

*BIN BIF/055-02269-69*

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page 27*

*R. Maratt  
als*



APR 4 - 1969

~~SECRET~~/DORIAN  
HANDLE VIA BYEMAN SYSTEM ONLY

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RELEASE 1 JULY 2016

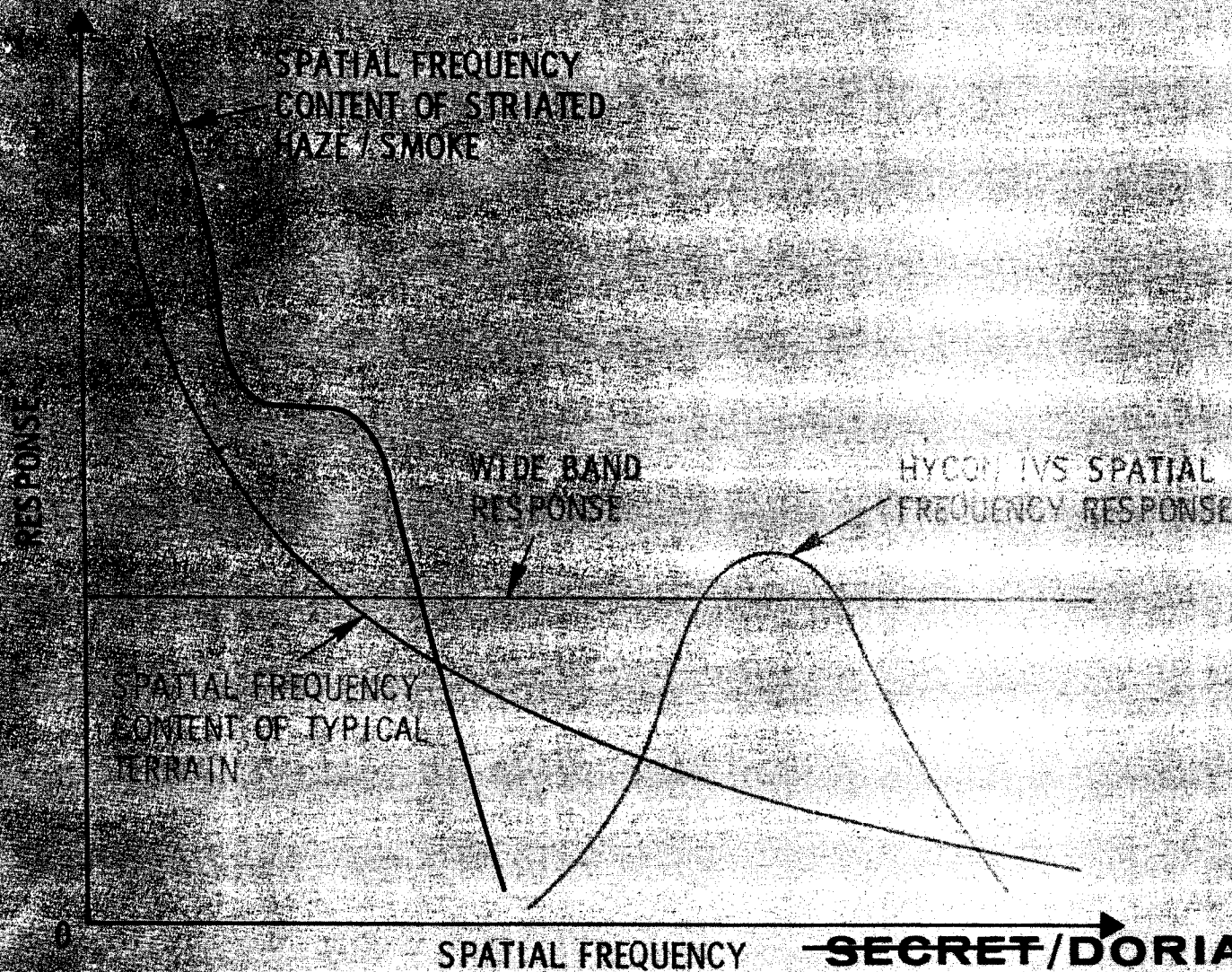
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*PURPOSE*

TO SENSE IMAGE MOTION THROUGH ATMOSPHERE

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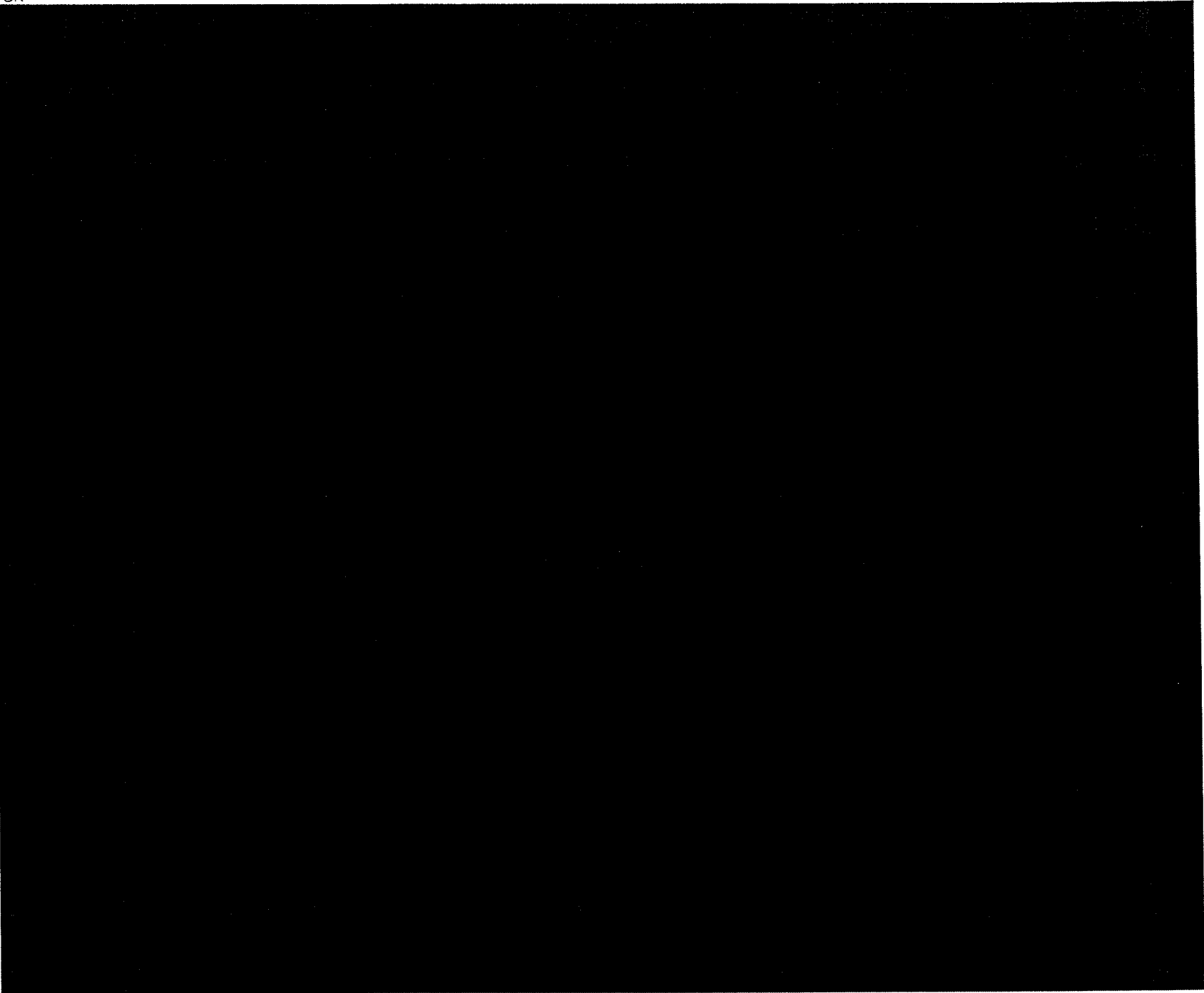
# ~~SECRET/DORIAN~~ SELECTION OF IVS SPATIAL FREQUENCY RESPONSE



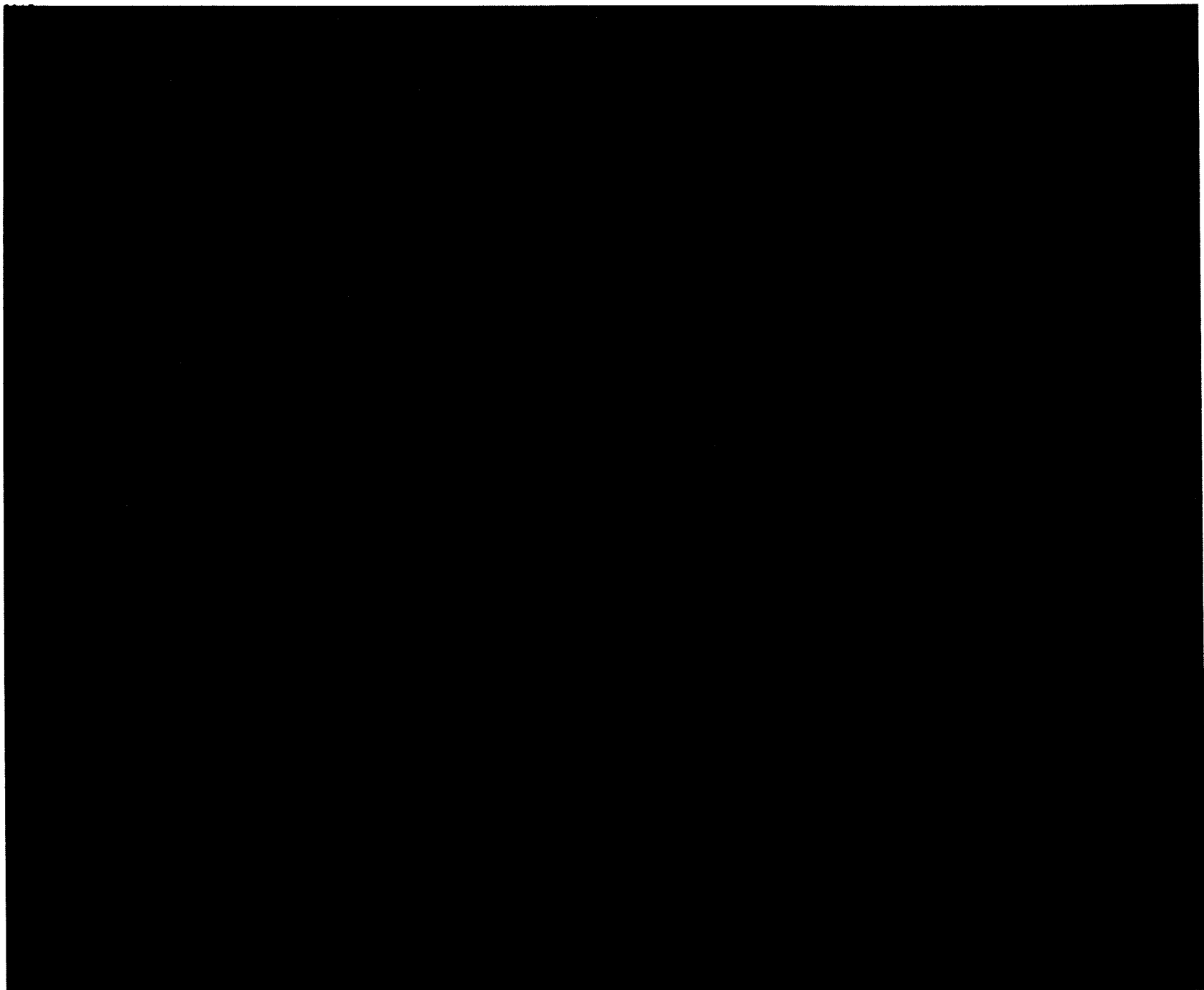
SPATIAL FREQUENCY

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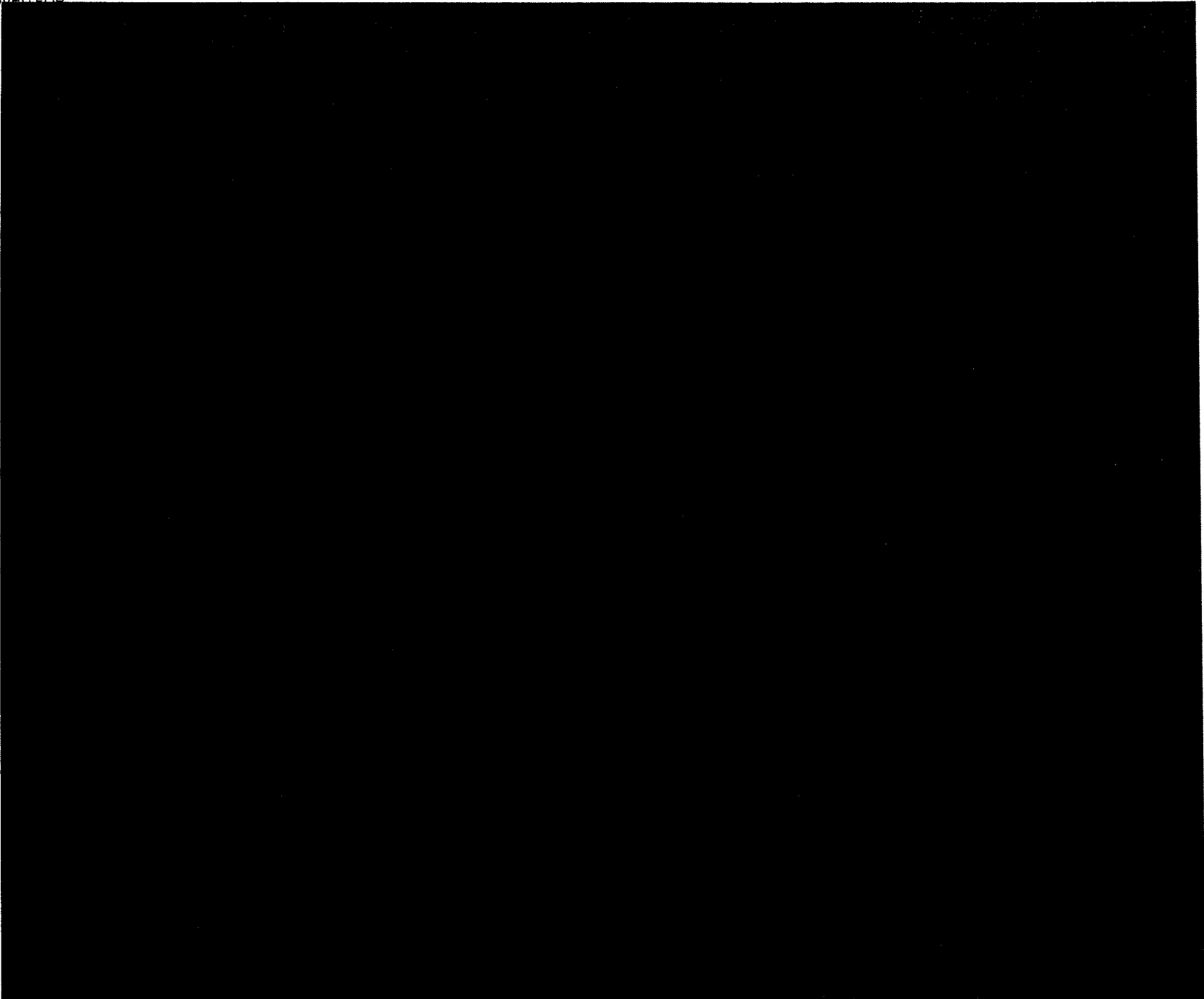
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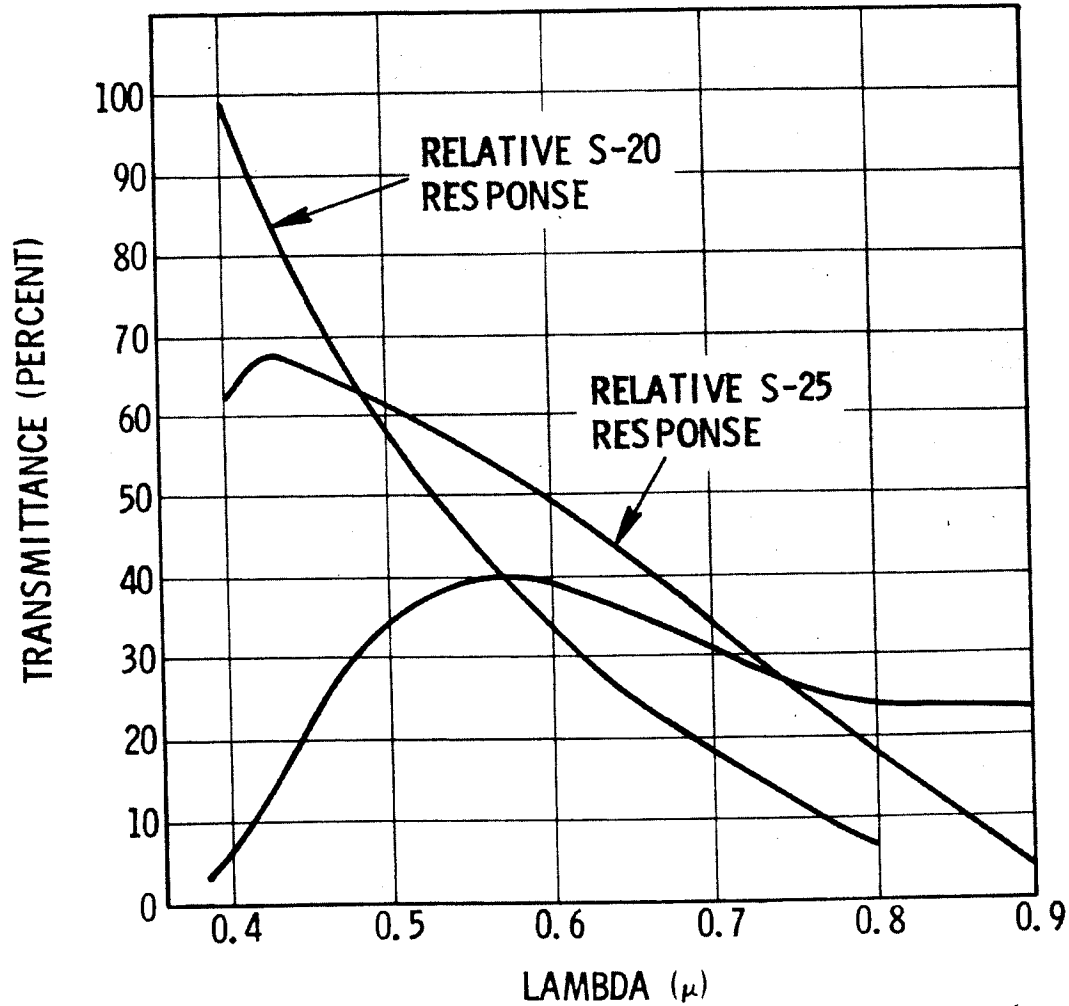


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S-20 VS S-25 PHOTOCATHODE

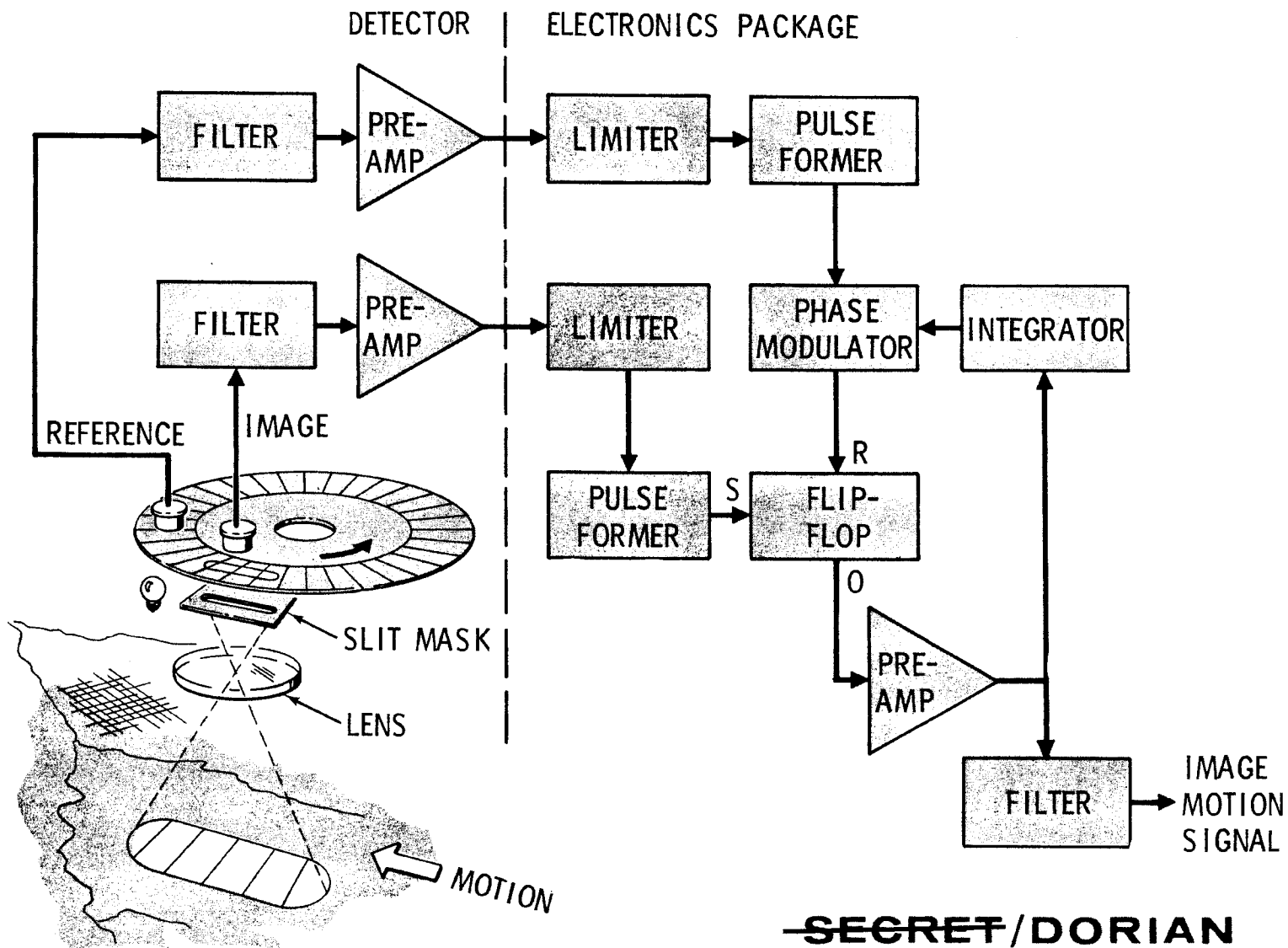


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# IVS OPERATION

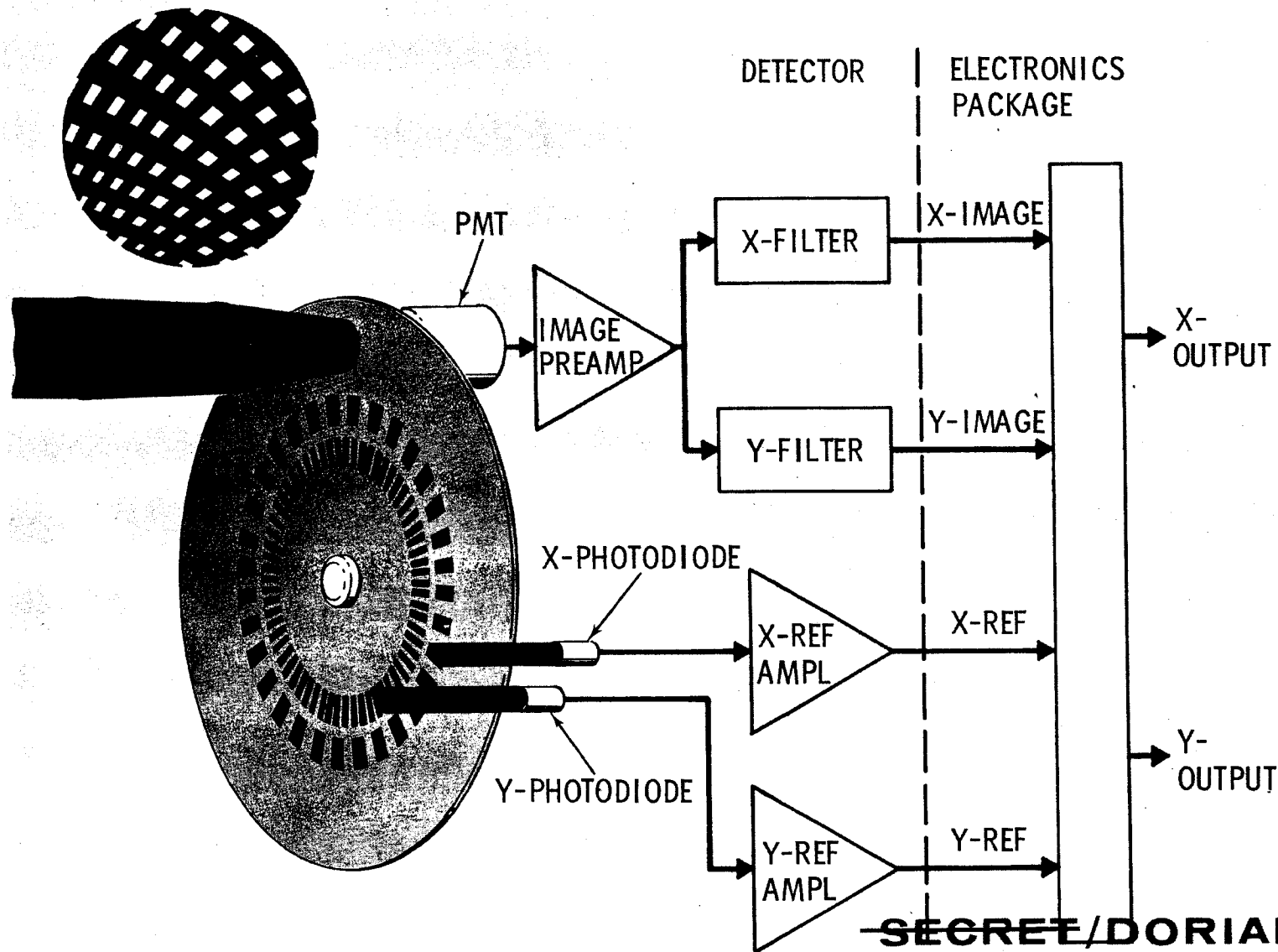


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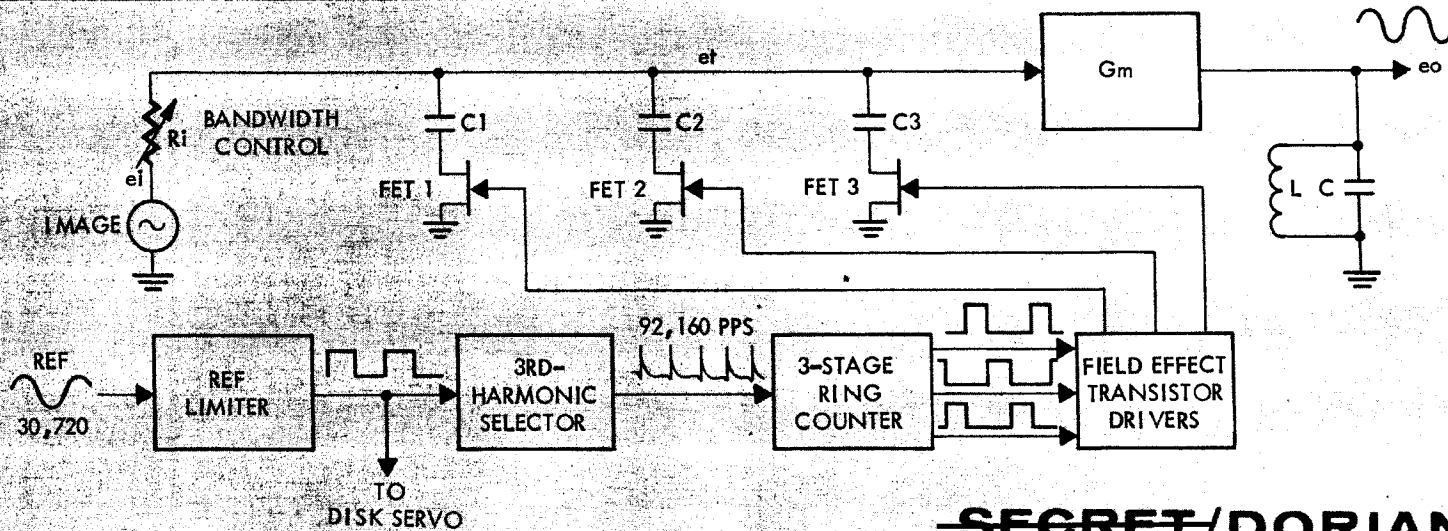
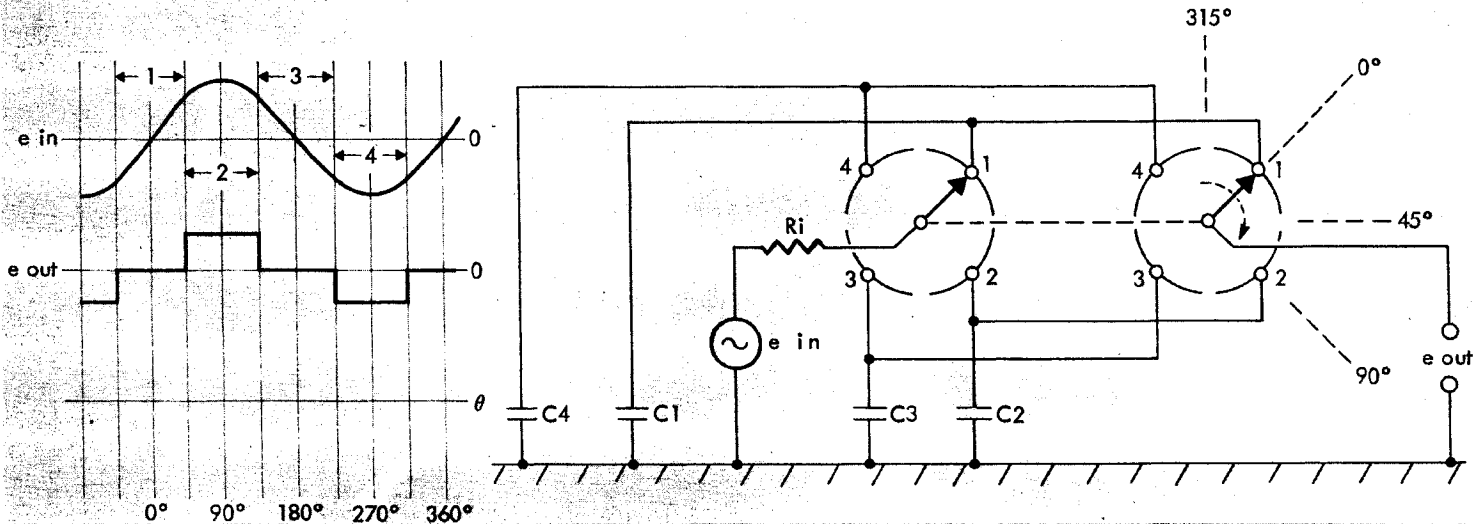
# HERRINGBONE X-Y SENSOR



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# THE COMMUTATING FILTER



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# *STATUS - APRIL 1968*

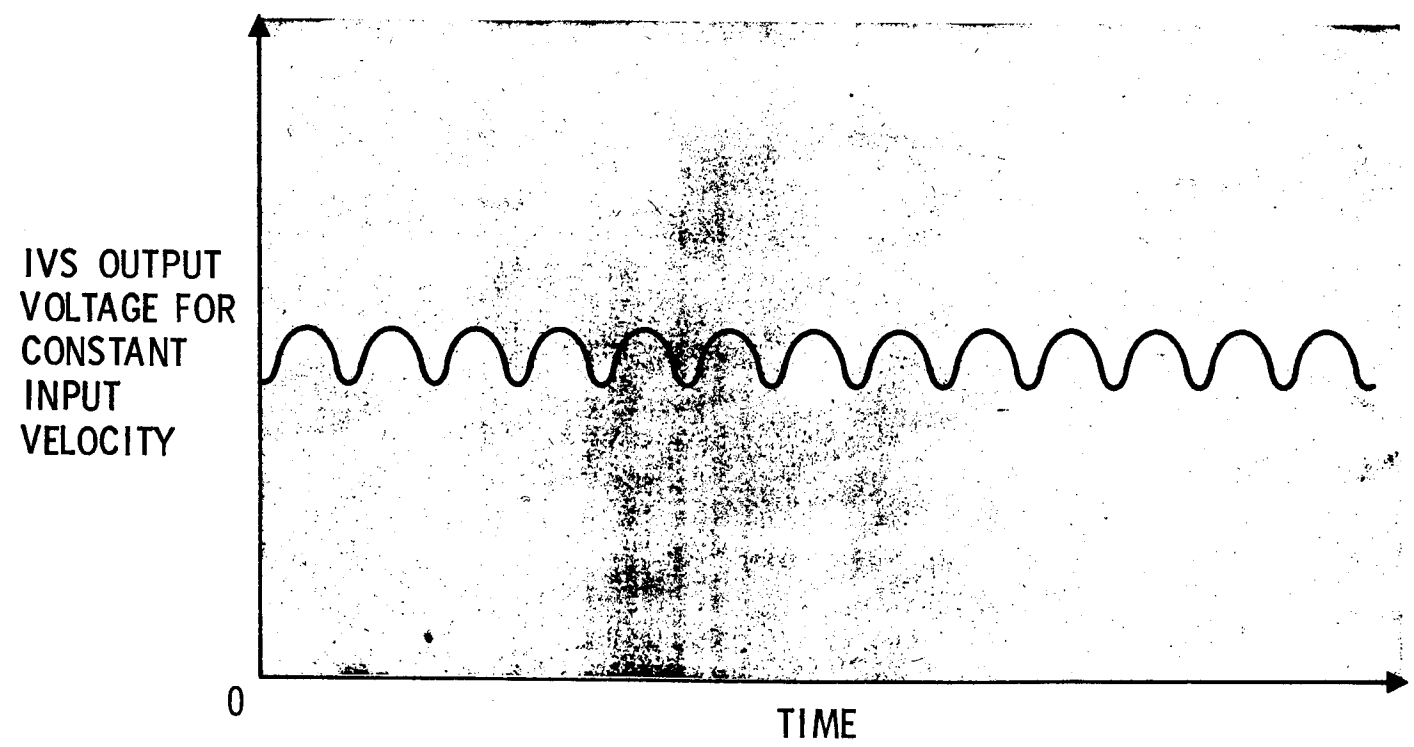
## PROBLEMS AND DESIGN IMPROVEMENTS

- SCALLOPING
  - APERTURE OPTIMIZATION
  
- DYNAMIC NULL PERTURBATIONS
  - APERTURE OPTIMIZATION
  - SLOPE LIMITING
  
- DROPOUTS
  - HERRINGBONE CONCEPT
  - MEMORY CIRCUIT
  - COMMUTATING FILTER

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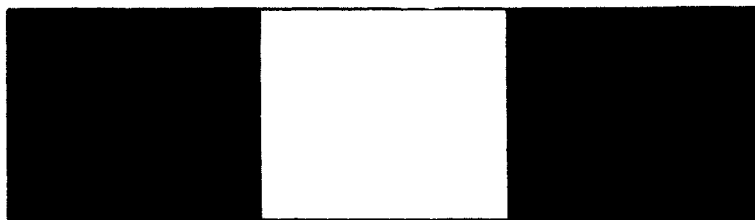
# SCALLOPING



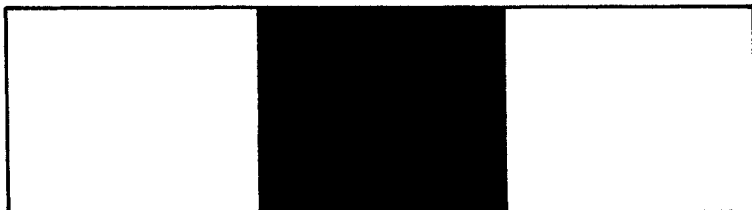
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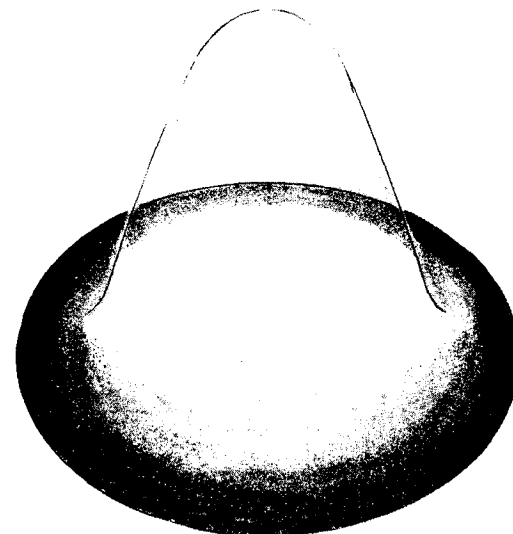
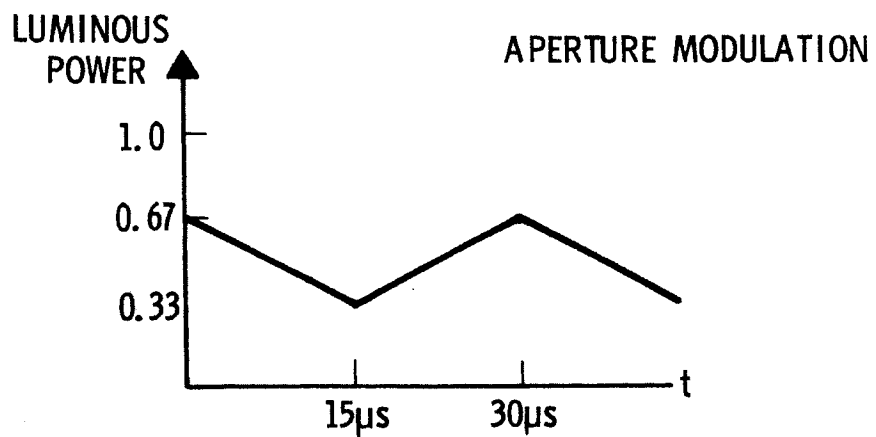
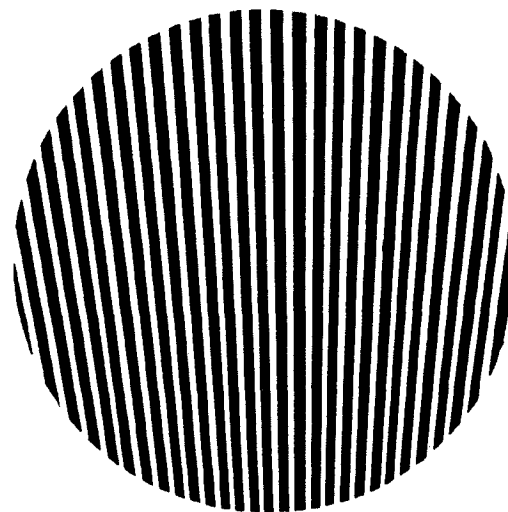
# SHADED APERTURE



$$T_1 = 0.33$$



$$T_2 = 0.67$$



11B

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# *CURRENT STATUS*

- SCALLOPING

ELIMINATED BY SHADING

- DYNAMIC NULL PERTURBATIONS

APERTURE OPTIMIZATION

PROPORTIONAL PLUS DERIVATIVE  
SENSING OF SIGNAL AMPLITUDE

- WEIGHT

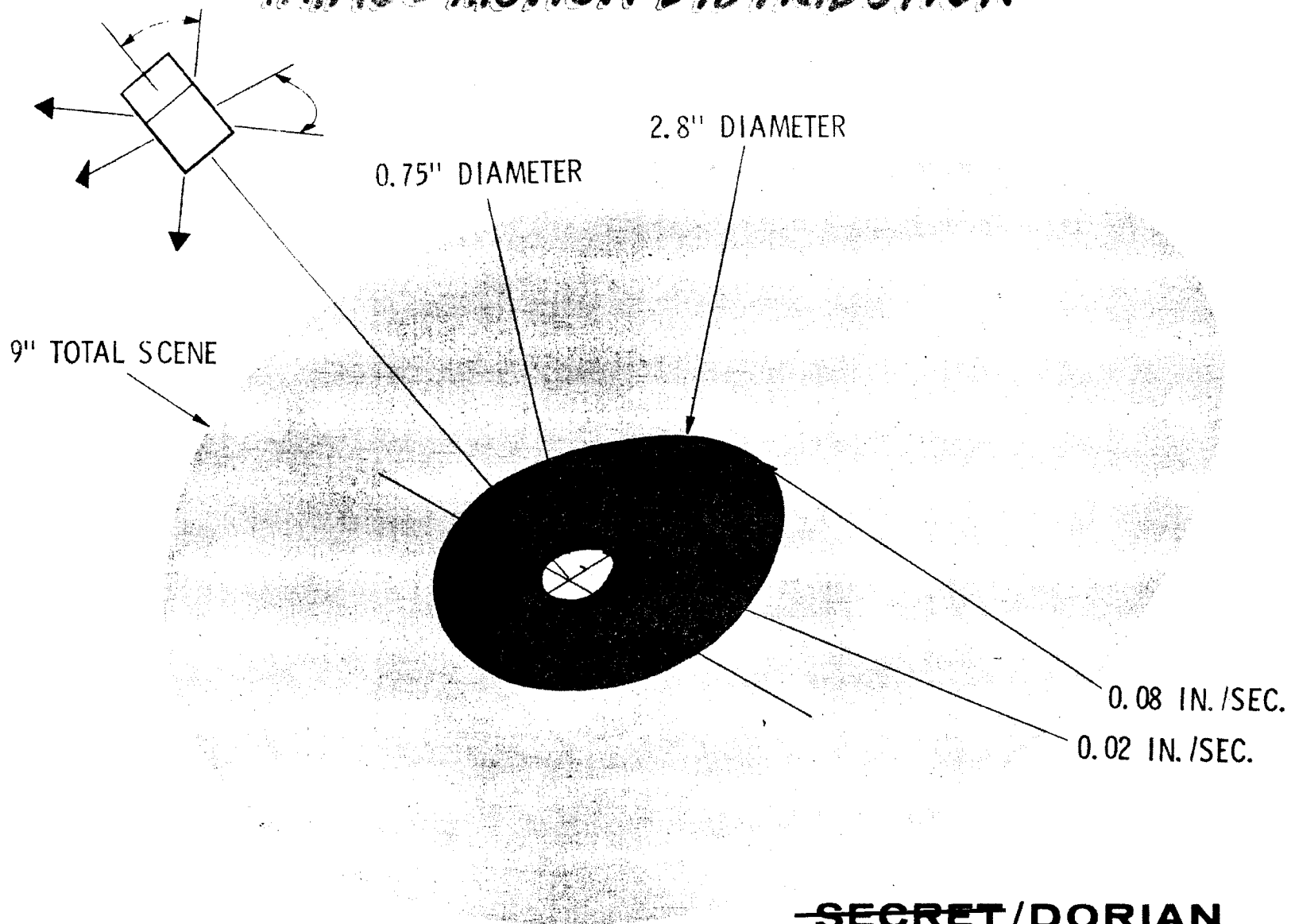
HERRINGBONE IVS

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# IMAGE MOTION DISTRIBUTION



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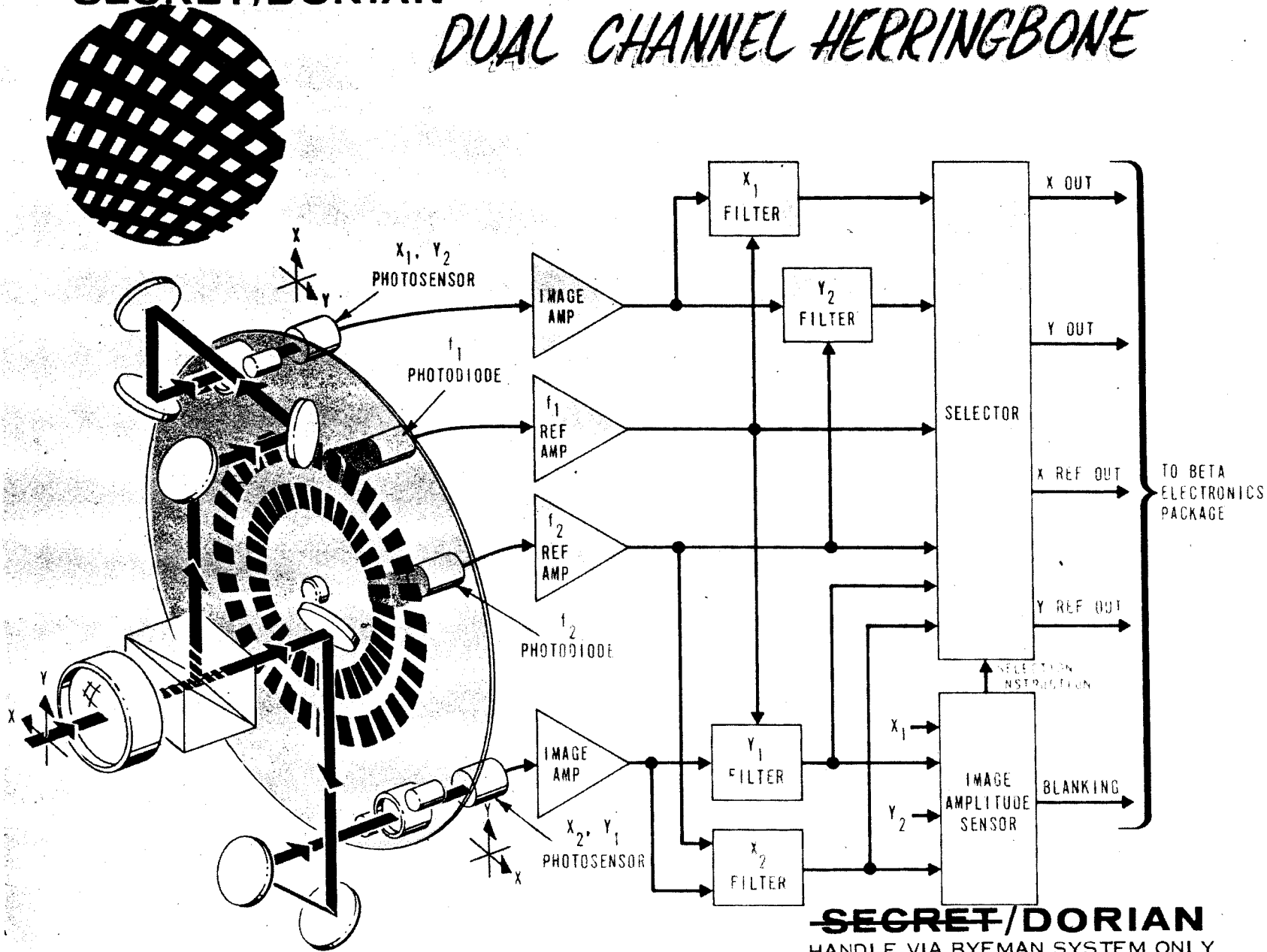
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IMPROVED IVS SPATIAL FREQUENCY  
RESPONSE BY IMAGE SCALE CHANGE

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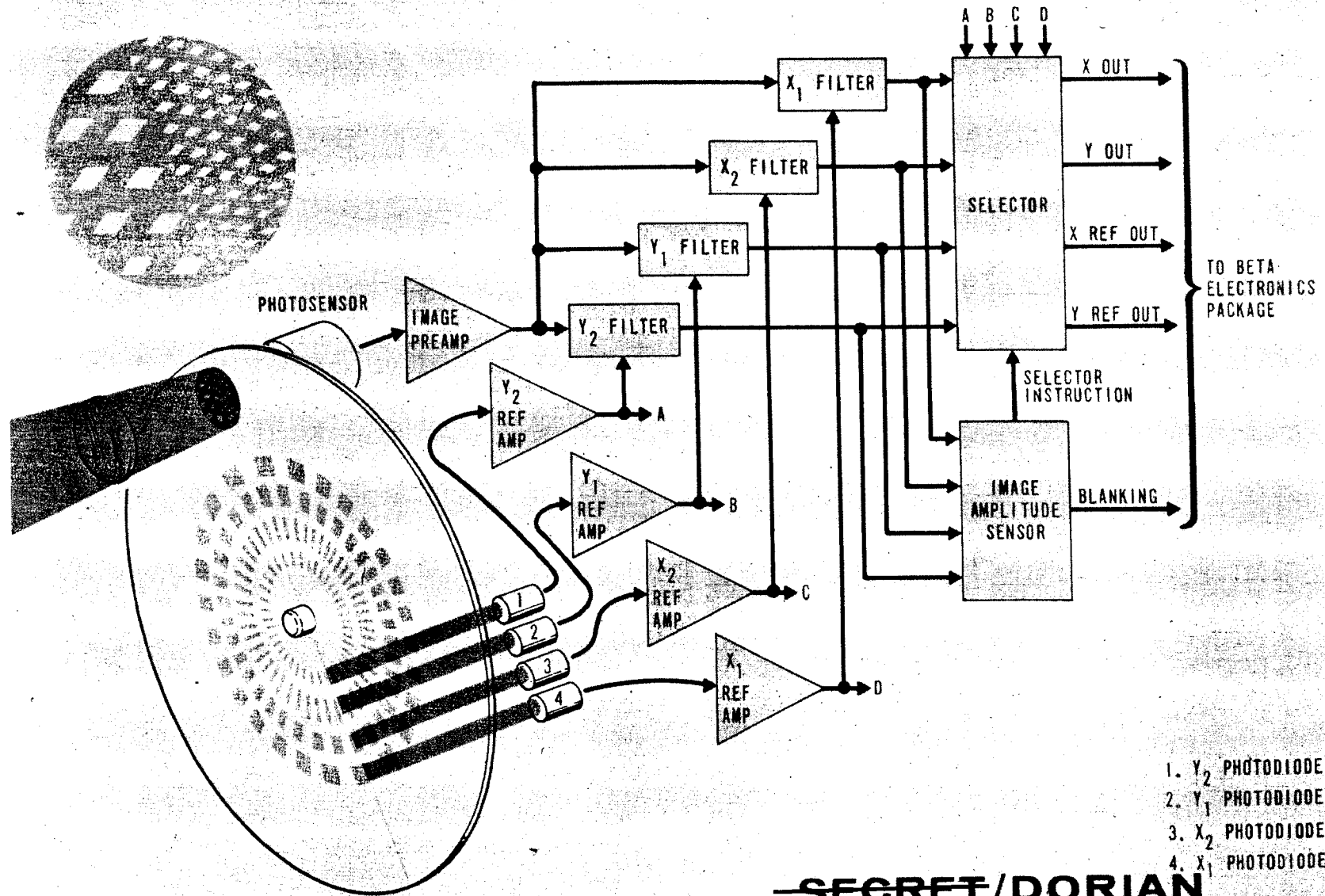
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# DUAL CHANNEL HERRINGBONE



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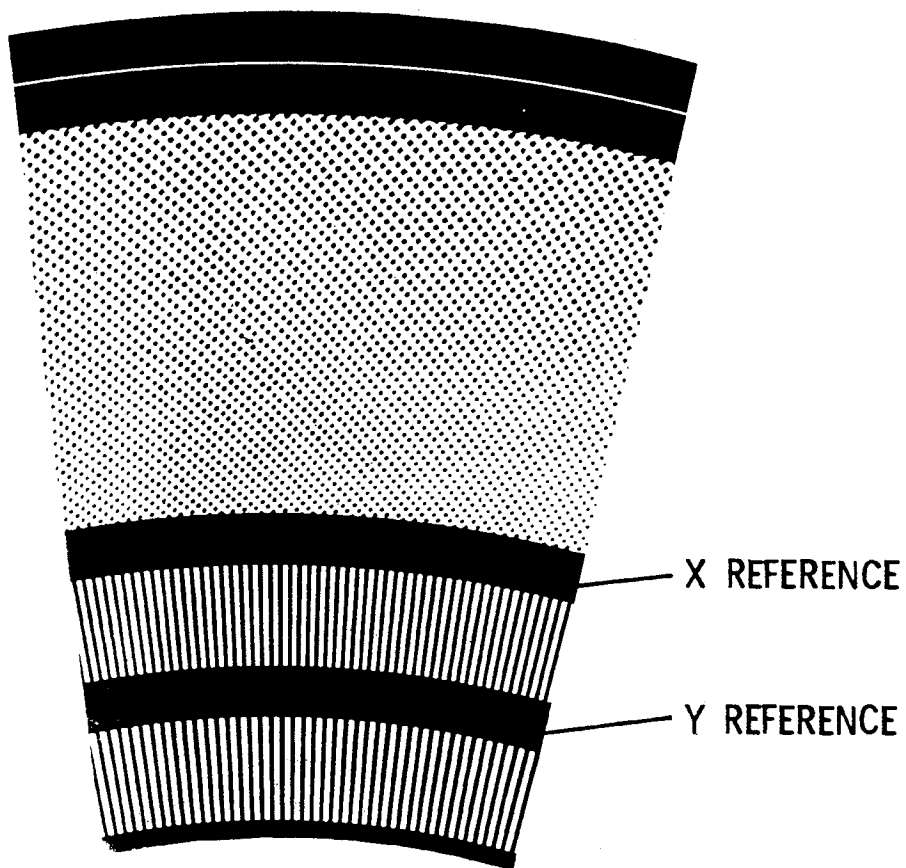
# ~~SECRET/DORIAN~~ SPLIT HERRINGBONE



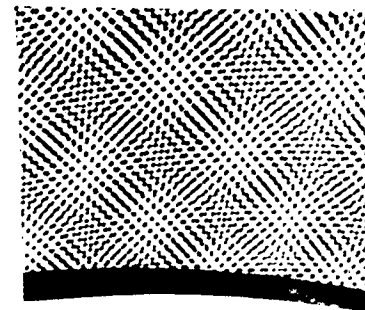
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# *DISC CONSTRUCTION*



SINGLE HERRINGBONE



DUAL HERRINGBONE

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# ~~SECRET/DORIAN~~ *EQUIPMENT PERFORMANCE REQUIREMENTS*

		PERFORMANCE	
	REQUIREMENT	NOW	CDR (EST)
● DYNAMIC RANGE	0 - 0.3 IPS	0 - 1.0 IPS	SAME
● GAIN FACTOR	16.67 V/IPS	16.67 V/IPS	SAME
● LINEARITY			
LARGE SIGNAL	SLOPE LIMITS 1.0 ± 0.25	SLOPE LIMITS 1.00 ± <0.10	SAME SAME
NULL	SLOPE LIMITS 1.00 ± 0.10	SLOPE LIMITS 1.00 ± <0.05	SAME SAME
● SATURATION	5V/0.3 IPS	MEETS REQUIRE- MENTS EASILY	SAME

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# EQUIPMENT PERFORMANCE REQUIREMENTS (CONT)

		PERFORMANCE		
	REQUIREMENT	NOW	CDR (EST)	
▲	NOISE AND BIAS (NULL REGION)	0.010 IPS (2 $\sigma$ )	$\leq 0.010$ IPS (2 $\sigma$ )	SAME ●
●	FREQUENCY RESPONSE	1ST ORDER LAG OVER OUTPUT RANGE 0.001 - 0.25 IPS. BREAK FREQ $\geq 1$ HZ	MEETS REQUIRE- MENTS	SAME
●	RECOVERY TIME AFTER SATURATION	IN SATURATION OVER 2 SEC., RECOVERY $\leq$ 0.5 SEC.; IN SATURA- TION 2 SEC. OR LESS, RECOVERY $\leq 0.1$ SEC.	$< 0.050$ SEC.	SAME




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**EQUIPMENT PERFORMANCE REQUIREMENTS**  
**(CONT)**

		PERFORMANCE	
	REQUIREMENT	NOW	CDR (EST)
● SUB-THRESHOLD IRRADIANCE SIGNAL	FLAT INPUT OF $4 \times 10^{-9}$ WATTS/CM <sup>2</sup> PER 10 NANOMETERS ( $\Delta \tau$ ) OVER RANGE 400 - 900 NANOMETERS	MEETS REQUIREMENTS	SAME
● RELIABILITY	MTBF $\geq 10,000$ HOURS	21,500 HRS (CAL)	WILL MEET
● WARM-UP TIME	$\leq 2$ MINUTES	< 40 SECONDS	SAME

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# ~~SECRET/DORIAN~~ **EQUIPMENT INTERFACE REQUIREMENTS**

		PERFORMANCE	
	REQUIREMENT	NOW	CDR (EST)
 INPUT POWER			
AVERAGE	< 26 WATTS	27 WATTS	25 WATTS
PEAK	< 50 WATTS	< 30 WATTS	≤ 30 WATTS
 WEIGHT			
HEAD	< 14 POUNDS	7.3 POUNDS	7.3 POUNDS
TOTAL	< 23 POUNDS	17.2 POUNDS	17.2 POUNDS
 SPACE ENVELOPE			
HEAD	PER DWG 711-03013	MEETS	WILL MEET
E. P.	6 X 9 X 6 INCHES	MEETS	WILL MEET

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**EQUIPMENT INTERFACE REQUIREMENTS (CONT)**

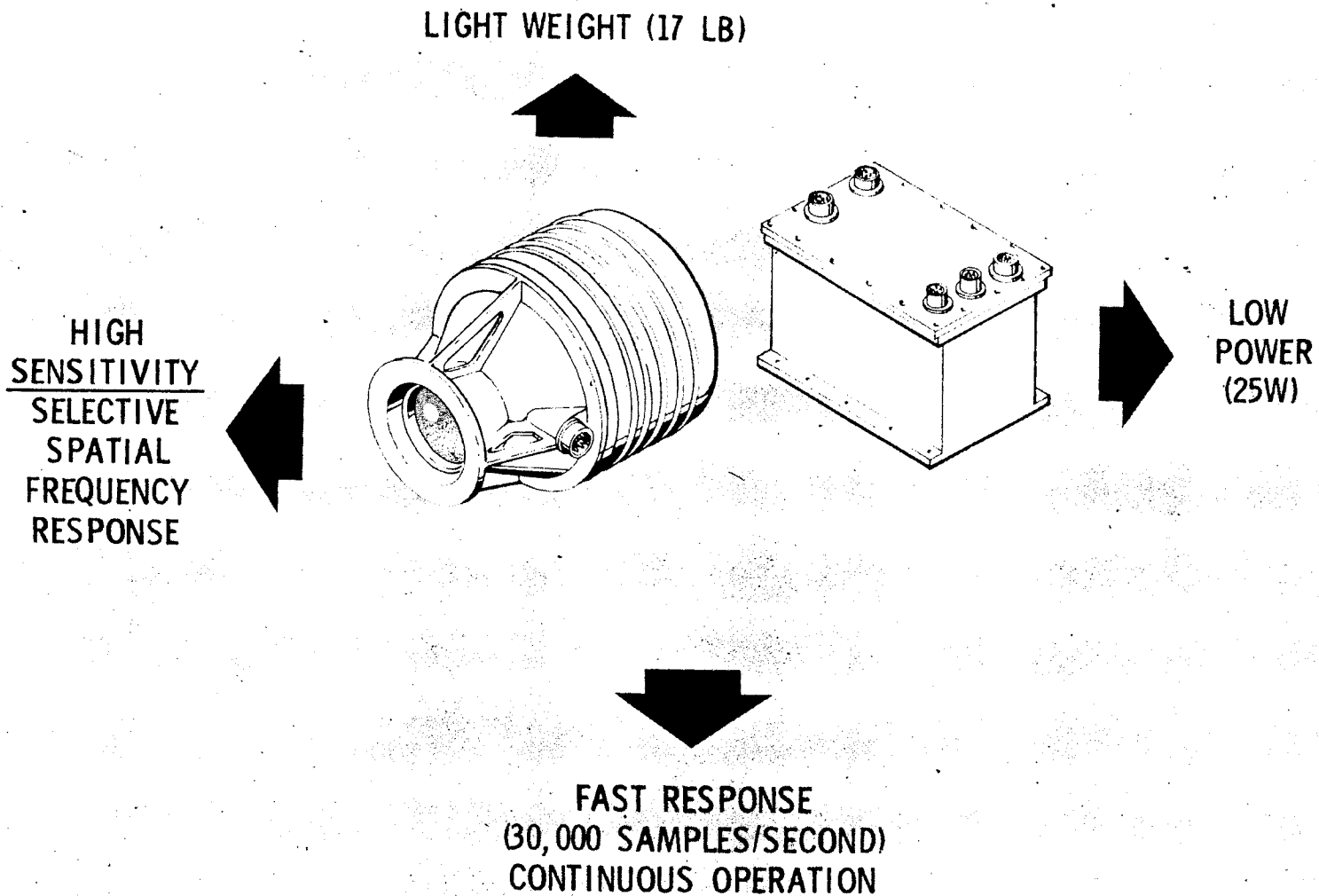
	REQUIREMENT	NOW	PERFORMANCE CDR (EST)
● GENERATED DISTURBANCE			
VIBRATION (DURING EXPOSURE)	≤ 3.0 IN-OZ (ANY AXIS)	MEETS	WILL MEET
	≤ 0.01-LB AXIAL FORCE (ANY AXIS)	MEETS	WILL MEET
VIBRATION (DURING SLEW)	2 X ABOVE	MEETS	WILL MEET
RESONANCE	> 55 HZ	MEETS	WILL MEET
ACOUSTIC NOISE	PER 3.2.13 OF DR-1100B	MEETS	WILL MEET

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**EQUIPMENT INTERFACE REQUIREMENTS (CONT)**

	REQUIREMENT	NOW	PERFORMANCE CDR (EST)
● CG OF HEAD			
DISTANCE FROM CENTERLINE NORMAL TO MOUNTING PLANE	WITHIN 0.25"	X = 0.17", Y = 0.49"	WILL MEET
DISTANCE FROM INPUT IMAGE PLANE	< 7.25"	4.53"	4.43"
● THERMAL DISSIPATION HEAD	MINIMUM POSSIBLE DESIGN GOAL $\leq 3$ WATTS	< 4 WATTS	< 4 WATTS

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