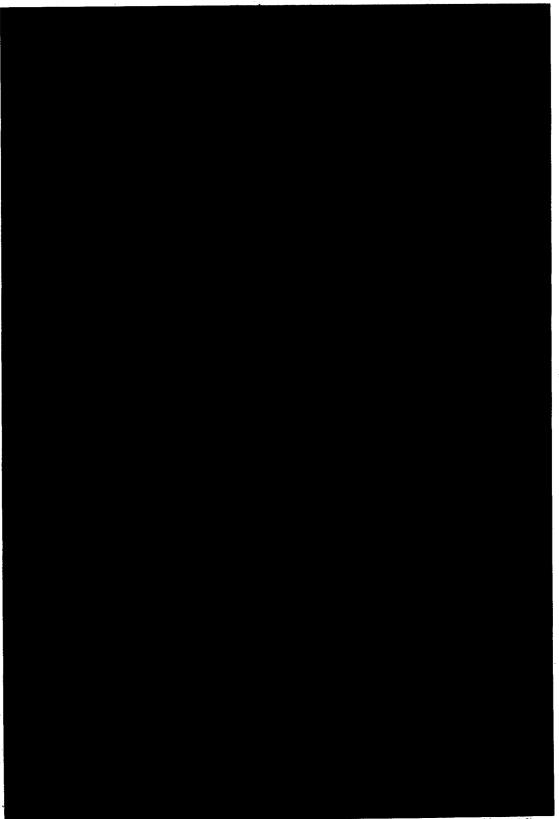


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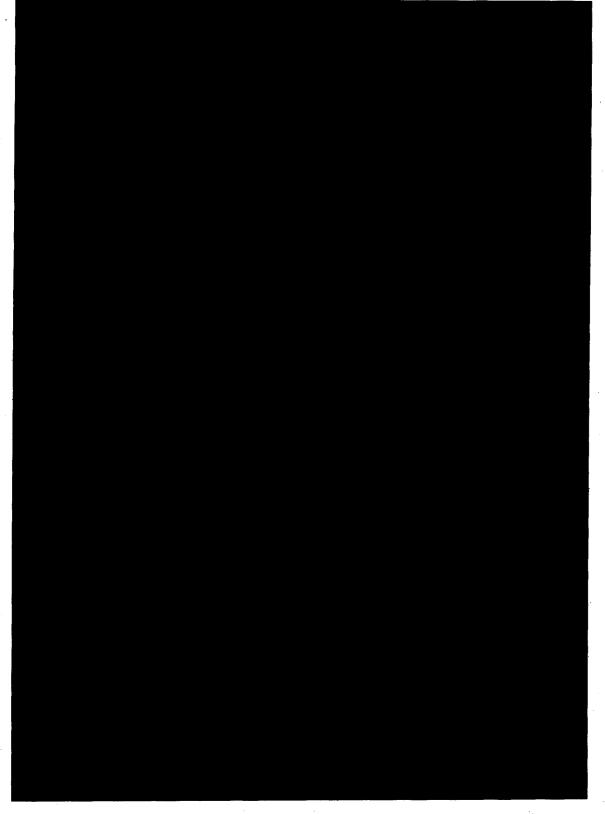
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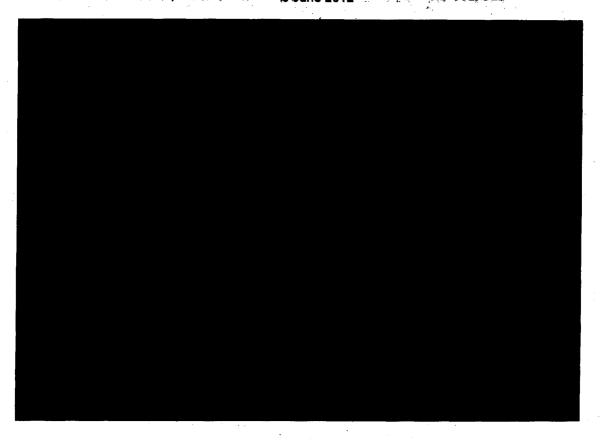
TINDLE VIA DYNAM TRAINS REPROCES 4489-301 CONTROL GENTLE JOINTEL



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-37-

TOP SECRET



CONTROL DATA DATA TO THE TANK THE PROPERTY OF THE PARTY O

VIII. IMPACT OF PROBLEMS AND ANOMALIES

Most project problems and anomalies lead to technical innovations and have been mentioned in preceding chapters. A brief summary of other obstacles is provided in the following paragraphs in the launch chronology.

A. FIRST LAUNCH - GRAB/DYNO 1, 22 JUNE 1960

This mission was useful for ELINT collection for just ninety. days. In addition to the short life, the need for Presidential authorization to interrogate the satellite was a constraint on the amount of data that was collected. The actual impact of these two factors was not overly important since stateside analog analysis and budding data processing capabilities were saturated by the amount of data collected. No anomalies were observed in the intercepted data. No problems were encountered in the interrogation of the satellite or in collection and forwarding of data tapes. Scientific cover experiment SOLRAD 1 was operational for 10 months and highly successful.

B. SECOND LAUNCH, 30 NOVEMBER 1960

The Thor rocket burned out 12 seconds early and was destroyed by Range Safety. Fragments landed in Cuba. The incident resulted in the prohibition of launch trajectories ideal for the desired 74-degree inclination and forced a dogleg injection effort on subsequent launches from Cape Canaveral, Florida. This failure resulted in a nine-month lapse in GRAB collection.

C. THIRD LAUNCH - DYNO 2, 29 JUNE 1961

This launch vehicle had three spacecraft stacked one on top of the other. Failure of separation system between the topmost pair caused Dyno 2 and State University of Iowa Dr. Van Allen's INJUN satellites to remain attached in orbit. Thus Dyno 2 was used on the odd days and INJUN used on the even days during the fourteen month Dyno 2 operational lifetime. The constraint of Presidential approval of interrogations was removed.

Time-sharing the satellite with INJUN precluded interrogation GRAB/Dyno 2 on half the potentially lucrative passes over the U.S.S.R.

D. FOURTH LAUNCH, 24 JANUARY 1962

The attempt was made to orbit a third ELINT satellite with the cover experiment SOLRAD 4A along with four other satellites. The

Thor-Able-Star launch vehicle exploded during launch due to a crack in the second stage engine. The impact of the loss of the satellite was a postponement of project intelligence collection activity.

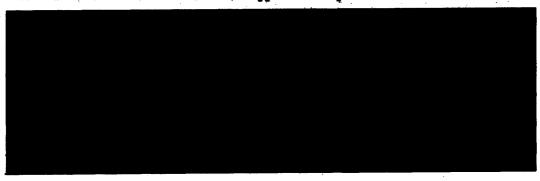
E. FIFTH LAUNCH, 26 APRIL 1962

Another launch failure occurred in the program's first attempt from the Western Test Range at Vandenberg AFB, California. The ELINT package was the same type of configuration used on the prior attempt and SOLRAD 4B provided a cover experiment. The Scout rocket rose for slightly over two minutes and landed in the ocean within sight of the launch pad.

F. SIXTH LAUNCH - MISSION 13 DECEMBER 1962

elliptical orbit of 124 by 1500 nautical miles because the Agena D continued to burn after its programmed turn-off time. This elliptical orbit made it difficult to detect and track the telemetry signal with the fixed elevation antennas used at the collection sites.

Near perigee, the field of view of was considerably reduced to a radius as low as 900 nautical miles, about half the radius of the field of view for the intended orbit. At apogee, the radius of the field of view was approximately 2700 nautical miles.



G. SEVENIH LAUNCH - MISSION 15 JUNE 1963

The attempt to place the into a circular orbit was not entirely successful when the second-stage Agena D failed to ignite on its second circularizing burn. The resulting orbit of 95 by 495 nautical miles decayed within seven weeks.

H. EIGHTH LAUNCH - MISSION 11 JANUARY 1964

Launched into a nearly circular orbit.

I. NINTH LAUNCH - MISSION 9 MARCH 1965

were deployed as separated The first 3-axis gravity gradient stabilization experiment did not perform as planned and the satellite flew sideways. Consequently, the first attempt to use a microthruster for stationkeeping could not be evaluated on this satellite.

caused their tasking suspensions after about of operation. The impact was a loss of some coverage, although

Low voltages created a problem with the after months of useful life, leaving several months of sporadic operations when high sunlight conditions prevailed. The satellite lasted for months.

J. TENTH LAUNCH - MISSION 31 MAY 1967

The thermal design of the Mission multifaced satellites favored the cold end of the thermal specification range and led to high battery voltages. The impact was negligible since the satellites could be activated to reduce the voltages even when not used for ELINT collection. Such activations were easily implemented by the 50-minute activation period and the capabilities for delayed activation and recycled activations at 100-minute intervals.

a stretched sphere with conservative solar cell power system design using four solar cell patches on each hemisphere, experienced power system low voltages during periods of low sunlight and had to be conservatively tasked thereafter.

In late 1969, as the orientation of precluded the use of its microthruster until the When aspect monitoring again indicated a favorable orientation,

the microthruster was activated. caught up with, then went ahead of the before the microthruster could again be used to eliminate the small velocity difference and restore proper spacing.

There were a number of instances of cross-talk between receivers on these satellites, resulting in inhibitions on certain tasking combinations. Many of the cross-talk situations eventually disappeared as battery voltages fell.

eventually succumbed to deteriorating storage batteries but not until attainment of over of useful life.

K. ELEVENTH LAUNCH - MISSION 30 SEPTEMBER 1969

Sowever, nothing out of the

ordinary was observed in the initial data.

On the fourth day after launch, the Agena D apparently exploded, but no immediate adverse consequences to the satellites were observed. The resulting orbit was nearly circular, and all satellites were predicted to be within a 240 nautical mile envelope by late November. All subsystems operated as desired. No constraints were imposed on ELINT collection. Operational tasking commenced on schedule in late

a mission ground station.

failed to respond to interrogation by later.

later. lalso failed to respond.

L. TWELFTH LAUNCH - MISSION 14 DECEMBER 1971

There were some occurrences of cross-talk in receivers of Mission, which very slightly constrained tasking combinations.

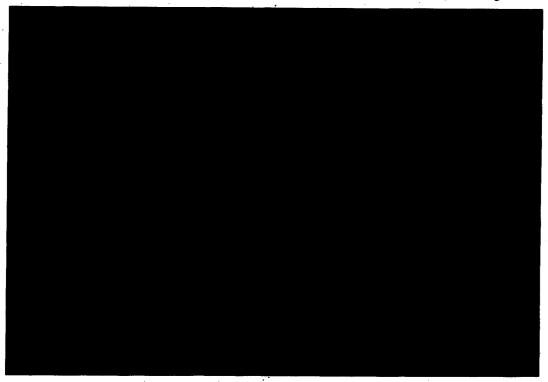
Eventual degradation of storage batteries, starting with in lead to power management procedures that slightly restricted tasking. Thus conserved, remain useful to date.

IX. PERFORMANCE VERSUS OBJECTIVES

Program objectives onew intelligence requirem proven capabilities.	changed over the ments and as a o	years, both in onsequence of the	response to e project's
proven capabilities,			

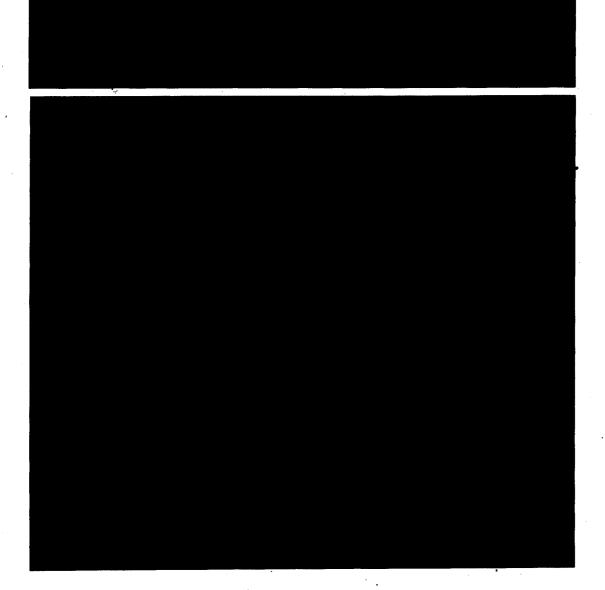
A. GRAB/DYNO 1

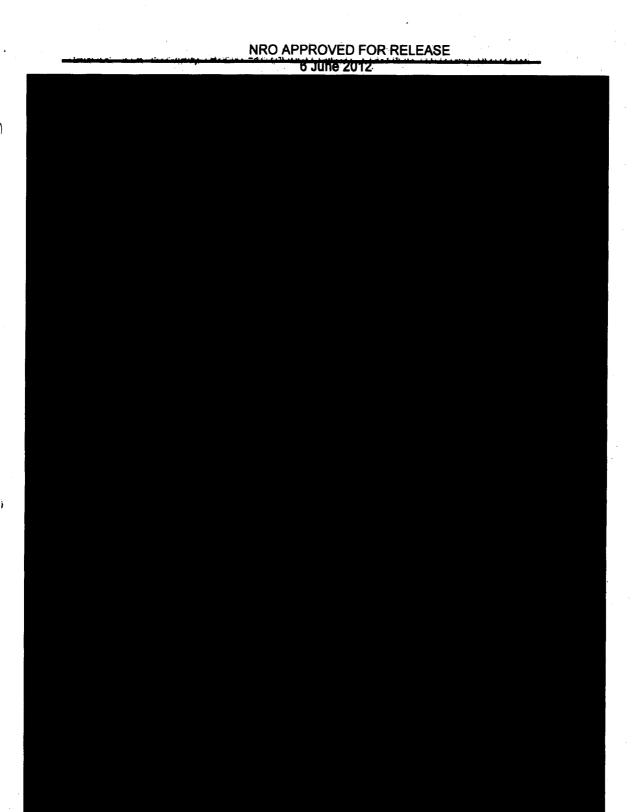
In response to the requirement to collect ELINT from the U.S.S.R., Dyno 1 was activated for the U.S.S.R. The chief result of this mission was the successful demonstration of the collection technology in the satellite and mission ground stations. ELINT results included the following:

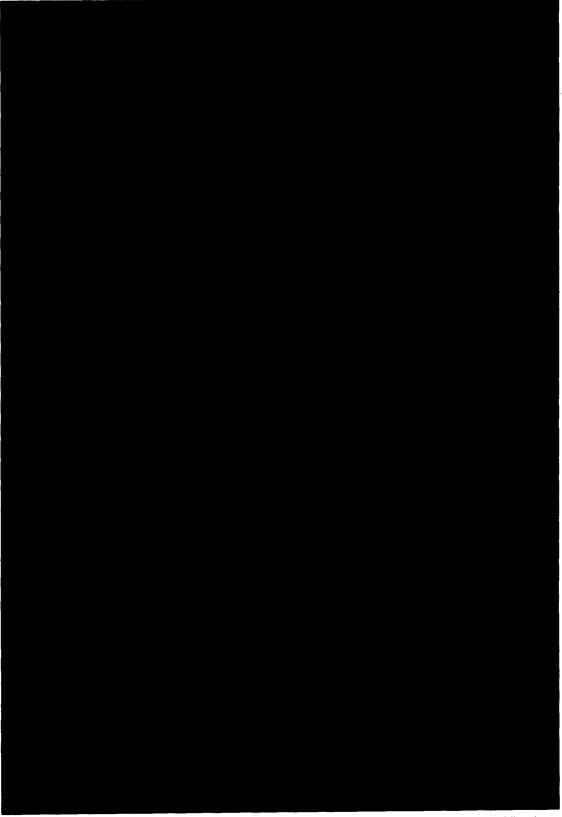


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B. GRAB/DYNO 2

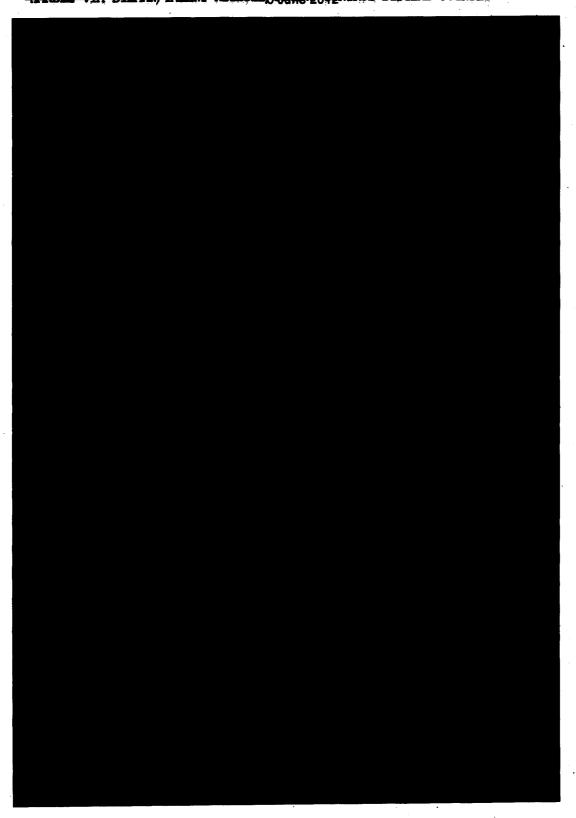




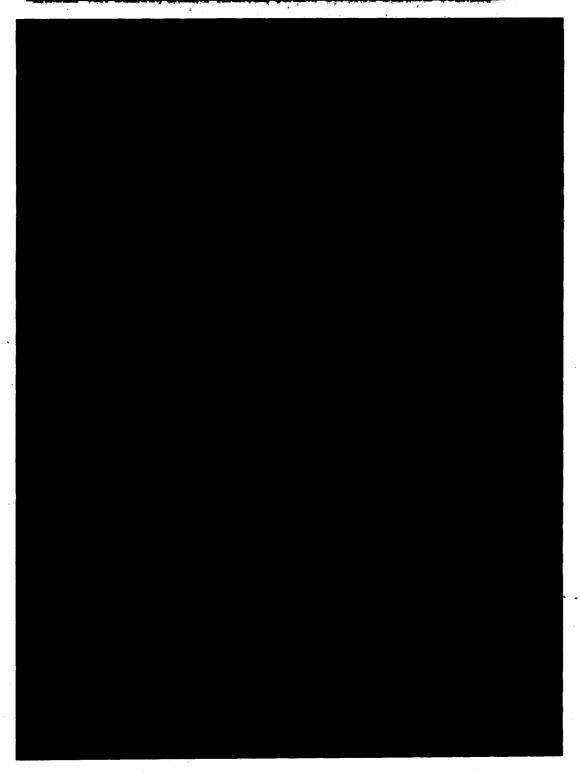


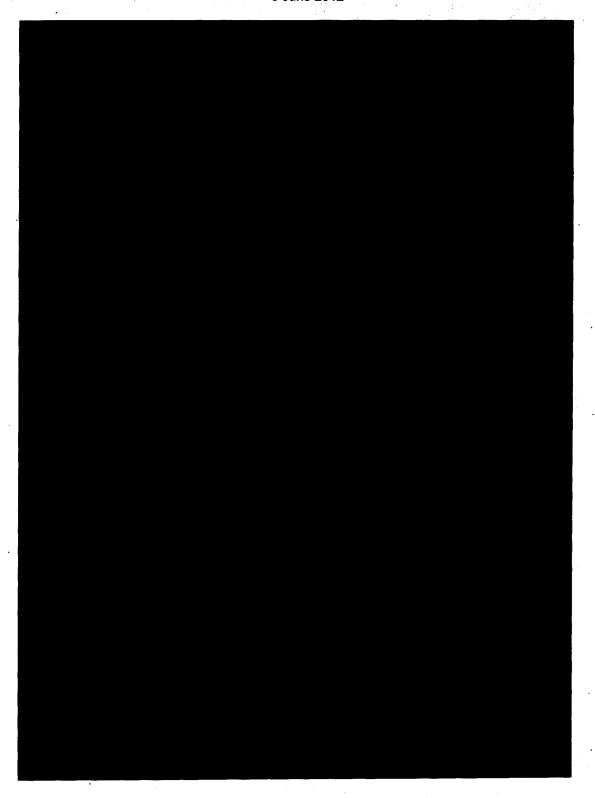
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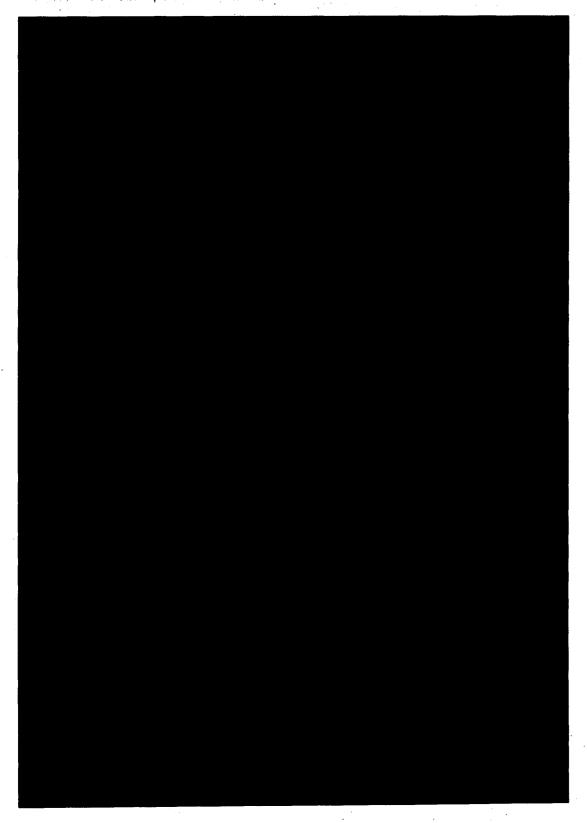


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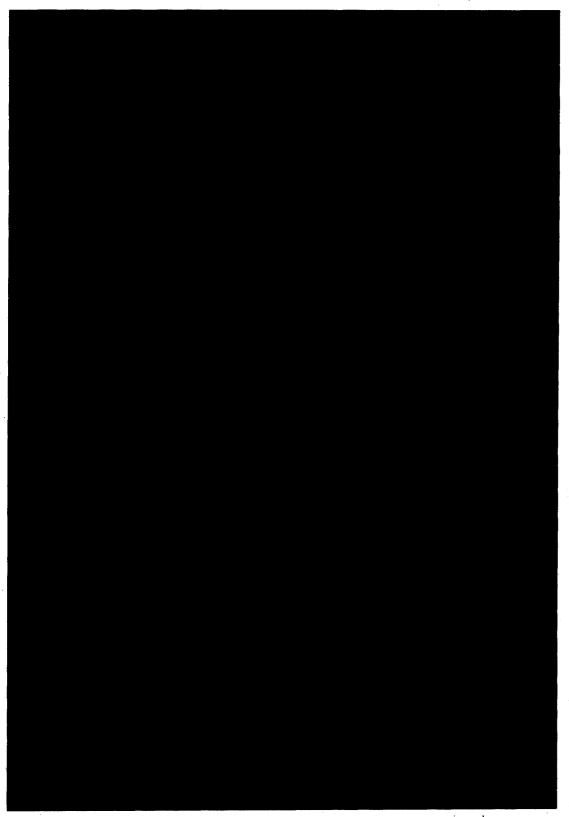


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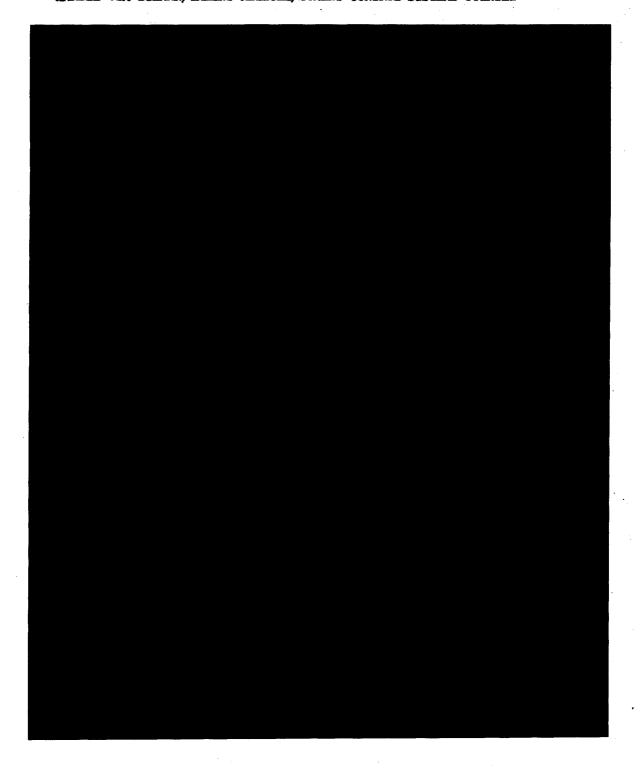


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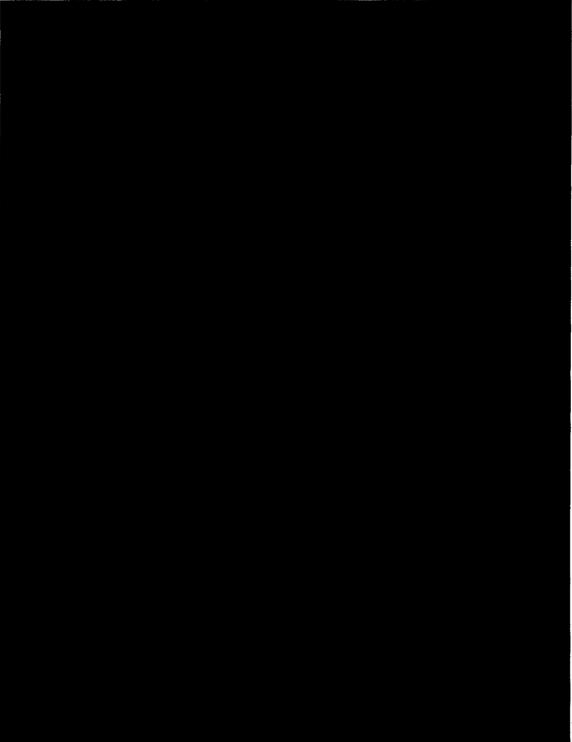
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- HANDLE VIA DYEMAN/THIENT KEYHOLE/GOMENALGONTTOL CYCTEMS JOINTEN



POPPY GROWTH



HANDLE VIA BIEMAN TALENT REMOLES CONTROL SISTING JOINTEL

ANNEX 1

MISSION CHARACTERISTICS

WARDER VII. DIEWAN/WARDER KERENGER MANAGER CONTROL CHEMPER JOINTEN

FIRST LAUNCH

PROJECT NAME:

GRAB (Walnut security clearance)

NRL MISSION:

Pre-NRO Launch: Thor-Able-Star from Cape Canaveral,

Florida on 22 June 1960

ORBIT:

Elliptical with 330 by 565 nautical mile altitude,

66.7 degrees inclination, and period of 101.6

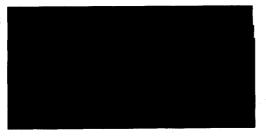
minutes.

REMARKS:

This was the first operational overhead intelligence

satellite for the U.S.

GROUND STATIONS:



SATELLITES:

Dyno 1 Transit 2A (APL)

DIAMETER INCHES: 2

WEIGHT POUNDS:

42

NUMBER RF BANDS:

3

RF COVERAGE MHZ:

END OF LIFE:

9 September 1960

USEFUL LIFE:

90 days

INNOVATIONS:

First U.S. satellite with an ELINT mission and first

successfully launched U.S. intelligence satellite.

First U.S. pickaback launch.

Fixed tuned crystal video receiver with six monopole antennas for omni-directional ELINT data reception.

ELINT receiver active for 40 minutes upon interrogation from the ground.

Intercepted pulses transponded at on 150 MHz omni-directional data down link.

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SECOND LAUNCH

PROJECT NAME:

GRAB (Walnut security clearance)

NRO MISSION:

Pre-NRO

LAUNCH:

Thor-Able-Star from Cape Canaveral, Florida on

30 November 1960

ORBIT:

Not achieved

REMARKS:

Booster vehicle malfunctioned and was destroyed. Impacted in Cuba causing an international incident. Resulted in restrictions on all future launches from Cape Canaveral relative to acceptable launch

azimuths.

SATELLITES:

Dyno Transit 3A (APL)

DIAMETER INCHES: 2

WEIGHT POUNDS: 40

NUMBER RF BANDS: 1

RF COVERAGE MHZ:

INNOVATIONS:

None

NRO APPROVED FOR RELEASE WILLIAM REVUOLE GOLFTON 400 MIDOL CUCHENC TOTAINLY

THIRD LAUNCH

PROJECT NAME:

GRAB (Walnut security clearance)

NRO MISSION:

Pre-NRO

LAUNCH:

Thor-Able-Star from Cape Canaveral, Florida on

29 June 1961

ORBIT:

Elliptical with 475 by 540 nautical mile altitude, 66.8 degrees inclination, and period of 103.8

minutes.

REMARKS:

Pickaback with INJUN - failed to separate. This was the second separation failure of NRL Satellites. Design of these separation systems had not been an NRL responsibility but on all future launches NRL took the responsibility for separating their own

satellites.

GROUND STATIONS:

USN-13 Adak, Alaska

SATELLITES:

Dyno 2, INJUN (SUI) and Transit IIIB (APL)

DIAMETER INCHES: 20

WEIGHT POUNDS:

55

NUMBER RF BANDS:

RF COVERAGE MHZ:

END OF LIFE:

August 1962

USEFUL LIFE:

14 months

INNOVATIONS:

RF coverage extended to two portions of the

spectrum.

NRO APPROVED FOR RELEASE GVE 6 June 2012 CONTROL SYSTEMS TOTATELY

FOURTH LAUNCH

PROJECT NAME:

GRAB (Walnut security clearance)

NRO MISSION:

Pre-NRO

LAUNCH:

Thor-Able-Star from Cape Canaveral, Florida on

24 January 1962

ORBIT:

Not achieved

REMARKS:

No guidance on Able-Star stage

SATELLITES:

Dyno + 4

DIAMETER INCHES:

WEIGHT POUNDS:

55

NUMBER RF BANDS:

RF COVERAGE MHZ:

INNOVATIONS:

Attempt to place five satellites into orbit using a single launch vehicle.

UNABLE LITA DVENAM MINTENTIL VEVUOT & ARRESTANDOT CVCTCMC TOTAMILV

FIFTH LAUNCH

PROJECT:

GRAB (Walnut security clearance)

NRO MISSION:

Pre-NRO

LAUNCH:

Scout from Vandenberg AFB, California on

26 April 1962

ORBIT:

Not achieved

REMARKS:

Scout was launched with no attitude control gas in

the fourth stage.

SATELLITES:

Dyno

DIAMETER INCHES:

20

WEIGHT POUNDS:

55

NUMBER RF BANDS:

RF COVERAGE MHZ:

INNOVATIONS:

First project launch from Western Test Range.

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THE VENTICE SCONDER COMMON CASTERING TOTALLY

SIXTH LAUNCH

PROJECT NAME:

POPPY (Byeman

NRO MISSION:

LAUNCH:

Thor-Agena D from Vandenberg AFB, California on

13 December 1962

ORBIT:

Highly elliptical with 124 by 1500 nautical mile apogee, 70.3 degrees inclination, and period of 116.0 minutes.

REMARKS:

First burn in second stage continued until fuel was

depleted.

GROUND STATIONS:

(D)(3)

SATELLITES:

DIAMETER INCHES:

28

28

WEIGHT FOUNDS:

55

NUMBER RF BANDS:

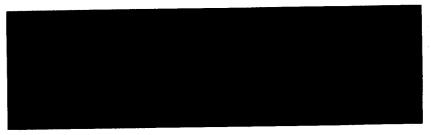
RF COVERAGE MHZ:

END OF LIFE:

USEFUL LIFE:

INNOVATIONS:

HANDLE LITA DVENAN /MAI ENTE VEVUOLO ANTHOLOGO CVENENC TOTANTO



Use of stretched 20-inch diameter sphere design on

First program launch without accompanying unclassified SOLRAD scientific cover experiment.

NRO APPROVED FOR RELEASE 6 June 2012

SEVENTH LAUNCH

PROJECT NAME: POPPY (Byeman

NRO MISSION:

Thor-Agena D from Vandenberg AFB, California on LAUNCH:

15 June 1963

Highly elliptical with 95 by 495 nautical mile ORBIT:

altitude rapidly decaying, 69.9 degrees inclination, and period of 94.1 minutes.

No Agena second burn - failed to circularize. REMARKS:

GROUND STATIONS:

(13)

SATELLITES: *

28 24 DIAMETER INCHES:

65 85 WEIGHT FOUNDS: 85

NUMBER RF BANDS:

RF COVERAGE MEZ:

END OF LIFE:

USEFUL LIFE:

INNOVATIONS:

BYE-56185-78

6 June 2012

SADED VII. DIRVEY PRIENT AUTHORS CONTROL SISTEM BOTHTHE

EIGHTH LAUNCH

PROJECT NAME:

POPPY (Byeman

NRO MISSION:

LAUNCH:

TAT-Agena D from Vandenberg AFB, California on

11 January 1964

ORBIT:

Nearly circular with 490 by 506 nautical mile

apogee, 69.9 degrees inclination, and period of

103.41 minutes.

REMARKS:

(TAT) thrust augmented Thor. Three solid rockets

strapped to booster.

GROUND STATIONS:

(b)(3)

24

89

SATELLITES:

DIAMETER INCHES:

28

WEIGHT FOUNDS:

84

28

NUMBER RF BANDS:

RF COVERAGE MHZ:

END OF LIFE:

USEFUL LIFE:

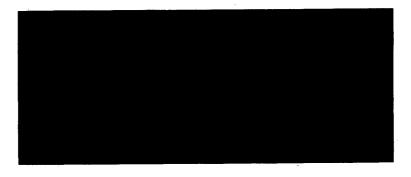
INNOVATIONS:

aligned to within degrees of ver-Axis of tical using 2-axis gravity gradient stabilization with sphere at end of 26-foot boom with tip mass

lite was designed to generate either boom up or boom

down by use of omni-directional antennas.

6 June 2012.



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WANTED REMOTE COMBIN COMBOL GREENE TODINER

NINTH LAUNCH

PROJECT NAME:

POPPY (Byeman

NRO MISSION:

LAUNCH:

Thor-Agena D from Vandenberg AFB, California on

9 March 1965

ORBIT:

Nearly circular with 490 nautical mile perigee by 506 nautical mile apogee, 70.1 degrees inclination,

and period of 183.6 minutes.

GROUND STATIONS:

(b)(s)

SATELLITES:

DIAMETER INCHES:

24

24

WEIGHT FOUNDS:

103

186

24

130

138

NUMBER RE BANDS:

RF COVERAGE MHZ:

END OF LIFE:

USEFUL LIFE:

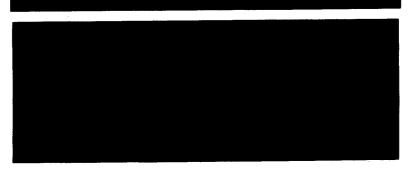
INNOVATIONS:

Three axis gravity gradient stabilization implemented with

6-lupe 2012

Used Eddy current damper to control librations.

Use of microthrusters for stationkeeping



NRO APPROVED FOR RELEASE 6 June 2012

TANDLE IN DAMAN MATERIA ARABOTE (CONTRACT CONTROL CARRIEDO). CARRIEDO

TENTH LAUNCH

PROJECT NAME:

POPPY (Byeman

NRO MISSION:

LAUNCH:

Thor-Agena D from Vandenberg AFB, California on

31 May 1967

ORBIT:

Nearly circular with 500 by 508 nautical mile

altitude, 70.0 degrees inclination, and period of

103.3 minutes.



DIAMETER INCHES: 24

27

27

27

WEIGHT FOUNDS:

169

182

162

222

NUMBER RF BANDS:

RF COVERAGE MEIZ

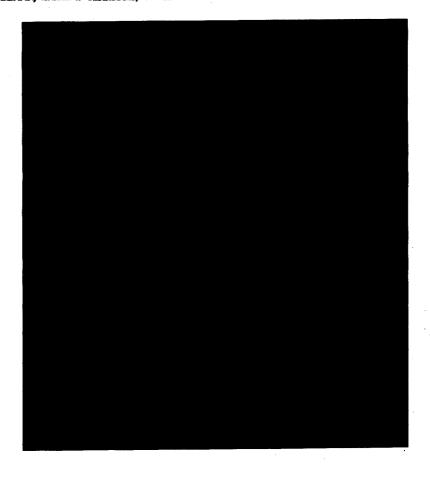
END OF LIFE:

USEFUL LIFE:

INNOVATIONS:

Aspect monitoring systems on all satellites.

6 June 2012 CONTROL SYSTEMS JOINTLY



6 June 2012

TAYLOR TAY DAENIN WATER A KEARCIE CONDA COMBOL CACARAC TOLISELY

ELEVENTH LAUNCH

PROJECT NAME:

POPPY (Byeman

NRC MISSION:

LAUNCH:

Thorad-Agena D from Vandenberg AFB, California on

30 September 1969

ORBIT:

Nearly circular with 491 nautical miles parigee and

506 nautical mile apogee, 70.0 degrees inclination,

and period of 193.5 minutes.

REMARKS:

Thorad-stretched fuel tank on booster

GROUND STATIONS:

(5)(5)

SATELLITES:

DIAMETER INCHES: 27

27

27

27

WEIGHT FOUNDS:

235

228

247

236

NUMBER RF BANDS:

RF COVERAGE MEIZ:

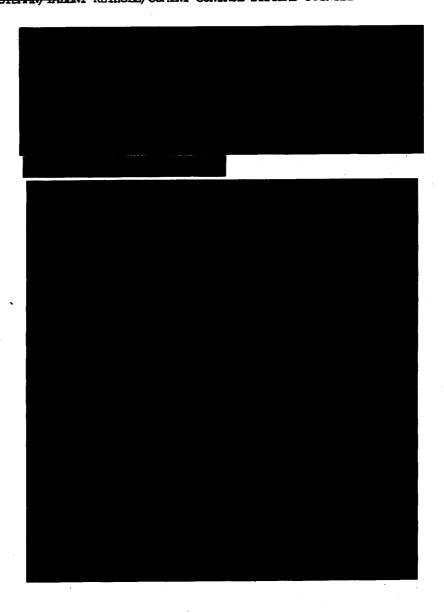
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END OF LIFE:

USEFUL LIFE:

INNOVATIONS:

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6 June 2012

UNDER UIT DEPUNIMENTE PERMOTE/CONDE COMPOL GUERDUC JOHNEY

TWELFTH LAUNCH

PROJECT NAME:

POPPY (Byeman

NRO MISSION:

LAUNCH:

Thorad-Agena D from Vandenberg AFB, California on

14 Decembeer 1971

ORBIT:

Nearly circular with 530 nautical miles perigee and 540 nautical mile apogee, 70.0 degrees inclination,

and period of 184.9 minutes.

GROUND STATIONS:

SATELLITES:

27

27

27

WEIGHT POUNDS:

DIAMETER INCHES:

270

279

282

282

NUMBER RF BANDS

RF COVERAGE MES

END OF LIFE:

USEFUL LIFE:

INNOVATIONS:



NRO APPROVED FOR RELEASE HANDLE VIA BYEMAN/TALENT KEYNOLE/CONTROL SYSTEMS JOINTLY

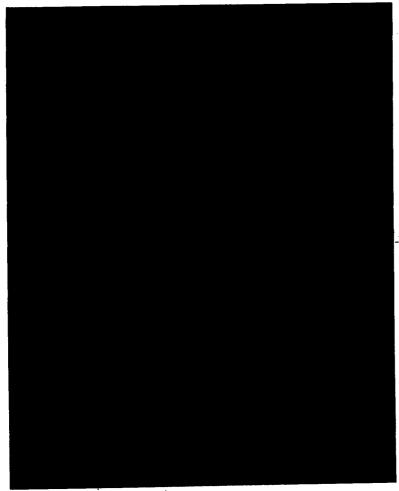
ANNEX 2

COST DATA

NRO APPROVED FOR RELEASE 6 June 2012

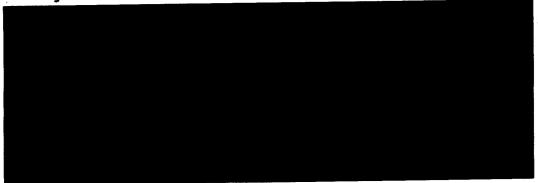
FUNDING AUTHORIZED IN \$MILLIONS

FISCAL YEAR	MISSIONS	ARPA/ NAVY	NRP 1	CCP ²	TOTAL
1958	NONE	0.2		ų.	
1959	NONE	Ø. 225			•
1960	DYNO 1	Ø.79			
1961	DYNO 2 AND ABORT	3 . Ø25			
1962	TWO FAILURES	1.5			



FOOTNOTES ON FUNDING

NRP funding authorizations do not include funding to Program A for costs of launch vehicles and for launch vehicle/satellite integration.



Cumulative program costs for 14 launches (11 successful)

as well as building, deploying, maintaining dedicated ground stations for an 18 year period was approximately dollars, excluding Program A costs for launch vehicles.

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WIA RYFMAN/TALENT KEYHOLE/COMINT CONTROL SYSTEMS JOINTLY

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ANNEX 3

KEY CONTRIBUTORS

NRO APPROVED FOR RELEASE 6 June 2012

KEY MANAGEMENT POSITIONS/INCUMBENTS

Director, Naval Intelligence/Director, Project GRAB:	
RADM L. H. Frost USN August 1959 to Septembe RADM V. L. Lowrance USN September 1960 to July	r 1960 1962
Director, Program C:	
RADM V. L. Lowrance USN	8 1 75
Director, Naval Security Group:	
CAPT L. R. Shulz USN June 1960 to July 1961 RADM T. R. Kurtz USN July 1961 to December 1 CAPT L. R. Shulz USN December 1961 to Januar RADM T. R. Kurtz USN January 1962 to August RADM R. E. Cook USN August 1963 to July 196	
Commander, Naval Security Group Command:	
RADM R. E. Cook USN July 1968 to June 1971 RADM C. G. Phillips USN June 1971 to August 197 RADM G. P. March USN August 1974 to September	4 r 1978
Naval Research Laboratory GRAB/POPPY Project Manager:	
Mr. H. O. Lorenzen August 1959 to February Mr. R. D. Mayo February 1973 to Present	7 1973 it

SIGNIFICANT EVENTS/INNOVATIONS AND KEY CONTRIBUTORS

- 6,June 2012--

INITIAL CONCEPT/SYSTEM PERFORMANCE REQUIREMENTS (NRL)

Mr. R. D. Mayo originated the concept of the Dyno ELINT satellite in early 1958. Messrs. H. O. Lorenzen and J. H. Trexler expanded the concept and coordinated with other organizations to provided for multi-agency participation, collection, and forwarding of data to NSA for processing and product dissemination. RADM Reed of ONI advanced the NRL Proposal through the Navy, ARPA, DOD elements, and the executive branch to secure presidential approval.

SATELLITE DESIGN (NRL)

Mr. M. J. Votaw adapted the Vanguard design to accommodate Dyno and the Solar Radiation cover experiment. He also established the interface between Dyno 1 and Transit 2A for the first dual-satellite launch. Subsequently, Mr. E. L. Dix was the chief design engineer for the satellites. Mr. P. G. Wilhelm became responsible for the satellite technology from 1965 to present.

SATELLITE POWER SUBSYSTEM AND THERMAL DESIGN (NRL)

Mr. F. W. Raymond supervised the overall design of the power subsystem with the solar cell array designed by Mr. J. Yuen and the power subsystem conditioning package designed by Mr. J. G. Winkler. Mr. R. S. Rovinski designed the thermal subsystem for all of the Dyno and POPPY satellites.

COMMAND AND TELEMETRY (NRL)

The command and telemetry subsystems for the first Dyno and the early POPPY satellites were implemented by Messrs. Dix and Wilhelm. Later refinements were made under the supervision of Mr. Wilhelm. These included improved telemetry and data link transmitters by Mr. L. E. Hearton; command and telemetry subsystem expansions and refinements by Mr. Winkler; on-board storage memory for engineering measurements and timed command activation by Mr. R. E. Eisenhauer; and development of the PCM telemetry subsystem by Mr. Eisenhauer and Mr. R. O. Wilson.

The original interrogation and telemetry readout subsystems for the ESV huts were designed and implemented by Mr. Dix. These subsystems were later expanded and refined by Messrs. W. E. Withrow and A. Q. Tool as the transition was made into permanent buildings.

6 June 2012

ELINT COLLECTION (NRL)

Mr. Mayo established the overall performance requirements for the ELINT subsystems in the succession of satellites based on derivation of suitable collection requirements from the current national intelligence requirements. The chief designer of the ELINT payloads was Mr. V. S. Rose. These designs were implemented, tested, and installed in the Dyno and POPPY satellites by Messrs. V. S. Rose, E. G. Becke, and L. E. Earl.

Mr. Mayo designed the original collection system for the ESV huts and supervised implementation. Later refinements and expansions of the collection system inside permanent buildings were supervised by Mr. Mayo with designs and implementation and testing by Messrs. F. V. Hellrich and W. M. McDavit of NRL and by Messrs. L. M. Hammarstrom, M. J. Van de Walle, and J. N. O'Connor of HRB-Singer, Inc.

SATELLITE STATIONKEEPING (NRL)

Mr. R. T. Beal designed and implemented the 2-axis gravity gradient stabilization used in the POPPY satellites. Mr. Beal also designed and implemented the passive tip mast yaw stabilization concept to provide 3-axis stabilization. The active, electronic flywheel yaw stabilization method was adapted from Nimbus satellites for POPPY by Mr. G. E. Flach. Mr. F. Raymond developed the specifications for injecting multiple satellites into their desired orbits. The microthruster subsystems were designed by Mr. Wilhelm and implemented by Mr. P. Carey. Satellite aspect monitoring and control methods were developed by Messrs. Wilhelm, Beal, Raymond, and Rovinski. Mr. Raymond determined the timing and degree of thrusting necessary for stationkeeping. Actual thrusting manuevers were conducted by Messrs. Wilhelm, Carey, and Beal.

LAUNCH VEHICLE/SPACECRAFT INTEGRATION

Mr. Dix coordinated integration efforts for the launches from Cape Canaveral. After 1962, the Director, Program A had the responsibility for booster/spacecraft integration. During later POPPY launch preparations, CAPT G. Geyer USAF supervised contractor functions and coordinated with NRL representatives from Mr. Wilhelm's organization.

SIGNAL LEVEL, (NRL)

Mr. Eisenhauer conceived and designed the signal level measurement experiments used in POPPY. These designs were implemented and refined by Messrs. B. W. Ryon and J. W. Phillips.

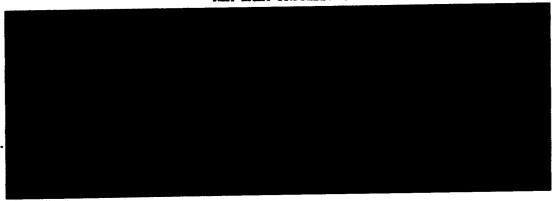
MISSION GROUND STATION FACILITIES (NRL)

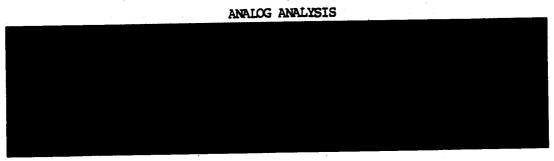
Mr. C. W. Price adapted the ESV huts for Dyno and POPPY interrogation and collection functions, including the ESV hut layouts and installations of equipment. Later, Mr. Price coordinated the moves into permanent buildings and equipment installations with cognizant personnel He developed the preliminary building design and facility concept as well as provided the layout of the operational equipment for the receiving recording and data processing for the three MILCON projects.

MISSION GROUND STATION OPERATIONS MANAGEMENT (NSG)

CDR F. Hitz chaired the first TOG steering committee and supervised the development of the GRAB/POPPY operations management system. Key focal point managers during the project's coming-of-age were Commanders L. McGraw and R. W. Olson. Among the POPPY project officers at mission ground stations making significant contributions to management and data exploitation were Lieutenants R. L. Potts, R. E. Lentz, B. F. Booth, and R. L. Kellogg. CPO R. B. Kargle was foremost among the senior enlisted men who managed personnel and day-to-day operations and propagated their knowledge of ELINT in the field. ICDR J. Morgan of NSG headquarters coordinated operations with POPPY project officers during the early seventies and organized the POCG at NSA in 1975.

NSA DATA PROCESSING



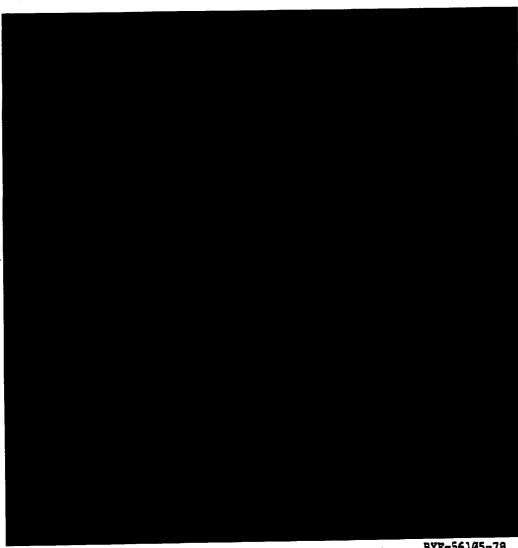


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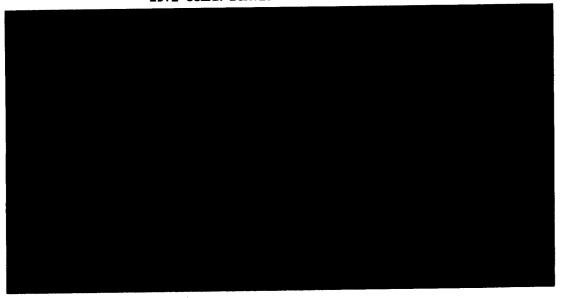
KENNOLE/CONDIN COMBOL SYSTEMS

FIELD DIGITIZATION

Mr. F. V. Hellrich of NRL and Mr. L. M. Hammarstrom of HRB were the architects of the system to digitize POPPY data in the field in 1967. Mr. M. J. Van de Walle of HRB developed the first linear phase receiving system and the RS-lA solid-state receivers. Mr. M. Sheets of NRL conceived of and specified the adaptive thresholding technique. Mr. T. W. Fisher and Mr. J. R. Lindley of NRL designed and implemented the buffered memory digital recording system for the ADDS/digital tape interface.



1971 OCEAN SURVEILLANCE AUGMENTATION



SYSTEM ENGINEERING AND INTEGRATION

Mr. L. M. Hammarstrom of HRB and, subsequently, NRL provided overall spacecraft/ground station engineering, integration, and testing functions 1964 through 1976.

GENERAL

The above names and contributions are representative of generations of talented and dedicated individuals from NRL, NSA, NSG, AFSS, ASA, CIA, HRB, CNI, Program C staff, Program A, NRO staff, and NAVSPASUR who developed, operated, supported and exploited the POPPY System.

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ANNEX 4

GLOSSARY OF POPPY-RELATED TERMS

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TERM EXPLANATION

Athos

- German-developed crystal video receiveer of WWII. Probably named after Mount Athos in northeastern Greece, home of celibate monks inhabiting 20 monastaries. One thousandth anniversary of founding of first monstary, Great Lavra, in 1963. Book on Athos monastaries published in Germany in 1943 (Moenchsland Athos by F. Doelger).

GRAB

- Galactic Radiation and Background. Covername for Project Dyno ELINT satellites.

GREB

- Galactic Radiation Energy Balance.

- NRO SOC title for Mission series Reports Control

Manual.

- Unclassified name used at NSA for POPPY project. Reptile

SISS ZULU - Unclassified name used within the Naval Security Group to refer to the POPPY project.

- Solar Radiation measurement packages carried along with SOLRAD ELINT payloads. This legitimate scientific payload formed excellent "cover story" for the Dyno ELINT payloads through the pre NRO period.

Transit 2A - Second Navy navigation satellite, shared launch vehicle with Dyno 1 on 22 June 1960. First successful dualsatellite launch.

Transit 4A - Navy navigation satellite was the primary payload on the launch vehicle with Dyno 2 on 29 June 1961.

Name of security project for safeguarding details of the Walnut Dyno ELINT satellites. CANIS security oath.

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ANNEX 5
BIBLIOGRAPHY

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NRL technical satff

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